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1 How to build a digital river

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16

17 **Abstract**

18 There has been an increasing practice of creating Earth-like, realistic synthetic
19 landscapes by Earth scientists and computer scientists for a variety of applications.
20 While together these two fields have made significant scientific and social contributions
21 to creating synthetic landscapes, it is presently infeasible to build artificial digital rivers
22 that represent the diversity found on Earth. To understand and summarize the state of
23 the science of rendering artificial river topography, we reviewed more than 225 scientific
24 articles and produced a road map for artificial synthesis of digital river topography. We
25 broadly classify methods of digital river synthesis by whether they are driven by expert-
26 based decisions or are strategic in the use of rules for objective rendering, with some
27 rules being physics-based theories of river morphogenesis. Expert approaches include
28 map, brush, geometric and interactive design. Strategic approaches include
29 deterministic equilibrium models, morphodynamic models, and stochastic approaches.
30 For each approach we discuss the conceptual basis for each method and how they can
31 be applied. Readers can then identify what methods can create different types of digital
32 riverscapes. We close by discussing how cross pollination can serve geomorphology
33 and computer science, the role of digital rivers in furthering geoscience progress, and
34 future directions in digital river synthesis.

35

36 Keywords: topography; rivers; morphology; landforms; digital elevation modeling

37 **1 Introduction**

38 There has been a steady practice of creating synthetic (aka artificial) landscapes
39 by Earth scientists, computer scientists, landscape architects, graphic artists, and civil

40 engineers (Goodchild, 2008, 2012; most figures in this article illustrate such
41 applications). Rivers are a key component of real and synthetic digital landscapes.
42 Digital rivers are artificial rivers created and experienced using computers; they
43 represent major elements of the digital Earth (Goodchild, 2012). Reviews exist for
44 creating entire landscape terrains from geomorphology (Coulthard, 2001; Martin and
45 Church, 2004; Wilgoose, 2005; Tucker and Hancock, 2010) and computer science
46 (Smelik et al. 2014), but none exist that combine these perspectives into a single
47 scientific road map spanning theories and procedures for creation of synthetic river
48 topography. The purpose of this article is to provide such a review.

49 The purpose of synthesizing artificial landscapes varies considerably, resulting in
50 a diverse spectrum of theories and methods capable of creating different virtual
51 realizations of artificial river corridors. Traditionally, Earth scientists, especially
52 geomorphologists, have explored synthetic terrain generation through landscape
53 evolution models (LEMs). In this context, the goal has been to understand the
54 mathematical requirements for creating observed landscapes as well as how they will
55 evolve in “what-if” scenarios, typically related to different tectonic and climatic regimes
56 (Tucker and Slingerland, 1997). Independently, computer scientists and graphic artists
57 approached terrain modeling with the goal of creating realistic virtual scenes with limited
58 user input and computing resources (Doran and Parberry, 2010). In an applied sense,
59 river scientists, engineers, and landscape architects also create digital river topography
60 for a wide variety of uses, such as experimentation (Brown et al., 2014), irrigation
61 (Lacey, 1929), navigation (Bhowmik et al., 1986), recreation, flow and sediment regime
62 management (Chang and Osmolski, 1988), and river restoration (Pasternack, 2013).

63 While these fields have made significant contributions to creating synthetic landscapes,
64 there does not exist a review on this topic that spans disciplines. This remains a
65 tremendous gap in a communal understanding of the state of ideas and practices in
66 building digital rivers.

67 There are several reasons why artificial digital river topography is important for
68 Earth scientists, engineers, computer scientists, landscape architects, graphic artists,
69 and river restoration designers. First, fluvial geomorphologists already use synthetic
70 channels to investigate form-process linkages (Wohl et al., 1999; Cao et al., 2003;
71 Pasternack et al., 2008; Brown et al., 2014) and potentially to test the realism of
72 landscape-scale morphodynamic models (Hillier et al., 2015). Second, in virtual scene
73 generation, artificial river topography enables simulated water flow to dynamically
74 interact with a non-trivial boundary so that water speed and water surface elevation can
75 be spatially explicit variables as opposed to flat water terrains being used. With the
76 advances in computational fluid mechanics and reduced complexity models, it is not
77 unrealistic to expect for dynamic water flow to become an integral aspect of digital
78 landscapes beyond their current use in video games and movies. Third, virtual scenes
79 with synthetic rivers would enable scientists, engineers, and stakeholders (i.e., the role
80 players) to interact with river topography and derivative environmental simulations in
81 more realistic ways than having a smooth and uniform riverbed. Video game players
82 already have such interactions with flow, fish, and other aquatic entities in digital rivers
83 for fun, but this could be put to practical use.

84 Multiple disciplines would benefit from an overview of the various ways synthetic
85 digital river topography can be generated. Moreover, it would benefit all communities by

86 guiding future modeling efforts with an understanding of what the current palette of tools
87 and methods can generate. There is a plethora of applications outside of fluvial
88 geomorphology, such as virtual reality and scene generation, education, and river
89 channel design, yet there is no comprehensive guidance that speaks to the
90 multidisciplinary aspect of creating artificial river topography.

91 This review bridges the gap between scientists, who study linkages between
92 process and form in the environment, and practitioners who create virtual landscapes
93 for a variety of practical and entertainment applications. The objectives of this scientific
94 review article are to: (i) present a road map for the synthesis of digital rivers from
95 existing methods, (ii) discuss the conceptual basis for each method and how they can
96 be applied, and (iii) discuss emerging methods and future directions for building digital
97 rivers. This review focuses on nontidal rivers with water flow driven by gravity, although
98 there is some mention of distributary channels that may occur on alluvial fans and
99 deltas as well as in tidal coastal lowlands broadly. More than 225 articles were
100 reviewed. This list is not exhaustive, because so many different topics are reviewed.
101 Rather, our approach has been to highlight key studies across the breadth of the
102 scientific road map that help meet the article's goals.

103 **2 Road Map For Building Digital Rivers**

104 Figure 1 is a flow chart to guide artificial synthesis of digital river topography
105 based on current approaches. First, the overall rationale of the flow chart is discussed
106 here along with nomenclature. Second, we briefly discuss the various routes for
107 synthetic terrain generation. Third, we discuss river generation when a surrounding
108 terrain is not present. Later in the article expert and strategic synthesis are discussed in

109 more detail and then each method is reviewed.

110 The first step in building a digital river is determining whether a terrain outside of
111 the river channel exists or is even needed. Primarily this serves to establish how the
112 planimetric alignment of the river or river network is located on the Earth's surface. If
113 there is an existing terrain with a channel on an alignment, then reach- (10^2 - 10^3 channel
114 widths) or segment- scale (10^3 - 10^4 channel widths) characteristics used to scale the
115 size of the river to the terrain need to be extracted for subsequent steps. For the rest of
116 this review we will refer to only river reaches for brevity, but the concepts apply to
117 segments, too, ideally by breaking them into reaches and proceeding to apply this
118 framework on each one, with some transitional blending from reach to reach. If a terrain
119 is needed, but does not exist, then one can be created from a variety of approaches
120 discussed in section 3. When a terrain is not needed, the user should conceptualize the
121 purpose of modeling along with the desired river typology, scale and resolution. At this
122 stage, the user can create river channel topography using either expert or strategic
123 approaches.

124 There are two broad approaches to digital river creation that we term as either
125 expert or strategic synthesis. In expert synthesis a user explicitly describes each aspect
126 of the river being created. It includes (i) geometric, (ii) object, (iii) map, and (iv) brush
127 approaches (discussed in Section 5). In strategic synthesis a user specifies a set of
128 initial attributes of the digital river, but subsequent modeling uses these attributes to
129 yield a "heightmap" (i.e., a 2D grid whose cell value is a height, making it a 3D digital
130 elevation model), analogous to procedural terrain generation methods in the computer
131 science literature (discussed in Section 6). Strategic synthesis relies on the rules or

132 specified probabilities to determine the final heightmap outcome and includes
133 deterministic and stochastic models. The difference between these two approaches to
134 strategic synthesis is that deterministic approaches are driven by underlying
135 mathematical equations based on mechanistic physics (as revealed through theory and
136 empiricism), while stochastic approaches represent terrains that have a chance to occur
137 with set probabilities and begin with random seeds. Deterministic approaches include
138 equilibrium models, traditional morphodynamic models, cellular automata variants, and
139 discrete particle models. Each of these requires that initial conditions be specified such
140 as the incoming flow and sediment load and initial channel geometry. There are
141 similarities in that these all evaluate the time evolution of the initial conditions specified,
142 but they differ in how the underlying mathematical rules are implemented, both
143 conceptually and computationally. Stochastic models include inverse spectral, auto-
144 regressive and object-based approaches.

145 **3 Generating Synthetic Landscape Terrains**

146 We define three approaches to landscape terrain synthesis: (i) geomorphic
147 landscape evolution models (LEMs), (ii) procedural models, and (iii) expert-based
148 modeling (Table 1). Each of these approaches has different goals in creating terrains
149 that have shaped their evolution through time. In the next paragraphs we first define
150 each approach and provide a cursory overview. Many reviews exist for LEMs (e.g.
151 Nicholas, 2005; Fonstad, 2006; Wilgoose, 2005; Tucker and Hancock, 2010) and
152 procedural models (Hendrikx et al., 2013; Smelik et al. 2014), while expert techniques
153 are rarely discussed in peer-reviewed literature. Hillier et al. (2015) discussed a few
154 approaches to creating synthetic terrains as analogs for testing the realism in LEMs.

155 3.1 LEMs

156 Geomorphic modeling uses geomorphic transport equations for erosion,
157 weathering, and deposition (Dietrich et al., 2013; Tucker and Hancock, 2010) to
158 generate steady and unsteady terrain states. Commonly called landscape evolution
159 models, these approaches aim to understand and replicate essential processes that
160 shape landforms over geologic time. LEMs numerically model landscape-scale
161 topographic change through geologic time, drawing on analytical and statistical
162 geomorphology through mass conservation and heuristic transport equations (Wilgoose,
163 2005; Tucker and Hancock, 2010). Some LEMs include sub-models for soils and
164 tectonics (Tucker & Slingerland 1994), vegetation (Colins et al., 2004) and climate
165 (Chase, 1992; Coulthard et al. 2002). While LEMs were founded on exploring Earth
166 surface processes in broader space and time scales, they do offer a potential route for
167 creating artificial terrains.

168 LEMs have employed varying approaches to deal with the fact that geomorphic
169 processes can operate over variable spatial and temporal scales. Temporal scale
170 variability can be controlled by simulation time steps, while spatial scale variability is
171 often addressed through the computational domain of the landscape. The latter is a
172 significant driver as to the resolution of river network typology and topography. Some
173 LEMs use adaptive and irregular meshes, so more nodes are present in areas with
174 more activity (e.g. Braun and Sambridge, 1997; Tucker et al., 2001b).

175 Commonly, channel widths are 3-4 orders of magnitude smaller than basin width so
176 that channels are effectively sub-grid scale features (Tucker and Hancock, 2010). It is
177 not that these models cannot create river topography per se, but they were never

178 intended for that purpose, because many address broader space and time scale
179 processes over entire landscapes (Wilgoose et al., 1991; Chase, 1992; Tucker and
180 Slingerland, 1994; Banavar et al., 1997; Rodriguez-Iturbe and Rinaldo, 1997). It is
181 possible to indirectly resolve sub-channel width scale features in basin scale LEMs (e.g.
182 Stark and Stark, 2001; Tucker and Slingerland, 1994; Willgoose et al., 1991), but this
183 comes at the expense of more complicated parameterization of sub models. Despite the
184 lack of emphasis on detailed channel dynamics related to river topography, most LEMs
185 can at least create river network typology (Coulthard, 2001; Van de Weil et al., 2007;
186 Tucker and Hancock, 2010). Lastly, some LEMs can nest small grid cells within larger
187 meshes, so that model time can be concentrated on relevant areas of geomorphic
188 change (Coulthard, 2001). Notably, the Cellular Automaton Evolutionary Slope and
189 River model (CAESAR; Coulthard et al., 1996; ; Coulthard et al., 2007) is capable of
190 modeling river topography at certain scales as discussed in more detail in Section
191 6.1.2.3.

192 Coulthard (2001) reviewed several free LEM software packages including
193 CASCADE (Braun and Sambridge, 1997), SIBERIA (Willgoose 2004), GOLEM (Tucker
194 & Slingerland 1994), CHILD (Tucker et al. 2001a), and CAESAR (Coulthard et al. 2002;
195 also discussed in Section 6.1.2.3) and discusses tradeoffs and capabilities. Coulthard
196 (2001) suggested that CASCADE and GOLEM are better suited for large-scale, long-
197 term simulations, whereas SIBERIA, CAESAR and CHILD may be better for shorter
198 periods requiring higher resolution. While many programs are free, they are in a variety
199 of programming formats and offered for researchers without typical user interface
200 elements necessary to be considered user-friendly (Coulthard, 2001). Interested

201 readers are also recommended to visit the Community Surface Dynamic Modeling
202 Systems website (http://csdms.colorado.edu/wiki/Main_Page), where they can license,
203 upload, and share LEMs.

204 3.2 *Procedural*

205 Procedural modeling is a term used to describe the generation of 3D objects and
206 environments automatically through rules, parameters and iterative algorithms (Ebert et
207 al, 1998; Smelik et al., 2014). These methods have been pioneered by computer
208 scientists to generate realistic synthetic landscapes at the individual mountain to
209 regional scales for virtual reality, video games, and even flight simulations (Cerqueira et
210 al., 2013). Commonly, procedural terrain methods strive for rapidly generating terrains
211 with the goal of visual realism (Hendrikx et al., 2013; Smelik et al. 2014). Generally, one
212 can further classify procedural methods as automated or semi-automated. Automated
213 models create terrains from basic user inputs such as the type, scale, and extent of the
214 desired landforms, while semi-automated models allow for user input during terrain
215 generation. Procedural terrain generation has historically relied heavily on fractal
216 geometry concepts (Mandelbrot and Van Ness, 1968; Mandelbrot, 1975; Fournier et al.,
217 1982) for automated generation. Recent advances include interactive sketching (Smelik
218 et al., 2010, 2011), software agents (Doran and Parberry, 2010), genetic algorithms
219 (Saunders, 2006, Raffe et al., 2012), and procedural blocks (Genevaux et al., 2013).

220 Within procedural modeling there has been an emphasis on algorithms in which
221 the development of river network typology is a significant driver for generating the
222 surrounding terrain. Some algorithms create the river first and then surrounding terrains,
223 while others work the opposite (Kelley et al., 1988), or create both in tandem (Musgrave

224 et al., 1989; Prusinkiewicz, and Hammel, 1993). Numerous algorithms of fractal river
225 network synthesis within existing terrains have been explored under the term *fractal*
226 *river basins* (Rodriguez-Iturbe et al., 1994; Banavar et al., 1997; Rodriguez-Iturbe and
227 Rinaldo, 1997). Despite the benefits of fractal Brownian motion and iterative fractals in
228 speed, Nagashima (1998) argued that modeled mountains and valleys were more
229 realistic looking when they incorporated basic geomorphic processes such as fluvial
230 erosion, rainfall, and weathering. For the case of an entire river network without the
231 surrounding topography, Cieplak et al. (1998) review models for creating fractal river
232 network typology of single thread rivers around which a landscape could be built. More
233 recently, Zhang et al. (2016) used Tokunaga networks to generate large scale
234 watersheds.

235 The ability to rapidly generate unique landscapes is often balanced with the level
236 of user control (Raffe et al., 2012; Smelik et al., 2014). A detriment to most automated
237 procedural terrain generators is that the user has no control over features until after the
238 terrain is built. Expert techniques have been blended with procedural methods to allow
239 for some expert-based feature design within procedural modeling. Examples include
240 interactive procedural sketching (Teoh, 2009; Huijser et al., 2010; Jensen, 2011;
241 Genevaux et al., 2013), procedural blocks (Genevaux et al., 2013), software agents
242 (Doran and Parberry, 2010) and evolutionary algorithms (Saunders, 2006, Raffe et al.,
243 2012). Smelik et al. (2010, 2011) advocated interactive procedural sketching, because it
244 blends the automation of procedural design with the control of interactive sketching. For
245 example, in the program RiverLand (Teoh, 2009; Jensen, 2011) the user defines the
246 shape of an island with ridge lines by drawing on a 2D canvas. Within the island a

247 meandering river is generated that does not cross the user-defined ridges. Combining
248 geometric modeling with procedural terrain generation, Huijser et al. (2010) developed a
249 procedural method that allows the user to define the path of the river and uses a
250 predefined sub model for the cross section of the river to create simple meandering river
251 topography. Another hybrid approach is to blend procedural sketching with evolutionary
252 algorithms (Saunders, 2006, Raffe et al., 2012). For example, in the program
253 Terrainosaurus (Saunders, 2006) the user can sketch regions in a layout that can be
254 associated with different reference heightmaps. For each region a genetic algorithm
255 melds together chunks of elevation data from the supplied examples creating a new
256 terrain that has attributes of the example heightmaps. Genevaux et al. (2013) combine
257 interactive sketching, procedural blocks, and basic concepts from hydrology and
258 geomorphology, illustrating how procedural methods have evolved to allow for user
259 control and rapid generation.

260 3.3 *Expert*

261 Expert-based techniques are the most open-ended avenue for creating terrains
262 but are seldom discussed in the scientific literature. In fact, today over 100 million
263 people around the world carry out landscape terrain manipulation by adding or
264 subtracting individual 1 m^3 voxels in Minecraft and other similar video games. Expert-
265 based techniques include (i) geometric, (ii) map, (iii) brush, and (iv) interactive methods.
266 Geometric modeling is the mathematical representation of shapes. Map-based
267 techniques include working in the XY plane and using contours, points, and/or break
268 lines that have assigned elevation attributes, similar to how most civil engineering
269 landscape grading occurs. Brush techniques also operate in the XY plane but use

270 colored and textured “brushes” on terrain canvases, where color scale of the brush has
271 a prescribed elevation range (de Carpentier and Bidarra, 2009). Finally, interactive
272 methods are embedded within software programs that allow the user to pull and stretch
273 an initial terrain to create specific landforms manually. Because these approaches are
274 so open-ended they are not discussed further for general terrain generation but will be
275 elaborated in Section 5 for creating river topography.

276 **4 Creating Digital Rivers Without A Surrounding Terrain**

277 Digital rivers do not require surrounding terrains for many applications. When
278 there is not a terrain to drive the type of river that is possible or desired, the user drives
279 the synthesis process through conceptualization at the reach scale. Then, “scaling
280 variables” are selected to be used in later steps (e.g., expert or strategic methods).

281 *4.1 Conceptualization*

282 In creating a synthetic river valley without an existing terrain, the purpose of
283 modeling, type of river(s), scale and resolution should be conceptualized by the user.
284 Conceptualization is important because it provides the broader template in which model
285 components and their characteristics are envisioned by the user (Brown et al., 2014).
286 Purposes of modeling could be to understand how specific channel and floodplain
287 configurations affect ecological and geomorphic processes (Brown et al., 2016;
288 Pasternack and Brown 2016), to create prototypes of channel configurations for
289 historical analysis (e.g., Jacobson and Galat, 2006), to develop river and stream
290 rehabilitation scenarios (Elkins et al., 2007; Pasternack and Brown, 2013), to evaluate
291 land management impacts and engineering scenarios, or for scene generation for virtual

292 reality purposes, such as for video games (Nelson and Mateas, 2007; Hendrix et al.,
293 2013), military training applications (Smelik et al., 2013) and flight simulators. The type
294 of river planform has a strong bearing on subsequent steps because, as will be shown,
295 not all methods are yet capable of creating all types of fluvial form.

296 Once the type of river planform is defined, then the scale and resolution of the
297 synthetic river should be defined. Scale is important because geomorphologists are now
298 learning more than ever that processes and landform variability are scale dependent
299 (Dragut et al., 2011). For example, river profiles show varying statistical and
300 mathematical characteristics depending on whether a single bedform, morphological
301 unit, or entire river system is being considered (Brown et al., 2014). Resolution is
302 important, too, because it can guide a user to the most effective approach. Resolution
303 should be set to the coarsest level necessary to capture the features needed for the
304 application. If bedforms, outcrops, and boulder clusters are needed, then a higher
305 resolution will be required.

306 4.2 *Defining Scaling Variables*

307 To create a synthetic digital river without a terrain there are fundamental scaling
308 variables that need to be determined, regardless of whether an expert or strategic route
309 of river synthesis is desired. If a terrain exists, then these can be extracted, but if one
310 does not exist, then they should be defined by the user. Fundamentally, fluvial
311 geomorphology posits that there are relationships between landscape position, flow
312 rate, sediment load, and the typology and geometry of a river (Leopold et al., 1964;
313 Singh 2003). Common scaling variables used for fluvial systems include bankfull
314 discharge Q_{bf} , reach averaged slope \bar{S} , median sediment size $\overline{D_{50}}$, and bankfull channel

315 width \overline{W}_{bf} and depth \overline{H}_{bf} (Parker, 1976; Church, 2006; Parker et al., 2007). These can
316 be specified outright by the user based on user conceptualization of the river under
317 design or determined from empirical relationships to conform to evidence-based
318 regional science. For example, if there is an existing terrain, the drainage area can be
319 determined from relations between drainage area (and/or climate metrics) and Q_{bf} (e.g.
320 Dury, 1976; Castro and Jackson, 2001). Then Q_{bf} , hydraulic geometry equations, and
321 channel regime relationships can be used to determine \overline{H}_{bf} and \overline{W}_{bf} (Leopold and
322 Maddock, 1953; see Williams et al., 2002 for tidal channel hydraulic geometry relations
323 governed by tidal prism). Alternately, for single thread gravel and sand bedded rivers
324 there exist several analytical and empirical equations from geoscience and engineering
325 research that can determine \overline{S} , \overline{W}_{bf} , and \overline{H}_{bf} from Q_{bf} and \overline{D}_{50} (Parker et al., 2007;
326 Wilkerson and Parker, 2011). Dodov and Fofoula-Georgiou (2004) provide a more
327 theoretical foundation and procedure for rendering synthetic hydraulic geometry. Many
328 other empirical functions suitable for scaling river designs exist among catchment scale
329 and reach scale geomorphic variables customized to valley setting (Knighton, 1998;
330 Shields et al., 2003). Davidson et al. (2013) reviewed river patterns and processes for
331 distributive fluvial systems that can be used to help select scaling variable values for
332 synthetic river design.

333 4.3 Planform Selection

334 In this section a brief overview is given on how to translate the scaling variables
335 to channel planform typology and actual channel alignments for scenarios where there
336 is no pre-existing terrain and one is not needed. In this situation, the user can determine

337 what type of planform is possible or likely given the reach characteristics. In expert-
338 based synthesis, the user would take the resulting planform type and then prescribe the
339 spatial alignment of the channel(s). This can be achieved through subjective means
340 where the user articulates the path of each channel within the synthetic domain. Time
341 invariant deterministic equations or mathematical models for meandering rivers can also
342 be utilized to prescribe an exact alignment. For strategic synthesis, deterministic and
343 stochastic models are possible and for the former, need to be initially specified.
344 Stochastic approaches rely on specifying the upstream and downstream limits and
345 using a combination of random numbers and rules to determine the alignment between
346 those two points. Time-varying deterministic models use input variables to generate an
347 evolving planform.

348 River planforms are commonly classified as meandering, braided, anastomosing,
349 straight, and transitional (Leopold and Wolman, 1957; Schumm, 1985; Eaton et al.,
350 2010). Clearly other fluvial planforms than these five exist in nature (Schumm, 1985),
351 and there are a variety of distributive terminal channel planforms where rivers meet the
352 sea in deltas, fjords, rias, and other estuaries (Perillo, 1995; Davidson et al., 2013).
353 There do exist several empirical and analytical relationships to predict the type of
354 channel planform a river would have depending on discharge, reach-averaged
355 hydraulics, sediment size and type, and channel slope, width and depth (Parker, 1976,
356 Eaton et al., 2010; Crosato and Mosselman, 2009). Parker (1976) derived a theoretical
357 state space which discriminates between straight, meandering, and braided planforms
358 based on the width, depth, slope, and bankfull discharge. Eaton et al. (2010) derived
359 discriminate functions between the critical slope, relative bank strength, and

360 dimensionless discharge that demarcate the transition from single thread to
361 anabranching channels and another describes the transition from anabranching to
362 braided channels. Crosato and Mosselman (2009) derived a physically based
363 expression for the number of channels based on Q_{bf} , \bar{S} , $\overline{W_{bf}}$, a friction parameter, and a
364 dimensionless sediment transport parameter. Overall, using any of these relationships
365 one can objectively evaluate reach scale variables to determine whether or not they
366 would likely be associated with single thread, anabranching, or braided planforms.

367 Once a planform typology is identified, it serves as the basis for developing the
368 channel alignment(s) of the river. Different methods for creating static and dynamic
369 planforms exist. Examples of meandering river models include sine generated curves
370 (Langbein and Leopold, 1966), disturbed periodic models (Ferguson, 1976), fractal
371 planforms (discussed in 6.2.1), and Kinoshita curves (Kinoshita, 1961). Mosselman
372 (1995) completed a review of dynamic models of planform change and concluded that,
373 while many approaches exist, they are not in software packages that facilitate broader
374 use. This has changed somewhat since then with programs such as RVR Meander
375 (Abad and Garcia, 2006), which is available as a standalone windows version and also
376 for ArcGIS® 10.0.

377 **5 Expert-based River Design**

378 Expert-based designs are driven by user creativity and knowledge in two
379 avenues, understanding fluvial landforms as well as software preference and
380 experience. Underlying all expert-based methodologies is a long history of scientific
381 discovery and technological development whose modern “black box” software platforms
382 may be taken for granted today, but which must be acknowledged in this review as

383 foundational literature (Myers, 1998; Farin et al., 2002; de Carpentier and Bidarra, 2009;
384 Li et al, 2015). The software with which a user is familiar heavily dominates what is
385 achievable. User depth and breadth of skill is enhanced through time with creative play,
386 attempting new challenges, and receiving software updates. As such, many theoretical
387 and procedural advancements are not found in the peer-reviewed literature, but instead
388 in software user forums- if publicized at all given constraints arising from proprietary
389 commercial value. An exception is geometric modeling, which has been recently
390 advocated by the authors to be a useful method for creating prescribed river topography
391 for fluvial geomorphic inquiry as well as river rehabilitation design (Brown et al., 2014).

392 All of these methods- geometric, brush, and map- can be used to create a new
393 river terrain or to modify an existing terrain. In addition, a surface can be transformed
394 through scaling, filtering, and pushing and pulling one or several terrain nodes. Most
395 terrain modeling software has diverse filters relevant for terrains, such as changing the
396 surface roughness and adding directional gradients and curvatures. Next, we review
397 each of the four types of expert-based synthesis and discuss their advantages and
398 disadvantages.

399 5.1 *Map River Design*

400 Map techniques require specifying the horizontal position and elevation of points
401 and lines along a contiguous path of descent. Contours are isolines of constant
402 elevation and are one of the oldest representations of landform topography. The
403 generation of design contours for engineering purposes has been a staple of modern
404 landform design (Schor and Grey, 1995). In this setting, contours of the existing Earth
405 surface are generated from collected point or transect data either by eye or by

406 computer. In landform design, new contours are generated manually over this existing
407 template and the composite is then used as a basis for the new landform. An advantage
408 of this approach is that valley and channel slopes are already accounted for in the pre-
409 existing contours. Once topographic contours and points are developed, a surface is
410 constructed, usually in the form of a triangulated irregular network that can then be
411 turned into a heightmap.

412 In civil engineering, computer aided design (CAD) is the industry standard for
413 map-based river design (Myers, 1998). Historically, CAD was a 2D plane-based method
414 for drawing sections and profiles. Nowadays, skilled users apply CAD programs such as
415 AutoCAD® Civil 3D® to yield sophisticated terrain models. More recently, Geographic
416 Information System (GIS) software can also be used to do many of the same terrain
417 generation steps as in CAD. Programming languages like Python and R can script
418 these steps in GIS to automate them.

419 An example set of design surfaces for an actual river restoration design was built in
420 CAD using contours and is shown in Figure 2. To have control over the slopes the
421 distance between contours needs to be considered. In most CAD programs this can be
422 achieved by specifying horizontal offsets of existing contours in a specified direction.
423 Breaklines are also sometimes used to delineate paths of constant elevation associated
424 with specific features, such as walls or steep banks that can be used to guide
425 interpolation.

426 Map techniques, such as contouring, are relatively quick to perform for
427 experienced users. Further, this technique is embedded in many engineering disciplines
428 as the de facto method for generating design surfaces. A drawback of using map-based

429 approaches is that using contours to represent topography can be non-intuitive to some,
430 just as brush-based approaches would be foreign to others. Further, creating contours,
431 points, and breaklines are intermediate to creating a terrain because these features
432 need to be interpolated. Interpolation can introduce an additional level of variability,
433 depending on the resolution of created objects relative to the interpolation domain.
434 Whether one or several contours are located within a single cell or multiple cells can
435 have an effect on the final heightmap. Like brush-based methods, map techniques do
436 not inherently and objectively specify key geomorphic values for the terrain but require
437 iterative creation and analysis to see if it came out as desired.

438 5.2 *Geometric River Design*

439 Geometric modeling of river channel topography is a method of synthesis where
440 specific 2D geometric elements of river topography, such as the bed profile, cross
441 section, and channel planform, are mathematically modeled in isolation and then
442 combined to produce a 3D heightmap (Brown et al., 2014). Deutsch and Wang (1996)
443 utilized aspects of this approach in developing a stochastic model for fluvial reservoirs
444 that utilized a channel geometry model that incorporated the position along a centerline,
445 the channel width, and an expression for variable cross section geometry. The use of
446 kriging in modeling channel topography from field measurements (Legleiter and
447 Kyriakidis 2008) and synthetically (Legleiter, 2012) was founded on a similar approach
448 whereby the channel alignment, bed profile, and cross section are modeled separately,
449 and then coupled to produce channel topography.

450 Although CAD software was not originally intended for geometric design, it is
451 increasingly adopting such capabilities. For example, the Corridors function in AutoCAD

452 Civil 3D® can create channels by drawing an alignment and specifying a cross section
453 that is projected through the alignment. This function was intended for roads, levees
454 and other civil infrastructure components, but it can be used for rivers. Without
455 additional information, Corridors yields highly simplistic canals, not natural channels.
456 There is grey literature on creating river channels using Civil 3D®.

457 A recent method that was developed specifically for the geometric modeling of
458 river corridors is called the synthetic river valleys (SRV) methodology (Brown et al.,
459 2014). The basic steps in developing a geometric model of a synthetic river valley are (i)
460 conceptualize, (ii) specify model domain, (iii) determine 2D fluvial geometric elements in
461 the model, (iv) determine reach-average values of geometric elements, (v) develop
462 geometric element equations, (vi) construct model, and (vii) parameterize. Two
463 important aspects of geometric modeling are the selection and construction of
464 appropriate geometric element equations, and their subsequent parameterization.
465 Brown et al. (2014) review models used for basic geometric elements (Table 2). For
466 single thread rivers there are a variety of models for planform alignments, longitudinal
467 profiles, and channel cross sections that can be used to create digital rivers. The
468 amount of control is driven by the types of mathematic models used within the
469 geometric element equations. For example, planform alignments can be generated
470 using deterministic sinusoid models or stochastic approaches such as auto-regressive
471 models (as discussed in Section 6.2). Despite using relatively simple functions, such as
472 sinusoids, the approach can yield remarkably diverse and complex river valleys.
473 Parameterization is a key step whereby the parameters of the geometric element
474 equations are adjusted to meet user-specified attributes defined through the

475 conceptualization process. This includes specification of reach-average properties of
476 the river corridor and also each control function parameter independently (e.g., the
477 frequency of bed oscillations) and in some cases dependently (e.g., the relationship
478 between thalweg elevation and bankfull width). The extent of independent and
479 dependent parameterization will depend on the purpose of modeling, which fluvial
480 elements are being included, the mathematical function used, and expert judgment.

481 A benefit of geometric modeling is that one can create channel and valley
482 topography of prescribed conditions. For example, varying GCS parameterization
483 between channel width and thalweg can yield rivers that have riffle and pool
484 topography, while varying the channel and valley width GCS can yield confined or
485 unconfined rivers (Figure 3). Complex channel patterns, such as braided rivers, have
486 not been explored to date. For the SRV approach, River Synth 1.1 is a Microsoft Excel[®]
487 implementation available upon request from author Brown, while River Builder (currently
488 version 0.1.1) is an open-source, free, public R package available from the
489 Comprehensive R Archive Network.

490 5.3 *Brush River Design*

491 Brush methods entail the digital “painting” of terrain canvases in the XY plane
492 using artistic methods available in free and commercial software packages (de
493 Carpentier and Bidarra, 2009). Recognizing that terrain is nothing more than a
494 heightmap, any raster-based software that can change the greyscale value of a blank
495 digital canvas can be used to create digital terrain. That means programs such as
496 Photoshop[®] and Gimp[®] are candidates for creating digital rivers. However, one can only
497 get so far working entirely in a 2D view, so there exist software packages with more

498 viewing perspectives and specific tools for manipulating what will ultimately be a terrain.
499 Examples include Bryce3D[®], SketchUp[®], World Painter[®], and Zbrush[®]. Video game
500 engine software, such as the Unreal Development Kit[®], CryEngine[®], and Unity[®], also
501 offer brush methods for terrain generation and modification.

502 Brush-based river synthesis is commonly used for scene generation in artificial
503 landscapes for video games and virtual reality. For example, the 2018 game Red Dead
504 Redemption II[®] developed by Rockstar Games, Inc. has the most advanced and
505 realistic synthetic rivers produced to date from an artistic approach (Figure 4b,c),
506 including a wide diversity spanning headwater to coastal settings. Though specific
507 design tools and workflows are not publicized, investigation of the developer's global
508 employee hiring advertisements for terrain development indicated that candidates
509 should be versed in expert-based brush and geometric terrain methods, suggesting that
510 these were the tools used to make those synthetic rivers. Brush-based methods have
511 not been used for scientific inquiry to the authors' knowledge. With advances in
512 geometric methods, brush techniques are no longer commonly the starting point for
513 terrain generation but are used extensively to refine terrains and are an increasing part
514 of hybridized toolsets (de Carpentier and Bidarra, 2009).

515 The use of brush-based software to create a river valley begins with designating
516 terrain extent and resolution. Then an existing or blank terrain canvas is modified with
517 digital brushes of varying size, shape, intensity, and texture/pattern to paint elevations
518 and gradients. Brushes can be set to add or remove elevation. The upper elevations of
519 the river valley are first painted with larger brushes, creating the broader valley
520 template. Then, smaller brushes with lower elevation paint settings are used to place

521 the river into the corridor (Figure 4a). In this way, multiple inundation zones are
522 hierarchically nested as would occur in nature. Finally, the resulting surface can be
523 smoothed to remove brush irregularities.

524 Because this technique is artistic-expert-based, the created river valley can have
525 a wide range of topographic characteristics that is bounded only by the user, operating
526 software, and time. For example, the mountain meadow in Figure 4b shows cutbanks,
527 point bars, riffle-pool undulations, islands, floodplains, and a large secondary channel.
528 An important aspect of using brushes to create synthetic rivers is relating brush
529 dimensions to actual river dimensions, both horizontally and vertically, which can be
530 done afterwards by applying scaling factors to convert to real-world coordinates.
531 Further, it is difficult to design specific river planform types and morphologies, because
532 the brush is driven by hand operation, for which the precision is limited by drawing
533 device (e.g., mouse, trackball, trackpad, or stylus). Artists commonly use digital drawing
534 tablets with a precision stylus. A benefit to brush synthesis is that built-in filters can be
535 used to smooth and sharpen brush strokes.

536 A key challenge to brush-based methods is the difficulty in matching
537 specifications for a variety of river metrics. This necessitates iterative brushing and
538 terrain evaluation. Note that even industry-standard CAD is unable to prescriptively
539 control several channel metrics and thus also requires iteration between artistry and
540 terrain analysis.

541 An improvement to the brush method could include fluvial-specific brush types
542 and surface material textures that are specifically tailored to creating riverine landforms.
543 For example, a brush could be designed with a lateral fall-off profile to create the

544 desired cross-sectional shape as one moves along the centerline. Also, brush texture
545 with grain-scale roughness and organization to include sedimentary facies could be
546 created.

547 5.4 *Interactive*

548 Interactive approaches are used in programs that allow a user to create an initial
549 terrain and then use a variety of other tools to do further manipulation (de Carpentier
550 and Bidarra, 2009). To provide an example, the “sandbox” tool in SketchUp® was used
551 to generate a blank grid of 100 one-meter cells (Figure 5A). To create a river channel in
552 a valley the surrounding cells were then extruded upwards to create mountains and
553 hillsides (Figure 5B). The channel is created by pulling the grid downwards between the
554 valley (Figure 5C). This inevitably brings to light the issue of constant grid spacing in
555 interactive and brush-based terrain methods. A user may want finer scale topographic
556 detail in the channel than the surrounding hillsides, and to do this the channel grid cells
557 would have to be subdivided further in the channel. While creating a domain as in
558 Figure 2 is relatively simple and straightforward, it would be very time consuming and
559 difficult to create scientifically meaningful and realistic terrain with sediment grain scale
560 variability using this method.

561 **6 Strategic River Design**

562 6.1 *Deterministic*

563 Deterministic methods include equilibrium, morphodynamic, cellular automata,
564 and discrete particle models, and each of these are possible in multiple dimensions,

565 although most common are one (1D) and two (2D) dimensional models. Models in
566 which elevation is the variable of interest as a function of distance along a river are
567 termed 1D, while those in which it is a function of both longitudinal and lateral distances
568 are termed 2D. A 3D model would be a terrain that has multiple elevations for an {X,Y}
569 position, which would happen with overhangs and undercuts. This article does not
570 address such 3D problems. For 1D models (typically long profiles or channel
571 alignments), outputs would have to be used with geometric modeling to create 3D
572 topography. For example, there exists a plethora of mathematical models for
573 longitudinal profiles, but a profile model would have to be linked to a model for the cross
574 section and alignment to create a heightmap. The benefit of these types of models is
575 their foundation in fluvial geomorphology. Similarly, a detriment is that these
576 approaches are limited by the existing palette of what fluvial geomorphologists can
577 model. For example, there are several methods for modeling single thread meandering
578 river alignments but far fewer exist for braided, anabranching, or anastomosing rivers.
579 Next, each of these deterministic approaches is discussed along with advantages and
580 disadvantages.

581 6.1.1 Equilibrium Models

582 Fluvial geomorphology has produced a considerable amount of research related
583 to the idea of equilibrium in river systems. Equilibrium refers to the idea that a river
584 maintains a modal state with respect to one or all of its geometric variables, while
585 adjusted to stable landscape parameters, such as water and sediment supply and base
586 level (Leopold et al., 1964). Many of these approaches have their basis in the concept
587 of a “graded” river (Mackin, 1948), which is defined as a river that has become adjusted

588 to water and sediment discharge over a modest period of time. Some use the term
589 “dynamic equilibrium” (Hack, 1975) whereby the river system is adjusted to exogenic
590 controls but change still occurs in metastable states. Most equilibrium models are for
591 single thread rivers in 1D, with an emphasis on straight and meandering planforms.
592 There are numerous deterministic relationships for physical characteristics of
593 equilibrium single-thread river topography that are founded on analytical and empirical
594 fluvial geomorphology. Namely, the longitudinal profile, channel alignment, and cross
595 section can all be modeled using deterministic equations. Some of these are purely
596 empirical, where the parameters of mathematical functions are fit from field data, while
597 others are simplified solutions to theoretical treatments of flow and sediment transport
598 relationships. In this section a few of these types of models are discussed for generating
599 watershed to reach scale longitudinal profiles, followed by analytical models for
600 equilibrium topography for single thread meandering rivers.

601 6.1.1.1 1D Longitudinal Profiles

602 One-dimensional longitudinal profiles of rivers are one of the most studied
603 attributes of river topography, and approaches exist for their generation at watershed to
604 morphologic unit scales. Methodologically, modeling has encompassed approaches that
605 (i) model basic geometric shape using mathematical equations with empirical
606 coefficients, (ii) provide deterministic equilibrium solutions based on 1D flow and
607 sediment transport relationships, and (iii) predict dynamic solutions modeling profile
608 shape as governed by a diffusive process or morphodynamic interactions. Mathematical
609 and diffusion models are used most commonly for generating entire watershed profiles
610 of a mainstem whereas the coupling of 1D flow and sediment transport relationships are

611 used to generate reach and sub-reach scale variability. The benefit of these types of
612 models is that they are computationally efficient and can generate long sections
613 relatively fast. However, an obvious detriment is that as a 1D series there is no lateral
614 variability for the river profile.

615 The use of geometric mathematical equations to model watershed scale
616 longitudinal profiles has been widespread and is considered a staple in fluvial
617 geomorphology. Linear, exponential, logarithmic and power functions have all been
618 used to model and describe river profiles (Leopold and Langbein, 1962, Langbein and
619 Leopold, 1964; Tanner 1971; Shepherd, 1985). These types of geometric models are
620 useful when one knows *a priori* the type of profile desired to be created and they can
621 also be easily adjusted by simple parameter manipulation. Further, they can be
622 contextualized with mathematical functions for different physiographic conditions such
623 as lithology (Brush, 1961), grain size (Yatsu, 1955) as well as fluvial regimes related to
624 aggradation and degradation (Ohmori, 1991).

625 In such cases where a fluvial foundation is desired, simple analytical models of
626 open channel flow and sediment transport can be used strategically to determine time-
627 invariant equilibrium solutions for watershed scale longitudinal profiles. An example of
628 this approach is from Snow and Slingerland (1987), who developed a model for graded
629 stream profiles using open channel flow and sediment transport equations coupled with
630 empirical relations for the downstream variation in flow discharge, sediment discharge
631 and size and channel width. The initial sets of equations in their model were time-
632 dependent and would thus be considered morphodynamic (e.g geometric or
633 morphologic properties change with time, as explained later in Section 6.1.2). However,

634 by explicitly analyzing for equilibrium geometry over graded time the equations were
635 simplified, allowing the determination of relatively simple analytical expressions. Their
636 comparison of model outputs to known mathematical models of profiles, such as
637 exponential, logarithmic, and power functions, showed that these functions do provide
638 representative descriptions of river profile shapes depending on substrate and external
639 controls.

640 Analytical models of equilibrium bed profiles have been used to attempt to model
641 channel-width-scale longitudinal undulations for gravel and sand bedded rivers. For
642 gravel bed rivers, Cao et al. (2003) developed a simple dynamic equilibrium model in an
643 effort to reconstruct the bed topography of a riffle-pool unit. Specifically, equations for
644 1D steady, uniform fluid mass and energy conservation, a flow resistance equation (e.g.
645 the Manning equation), and a sediment transport relationship, (e.g. the Meyer-Peter
646 Muller equation) were coupled to determine the equilibrium bed elevation for a river
647 reach with fixed channel width. The utility of this approach is that it illustrates that
648 variable bed topography at the sub-reach scale, such as riffles and pools, can be
649 created using 1D analytical equations, so long as the channel width series is specified *a*
650 *priori*. For sand-bed rivers, Julien and Klassen (1995) developed analytical and
651 empirical approximations of dune height and steepness based on a dimensionless
652 particle diameter and transport stage. While these models only give the bedform
653 geometry (e.g. height and steepness), which approximates topography, they can still
654 guide the synthesis of these types of bedforms using other techniques. For example,
655 based on calculated bedform geometry parameters, mathematical models can be used
656 to generate profiles with those dimensions.

657 Mathematical profile models for riverbeds are advantageous in that they are
658 widespread and span a wide domain of approaches. These types of models are
659 appropriate for mostly the river reach scale or greater, so finer scale topographic
660 variability would have to be incorporated separately. The main detriment is that only the
661 profile is generated, so other models for the alignment and cross section of the river still
662 need to be specified. However, this can be accommodated by combining these models
663 within a geometric modeling framework (e.g. Section 5.2).

664 6.1.1.2 2D and 3D Equilibrium Meander Bed Topography

665 While 1D models for simulating longitudinal profiles are numerous, 2D
666 equilibrium models that directly generate heightmaps are less prevalent and are
667 primarily restricted to meandering rivers. For example, Bridge (1976, 1982, 1992)
668 developed an equilibrium model of flow, bed topography, and grain size based on
669 analytical and empirical relationships for individual meander bends. Bridge and Gable
670 (1992) also showed that this general model could be applied to either side of
671 anabranches. Beck (1988) developed a simplified analytical model for meandering
672 rivers in equilibrium that can generate topography from simplified expressions for the
673 transverse bed slope and maximum depth that require only the channel half width,
674 curvature of the channel, and average depth. Fluvial geomorphologists have already
675 been using this model to develop synthetic topography to evaluate computational fluid
676 dynamics models within meandering rivers (Abad and Garcia, 2008). These 2D
677 equilibrium models are advantageous in that for meandering rivers, bed topography can
678 be predicted from a modest amount of reach-averaged input variables (as in Section
679 4.2) with relatively low computational expense. A detriment is that they produce very

680 simple topographies that are much smoother than real rivers, but this could be dealt
681 with by superimposing random variability in the bed topography from stochastic models
682 (described in Section 6.2). The 2D models of equilibrium bed topography by Bridge
683 (1976, 1982) have also been extended to model the 3D sedimentary structure of point
684 bar deposits (Bridge 1977; Willis 1989; Willis and Tang 2010), incorporating lateral and
685 vertical variations in sediment size through meander evolution.

686

687 6.1.2 Morphodynamic Modeling

688 Morphodynamic models of river topography explicitly consider the relationship
689 between water flow, sediment transport, and changes in boundary geometry over
690 computational grids to determine time varying solutions of riverbed topography
691 (Mossleman, 2012). These types of models can be formulated in 1D as for a
692 longitudinal profile or in 2D for planform pattern. The former must be combined with
693 alignment and channel cross section models through geometric modeling to create a
694 heightmap. 2D morphodynamic models can generate river topography from steady-
695 state solutions or taking the output of unsteady solutions. As they are non-equilibrium,
696 evolutionary models, any resulting topography is a product of (i) initial conditions, (ii)
697 grid type and resolution (Doeschl-Wilson and Ashmore, 2005; Nicholas et al., 2006;
698 Nicholas et al., 2013), (iii) boundary conditions (Murray and Paola, 1997; Nicholas et al.,
699 2013), and (iv) the processes considered in the model's structure (Nicholas, 2013). Note
700 that boundary conditions include dynamic hydrologic and sediment flux regimes, which
701 are often challenging to specify to characterize future conditions for real-world design. A
702 common approach is to use historical discharge time series as representative of future

703 flows. There is rarely any sediment flux data, so inputs have to be designed from
704 scratch. While it is not possible to prescribe the exact creation of river topography
705 desired, these models are powerful in their ability to simulate interactions between
706 channel flows, sediment transport, and vegetation to produce emergent forms. Below
707 1D and 2D morphodynamic models are discussed. We exclude explicit 3D models for
708 brevity, recognizing that the concepts associated with 2D models are sufficiently similar
709 to provide the context.

710 6.1.2.1 1D Morphodynamic Models

711 One-dimensional morphodynamic models predict the evolution of the channel bed
712 profile of rivers from coupling open channel flow and sediment transport capacity
713 equations, and in some cases the grain size distribution is also predicted. Since the
714 1970's 1D morphodynamic models have been applied to both sand and gravel bed
715 rivers at reach and watershed scales (USACE, 1993; Havis et al., 1996). Most
716 commonly, channel hydraulics are computed from the energy equation using the
717 standard step-method, so that backwater effects are incorporated. For each time step a
718 water surface profile is calculated, thereby providing energy slope, velocity, and depth
719 at each cross section node. Next, the sediment transport capacity is computed and
720 when combined with the duration of the flow, permits a volumetric accounting of
721 sediment. Changes in sediment transport capacity between nodes are translated into
722 changes in bed elevation via the Exner equation for the continuity of sediment flux. With
723 updated cross section bed elevations, the computations then proceed to the next flow in
724 the sequence and the cycle is repeated beginning with the updated geometry. The
725 sediment calculations are performed by grain size fraction thereby allowing the

726 simulation of hydraulic sorting and armoring.

727 At smaller spatial scales, analytical 1D morphodynamic models can be developed
728 using the basic relationships of flow and sediment transport, analogous to the Cao et al.
729 (2003) model but for dynamic simulations. For example, Wallerstein (2003) developed a
730 dynamic model that determines the equilibrium or time dependent pool scour from
731 channel constrictions. Again, equations for fluid and sediment mass conservation,
732 conservation of energy, and sediment transport were coupled to determine the bed
733 elevation between two rectangular cross sections, where the second section is
734 constricted. The model varies from Cao et al. (2003) in that specific energy is calculated
735 between the two sections to determine the change in water depth and thus energy
736 slope, sediment transport, and ultimately bed elevation. Rather than explicitly
737 accounting for water flow and how that drives sediment transport, another approach is
738 to treat topography as a flowing media unto itself in consideration of the time-averaged
739 behavior of landforms when viewed over decades to millennia. If one could watch a time
740 lapse movie of a landscape at those scales, water flows would not be seen and just the
741 resultant landscape movements would be seen. The type of analytical model that
742 achieves this dynamism uses the diffusion equation to model river and watershed scale
743 longitudinal profiles. Begin (1988) for example, used the diffusion equation to simulate
744 river longitudinal profiles in response to base level lowering at the basin scale. Diffusion
745 models are governed by only two parameters- an initial height profile and the “diffusivity”
746 of topography, making them very simple to implement. Good approaches exist for
747 constraining and quantifying diffusivity (Paola et al., 1992; Pasternack et al., 2001).

748 One-dimensional morphodynamic models can be used to create longitudinal profiles

749 in two different ways. First, they can generate a river profile from an initially flat surface
750 or highly simplified channel network. Second, they can start with an existing profile and
751 evolve that over a time period to obtain a subsequent profile given the model inputs a
752 user wants to specify. Examples of 1D morphodynamic models include HEC-RAS
753 (Hydrologic Engineering Center River Analysis System ;
754 <http://www.hec.usace.army.mil/software/hec-ras/>), FLUVIAL-12
755 (<http://chang.sdsu.edu/fluvial.html>), and various Excel workbooks by Gary Parker
756 (http://hydrolab.illinois.edu/people/parkerg/morphodynamics_e-book.htm). HEC-RAS, in
757 particular, is a widely used 1D morphodynamic model in civil engineering and fluvial
758 geomorphology. Initially known as HEC-6 (USACE, 1993) the model has been
759 successfully used to model changes in bed elevation in large river systems (Havis et al.,
760 1996) and even replicate riffle-pool bedforms (de Almeida and Rodriguez, 2012). Using
761 this type of model for synthesizing 1D river topography requires more information and
762 computational effort than the 1D equilibrium models described in Section 6.1.1. Namely,
763 a hydrograph needs to be generated and a bed sediment distribution needs to be
764 specified for the incoming sediment load and at each node. To generate a hydrograph,
765 the selected discharge from the conceptualization step (e.g. Section 4) can be used with
766 hydrologic methods that convert peak discharge to storm events (Clark, 1945; Aron and
767 White, 1982). Similarly, a grain size distribution can be generated from the previously
768 defined median sediment size and a sediment distribution relation using the equation
769 presented by Fuller and Thompson (1906).

770 6.1.2.2 2D Morphodynamic Models

771 Morphodynamic models in two dimensions are an avenue for autogenically

772 deriving a heightmap. They differ from 1D models in that more sophisticated
773 relationships are used to model water flow that account for local spatial accelerations
774 and decelerations as well as 2D flow fields. Compared to LEMs, 2D morphodynamic
775 models are different in that only channel processes are considered, typically in
776 computational grids that explicitly are channel orientated as opposed to Cartesian
777 coordinates and with grid cells that are much smaller than a channel width (Struik
778 1985; Ikeda and Nishimura, 1986; Nelson and Smith, 1989; Sun et al., 1996; Vasquez
779 et al., 2007). Moreover, they differ from cellular automata models in that the 2D St.
780 Venant equations are solved numerically, rather than simplified through abstracted rules
781 (Nicholas, 2010). While morphodynamic models all have the basic attributes of
782 combining partial differential equations for flow and sediment transport to predict bed
783 change and or equilibrium conditions, they have some common types of differences that
784 influence the type of topography produced. For example, models can differ in the
785 coordinate systems used, the type of grid, specific hydrodynamic components such as
786 secondary flows and convective accelerations, the type of sediment transport
787 mechanisms and empirical functions used to estimate sediment transport. In many of
788 these early models, bank erosion is absent and only bed topography is predicted for
789 fixed width (Nelson and Smith, 1989) or small width variations (Struik 1985). Since
790 then, models are now capable of having variable channel widths and also now can
791 incorporate processes such as bank erosion (Mossleman, 1998; Duan and Julien, 2010)
792 as well as geotechnical bank failure processes. In addition, many models are striving to
793 incorporate the effects of vegetation (Li and Millar, 2011; van Oorschot et al., 2016).
794 However, many potentially important processes are also commonly neglected, including

795 riverbank freeze-thaw (Wolman, 1959; Yumoto et al., 2006) and stochastic events.

796 Recently, 2D morphodynamic models have become more successful in
797 simulating braided rivers (Jang and Shimizu, 2005; Williams et al., 2016) as well as the
798 ability to model both meandering and braided river planforms (Nicholas et al., 2013).
799 The Hydrodynamics and Sediment Transport in Alluvial Rivers model (HSTAR) is a
800 depth-averaged morphodynamic model based on the shallow water equations, with a
801 two-fraction sediment transport scheme and relatively simple treatments of bank erosion
802 and vegetation growth (Nicholas et al., 2013) shown to simulate a wide array of channel
803 planforms with realistic process dynamics (Figure 6). In comparing morphodynamic
804 models, Nicholas (2013) highlighted five important model components necessary to
805 model dynamic planforms: (i) simple grid structure capable of representing channel-
806 floodplain dynamics without the need for mesh refinement, (ii) limiting diffusion of the
807 bank line migration in the bank erosion sub-model, (iii) including momentum
808 conservation in the hydrodynamic sub-model while including secondary circulation, (iv)
809 at least two grain size fractions, and (v) a simple vegetation sub-model that incorporates
810 stabilization of new floodplains by vegetation.

811 The explicit treatment of 2D morphodynamically derived models of river
812 topography have shown considerable promise (Engelund, 1974; Struiksmá, 1985; Ikeda
813 and Nishimura, 1986; Nelson and Smith, 1989; Seminara, 2006; Vasquez et al., 2007;
814 Wang et al., 2010a). However, these models are still in their infancy when it comes to
815 simulating large river reaches with multiple scales of material heterogeneity with modest
816 computing capabilities. Early morphodynamic models were built to determine
817 interactions between multiple dependent variables and not necessarily to completely

818 represent all aspects of river topography (e.g., Sun et al., 1996). Therefore, similar to
819 LEMs they are strong methods for directed artificial synthesis obeying transparent
820 process characterizations, even if they have yet to prove valid for predicting changes at
821 real sites with real events in light of the inherent stochasticity of real dynamic
822 phenomena. Rather, they do have the capability of autogenically simulating river
823 topography over time and are considered a potential avenue of artificial river
824 topographic synthesis. The utility of morphodynamic models is that these tools can be
825 used as an autogenic method to determine the bed topography given some specified
826 set of boundary conditions. For example, Wang et al. (2010b) showed that by altering
827 initial and boundary conditions, varying channel patterns including meandering, braided,
828 and anabranching could be produced. Similarly, Nicholas et al. (2013) illustrate how
829 model parameters can also affect the final planform generated. The construction of
830 morphodynamic models requires skill sets not familiar to most fluvial geomorphologist
831 and this may be a barrier that prohibits the widespread development and use of these
832 types of models in favor of more simplified approaches. Moreover, to generate diverse
833 channel types models may have to be run for long periods that may pose computational
834 constraints on their use. A potentially difficult aspect of using morphodynamic models to
835 create synthetic rivers is determining when to stop the model. That is, a user needed to
836 determine *a priori* when to stop a model, which is difficult to objectively constrain in the
837 virtual sense. Some morphodynamic models are freely offered such as River2D-Morph
838 (<http://river2dm.wordpress.com/about/>) Delft3D, SRH2D V2
839 (<http://www.usbr.gov/pmts/sediment/model/srh2d/>), and Nays2DH within the IRIC
840 platform (<http://i-ric.org/>). Other models can also be found through the Community

841 Surface Dynamics and Modeling System, a community sharing website at
842 https://csdms.colorado.edu/wiki/Main_Page.

843 6.1.2.3 Cellular Automata

844 Cellular automata (CA) modeling is an emerging tool within geomorphology
845 (Nicholas, 2005; Fonstad, 2006; Tucker and Hancock, 2010). Cellular automata models
846 differ from LEMs and traditional morphodynamic models in that they use expert-based
847 rules that are simplified abstractions of geomorphic transport laws and/or hydraulic and
848 hydrodynamic equations of motion. However, because they incorporate time dependent
849 interactions of flow and sediment transport, they are grouped under morphodynamic
850 models in this article. The rule-based representation of fluvial and geomorphic processes
851 has a large bearing on the types of outputs generated (Murray and Paola, 1997; Nicholas,
852 2010). Cellular automata models operate almost exclusively on discrete grids and are
853 favorable because of their ability to implement deterministic, probabilistic, and rule-based
854 expressions that while simplistic, can be constructed in ways that mimic the complexity
855 of many natural phenomena (Wolfram, 2002). A CA model consists of an array of cells or
856 nodes either in 1D or 2D, whereby the state of each cell evolves based on transition rules
857 that mediate the dynamics of the model on a moving neighborhood within the model
858 domain (Wolfram, 2002).

859 Since its inception, CA models have blossomed into modeling river
860 morphodynamics. The first CA model applied to river topography was the braided river
861 model of Murray and Paola (1994, 1997) using simple water flow and sediment routing
862 schemes. Over the computational neighborhood, water flow is routed to 3 downstream
863 cells according to the topographic gradients, in that flow is proportional to the cell-to-cell

864 gradient. Then, sediment flux is determined based on water flow rate and a discretized
865 and simplified version of the Exner equation. Since then, other studies have provided
866 further refinements in cellular automata models including modeling vegetation (Murray
867 and Paola, 2003), unsteady effects (Parsons and Fonstad, 2006), accounting for bank
868 erosion (Coulthard and Van de Weil, 2006), multiple grain sizes (Hodge et al., 2013), and
869 also refinements to compete with physics-based 2D and 3D hydrodynamic models
870 (Nicholas, 2010; Nicholas et al., 2013). A well-documented and freely available cellular
871 automata model that is capable of basin and reach-scale topographic simulations is the
872 Cellular Automaton Evolutionary Slope and River model (CAESAR; Coulthard et al. 2013;
873 Van de Weil et al., 2007). CAESAR now uses the LisFlood routine to model 2D water flow
874 (Seybold et al. 2007; Bates et al., 2010; Coulthard et al., 2013). CAESAR can handle
875 bedload and suspended load and uses two different routing schemes for each of these
876 types of sediment transport. At the catchment scale, CAESAR can simulate meandering
877 and braiding planforms (Figure 7). Bank erosion is possible, but it is calculated
878 independent of flow and sediment routing (Coulthard and Van de Weil, 2006). While not
879 currently publicly available, the model of Nicholas (2010) has excellent hydrodynamic
880 capabilities compared with earlier schemes and has been shown to (i) compete with 2D
881 and 3D CFD models (Nicholas, 2010; Nicholas et al., 2013) and (ii) simulate the initiation
882 and growth of free bars within straight channel geometries (Nicholas, 2010).

883 Overall, CA models have shown how simple rules can be utilized to construct
884 models capable of synthesizing relatively complex river topography, ranging from
885 meandering rivers to river deltas (Seybold et al. 2007; Nicholas, 2010; Liang et al. 2015;
886 Schurmann et al. 2011; Nicholas et al., 2013). Fonstad (2006) argued that cellular

887 automata models are good for multidisciplinary studies, such as between fluvial
888 geomorphology and ecology, because of the differences in the type and complexity of
889 conceptual schemas employed by various fields are readily incorporated into these types
890 of models as transition rules. To date it has been demonstrated that CA models can create
891 the topography of specific river planforms but are limited at the reach scale and catchment
892 scales (Coulthard and Van De Wiel, 2006; Van De Wiel et al., 2007; Nicholas, 2009,
893 2010). Some freely available CA models are CAESAR
894 (<http://www.coulthard.org.uk/CAESAR.html>) and an Excel version of the Murray-Paola
895 braided river model (http://www.coulthard.org.uk/downloads/murray_and_paola.htm).

896 6.1.2.4 Discrete Particle Modeling

897 Discrete particle models operate at the grain scale. They differ from LEM and CA
898 models in that model cells represent individual particles, rather than sediment mass
899 (Naden, 1987, Jiang and Haff, 1993, Tribe and Church, 1999, Maelmaeus and Hassan,
900 2002, Schmeckle and Nelson, 2003, MacVicar et al., 2006, Hodge et al., 2007). These
901 models have been constructed in both 2D vertical and horizontal grids. The generation
902 of bed topography using these models has been primarily focused on modeling sub
903 channel width scale features such as pebble clusters, transverse bedforms, and steps.
904 Commonly, probabilistic rules are used that determine particle trajectories and
905 interactions and these can further be related to flow hydraulics that dictate the
906 probability of erosion and deposition. Most models have a similar computational
907 algorithm, with deviations related to whether or how flow calculations are performed and
908 the exact rules for particle entrainment and flow and sediment feedback. To provide
909 further detail a brief summary of several discrete particle models is presented next.

910 One of the earliest particle models developed was by Naden (1987) who
911 modeled sub-channel width scale gravel bed river topography from sediment transport
912 as particle queuing. Arranged within a 2D vertical grid of sediments, the model was able
913 to simulate profiles with characteristics of step-pools and antidunes. Tribe and Church
914 (1999) developed a 2D kinematic model of gravel stream beds focusing on particle
915 interactions rather than flow-based transport and deposition (e.g. Naden, 1987). Within
916 the 2D planform model domain, gravel particles are modeled as discrete circular disks
917 and particle entrainment and deposition are not based on modeled flow hydrodynamics
918 but the local configuration and interactions of particles. Advancement to this model was
919 made by Maelmaeus and Hassan (2002) by allowing particle interactions without direct
920 contact and also allowing for particle skimming. The model was found to be able to
921 simulate realistic particle interactions and bed sediment structures (Hassan and Church,
922 1992) reported in the literature and represent an avenue for further exploration in these
923 types of channels. MacVicar et al. (2006) developed a 2D discrete particle model for
924 gravel-bed rivers that considers turbulence, flow accelerations, and feedbacks between
925 both the flow and sediment bed. Structurally, the model domain is similar to Naden
926 (1987) in that a 2D vertical matrix is used along the channel centerline, but the model
927 differs in that flow and sediment interactions are not strictly empirical. Instead, the
928 model allows for feedback. Because of these modifications to prior particle-based
929 models, such as the inclusion of feedback rules between flow and sediment, larger
930 scale emergent bedforms can be created such as pools and riffles. With the goal of
931 nesting discrete particle models within reach-scale cellular automata modeling, Hodge
932 et al. (2007) developed a 3D grain DEM based model of bedload transport. The input to

933 this model is an artificial 3D grain DEM. Grain movement is determined probabilistically
934 with weights based on shear stress. The exact flow model was not specified in their
935 study, so flexibility does exist in coupling the bedload grain model with more
936 sophisticated flow models. A key benefit of this modeling approach is the treatment of
937 fractional bedload transport and its ability to model changes to grain size distributions at
938 the grain scale.

939 Discrete particle models have been useful to geomorphologists in understanding
940 how bedforms are generated. Particularly, these models have been successfully applied
941 to steeper channels (e.g. >1%) whereas traditional morphodynamic models have not.
942 Translating 1D profiles generated from discrete particle models to topography would
943 require hybridizing with geometric modeling, as described in Section 5.2. It seems that
944 2D discrete particle model outputs could be easily translated to a heightmap, but the
945 authors have not tried these themselves. To the authors knowledge, there are no
946 publicly available discrete particle models, but models may be available from authors.
947 Overall, outside of geomorphic inquiry, these types of models may not have much utility
948 because similar outputs could be generated with far less user complexity.

949 6.2 *Stochastic*

950 Using statistical models, it is possible to create spatial series associated with
951 geometric elements of river topography and less commonly discrete polygon objects.
952 These approaches are primarily based on (i) fractal, (ii) auto-regressive, (iii) inverse
953 spectral, and (iv) object-based methods. Each of these approaches makes inherent
954 assumptions of the overall statistical structure of the data that limits the potential
955 variability of the output. For inverse spectral methods, additional criteria, such as the

956 frequency composition, are further specified, either on the basis of observational data or
957 as artificial constructs.

958 6.2.1 Fractal Modeling

959 Fractals have played a large role in general terrain synthesis and procedural
960 modeling. In fluvial geomorphology, fractals have been primarily utilized as an analytical
961 tool for investigating longitudinal profiles (Robert, 1988), planform geometry (Nikora,
962 1991, Sapozhnikov and Fofoula-Georgiou, 1996; Stolum, 1998), and river networks
963 (Rodriguez-Iturbe and Rinaldo, 1997). While fractal terrain and river network algorithms
964 exist for heightmaps (as described above in Section 2.1) no such approach exists for
965 the creation of river topography. Overall fractal methods are currently limited to the
966 simulation of 1D meandering planforms. Nikora and Sapozhnikov (1993) developed a
967 random walk method of simulating fractal river meanders by using rule-based
968 probabilities. The novelty in this method is that it explicitly accounted for valley width
969 constraints on meander wavelengths and was also capable of simulating planforms with
970 similar fractal dimensions of real rivers. This could be highly useful as an input for a
971 combination-geometric approach.

972 6.2.2 Inverse Spectral Modeling

973 Commonly the analysis of 1D spatial series (e.g., bed-elevation, width, and/or
974 width as a function of elevation series) and 2D fields is achieved through spectral analysis,
975 whereby measurements in the space domain are transformed to the frequency domain
976 via a convolution (Newland, 2012). Typically, such a convolution is performed using the
977 Fourier transform, although wavelets offer another avenue for non-stationary series.
978 Since the 1960's geographers have applied spectral methods to Earth surface landforms

979 (Rayner, 1971). As Pike and Rozema (1975) state, spectral analysis can quantify the
980 characteristics of general landforms, such as the presence of nonrandom periodic
981 features, the roughness or power of specific frequencies, and the relationship between
982 high and low frequency content, which implies how important large and small landforms
983 are.

984 Although periodic signals are most commonly constructed by adding sine and
985 cosine functions with different amplitude, angular frequency, and phase, it is possible to
986 begin with a complex spectral pattern and then invert the spectral analysis procedure.
987 The value comes from expert-based knowledge of how different spatial series interact
988 across a range of flows to yield different hydrogeomorphic processes (e.g., Brown et al,
989 2016; Brown and Pasternack, 2017). To do this, a power spectral density function is first
990 synthesized for the variables of interest in the frequency domain. This is where
991 geomorphic interpretation of stage-dependent processes is needed- one a set of
992 generic, end-member power spectral density functions is well-known for different
993 hydrogeomorphic regimes, then individual random realizations (i.e., synthetic
994 surrogates) are created by randomly re-assigning phases between 0 and 2π to the
995 Fourier Transform, and then returning the data to the space domain using the inverse
996 transform algorithm (Newland, 2012). The inverse Fourier transform allows one to
997 exactly recover the series x_r and is given by:

$$998 \quad x_r = \sum_{k=0}^{N-1} X_k e^{2\pi ikr/N} \quad (1)$$

999 It is rather straightforward to generate a random signal using the inverse DFT
1000 approach. First, X_k is calculated from a defined set of spectral data. Then, the phases,
1001 θ_k , are randomly selected and re-assigned. Finally, the inverse transform is used to

1002 reconstruct a realization based on the original data series.

1003 If one wants to avoid the comprehensive frequency domain it is also possible to
1004 determine the inverse autocorrelation sequence using auto-regressive modeling while
1005 remaining in the space domain (Cleveland, 1972; Chatfield, 1979), though this yields far
1006 fewer periodic functions than inverse spectral modeling, as only the biggest 1-3
1007 fluctuations are used. Regardless of whether inversion occurs in the space or frequency
1008 domain, it represents a compact method of statistically synthesizing 1D spatial series. If
1009 1D series are generated, then these can be utilized within geometric modeling, along
1010 with other fluvial geometric element spatial series to create 2D topography. To date, this
1011 approach has not been used to model or create 1D spatial series or 2D height fields of
1012 river topography. This procedure can be extended to correlations between other random
1013 variables and for 2D processes as well (Newland, 2012). However, direct application to
1014 2D processes would need to address the fact that this approach assumes that data is
1015 spatially isotropic, while river topography is inherently anisotropic (Merwade et al.,
1016 2009). One way to address this is to simply switch from sine and cosine functions to
1017 longitudinally anisotropic periodic functions, such as the cnoidal wave function. Cnoidal
1018 waves can be parameterized to have any shape, ranging from nearly sinusoidal to
1019 nearly flat-bottomed. This could be highly useful for step-pool and even riffle-pool
1020 longitudinal profiles, as well as for river width profiles dominated by periodic bedrock or
1021 manmade constrictions.

1022 6.2.3 Auto-Regressive Modeling

1023 Auto-regressive modeling is another method of statistical simulation capable of
1024 creating 1D spatial series of topographic attributes, such as the planform alignment and

1025 longitudinal profile. An auto-regressive model qualitatively states that current values are
1026 related to both past values and some level of randomness in the form of white noise
1027 (Newland, 2012). Auto-regressive models are considered random process models that
1028 use linear prediction formulas to predict an output of a system based on the previous
1029 outputs. These types of models are used when a trend is not assumed *a priori* and have
1030 been used extensively to analyze and model riverbed profiles (Bennett, 1976; Richards,
1031 1976a,b; Knighton, 1983) and river planforms (Ferguson, 1976; Phillips and Robert,
1032 2007).

1033 There are no readily available models to download that the authors are aware of, but
1034 programming a 1D auto-regressive model is elementary. Auto-regressive modeling can
1035 be used in two primary ways to create synthetic longitudinal profiles and planforms. First,
1036 coefficients from existing studies can be utilized inasmuch as they represent landscape
1037 characteristics that are of interest. Second, for 2nd order auto-regressive models,
1038 Ferguson (1976) has cast the coefficients in terms of wavelength and a damping factor
1039 so that there is some control over the spatial series being created. For this first case, one
1040 would need to draw on the existing body of literature that is limited by the types of streams
1041 analyzed, the sampling distances in each study, and the scale of the rivers analyzed.
1042 From several existing studies, there is some context to how one could expect the AR
1043 coefficients would change with discharge, sediment size, and land use that could guide
1044 their use in synthesis (Bennett, 1976; Richards, 1976a,b; Knighton, 1983). Given that
1045 model coefficients can provide a simple stochastic model for spatial series oscillations,
1046 these studies show that these coefficients can also be used to model changes associated
1047 with differing bed material, sediment sizes, and water discharge. Thus, AR modeling is a

1048 simple and compact method of modeling 1D profiles and alignments.

1049 6.2.4 Object-Based Synthesis

1050 Object-based synthesis rests on the idea that attributes of river topography,
1051 primarily morphologic units (e.g. quasi-discrete fluvial geomorphic units such as riffles
1052 and pools), can be treated as discrete objects. To date this has been performed as
1053 stochastic object synthesis, where probabilities of occurrence and even adjacency
1054 probabilities are assigned to differing morphologic units from specified distributions
1055 based on empirical studies of morphological unit organization (e.g. Grant et al., 1990;
1056 Meyers and Swanson, 1997; Thompson, 2001; Wyrick and Pasternack, 2014). These
1057 types of models assume that specific morphologic units are preceded by other units,
1058 analogous to auto-regressive modeling, and that for certain combinations, exclusions
1059 may occur. For example, Meyers and Swanson (1997) developed a stochastic model of
1060 pool-to-pool spacing and widths in small, rangeland streams in Nevada, USA using a
1061 compound Poisson process. Later, Thompson (2001) modeled pool-to-pool spacing in
1062 coarse bedded streams whose pools are dominated by channel constrictions. A
1063 fundamental assumption of the Thompson (2001) model is the minimum length
1064 assumption, whereby there is a minimum length, and thus spacing, of pools related to
1065 hydraulic factors that lead to their formation, such as a backwater effect. The result of
1066 such an assumption is that there exists an exclusion length driven by local hydraulics
1067 where a new pool cannot exist (Thompson, 2001). In the model, the location of pool
1068 forming elements (PFE) are generated from uniformly and randomly distributed
1069 numbers and the sorted distances used to represent PFE locations within a simulation
1070 reach. A pool is assumed present at the first PFE and its length determined from a

1071 probability distribution based on empirical values. After the pool, a riffle is assumed to
1072 form with a set spacing. At the next PFE a determination is made whether or not the
1073 PFE is located within an existing pool-riffle couplet. A new pool-riffle couplet is then
1074 added only when it does not occupy an existing one. Overall, the modeling procedure
1075 creates a series of pool-riffle couplets as a function of distance. The impact of this study
1076 was that the synthetic modeling of pool spacing allowed insights into how regular pool
1077 spacing values commonly reported could exist, despite random controls on pool
1078 locations.

1079 To date, only discrete units in 1D have been generated, as opposed to 2D object
1080 maps and heightmaps, so this approach has not been fully demonstrated. However,
1081 Wyrick and Pasternack (2014) analyzed the adjacency of laterally explicit morphological
1082 units and generated both abundance and size statistics as well as the probability of
1083 each unit type being adjacent to each other one. They also showed that each unit type
1084 has characteristic hydraulics, and to the extent that depth is a type of slope-detrended
1085 elevation, it would be possible to assign characteristic heights to each morphological
1086 unit type. That points toward the feasibility of translating this approach to yield
1087 heightmaps but would require additional development. Namely, the statistical and rule-
1088 based models for object location could be coupled with statistical models for bed
1089 topography for specific morphologic units.

1090 **7 Discussion**

1091 *7.1 Digital realism*

1092 Digital rivers are constructed for a wide range of purposes by individuals with

1093 backgrounds drawing from graphic arts, computer sciences, earth sciences, engineering
1094 and architecture. Currently, this diversity in user background and purpose yields an
1095 inherent conflict in digital realism in that there exists no universal standard as to what
1096 makes a digital river adequately realistic. Part of this is intrinsic to visual assessments
1097 that are classically in the eye of the beholder. While geomorphologist may develop
1098 quantitative topographic, stratigraphic, statistical and morphologic metrics of realism in
1099 the scientific context, most people experience rivers without this background. An
1100 observer could inspect a river corridor surface constructed using 2D morphodynamic
1101 modeling that embodies the state of the art in fluvial geomorphology (e.g. Figure 6), but
1102 the untrained eye may not even recognize it as a river due to the lack of surficial
1103 sedimentary texture, or the presence of vegetation and animals. Conversely, an
1104 artistically derived river corridor surface with those three types of elements (e.g. Figure
1105 4b) could have no underlying physical basis, yet appear more realistic than something
1106 created using a morphodynamic model that even includes stratigraphic layering.
1107 Trained geomorphologists may view these artistic representations as lacking the basic
1108 physical attributes of real river corridors (Figure 8A).

1109 Given the value of digital rivers to multiple applications, such as science,
1110 engineering, entertainment and art, there need not be a singular standard as to what
1111 constitutes a real river for all purposes, but this idea does deserve some attention. In a
1112 scientific context, one may want to test one or more unrealistic and realistic digital rivers
1113 to test the presence/absence of specific processes in different contexts. The
1114 juxtaposition of results from different designs can provide powerful insights about why
1115 rivers with specific features function as they do (Jackson et al., 2015). However, in an

1116 engineering context, one might only test realistic designs, but each with slight variations
1117 and embellishments to layer on unique features serving different management goals. In
1118 a video game context, realism is often outweighed by playability, leading to fluvial
1119 landscapes with much higher relief and vastly more discharge than naturally occur. A
1120 goal of this paper has been to provide a review of these different approaches so that
1121 ultimately digital rivers can be created that are realistic to scientists and casual
1122 observers who interact with digital rivers in through entertainment.

1123 *7.2 From Headwater To Sea –What Is Possible?*

1124 This section aims to discuss what types of river systems are currently possible to
1125 simulate using different approaches, and then, what approaches could simulate the
1126 longitudinal diversity of channel form within a watershed. From headwater streams
1127 down to river deltas there is a continuum of fluvial form, ranging from hillslope hollows to
1128 step-pool streams, meandering rivers and ultimately to distributary channel networks
1129 through depositional terrain. Hypothetically, expert methods can be used to create any
1130 type of river morphology and planform, provided the user is knowledgeable in both
1131 fluvial geomorphology and the software platform(s) being used; Red Dead Redemption
1132 II[®] boldly illustrates the achievable scope given enough resources. For the strategic
1133 approaches discussed in this article, Table 3 shows what is currently possible in terms
1134 of stream morphology and planform typology. In terms of river planforms, straight,
1135 meandering, braided, anabranching, and distributary can be created from a variety of
1136 methods with varying assumptions and complexities (Table 3). Straight channels are
1137 geometrically and topographically simple and can be created in a simple and
1138 straightforward manner in most approaches. Other than straight rivers, meandering

1139 rivers have the most methods available and can be simulated rather quickly, while other
1140 planforms, such as braided and anabranching, are more limited. With regards to
1141 channel morphology, dune-ripple, riffle-pool, and step-pool profiles can be simulated in
1142 1D from statistical and analytical methods. Discrete particle models have been shown to
1143 simulate a plethora of channel profiles, such as those just mentioned, as well as
1144 channel forms associated with steeper gradients (e.g. >1%), such as transverse ribs,
1145 sediment clasts, and cascades. However, both of these would need to be combined
1146 with geometric modeling to create 3D river channel topography.

1147 Presently, there is no single tool or approach to simulate the continuum of channel
1148 form from headwaters to the sea. Most planforms associated with lowland river valleys,
1149 including river distributary networks, have been simulated using 2D morphodynamics
1150 within the Delft3D platform (e.g. see Table 3), but this approach has not been used to
1151 model or create the continuum of these forms within a catchment. To create the
1152 topography of rivers and stream networks within complete landscapes, a mosaic of
1153 techniques appears to be needed (de Carpentier and Bidarra, 2009). By analogy with
1154 global climate models, river synthesis models may require multiple modules connected
1155 within a larger framework to achieve the range of outcomes needed, as any one single
1156 algorithm does not capture the diversity of processes and forms across multiple scales
1157 at this time.

1158 When considering the headwater to sea problem, expert approaches can be used
1159 to create multiscalar surfaces with as much detail as one wants to invest time to create,
1160 and with the outcomes as good as the user, software platform, and time investment. In
1161 many regards, this is the current state-of-the art for professional practice in engineering

1162 and landscape architecture with CAD, though engineers rarely design at the catchment
1163 scale unless they are addressing a problem like reclamation design for mountain mining
1164 (DePriest et al., 2015) or large-scale housing development. Engineers tend to limit their
1165 efforts to just essential topographic design at a scale that is practical for construction. In
1166 contrast, landscape architects aim to convey more detail since their work interacts with
1167 the public to gain support for implementation. Most of their efforts tend to be in planform
1168 view or cross-sectional view, both with feature-based elements, but they can include
1169 intensive 3D design as well. However, from a practical level the extreme cost of
1170 implementing laborious brush and map expert approaches is never going to be
1171 affordable for environmental problem solving using traditional consultant-based funding
1172 approaches. Thus far, this has only been affordable for open-world video game design
1173 where billion-dollar revenues justify such effort. The construction of entire terrains,
1174 including rivers, in video games such as Skyrim, Dragon Age Inquisition, Assassins
1175 Creed III, and countless user-generated maps in Minecraft are all testimony to what
1176 people can achieve with these tools at the catchment scale if they want to invest the
1177 time into it and when working as a large collaborative team. Nevertheless, for traditional
1178 business use with low labor investment, it is essential to move beyond these traditional
1179 methods and get at automated approaches.

1180 7.3 *Cross-Pollinating Among Disciplines*

1181 A key outcome of this review is that real and artificial rivers are generated for digital
1182 environments from a variety of applied and scientific disciplines. An interesting aspect of
1183 cross pollination is that, broadly speaking, Earth science and computer science
1184 applications have different measures of success. While computer scientists strive to

1185 create landforms that are visually realistic and are driven by aesthetics (e.g. Smelik et
1186 al., 2014), fluvial geomorphologists seek to understand how and why specific forms
1187 originate as well as how they change spatially and temporally. River engineers want to
1188 build real analogues to geomorphologist ideals. Put another way, fluvial
1189 geomorphologists seek hydrogeomorphic process realism over landform realism, with
1190 terrains generated by systems of equations that can be simplified (CA models) or highly
1191 complex (3D morphodynamic process models). Inevitably models simplify real world
1192 processes and forms. Some models do aim to achieve as much realism as possible,
1193 while others aim for parsimonious methods (Willgoose, 2005). Modeling of fluvial form
1194 and process has focused on developing, calibrating and validating models to real world
1195 conditions. To this, many mathematical models of river flow and sediment transport
1196 suffer from scientific criticisms related to underlying model assumptions, lack of
1197 validation, and unrealistic outputs (Cao and Carling, 2002). However, their utility in
1198 computer science may be unbounded because those applications do not have to
1199 adhere to the constraints of real-world calibration and validation. Therefore, many
1200 models that are considered inadequate for understanding fluvial geomorphologic
1201 processes may be useful computer science applications in creating digital rivers. Fluvial
1202 geomorphologists can identify processes and mathematical relationships for specific
1203 types of topography, but computer scientists can help those ideas be implemented in
1204 user friendly and dynamic platforms for uses in other fields.

1205 An opportunity for both disciplines to collaborate is to develop ways of relating
1206 visual realism and landscape aesthetics to quantitative measures of river corridor
1207 variability. Leopold (1969) developed an objective approach to evaluate landscape

1208 aesthetics that could be used to forward this idea. Physical, biological and human
1209 interests are used as organizing elements in developing metrics for characterization.
1210 For example, the amount of trash in a river corridor is a human centric attribute that can
1211 be quantified by direct measurement. If geomorphologists and computer scientists could
1212 agree on which attributes have the most utility in providing a link between the physical
1213 form of river corridor and their aesthetics, then there could possibly be a greater
1214 exchange between disciplines. River channel classification may provide an adequate
1215 bridge in this context, as the more advanced procedural models of rivers have already
1216 shown their utility (Genevaux et al., 2013). Habitat typing classifications that consider
1217 biotic forms, such as vegetation, over those that are strictly geomorphic may be more
1218 useful to graphic designers, because of the role vegetation plays in most real and
1219 artificial scenes (Figure 4).

1220 We posit that much can be gained from cross-disciplinary collaborations, especially
1221 considering the fiscal motivation behind each discipline. Comparatively, the total
1222 economic motivation to have tools capable of synthetic terrain generation and
1223 modification for use in river restoration, engineering, and science is on par with that for
1224 use in computer games and movie animation, but the latter are far more visible to and
1225 used by the public. Of course, the societal value of these different uses is debatable, but
1226 ultimately both are driving advances that can benefit each other if there were cross-
1227 pollinating efforts. Costs for restoration projects are highly concentrated and centralized,
1228 whereas those for video games and animations are distributed among a wide user
1229 base, making it more feasible to expend more and adapt to the latest technologies. The
1230 annual expenditure for river restoration activity worldwide is poorly documented, but for

1231 the United States Bernhardt et al. (2005) estimated it to be ~ \$1 billion. A primary cost
1232 associated with large, marquee river restoration projects is land purchase, such as the
1233 expenditure of ~ \$300 million to buyback land for the Kissimmee River Project in
1234 Florida, which is currently estimated to have an eventual total cost of \$980 million,
1235 though this is spread over many years (Bousquin, 2010). The Kissimmee River Project
1236 is an excellent example where the river's terrain was heavily altered. As another
1237 example the cost of the Elwha Dam Restoration Project, including but not limited to the
1238 removal of two large dams, has been estimated at \$324.7 million (Callis, 2011).

1239 Meanwhile, individual video games have sales on par with the cost of the largest
1240 restoration projects. The most heavily used terrain generating and modifying video
1241 game ever is Minecraft[®], which uses procedural generation to create infinitely sized
1242 worlds. Users can modify generated worlds either by adding or subtracting individual 1³
1243 m blocks or using external third-party software, such as the free World Painter[®]. As of
1244 June 2016, there were over 100 million registered users of Minecraft on sales of over
1245 106 million units. Sales revenue in 2013 alone was \$330 million (Grundberg and
1246 Hansegard, 2014). Minecraft[®] uses simple volumetric pixels, so in contrast to that
1247 consider a premiere exemplar for the application of synthetic terrain and river in
1248 advanced graphics video games from the same vintage— The Elder Scrolls V: Skyrim[®],
1249 an open-world fantasy adventure game with stark mountain terrain, waterfalls, and
1250 many rivers covering an estimated ~ 17 km² of horizontal terrain and 3.2 km of height
1251 (Sutton, 2012). This game has sold more than 30 million copies with over \$1.3 billion in
1252 revenues. Another open-world historical science fiction game with realistic terrain and
1253 rivers, Assassin's Creed 3[®], sold 12 million units in its first four months on the market.

1254 With a fixed retail price of ~ \$60 at that time, gross income was ~ \$720 million. It is
1255 being remastered and resold with improved graphics in 2019. Red Dead Redemption II
1256 sold 23 million units in its first fiscal quarter available, generating \$1.38 billion in
1257 revenues. Other examples in recent years include the Far Cry® series, Supersonic
1258 Sled®, and Rigs of Rods® (a vehicle simulator). Usually a handful of high-revenue
1259 games (>\$100 million) are produced each year along with many low-budget games
1260 using terrain generators. Comparatively, the profit motive for advancing methods for
1261 synthetic river terrain generation and modification clearly resides with the video game
1262 and animation industries over scientific and engineering ones.

1263 Outside of collaborations between geomorphologists and computer scientists,
1264 further exploration and development of digital river design could benefit the growing
1265 research and applied science of how to restore or recreate heavily impacted rivers and
1266 streams. This is an area where both computer and earth scientists have a lot to offer. In
1267 developing designs for restoration projects, rivers are often recast in light of significant
1268 anthropogenic impacts, such as flow regulation, floodplain development, stream burial,
1269 dredger and dredge mining, to name a few. For example, in river restoration design,
1270 ideas and concepts are typically conveyed to public stakeholders using 2D rendered
1271 conceptual sketches, idealizations using landscape architecture methods, or abstract
1272 CAD drawings meant for construction. While these are helpful, they do not convey the
1273 full topography of what is envisioned, let alone the associated processes. Artistic
1274 renderings can be time consuming and are only as good as the artist. Design details
1275 and drawings are common staples of engineering, but primarily due to technological
1276 deficiencies as the field developed over time - not because they are the best way to

1277 convey ideas. One way that this process could be improved is through Virtual
1278 Geographic Environments (VGEs, Goodchild, 2009, Konecny, 2011, Lin et al., 2013)
1279 whereby stakeholders can experience and interact with designs before they are
1280 constructed in the real world. VGE's can nest not only terrain but other sub models, too,
1281 that users can virtually interact with, such as vegetation and human infrastructure. While
1282 VGEs are currently in their infancy in terms of widespread usage, they are a prime
1283 example of cross-pollination that should be pursued by river restoration scientists and
1284 practitioners.

1285 *7.4 Future Directions*

1286 Future research into building digital rivers is relatively open ended depending on
1287 purpose. Here we discuss several future directions that may hold promise including:
1288 morphodynamic, hierarchical, procedural, object based, hybrid modeling, and machine
1289 learning.

1290 Recent developments in morphodynamic modeling using reduced complexity and
1291 traditional physics suggest that process-based models capable of producing emergent
1292 digital river topography will improve dramatically with time and become more accessible
1293 to users across engineering, geomorphology, and landscape animation. The recent shift
1294 of the DELTARES morphodynamic model to be open source marks a potential turning
1295 point along this line and will surely pressure other developers to open their sources as
1296 well, though such models can have steep learning curves. Using morphodynamic
1297 models has the advantage over most strategic methods in that they are based on
1298 physical processes as we perceive and model them today. They can develop emergent
1299 forms that are related to exogenous terrain features. Morphodynamic models have

1300 commonly been criticized for excessive computational demands, a limited inclusion of
1301 relevant processes, lack of stochastic processes, simplified bed and bank material
1302 heterogeneity, lack of vegetation feedbacks, and divergent outcomes when different
1303 models of the same type are used with the same starting inputs. Also, it is challenging
1304 to know what hydrologic and sediment flux regimes to use and how long to run
1305 unsteady models in light of dynamic boundary conditions. Advances in parallel
1306 computing and/or graphical processing units and associated software should address
1307 computational aspects making larger and more detailed models more feasible. Further,
1308 research has over time identified key physical processes, such as convective
1309 accelerations and secondary flow needed to produce emergent fluvial forms such as
1310 meanders and anabranches. These processes can be reduced to more simplified forms
1311 allowing use over greater spatial domains in reduced complexity models. Simplifications
1312 of bed material heterogeneity are often used to limit computational demands, but this
1313 too should continue to evolve. Considering how far morphodynamic modeling has come
1314 over the last 30 years we expect this growth to not only continue but accelerate.

1315 Fluvial systems exhibit hierarchical organization in that smaller scale processes
1316 and features are nested within larger scale features (Hallet, 1990; de Boer, 1992). The
1317 implications of hierarchical organization in river systems have significant bearing on how
1318 they can be modeled. Larger features typically operate over larger time scales, while
1319 smaller scale features operate over shorter time scales (de Boer, 1992; Werner, 1999).
1320 Werner (1999) advocated for the use of hierarchical modeling for simulating complex
1321 landforms because the smaller scales processes are “slaved” to larger scale dynamics.
1322 Drawing on this, Doeschl-Wilson and Ashmore (2005) demonstrated conceptually how

1323 hierarchical modeling could be used to overcome some of the pitfalls of the Murrary and
1324 Paola braided river model (1994). One way to perform hierarchical modeling is to
1325 represent features, and not necessarily the dynamics, with models that describe
1326 variability at specific scales. As an example, Clarke (1988) proposed a scale dependent
1327 method for creating terrain that married fractal geometry and inverse spectral synthesis.
1328 While Clarke's model (1988) has not been used to create river topography, it is worth
1329 considering here because of the potential for this method to yield spatially dynamic river
1330 topography. The elevation field of the model considers both scale-dependent and scale-
1331 independent features defined by the equation:

$$Z_{x,y} = T_{x,y} + F_{x,y} + H_{x,y} + E_{x,y} \quad (2)$$

1332 where $T_{x,y}$ is a trend model, $F_{x,y}$ are the scale dependent surface components related to
1333 the Fourier coefficients, $H_{x,y}$ is the scale independent surface components, and $E_{x,y}$ is
1334 an erosion component. Each of these components are argued by Clarke (1988) to be
1335 vital aspects of natural terrain and together, create terrains with both visual and realistic
1336 properties by merging stochastic and deterministic models. Thus, this model shows how
1337 a reductionist analysis of topography can be inverted by considering the total elevation
1338 field to be a linear combination of scale independent and scale dependent attributes.
1339 While it hasn't been explored in great detail for river topography to date, hierarchical,
1340 scale dependent modeling represents a relatively untapped area of research for digital
1341 rivers. In particular, this approach fits within the synthetic river valley approach, whereby
1342 each geometric element can be designed by creating linear combinations of scale
1343 independent and scale dependent attributes (Brown et al., 2014).

1345 Procedural modeling has been successfully applied to the creation of terrains

1346 and river networks. However, it has also recently been applied to more complex
1347 problems such as structurally sound masonry buildings (Whiting et al., 2009) and entire
1348 cities (Parish and Muller, 2001). While it has begun to incorporate geomorphic theory,
1349 such as in Geneveaux et al. (2013), this is still very simplistic compared to natural river
1350 topography (Figure 8). Fluvial geomorphology has produced a wealth of knowledge
1351 related to how rivers and stream look and function, yet most of this is untapped in the
1352 realm of procedural modeling, likely because the coders and users are experts in math
1353 and art, not geoscience and engineering.

1354 Technological advances in data collection have begun to yield high-resolution
1355 surveys of real rivers in a variety of settings (Bangen et al., 2013), the sharing of
1356 topographic data sources is now possible through websites such as
1357 www.opentopography.org, which allows researchers to have access to a wide array of
1358 meter-scale topographic data sources. A key area of research should be distilling data
1359 for specific channel typologies (e.g. both planform and morphology) into adjustable and
1360 scalable ‘topographic templates’ that can be used in evolutionary algorithms, procedural
1361 blocks and in object-based modeling for river restoration and computer science
1362 applications. Using topographic templates as a basis for procedural modeling primitives
1363 could be a way to capture the benefits of procedural modeling while also incorporating
1364 data on actual river topography. For example, terrain simulation techniques using
1365 evolutionary algorithms, such as Saunders (2006), rely on the user providing a
1366 reference heightmap. If topographic templates for specific types of rivers could be
1367 generated, then they could be used in video games if a library of topographic templates
1368 for specific types of rivers was also available. Further, object based procedural

1369 modeling may be a way to model boulders and stream wood for more diverse channel
1370 typologies of smaller order streams in mountainous regions (Figure 9). Many civil
1371 engineers use 3D “blocks’ for these types of features in river restoration plans, so the
1372 technology already exists. What is needed is developing object blocks and merging
1373 them with models of channel form, so they can hierarchically nested as they are in
1374 nature (Hallet, 1990).

1375 Landscape terrain modeling software that hybridizes procedural, morphodynamic,
1376 and geometric modeling methods already exists and can be further enhanced to provide
1377 the best balance between realism (both process and form) and computational speed.
1378 For example, it is presently possible to begin with the “blue line” hydrography of a river
1379 network and a sloped plane representing the frontal slope of the mountain that the
1380 hydrography will sit in, combine them mathematically, and then hit them with LEM-style
1381 hillslope and channel erosion processes already built into the software to yield a
1382 dendritic watershed on a mountain front. The recent development of an expert-based
1383 geometric method/model for synthetic river valleys shows that it is highly feasible to take
1384 the principles of geomorphology and apply them to create realistic terrains with
1385 geometric modeling that in turn have real physical processes and associated ecological
1386 functions (Brown et al., 2014). With modest effort, this river-centric approach can be
1387 built into landscape-scale and reach-scale terrain generators, such as World Machine®
1388 and Bryce®. An example of this approach is shown in Figure 10. Processing time to
1389 generate such a model would be seconds to a few hours depending on terrain size and
1390 complexity, which would be far faster than pure CA and morphodynamic modeling.
1391 Meanwhile, geometric modeling has the value of being able to create unconstrained

1392 terrains as well as constrained ones without having to re-code and re-run the way a
1393 morphodynamic model would require you to really delve into its innards to deviate from
1394 the pre-programming. Recognizing that there is still more we don't know about rivers
1395 than we do know, it is highly important to have this capability. Another important
1396 advantage of this approach over pure morphodynamic modeling is that it is explicitly
1397 multi-scalar, with a wide limit on the range and resolution of scales to address; only
1398 constrained by computation time. Overall, the value of pursuing procedural hybrid
1399 modeling appears to be high, even as morphodynamic models continue to advance.

1400 On 29 October, 2018, the video game publisher Electronic Arts announced Project
1401 Atlas, which may prove to be a fundamentally disruptive scientific and technological
1402 development for digital river synthesis, if not for geoscience as a whole. Project Atlas
1403 recognizes that expert-based synthesis involving manual labor is reaching its limit of
1404 scalability due to labor cost, necessitating adoption of widespread automation
1405 throughout video game development. At the core of this automation lies Artificial
1406 Intelligence (AI). Quoting Ken Moss, Electronic Arts' Chief Technology Officer, "With
1407 Project Atlas, we are starting to put the power of AI in the creative's hands... we are
1408 using high-quality LIDAR data about real mountain ranges, passing that data through a
1409 deep neural network trained to create terrain-building algorithms, and then creating an
1410 algorithm which will be available within the platform's development toolbox. With this AI-
1411 assisted terrain generation, designers will within seconds generate not just a single
1412 mountain, but a series of mountains and all the surrounding environment with the
1413 realism of the real-world." Already, AI has transformed many industries, and now it is
1414 moving into geosciences. Shen (2018) reviewed the potential applications for hydrologic

1415 sciences, while specific applications of AI for geomorphic analysis are emerging
1416 (Brungard, 2015; Perry and Diskson, 2018). Yet, Project Atlas is offering something far
1417 beyond mere interdisciplinary analysis of any one geoscientific phenomenon; it is a
1418 comprehensive and integrated AI system that will phenotypically understand and
1419 produce holistic combinations of synthetic natural worlds, not only with hyper-realistic
1420 terrain, but also biota, ecological interactions, human infrastructure, and human culture.
1421 Further, it will not just produce outputs, but more importantly provide tools to those who
1422 want to use this power to make their own customized outputs. In theory, AI could
1423 hybridize all pre-existing toolsets, bring in new deep learning toolsets, as well as invent
1424 entirely unforeseeable new approaches. Can and will such creative capability be
1425 available to and taken up by scientists and engineers? Not only that, but under Project
1426 Atlas, which also includes a suite of video game engines, there is the opportunity to fully
1427 integrate synthetic river development with immersive experiential visualization systems
1428 to put stakeholders into those river corridors before construction to fully experience a
1429 wide range of geophysical processes and ecological functions. This could allow for
1430 troubleshooting problems interactively before spending large sums on construction.
1431 Thus far that has not been possible due to the manual labor of video game engines, but
1432 Project Atlas would change that, too. Overall, the future is exciting and bright for
1433 synthetic river development.

1434 **8 Concluding Remarks**

1435 This paper shows that there are many avenues to building artificial digital rivers,
1436 and we have made the first attempt to synthesize a wide array of approaches drawing
1437 on Earth and computer sciences and video games. From the review, it was found that

1438 while a diverse array of channel types can be simulated for river reaches or segments,
1439 complex and spatially dynamic models do not exist to date that can represent the full
1440 topography of rivers within watersheds. Expert-based strategies that rely on artistry are
1441 unbounded, but laborious and often not grounded in how rivers are shaped and formed.
1442 Strategic approaches are grounded in deterministic or stochastic physical rules but are
1443 limited by our current knowledge of riverine geomorphology, which of course is still
1444 evolving. To bridge this gap, we proposed a now obvious need for multidisciplinary
1445 collaborations that will improve all approaches for creating synthetic river topography.
1446 Importantly, we do not advocate for one approach over another, as the spectrum of
1447 methods presented affords a wide range of approaches to an inherent multidisciplinary
1448 problem. Ultimately this begs the question as to what is considered realistic or accurate
1449 in depicting the Earth, which is application specific. Considering how much of our world
1450 is being recast in digital formats, having realistic rivers for scientific work – and play - is
1451 an area of research that should be prioritized in both fluvial geomorphology and
1452 computer science.

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2001 [Skyrim-overworld?q=how+large+skyrim+size](http://www.quora.com/The-Elder-Scrolls-V-Skyrim/How-large-is-Skyrim-overworld?q=how+large+skyrim+size)
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Table 1. Conceptual basis and goals for the three primary approaches to terrain generation.

Type	Concept	Goals
Procedural	Uses algorithms that blend rules with randomness. Can incorporate geomorphic laws	Visual realism Rapid generation Some user control
Expert	Completely user defined	Visual realism or engineering design
Geomorphic	Driven by geomorphic theory on how landscapes form and evolve	Replicate essential physics Identify relevant processes and timescales

Table 2. Mathematical functions used to model the meander planform alignment, thalweg profile, and cross-section geometric elements drawn from the literature. M refers to morphologic unit scale (10^0 - 10^1 channel widths), R refers to reach scale (10^2 - 10^3 channel widths), and B refers to basin scale ($>10^1$ channel widths).

Geometric element	Mathematical function/ model type	Scale	Sources
Channel profile	Exponential	B	Tanner, 1971; Yang 1971; Snow and Slingerland 1987
	Power	B	Yang 1971; Snow and Slingerland 1987
	Logarithmic	B	Yang 1971; Snow and Slingerland 1987
	Hybrid	B	Schumm 1960; Langbein and Leopold 1964; Ohmori, 1991
	2nd order, autoregressive	R, M	Knighton, 1983; Richards, 1976a
	Variogram	R, M	Robert and Richards, 1988
	Regression	R, M	Anderson et al, 2005
	Linear trend	R, M	Leopold et al, 1964; Knighton, 1998
	Variogram	R	Legleiter and Kyriakidis, 2008; Legleiter, 2012
	Polynomial	NA	James, 1996
Cross section	Statistical distribution	NA	Merwade and Maidment 2004; Jacobson and Galat, 2006
	Curvature based asymetry	NA	Deutch and Wang, 1996
	Analytical	NA	Bridge, 1977; Beck, 1988
	Rectangular	NA	Chow, 1959
	Semi-circle	NA	Chow, 1959
	Traiangular	NA	Chow, 1959
	Trapezoid	NA	Chow, 1959
Channel alignment	2nd order, autoregressive	M,R,B	Ferguson, 1976
	Analytical	M,R,B	Kinoshito, 1961
	Sinusoid	M,R,B	Langbein and Leopold, 1966

Table 3. Examples of current strategic approaches to topographic synthesis by channel morphology and planform typology. P denotes that it is possible but no peer-reviewed studies to date and N denotes not able to be created

Channel Morphology	1D Spatial Series	2D Height Map
Dune-ripple	van Rijn, 1984; Karim, 1999; MacVicar et al., 2006	Paarlberg et al., 2009; Nabi et al., 2013
Riffle-pool	Cao et al., 2003; MacVicar et al., 2006; de Almeida and Rodriguez, 2012	Beck, 1988; Nicholas, 2010, 2013
Plane bed	P	P
Step-pool	P	Tribe and Church, 1999; Malmaeus and Hassan 2002
Cascade	N	N
Planform		
Meandering	Langbein and Leopold, 1966; Nikora and Sapozhnikov, 1993	J and Van De Wiel, 2006; Wang et al., 2010; Sylvester et al. 2011; Nicholas et
Braided	N	Murray and Paola, 1994; Nicholas et al., 2013; Schuurman et al. 2013
Anastomising	N	Murray and Paola, 2003; Wang et al., 2010; Nicholas et al., 2013
Distributary	N	cz, 2009; Edmonds and Slingerland, 2007; Seybold et al. 2007; Liang et al. 20

2103 11 Figure Captions

2104 Figure 1. A flow chart for building synthetic digital rivers.

2105

2106 Figure 2. Two contrasting map-based designs for a river restoration project on the
2107 Trinity River, CA (modified after Pasternack and Brown, 2013).

2108

2109 Figure 3. Surface topography for unconfined (A) and confined (B) rivers valleys created
2110 using the synthetic river valley framework of Brown et al. (2014).

2111

2112 Figure 4. Example digital river created using brush techniques (A). The heightmap
2113 shown was created in Bryce 3D® as explained in the text. Datum and scale are
2114 arbitrary. Also shown are two riverscapes (B,C) created using brush techniques from the
2115 game Red Dead Redemption.

2116

2117 Figure 5. Example digital river created using interactive technique in Sketchup®. First a
2118 blank grid is produced with 1m spacing (A). Next, mountains are created by extruding
2119 cells upwards along the edge of the grid (B). Finally, cells in the middle are pulled
2120 downward to create the river channel (C). The circled object is a 1.68-m tall person for
2121 scale.

2122

2123 Figure 6. Examples of morphodynamic model outputs and real rivers from Nicholas
2124 (2013). Natural and modelled braided sand-bed rivers: South Saskatchewan River (A),
2125 Canada; simulated morphology after 150 years of channel evolution (B). Colour scale
2126 bars indicate water depth (blue), surface height above a fixed datum (mean low flow
2127 water level) at dry channel locations (yellow to red), and age of vegetated surfaces
2128 (green). Labels 'x' in (A) indicate unit bars. Key model parameter values for this
2129 simulation are listed in Table I in Nicholas 2013. All model results are shown at low flow
2130 (discharge ~10 000–11 000 m³ s⁻¹). Flow is left to right (indicated by arrow).

2131

2132 Figure 7. CAESER model outputs of a 12-km stretch of the Upper Severn, UK at 1000
2133 (A), 3000 (B), and 6000 (C) days of simulation illustrating planform changes. The model
2134 grid resolution is 20 m. Image courtesy of Tom Coulthard, University of Hull.

2135

2136 Figure 8. Examples of procedural modeling at channel (A,B) and valley scales based on
2137 Geneveaux et al., 2013 compared with photographs of real rivers (C,D). The braid bars
2138 in (B) lack anisotropy in bar geometry found in real rivers (C). Further, there is no
2139 transition in the braid plain width (B) with increasing valley width (D) as commonly
2140 occurs in nature. The photograph in (C) is the Son-Kul River in Kyrgyzstan and in (D) is
2141 the Resurrection River, Kenai Peninsula, Alaska. Images A and B are courtesy of Eric
2142 Galin, University of Lyon and photographs C and D are courtesy of Marli Miller,
2143 University of Oregon.

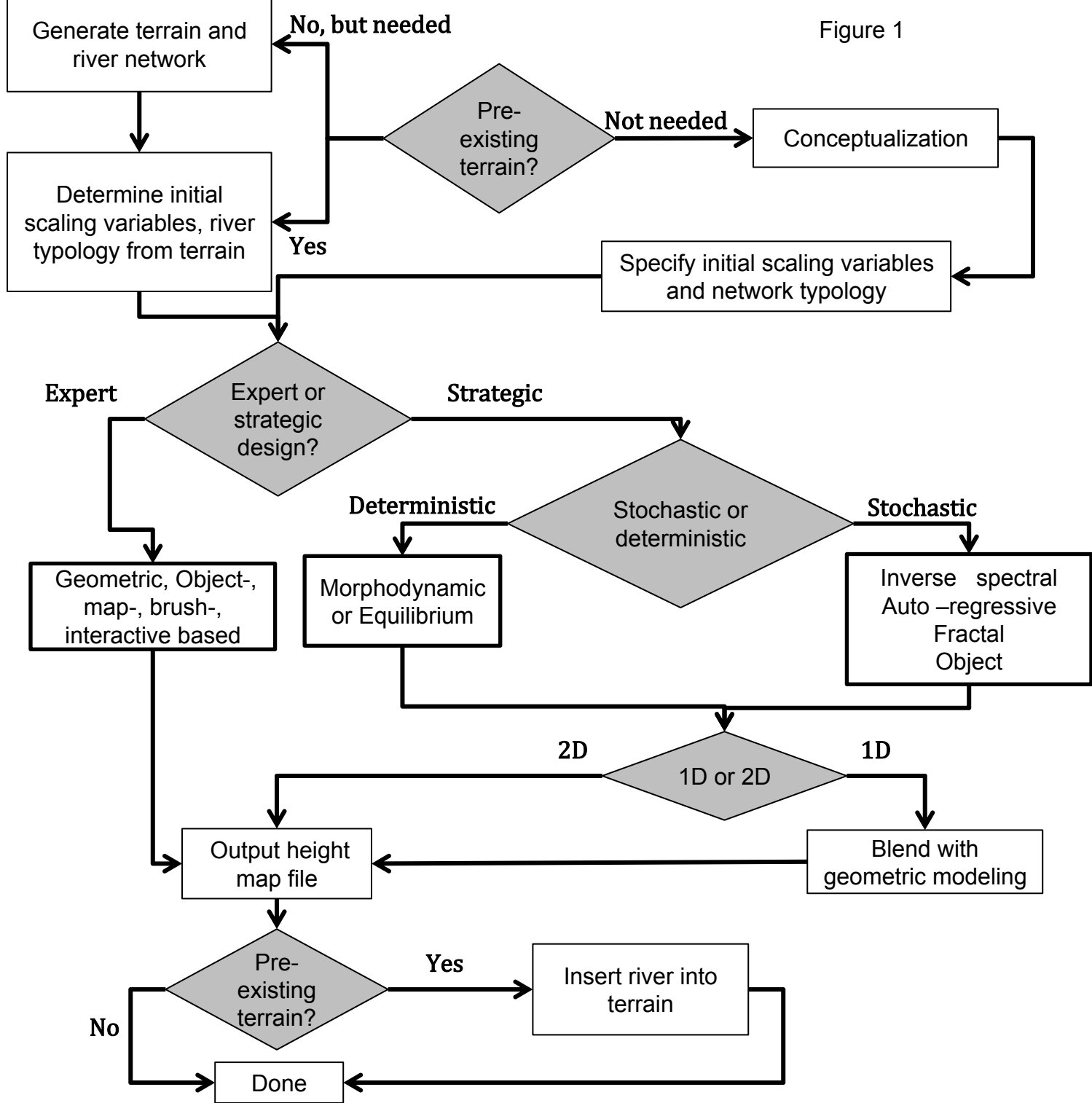
2144

2145 Figure 9. Examples of fluvial topography with boulders and streamwood. These local 3D
2146 objects yield complex surfaces that cannot currently be created procedurally from any
2147 as-of-yet articulated methods other than expert-based techniques that rely on artistry.
2148 Future efforts could solve this problem if attended to.

2149

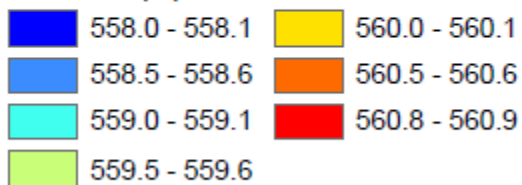
2150 Figure 10. Oblique view of an artificial river valley created using the Synthetic River
2151 Valley geometric modeling approach now built into World Machine®.

Figure 1





Elevation (m)



— 0.1 m contours

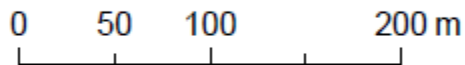
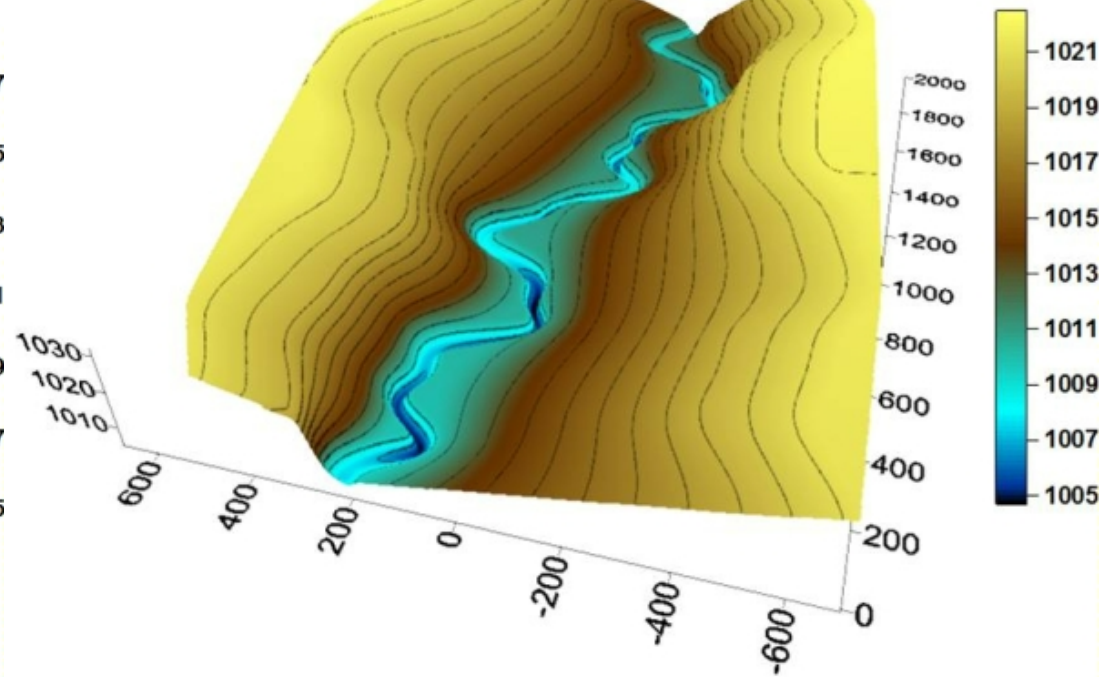
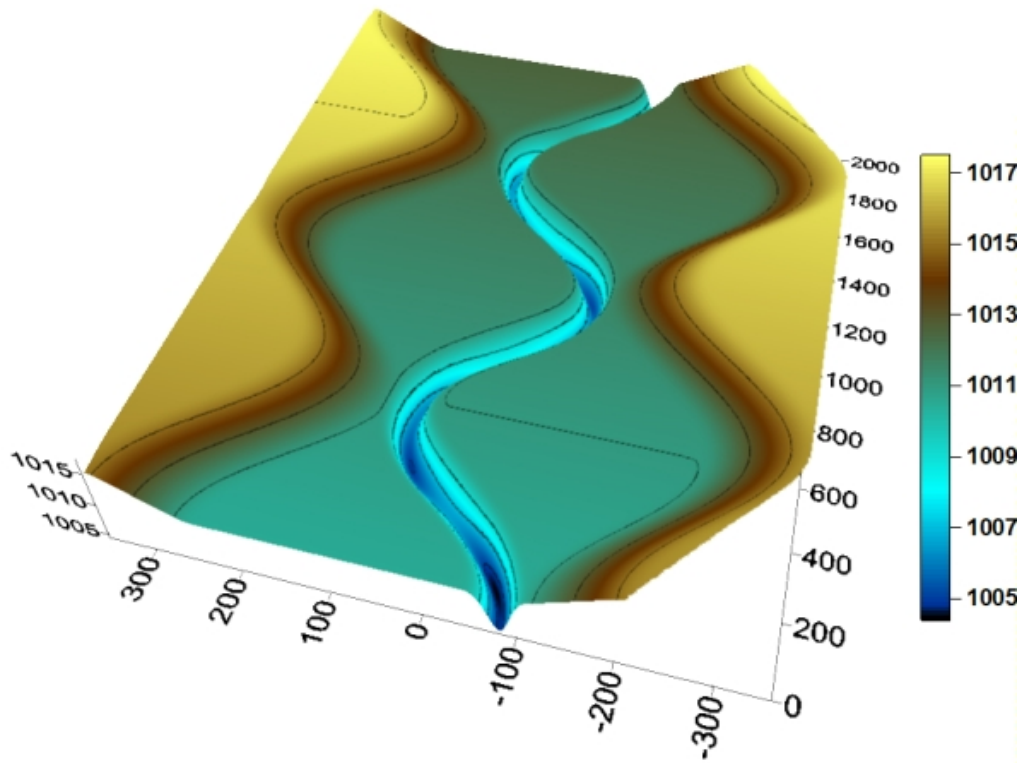
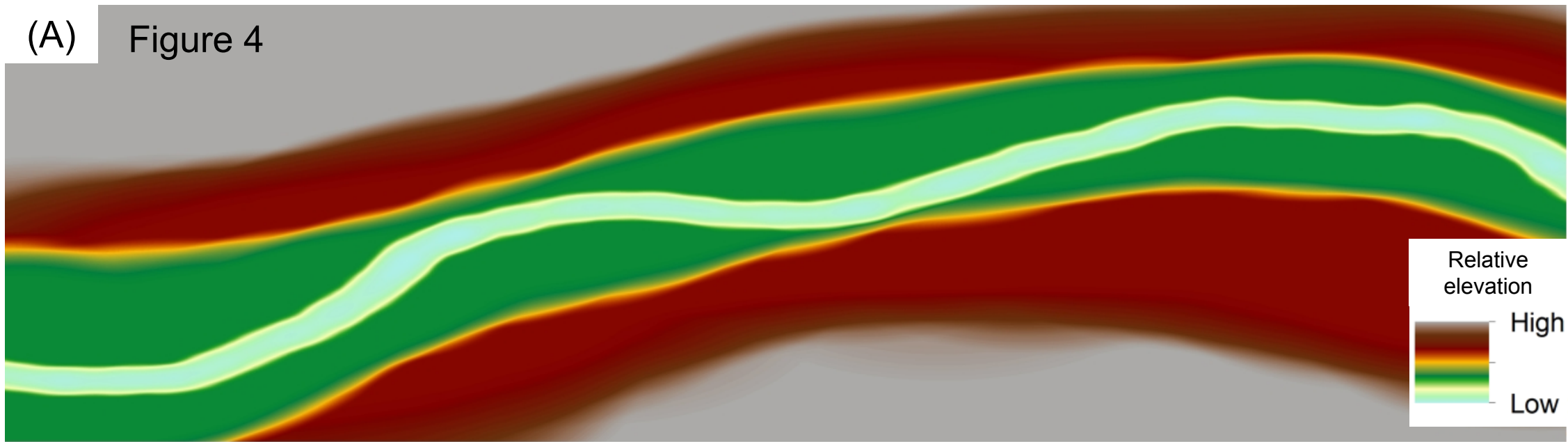


Figure 2

Figure 3



(A) Figure 4



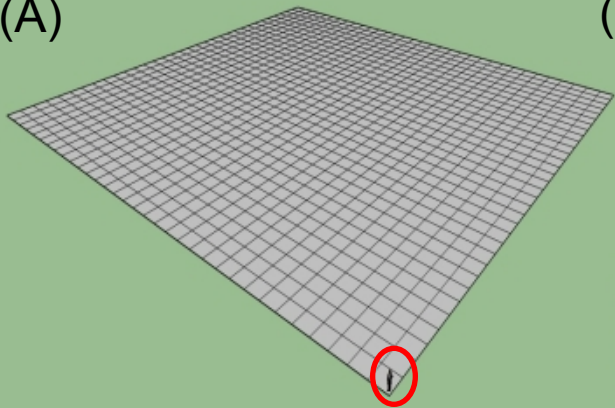
(B)



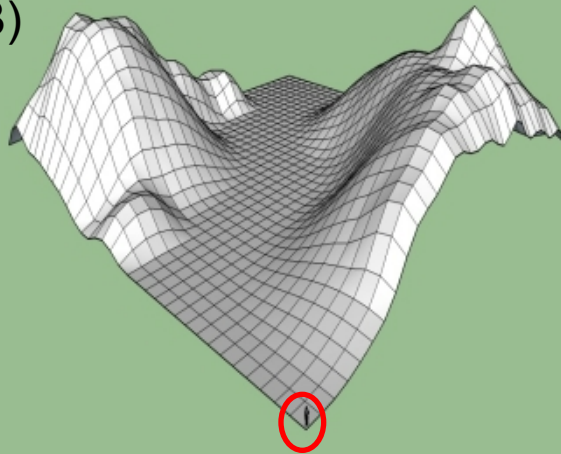
(C)



(A)



(B)



(C)

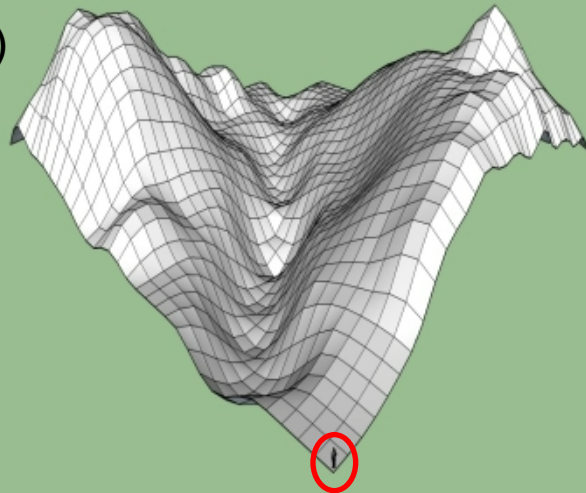


Figure 5

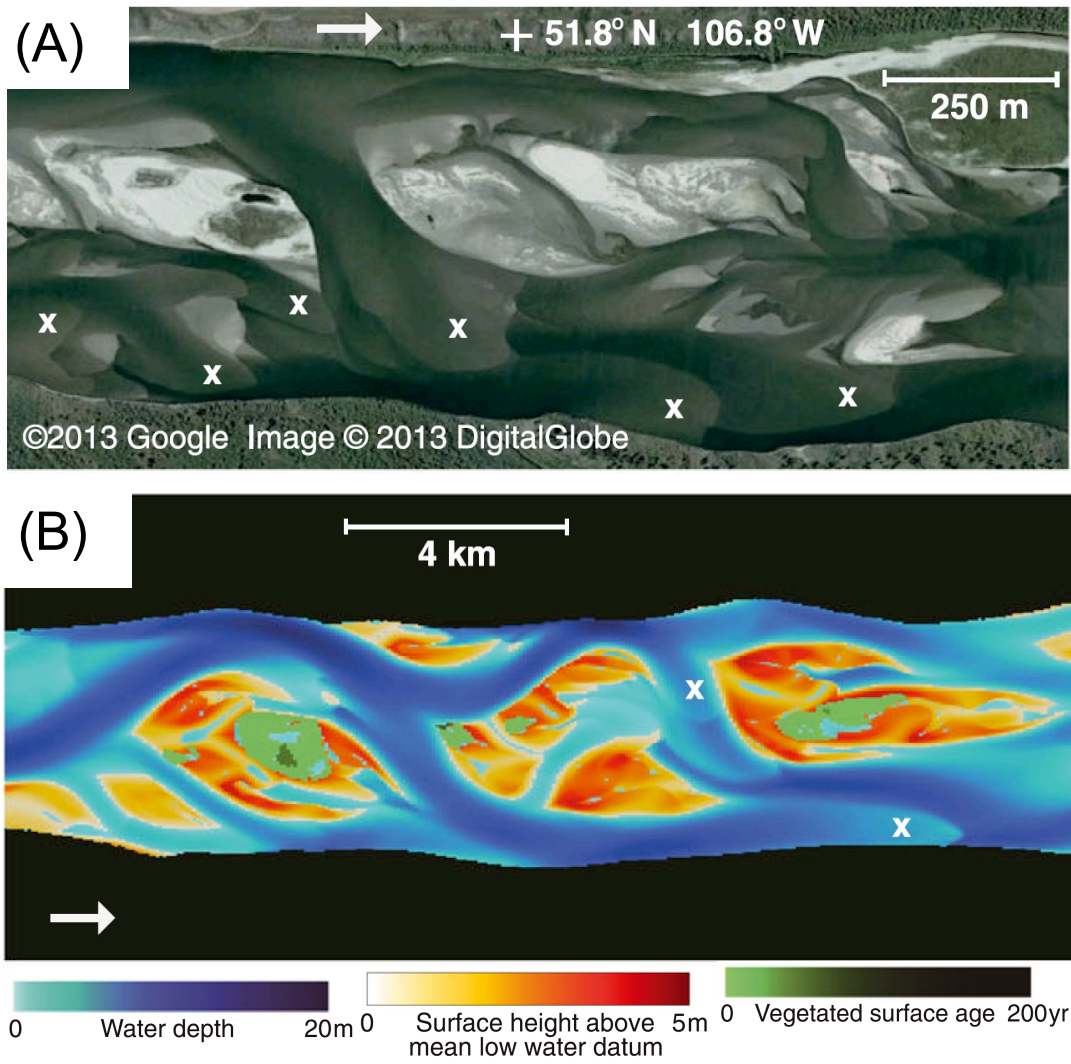


Figure 6

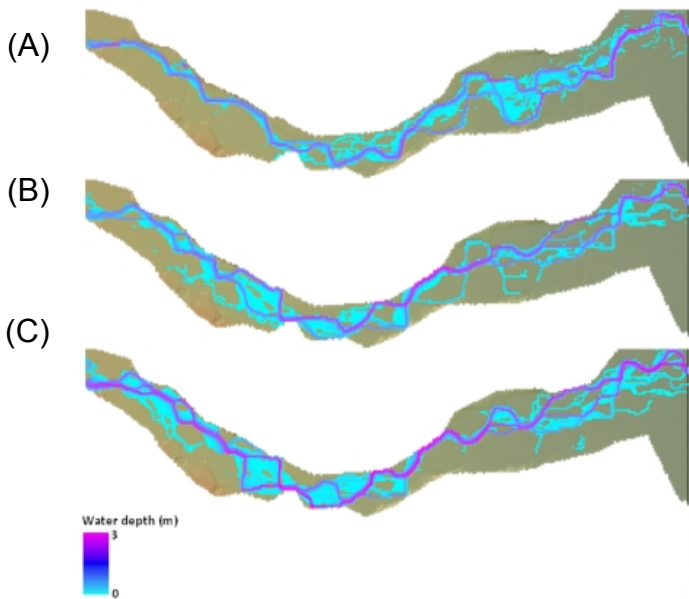


Figure 7

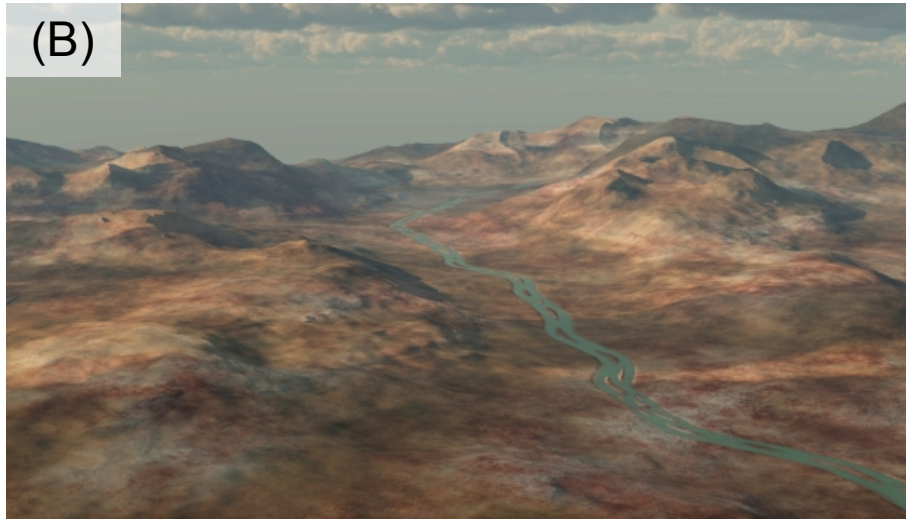
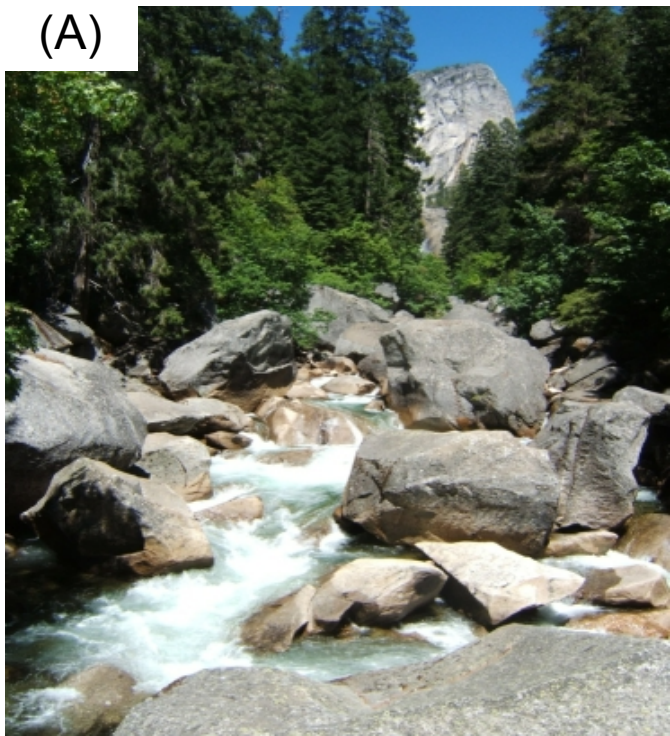


Figure 8

(A)



(B)



(C)



Figure 9



Figure 10