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Flexible Culverts Under High Fills: Equilibrium Considerations

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FLEXIBLE CULVERTS UNDER HIGH FILLS:
EQUILIBRIUM CONSIDERATIONS

A Report of an Investigation

by

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Department of Public Works
State of California
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PREFACE

The work of Brown^(1,2) on the subject of the loads on rigid culverts under high fills is extended to account for certain deformations of the culvert. However, the study considers only equilibrium states of the flexible culvert and the problem of buckling is ignored. The extensions of existing analytical solutions to provide for deformations of the culvert were carried out by D.R. Green. These additional matters were included in a computer program with the aid of S. Pawsey. The solution of special problems was carried out by the authors and comparisons were made with field test results and statements about the effects of construction methods, culvert rigidity and base material were possible.

Quantitative results were obtained by the use of the I.B.M. 709⁴ computer at the University of California, Berkeley. The field test results and material properties were provided by the Bridge Department of the Department of Highways, with the co-operation of the Materials and Research Department. Prof. J. Sackman provided remarkable liason facilities during the final stages of the work, after the departure of two of the authors from Berkeley.

The program of investigation was supported by the California State Division of Highways and The Bureau of Public Roads.

Introduction

Recently the loads on rigid culverts under high fills has been studied.^(1,2) In particular, interest has been focussed on the possibility of predicting the load distribution on the culvert when the fill material, base material and method of fill were specified. Here the additional feature of the deformation of the culvert as the fill material is placed is taken into consideration. Equilibrium culvert modes are dealt with and no concern has been given to likelihood of the culvert buckling. After a brief review of the existing state of the problem the important analytical additions are developed and then employed in the solution of typical problems. These allow engineering statements to be made of the effects of culvert flexibility and comparisons with field tests.

The Problem of Incremental Effects

In the stress analysis of elastic bodies which reach their final dimensions by accretion of material the final stress and displacement fields due to gravitational loading depend upon the order and manner in which the body reaches its final state. This absence of uniqueness is attributable to a dislocation of the Somigliana type being formed between the added material and the existing body. With the addition of a subsequent layer of material this dislocation is healed but the final effect is that of incompatibility tensor occurring in the final description of the state of the completed body. The stresses and displacement at $C(x,y)$ due to a layer of material added at A can be described for a plane strain case as

$$\begin{aligned} \bar{u}_i^A &= \bar{u}_i^A(x,y) \\ \bar{\sigma}_{ij}^A &= \bar{\sigma}_{ij}^A(x,y) \end{aligned} \quad (1)$$

A dislocation is formed at A which is healed when the next layer at A' is added. Thus an additional layer causes conditions at C as (1) except for A' instead of A. Fig. 1 illustrates this geometry. Further the construction to the final contour, F, can be similarly described. If the material addition process is continuous then the final state in the body at C may be obtained by the integration of such increments and

$$\begin{aligned}
 u_i &= \int_c^F \bar{u}_i dy \\
 \sigma_{ij} &= \int_c^F \bar{\sigma}_{ij} dy
 \end{aligned}
 \tag{2}$$

These details have been fully formulated in references 3 and 4.

The presence of a culvert which is flexible also demands an incremental solution which takes account of the historical sequence of events. Consider Figure 2. As the fill is placed up the side of the culvert it takes on a shape of Fig. 2(a). The fill placed over the culvert tends to change the shape to that of Fig. 2(b). This tendency may be additionally affected by the base material under the culvert, the fill properties and the possible presence of organic back fill in the region over the crown. These susceptibilities and the proper description of the culvert deformation effects are the main considerations of this study. The extension to the previous papers (1,2) is in this element of the work. The main problem is the description of the deformation of the flexible culvert with load and the coupling of this response to the behaviour of the fill and foundation.

Modeling of Fill and Foundation

This part of the work followed the program developed previously for a rigid culvert (1,2). Specifically the embankment with the included culvert was considered as a plane of unit thickness and the materials as being linear. From the

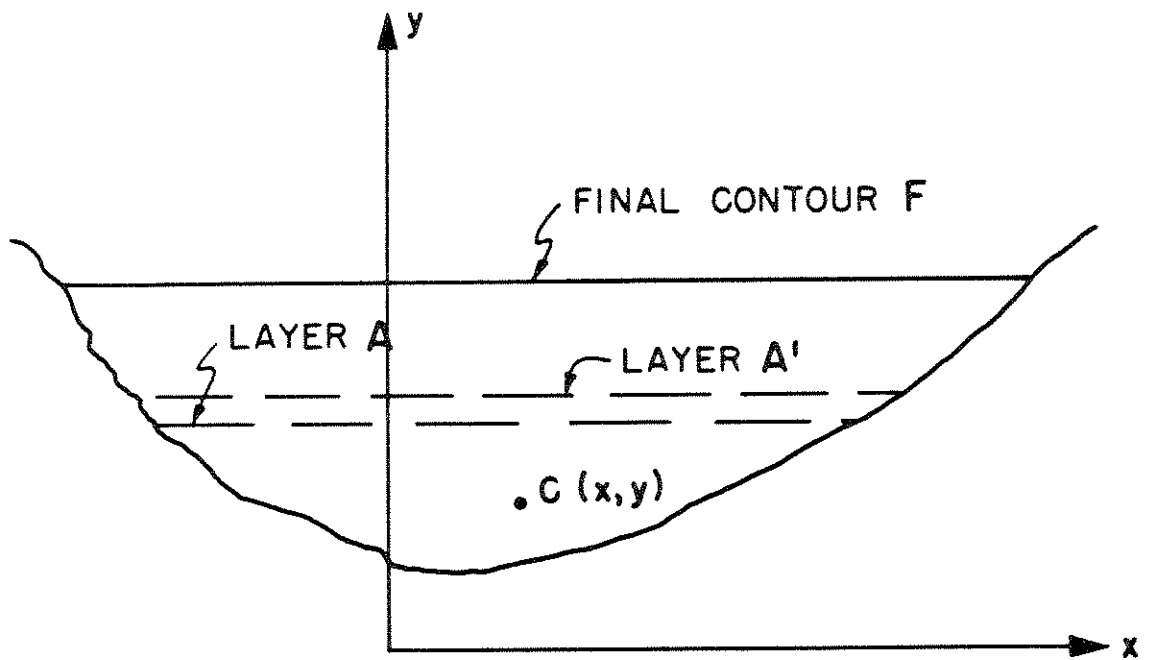


FIG. 1

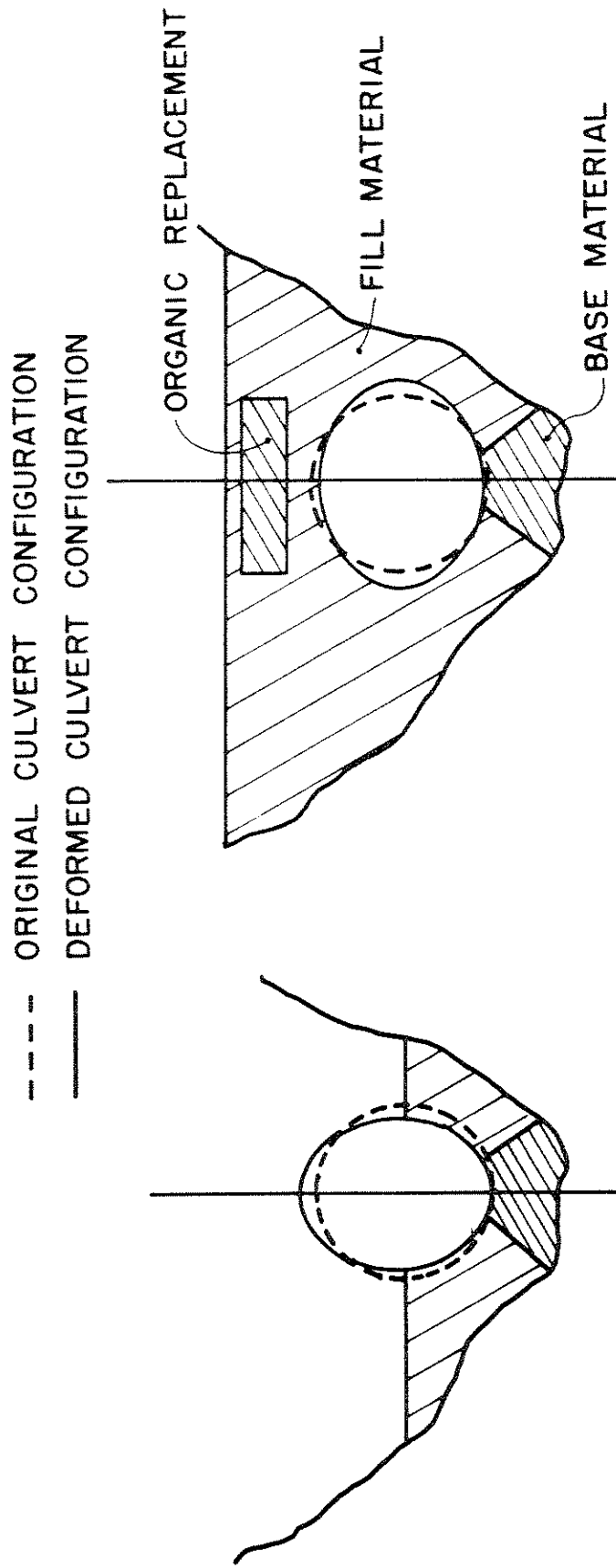


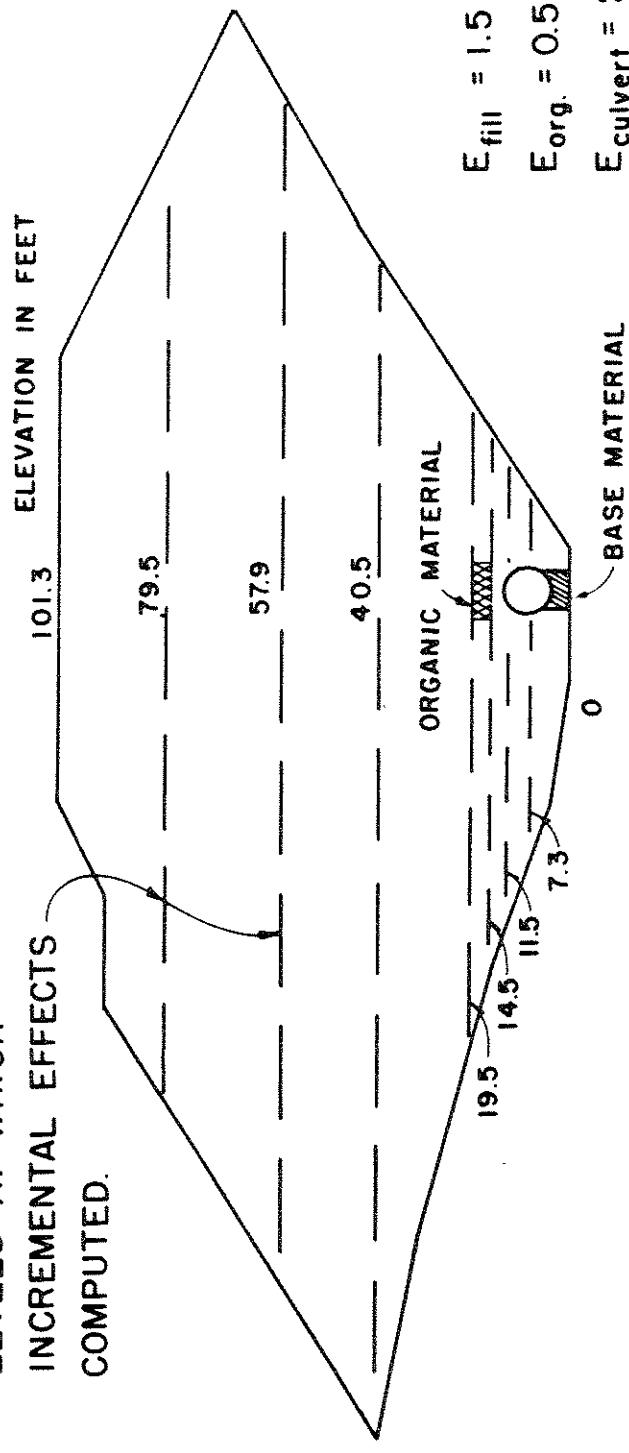
FIG. 2

experience of the analyses of references 1 and 2 the earth's surface was considered to be rigid. However, for the case when the material stiffness of the fill is of the same order as the earth on which it rests then the developments of these references allow for the involvement of this information. The common practice of placing a block of organic matter (hay) over the crown was included in the analysis. This required the consistent duplication of the construction sequence as follows:

- 1) construction of homogeneous fill up to the proposed top level of the organic block--determination of stresses due to this
- 2) trenching of the block region--the application of reverse normal and shear stresses, described in (1), on the perimeter of the block and the addition of the effects of their reversal to the stresses computed in (1)
- 3) addition of organic material--the dead load pressure of this material applied to the base of the organic block and the stresses from this added to those of (2).
- 4) continued fill above the level of the organic block--continued incremental analysis, but now on the heterogeneous existing body of fill
- 5) eventual rotting out of the organic block--reversal of all normal and shear stresses around the perimeter of the block due to the full height and the addition of these reversal effects to these stresses due to the full fill.

Fig. 3(a) shows the arrangement used for the analysis of the problem at Chadd Creek in Northern California. Fig. 3(b), (c) and (d) show the finite element array employed to model the fill with incremental effects at the eight levels.

LEVELS AT WHICH
INCREMENTAL EFFECTS
COMPUTED.



$E_{fill} = 1.5 \times 10^5 \text{ p.s.f.}$
 $E_{org.} = 0.5 \times 10^5 \text{ p.s.f.}$
 $E_{culvert} = 2.7 \times 10^7 \text{ p.s.i.}$

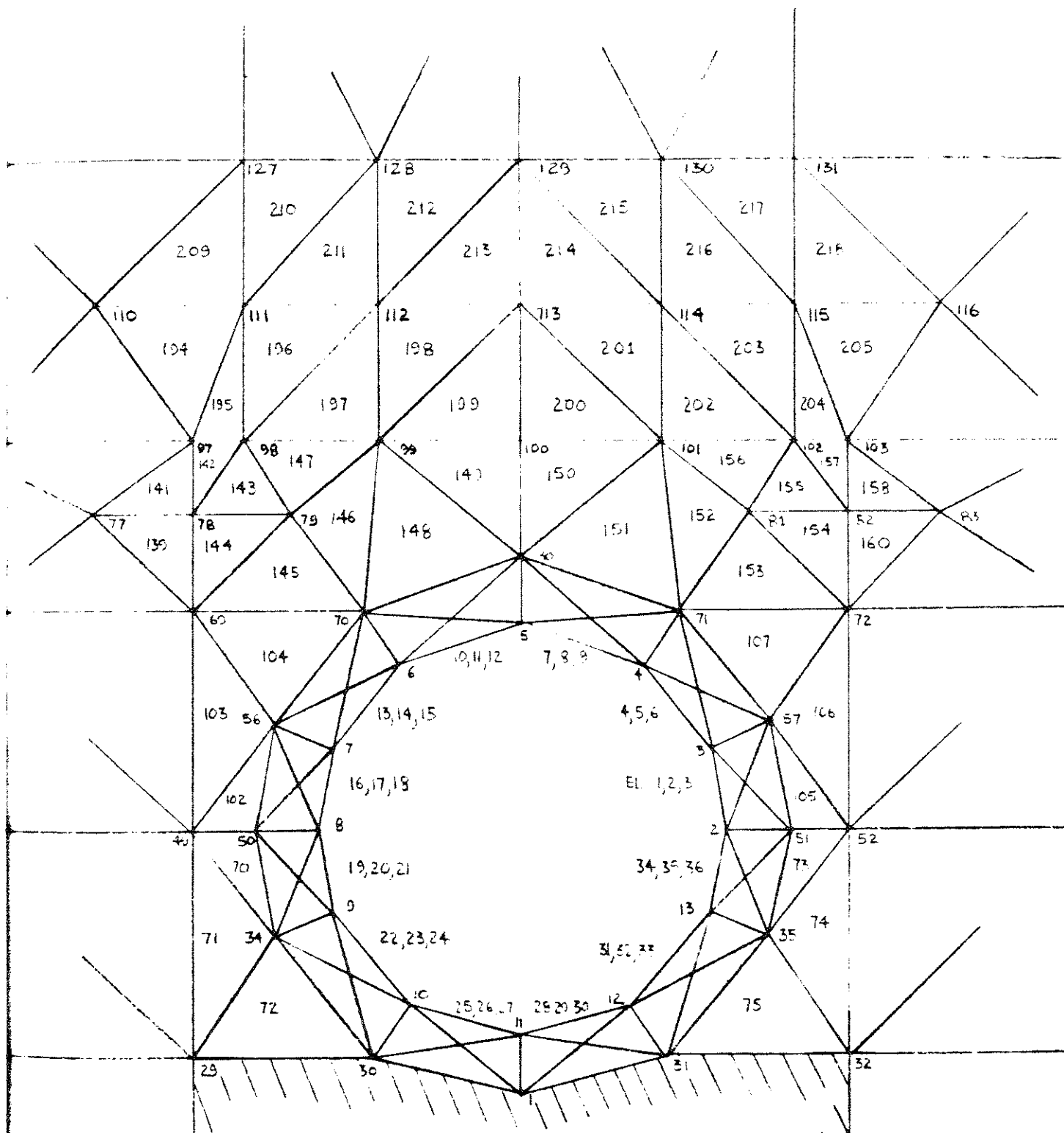
$\nu_{fill} = \nu_{org} = 0.4$

$\nu_{culvert} = 0.3$

Culvert wall thickness = 0.2758"

Culvert mean diameter = 9' - 6"

FIG. 3 (a)



**ELEMENT ARRANGEMENT
AROUND CULVERT**

FIG. 3(b)

FIG. 3(c)

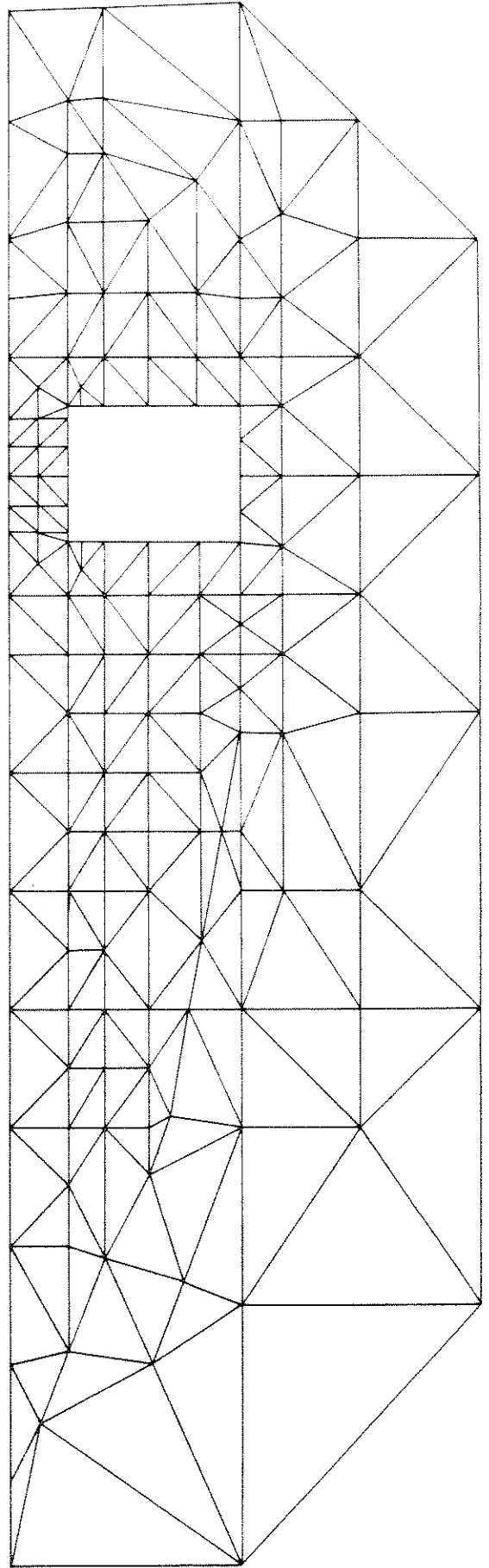
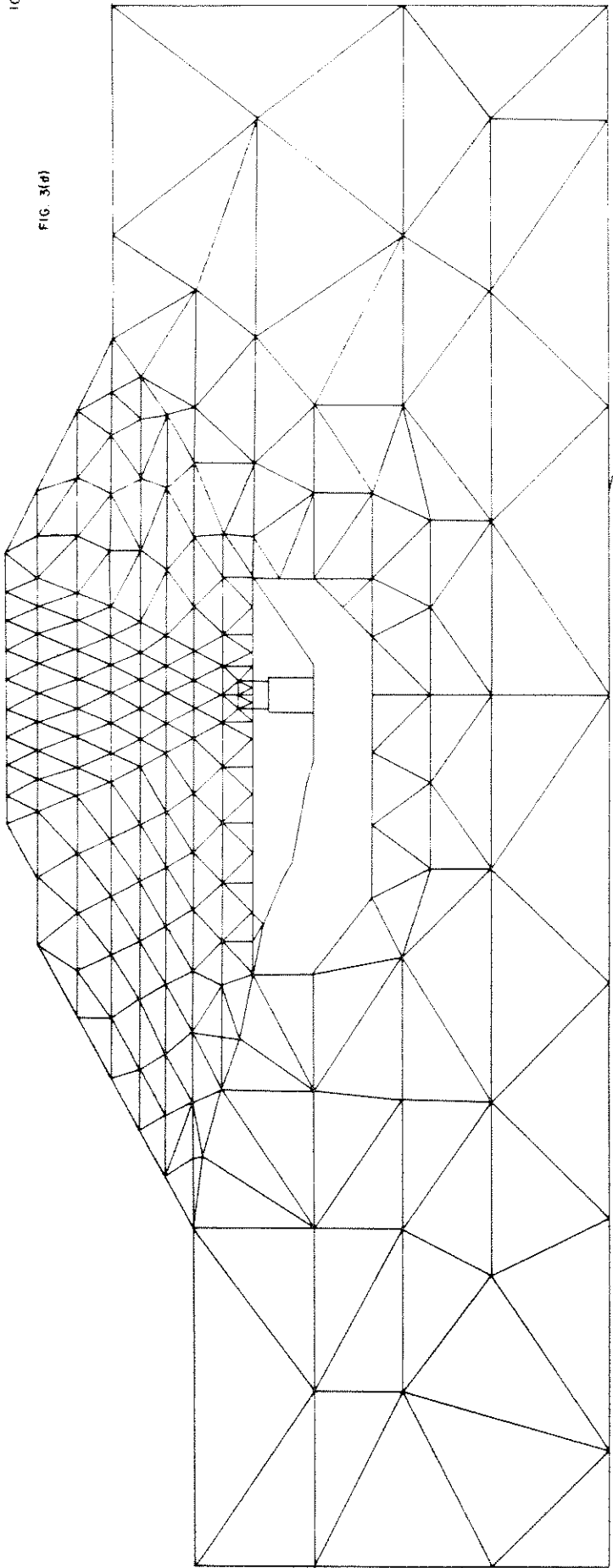


FIG. 3(d)



Modeling of the Flexible Culvert

One way to include for culvert flexibility is to replace the culvert region by a material of equivalent response. As indicated in Reference 1 this is not altogether successful. Here we choose to consider the analysis of a segment of the culvert boundary and then refer the results to a fixed coordinate system.

Consider the portion of the culvert indicated in Fig. 4(a); it is pinned at A and constrained from vertical motion with a horizontal slide at E. In the plane problem the six generalized forces F_i ($i=1$ to 6) may act but

$$F_2 = f_1(F_3, F_4), \quad F_5 = f_2(F_3, F_4) \quad (3)$$

and $F_1 = -F_6$.

The independent forces may be chosen as F_3 , F_4 and F_6 . Similarly the six displacements δ_i ($i=1$ to 6) may exist but

$$\delta_1 = \delta_2 = \delta_5 = 0 \quad (4)$$

leaving the interesting values δ_3 , δ_4 , δ_6 .

Under unit loads at 3, 4 and 6 we have the nine responses at these points, namely Δ_{33} , Δ_{34} , Δ_{36} , Δ_{44} , Δ_{43} , Δ_{46} , Δ_{66} , Δ_{63} , Δ_{64} . If the internal forces are considered for this problem to be independent of the deformations then the reciprocity condition holds and

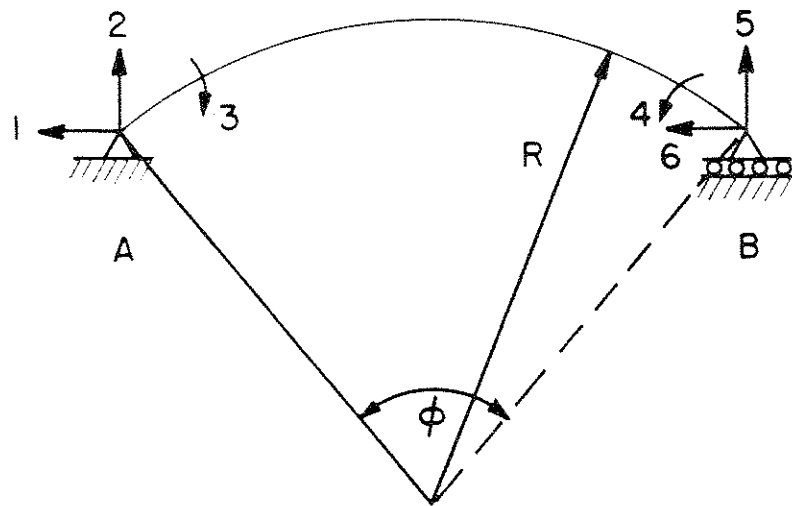
$$\Delta_{ij} = \Delta_{ji}. \quad (5)$$

With this in mind

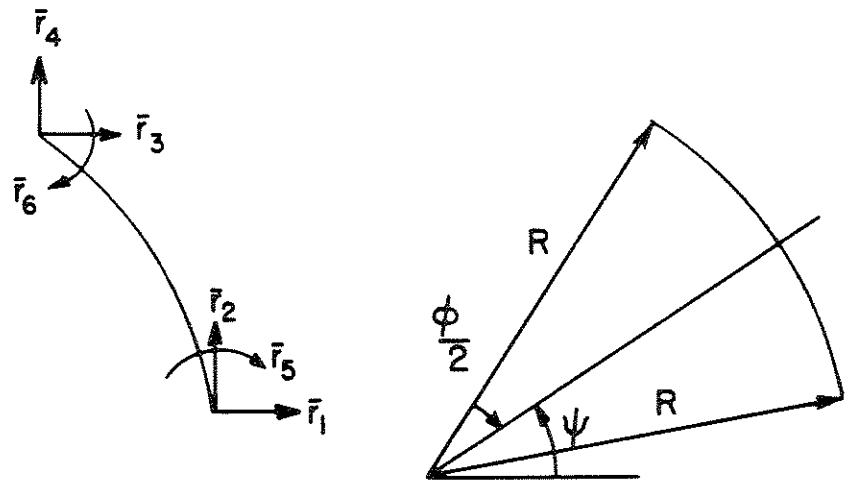
$$[\sigma] = [f][F] \quad (6)$$

where $[f]$ is the flexibility matrix for a circular arc expressed in terms of R , ϕ and EI . The inversion of (6) gives the member stiffness matrix $[k]$;

$$[F] = [k][\sigma]. \quad (7)$$



(a)



(b)

FIG. 4

It is now necessary to refer (7) to a fixed coordinate system. Reference to Fig. 4(b) indicates the manner in which the stiffness matrix may be written in the fixed U, V coordinate system in terms of six motions \bar{r}_i ($i = 1$ to 6)

$$[\delta] = [a][\bar{r}] \quad (8)$$

and therefore

$$[\bar{k}] = [a]^T[k][a] \quad (9)$$

where $[\bar{k}]$ is the standard stiffness matrix in the fixed coordinate system.

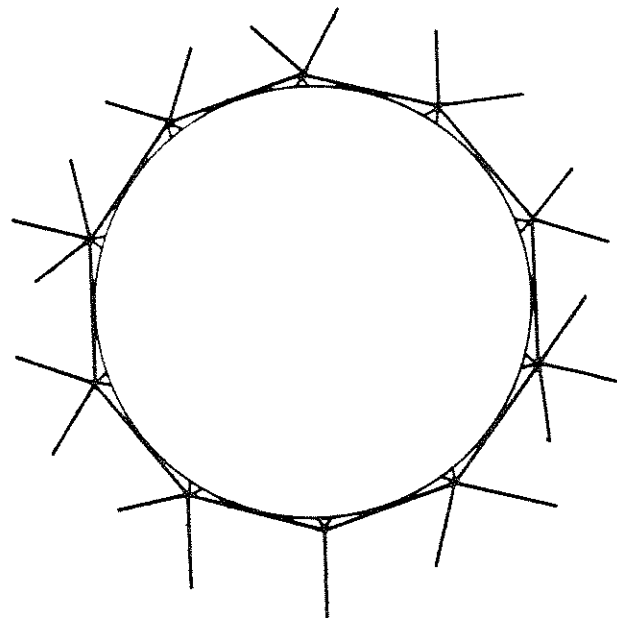
The details of the key equations (8) and (9) are given in the Appendix A.

Triangular Element Representation of Culvert

In order to be able to absorb the properties of the curved elements directly into a program designed for triangular two-dimensional elements, the curved member is represented by three overlapping triangular elements, whose stiffnesses are defined by suitably extracted terms of the stiffness of the curved element.

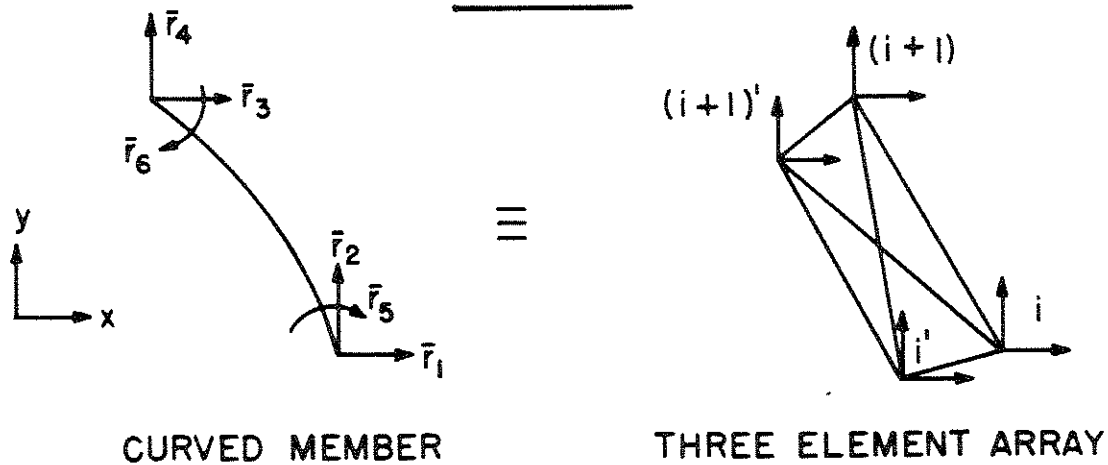
The x,y displacements of the points $i, (i+1)$ are defined to represent those of the corresponding ends of the curved element and the x displacement of points i' and $(i+1)'$ are defined to represent the rotations of the curved element at the respective ends. The y displacements of these latter two points have no physical meaning and for simplicity, the generalized forces associated with these degrees of freedom are set equal to zero.

The elements of the stiffness matrices of the triangles p, q and r are taken from $[\bar{k}]$ computed previously, and arranged so that the stiffness of the assemblage p+q+r matches exactly that of the curved element. Note that if only two triangles, e.g., p and r are included, then the assembled structure p+r could not reproduce the curved structure exactly, since there would be no connectivity between points i' and $(i+1)'$ and thus the elements \bar{k}_{16} and \bar{k}_{26} would be zero, which is incorrect for the curved element.



MECHANICAL MODEL of FILL-CULVERT INTERACTION

FIG. 5(a)



CURVED MEMBER

THREE ELEMENT ARRAY

$$p \equiv [i', i, (i+1)]$$

$$q \equiv [(i+1)', (i+1), i]$$

$$r \equiv [(i+1)', (i+1), i']$$

FIG. 5(b)

Thus we define the stiffness of elements p,q,r as follows

Element p (i', i, i+i)

$$\begin{bmatrix} \bar{k}_{55}^{-1} & 0 & \bar{k}_{51} & \bar{k}_{52} & \bar{k}_{53} & \bar{k}_{54} \\ 0 & 1 & 0 & 0 & 0 & 0 \\ \bar{k}_{15} & 0 & \bar{k}_{11}^{-1} & \bar{k}_{12} & \bar{k}_{13} & \bar{k}_{14} \\ \bar{k}_{25} & 0 & \bar{k}_{21} & \bar{k}_{22}^{-1} & \bar{k}_{23} & \bar{k}_{24} \\ \bar{k}_{35} & 0 & \bar{k}_{31} & \bar{k}_{32} & \bar{k}_{33}^{-1} & \bar{k}_{34} \\ \bar{k}_{45} & 0 & \bar{k}_{41} & \bar{k}_{42} & \bar{k}_{43} & \bar{k}_{44}^{-1} \end{bmatrix}$$

Element q (i, i+1, [i+1]')

$$\begin{bmatrix} 1 & 0 & 0 & 0 & \bar{k}_{16} & 0 \\ 0 & 1 & 0 & 0 & \bar{k}_{26} & 0 \\ 0 & 0 & 0 & 0 & \bar{k}_{36} & 0 \\ 0 & 0 & 0 & 0 & \bar{k}_{46} & 0 \\ \bar{k}_{61} & \bar{k}_{62} & \bar{k}_{63} & \bar{k}_{64} & \bar{k}_{66}^{-1} & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Element r (i', i+1, [i+1]')

$$\begin{bmatrix} 1 & 0 & 0 & 0 & \bar{k}_{56} & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ \bar{k}_{65} & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

then the assemblage $p + q + r$ has stiffness

	i		(i+1)		i'		(i+1)'		
	x	y	x	y	x	y	x	y	
i	x	\bar{k}_{11}	\bar{k}_{12}	\bar{k}_{13}	\bar{k}_{14}	\bar{k}_{15}	0	\bar{k}_{16}	0
	y	\bar{k}_{21}	\bar{k}_{22}	\bar{k}_{23}	\bar{k}_{24}	\bar{k}_{25}	0	\bar{k}_{26}	0
(i+1)	x	\bar{k}_{31}	\bar{k}_{32}	\bar{k}_{33}	\bar{k}_{34}	\bar{k}_{35}	0	\bar{k}_{36}	0
	y	\bar{k}_{41}	\bar{k}_{42}	\bar{k}_{43}	\bar{k}_{44}	\bar{k}_{45}	0	\bar{k}_{46}	0
i'	x	\bar{k}_{51}	\bar{k}_{52}	\bar{k}_{53}	\bar{k}_{54}	\bar{k}_{55}	0	\bar{k}_{56}	0
	y	0	0	0	0	0	2	0	0
(i+1)'	x	\bar{k}_{61}	\bar{k}_{62}	\bar{k}_{63}	\bar{k}_{64}	\bar{k}_{65}	0	\bar{k}_{66}	0
	y	0	0	0	0	0	0	0	2

When we extract rows and columns $i'y$ and $(i+1)'y$ which have no significance physically, we are left with the correct curved element stiffness. The computer program of refs. 1, 2 was altered to allow the culvert stiffness to be included in the analysis, as outlined above.

The full program is included in Appendix B.

Discussion of Various Analytical Results

Fig. 3(a) shows a schematic of the fill at Chadd Creek with a flexible included culvert. Fig. 6 plots the results for normal pressure on the culvert where the material directly under the culvert was considered rigid. The physical condition for each pressure line is given in the Table

Analyses	Fill	Interface Condition (Fill to Culvert)	Culvert
1	homogeneous	No slip	rigid
2	homogeneous	slip	rigid
3	hay replacement	slip	rigid
4	homogeneous	No slip	flexible
5	hay replacement	No slip	flexible

These pressure distributions allow comment on the effects of modifying the interface condition between the culvert and fill to allow for tangential slip, the effect of culvert flexibility and the effect of the hay replacement over the culvert crown.

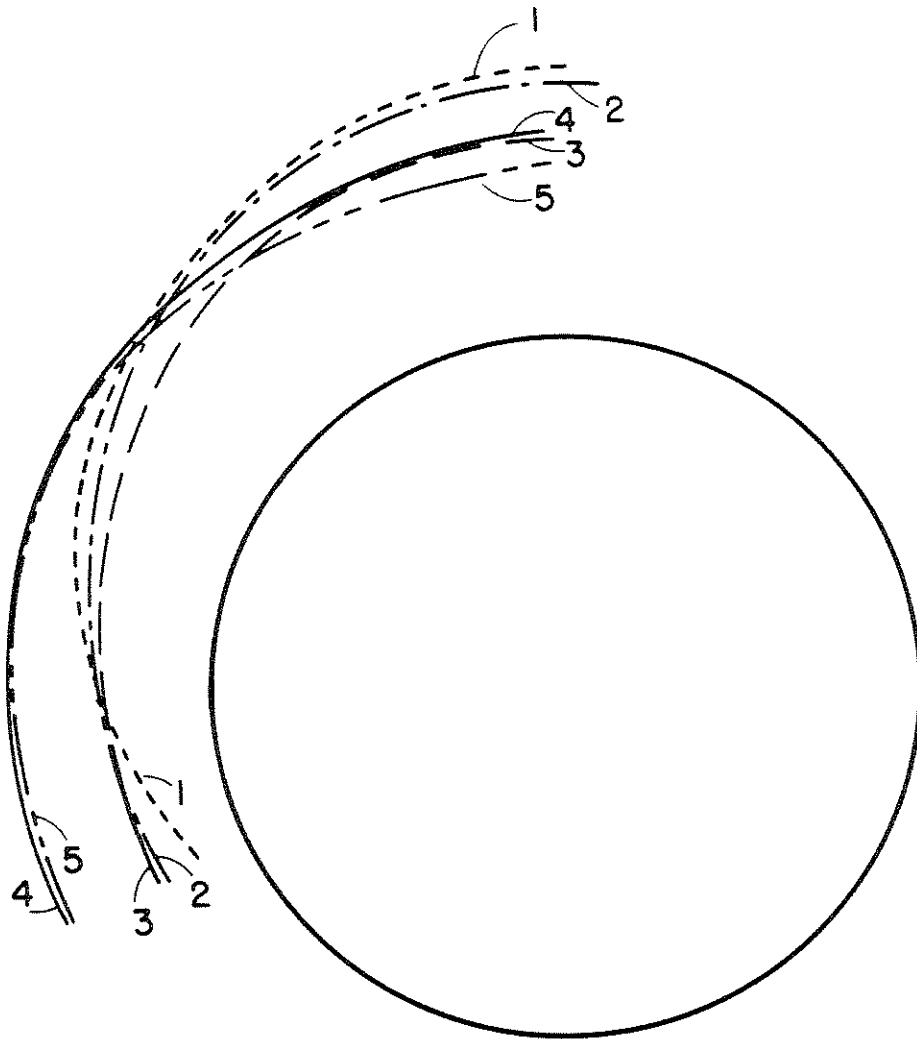
Interface Condition

Analyses 1 and 2 allow the comparison of the extreme interface conditions of slip and no-slip. These lines are typical of those obtained in reference (1) and the sensitivity to this interface condition is apparently negligible in the rigid culvert case. It is this information which justifies the use of the analytically easier no-slip condition in the flexible culvert case.

Culvert Flexibility

Analyses 1 and 4 and analyses 3 and 5 may be compared to determine the effects of culvert flexibility. Both these comparisons indicate that the

SCALE:

 $1'' = 10,000 \text{ p.s.f.} = 70 \text{ p.s.i.}$ **FIG. 6**

arguments of Fig. 2 are correct. Essentially the deformation of the culvert results in reduction of the crown region pressures and the increase of wall pressures due to the additional inducement of passive pressures.

Hay Replacement on Flexible Culvert

Analyses 4 and 5 indicate the effect of hay replacement on a flexible culvert. The effect may be considered as increasing the local flexibility of the culvert over the crown and causing an additional reaction of the walls into the fill. The results are reduced crown pressures and increased wall pressures. It is of interest to compare this with the rigid case (Analyses 2 and 3) where the inability of the walls of the culvert to push into the fill results in minor alterations of the wall pressures. However, the hay effectively increases the crown flexibility of the rigid culvert and reduces the pressures in this region. These conclusions lead to a question concerning the effect of the stiffness of the base material directly beneath the culvert. To investigate this two cases were run on the arrangement of Fig. 3(a) with no hay inclusion. This comparison is indicated in Fig. 7 where the base material was

- a) rigid (Line 1)
- b) flexible with $\frac{E_{\text{base}}}{E_{\text{fill}}} = 2$ (Line 2)

The absence of a hay inclusion allows the full effect of the base stiffness to be appreciated. For regions away from the base a minor reduction in all pressures is evident. For regions involving the contact between the base and the foundation the results of analyses 2 would only be of interest; analysis 1, with a rigid base would involve an impractical pressure singularity.

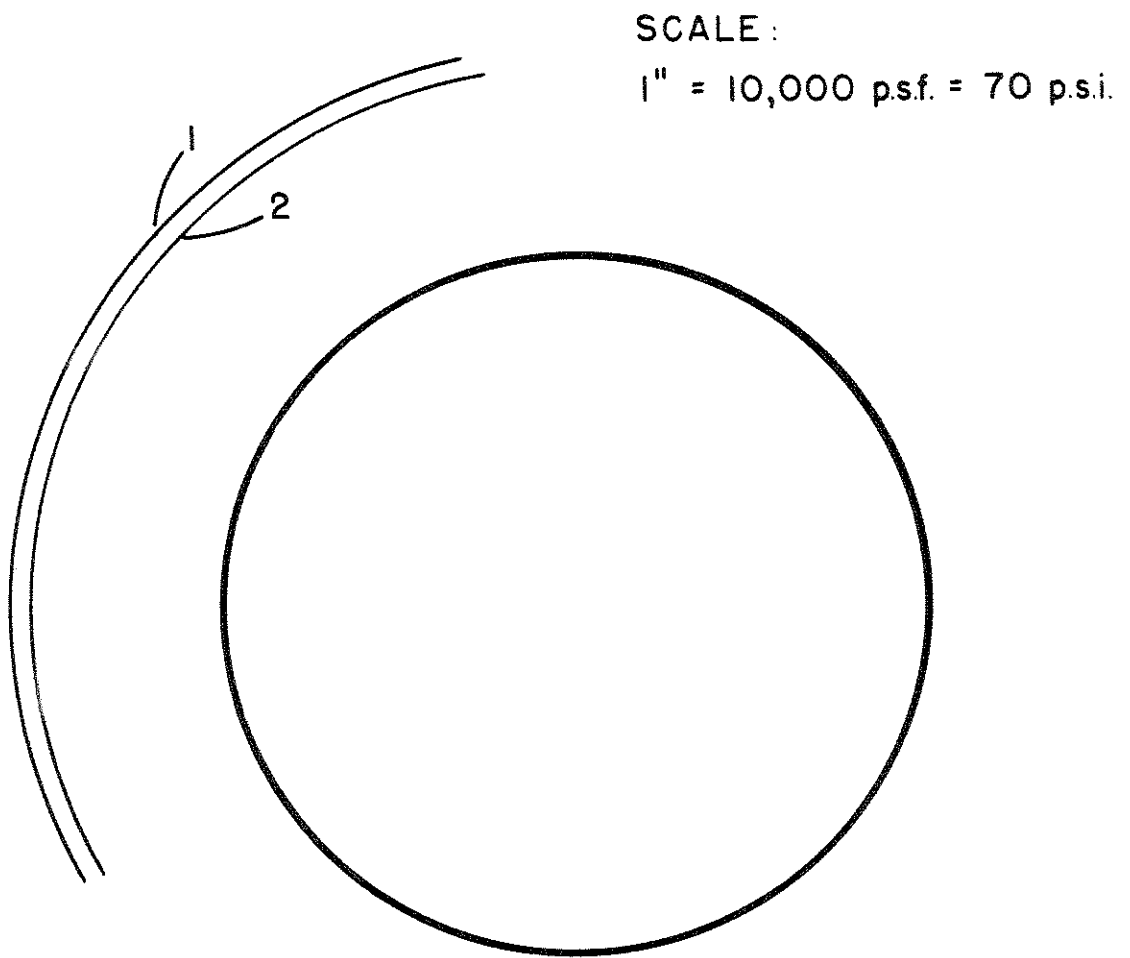


FIG. 7

A final point observed in References 1 and 2 involves the change in pressure distribution as the organic hay material rots away over a period of time. This amounts to the hay having zero stiffness and a dramatic reduction of crown pressures will be evident.

Synthesis of Analytical Results

The previous discussion indicates that the base, culvert and hay inclusion may be considered as a system the vertical flexibility of which is influenced by all the parts and the horizontal flexibility by the culvert alone. The pressures on the crown are reduced with the reduction of vertical stiffness and those on wall increased with reduced horizontal stiffness. This suggests that the effect of isotropic normal pressure may be attained by proper adjustment of the hay and base characteristics.

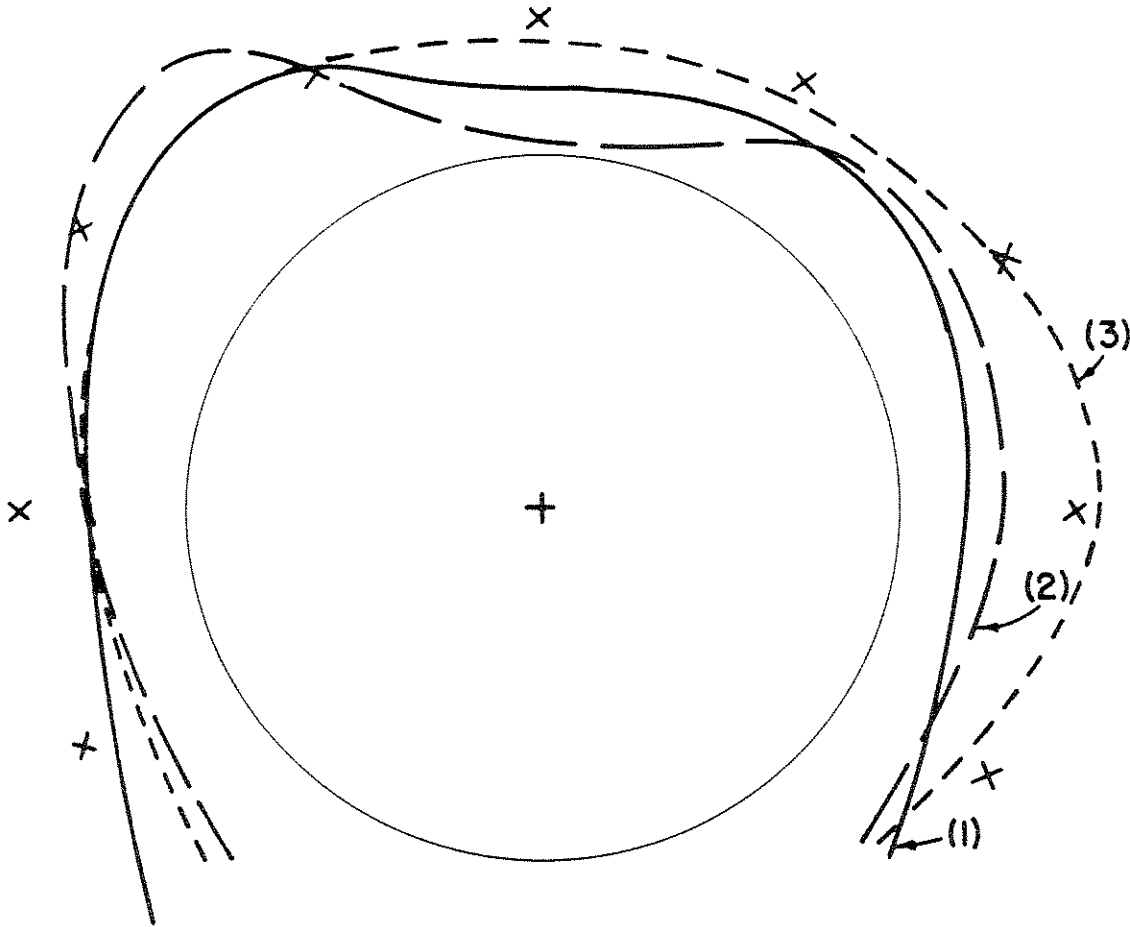
Comparison of Analysis with Field Measurements

Figure 8 shows measured pressures on the culvert at Chadd Creek with a total over-fill of 79'. The conditions above the crown are

Line 1	-1' earth + 5' straw
Line 2	-2' earth + 5' straw
Line 3	-2' earth + 3' straw

Also plotted are the analytical results for a homogeneous over-fill with rigid base. A comparison with the straw inclusion and flexible base analysis may be obtained by the use of Figs. 6 and 7.

From a quantitative viewpoint it is clear that the analytical results are of the correct order of magnitude and portray the distribution of pressure fairly well. However, the most significant feature is that the analytical results are essentially symmetric about the center-line whereas the



SCALE 1" = 10,000 psf
= 70 psi

X - Computed values for
homogeneous embankment
with rigid base.

FIG. 8

pressure meter measurements indicate no such regularity. This would suggest that an initial absence of circularity in the culvert could lead to such results under gravity loading. For the case of an axial point load on the surface it has been shown that the pressure distribution is sensitive to the initial ellipticity of the culvert⁵. As the arguments developed here are based on an influence diagram made up of the integration of such surface effects, then it would not appear unreasonable to expect that the final pressure distribution would be gravely affected by the initial configuration and its subsequent motion. To obtain a complete picture it would be necessary to

- a) know the initial configuration
- b) follow the changing configuration with increase or fill.

From a practical design viewpoint it is apparent that pertinent pressure figures are obtainable from the analyses provided here. It is believed that more refined analyses would not be relevant to this work until the fill properties and behaviors are more reasonably understood.

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5. Scheffey, C. F., Private Communication

Appendix A

Equation (6) may written more fully in the form

$$\begin{array}{rccccc} \delta_3 & & \Delta_{33} & \Delta_{3L} & \Delta_{3\epsilon} & F_3 \\ \delta_4 & = \frac{R}{EI} & \Delta_{L3} & \Delta_{LL} & \Delta_{L\epsilon} & F_4 \\ \delta_6 & & \Delta_{\epsilon 3} & \Delta_{\epsilon L} & \Delta_{\epsilon\epsilon} & F_\epsilon \end{array}$$

Where

$$\begin{aligned} \Delta_{33} &= \Delta_{L4} = \frac{1}{2} \alpha^2 (2\phi - \phi \cos \phi - \sin \phi) \\ \Delta_{3L} &= \Delta_{L3} = \frac{1}{2} \alpha^2 (-\phi \cos \phi + \sin \phi) \\ \Delta_{3\epsilon} &= \Delta_{\epsilon 3} = \Delta_{4\epsilon} = \Delta_{\epsilon 4} = \frac{1}{2} R \alpha (\phi \sin \phi + 2 \cos \phi - 2) \\ \Delta_{\epsilon\epsilon} &= \frac{1}{2} R^2 (2\phi + \phi \cos \phi - 3 \sin \phi) \end{aligned}$$

and

$$\alpha = \left[2R \sin \frac{\phi}{2} \right]^{-1} \quad \text{from Fig. 4.}$$

Equation (8) may be written more fully in the form

$$\begin{array}{rccccccc} \delta_3 & -\alpha \cos \psi & -\alpha \sin \psi & \alpha \cos \psi & \alpha \sin \psi & 0 & 1 & \overline{r_1} \\ \delta_4 & = \alpha \cos \psi & \alpha \sin \psi & -\alpha \cos \psi & -\alpha \sin \psi & -1 & 0 & \overline{r_2} \\ \delta_6 & -\sin \psi & \cos \psi & \sin \psi & -\cos \psi & 0 & 0 & \overline{r_3} \\ & & & & & & & \overline{r_4} \\ & & & & & & & \overline{r_5} \\ & & & & & & & \overline{r_6} \end{array}$$

STEFIC PYPST DECK
 CPYPST LAYER ANALYSIS WITH PIPE AND FACILITY FOR REPLACING MATERIAL
 DESCRIPTION OF DATA FOR PYPST

INPUT

THE ELEMENTS MUST BE NUMBERED CONSECUTIVELY STARTING WITH THE
 IN PLACE ELEMENTS AND CONTINUING ROW BY ROW

1ST CARD	COL.1-72	TITLE	
2ND CARD		PARAMETER ARRAY (1 CARD ONLY)	
	COL.1-4	TOTAL NUMBER OF ELEMENTS	14
	COL.5-8	TOTAL NUMBER OF NODAL POINTS	14
	COL.9-12	NUMBER OF ANALYSES TO PERFORM	14
	COL.13-16	TOTAL NUMBER OF BOUNDARY POINTS	
	COL.17-20	FORCE UNBALANCE PRINT INTERVAL	14
	COL.21-24	OUTPUT INTERVAL OF FULL RESULTS	14
	COL.25-28	CYCLE LIMIT	14
	COL.29-32	FIRST NODAL POINT FOR INITIALIZATION OF DISPLACEMENTS	14
	COL.33-36	ELEMENT NO.-PRINT OF STRESSES FROM NEXT ELEMENT	14
	COL.37-38	DUMMY VARIABLE CONTROLLING OUTPUT. IF DUMMY =0 THEN PRINT INPUT MESH ARRAYS,OTHERWISE NOT	12
	COL.39-40	NUMBER OF ANALYSES FOR WHICH PRINTOUT OF INTERMEDIATE CALCULATIONS DESIRED. (COMMENCING WITH FIRST ANALYSIS).	12
NEXT CARD		ELEMENT ARRAY (1 CARD FOR EACH ELEMENT)	
	COL.1-4	ELEMENT NUMBER	14
	COL.5-8	NUMBER OF NODAL POINT I	14
	COL.9-12	NUMBER OF NODAL POINT J	14
	COL.13-16	NUMBER OF NODAL POINT K	14
	COL.17-28	MODULUS OF ELASTICITY	E12.4
		EACH TRIANGULAR ELEMENT OF PIPE MUST HAVE NODES IN CORPECT ORDER.	
NEXT CARD		NODAL POINT ARRAY (1 CARD FOR EACH NODAL PT.)	
	COL.1-4	NODAL POINT NUMBER	14
	COL.5-12	X-COORDINATE OF POINT	F8.1
	COL.13-20	Y-COORDINATE OF POINT	F8.1
	COL.21-32	X-LOAD AT POINT	F12.2
	COL.33-44	Y-LOAD AT POINT	F12.2
	COL.45-56	INITIAL X-DISPLACEMENT	F12.8
	COL.57-68	INITIAL Y-DISPLACEMENT	F12.8
NEXT CARD		BOUNDARY ARRAY (1 CARD FOR EACH POINT)	
	COL.1-4	NUMBER OF BOUNDARY POINT	14
	COL.5-8	INDICATES RESTRAINT. (0 FOR FIXED IN BOTH DIRECTIONS. 1 FOR FIXED IN X DIRECTION. 2 FOR FIXED IN Y DIRECTION.)	14
	COL.9-16	SLOPE AT BOUNDARY POINT.WITH 2 IN COL.8	F8.3

C	NEXT CARD	PIPE INTERIOR	27
C		COL.1-4 1ST ELEMENT ON INSIDE OF PIPE	14
C		COL.5-8 LAST ELEMENT ON INSIDE OF PIPE	14
C		COL.9-12 1ST NODAL POINT ON INSIDE OF PIPE	14
C		COL.13-16 LAST NODAL POINT ON INSIDE OF PIPE	
C		NUMBER ELEMENTS AND NODAL POINTS CONSECUTIVELY	
C	NEXT CARD	PIPE GEOMETRY	
C		COL.1-10 RADIUS OF PIPE	F10.1
C		COL.11-20 ABSCISSA OF PIPE CENTRE	F10.1
C		COL.21-30 ORDINATE OF PIPE CENTRE	F10.1
C		COL.31-40 NUMBER OF INTERNAL NOSES ON CULVERT	I10
C		COL.41-51 MODULUS OF ELASTICITY OF PIPE	E11.4
C		COL.52-61 THICKNESS OF PIPE WALL	F10.5
C	NEXT CARD	EXTERNAL NODES ON CULVERT LISTED FROM NODE	
C		CORRESPONDING TO 1ST NODAL POINT INSIDE PIPE	
C		(SEE ABOVE) AROUND CIRCUMFERENCE TO LAST	
C		NODAL POINT INSIDE PIPE. THE 1ST POINT MUST BE	
C		IN 1ST TWO QUADRANTS OF CIRCLE, BUT NOT AT PI	
C			2014
C	NEXT CARD	MATERIAL REPLACEMENT CARD (1 CARD ONLY)	
C		COL.1-4 NO. OF ELEMENTS TO TAKE OUT	14
C		COL.5-8 NO. OF NODAL POINTS ALONG THE FREE	
C		EDGES OF THE EXCAVATION	14
C		COL.9-12 ANALYSIS AT WHICH MATERIAL IS TO	
C		BE REPLACED	14
C		COL.13-24 DENSITY OF REPLACEMENT MATERIAL	E12.4
C		COL.25-36 MODULUS OF ELASTICITY OF	
C		REPLACEMENT MATERIAL	E12.4
C		COL.37-48 ASSUMED INITIAL VERTICAL DISPLACEMENT	
C		DUE TO REMOVAL OF MATERIAL	E12.4
C	NEXT CARD	ELEMENTS TO BE REMOVED. THE ELEMENTS ARE LISTED	
C		20 ON EACH CARD WITH A FIXED POINT FORMAT	
C		UNTIL ALL ELEMENTS WHICH ARE TO BE REMOVED	
C		ARE LISTED	2014
C	NEXT CARD	NODAL POINTS ALONG THE FREE EDGES OF THE	
C		EXCAVATION ARE LISTED 20 ON EACH CARD	
C		WITH A FIXED POINT FORMAT UNTIL ALL THE FREE	
C		NODAL POINTS ARE LISTED	2014
C	NEXT CARD	ANALYSIS CONTROL CARD (1 CARD FOR EACH ANALYSIS)	
C		COL.1-4 NUMBER OF ANALYSIS	14
C		COL.5-8 NO. OF LAST ELEMENT IN ANALYSIS	14
C		THE ELEMENTS OF EACH ANALYSIS MUST BE NUMBERED	
C		IN SEQUENCE	
C		COL.9-12 NO. OF NP.S IN EACH ANALYSIS	14
C		THE NP.S NEED NOT BE NUMBERED IN SEQUENCE FOR	
C		EACH INDIVIDUAL ANALYSIS, BUT MUST BE IN	
C		SEQUENCE FOR THE COMPLETE STRUCTURE	
C		COL.13-16 NO. OF BOUNDARY POINTS IN ANALYSIS	14
C		COL.17-24 POISSONS RATIO FOR ADDED LAYERS	F8.3

COL.25-34	DENSITY FOR ADDED LAYERS	E10.4
COL.35-44	INITIAL GUESS OF VERTICAL DISPLACEMENT	E10.4
COL.45-54	TOLERANCE LIMIT	E10.4
COL.55-62	OVER RELAXATION FACTOR	F8.4

NEXT CARD LOAD APPLICATION CARD (12CARD FOR EACH ANAL.)
 UNIFORMLY DISTRIBUTED LOAD IS APPLIED
 BETWEEN THE FIRST AND THE LAST NODAL
 POINT.TWO REGIONS OF DISTRIBUTED LOAD
 ARE POSSIBLE ALONG A ROW OF NODAL POINTS
 AT THE SPECIFIED ELEVATION.IF THE
 CARD IS BLANK,GRAVITY LOAD IS APPLIED
 TO THE STRUCTURE.

COL.1-4	FIRST NP	I4
COL.5-8	LAST NP.	I4
COL.9-12	FIRST NP	I4
COL.13-16	LAST NP.	I4
COL.17-26	ELEVATION	E12.4

END OF DATA CARDS.

OPTIONAL NEW PROBLEMS. REPEAT AS OFTEN AS DESIRED.

NEXT CARD BLANK. FOLLOW BY DATA CARDS FOR COMPLETELY
 NEW PROBLEM, STARTING WITH TITLE CARD.
 DIMENSION AND COMMON STATEMENTS

DIMENSION XORD(262), YORD(262), DSX(262), DSY(262), SIGXXT(472),
 1 MNP(265), XLOAD(262), YLOAD(262), NP(265,6), NPI(472), NPJ(472),
 2 NPK(472), NMEL(20), NMNP(20), NYBC(20), ET(472), XU(20),
 3 RC(20), SLOPE(50), NPH(50), NFIX(50), SXX(1048), SKY(1048),
 4 SYX(1048), SYY(1048), FRX(262), FRY(262), ELEV(20), SIGXX(472),
 5 SIGXY(472), SIGYY(472), LM(3), A(6,6), B(6,6), C(6,6),
 6 SIGYIT(472), SIGYIT(472), NELCUT(50), NPFREE(50), SIG(3)

DIMENSION NRMPNT(20)

COMMON I2,NELP1,N,KIK,IN,NRMPNT,ARMPTS,YORD,YCENTR,XORD,

1 XCENTR,THPIPE,RADIUS,EPIPE,S, NNPF1,NUMNP,NPF1,MNP,DSX,DSY,NPF2
 NDIM = 1048

FORMAT STATEMENTS

1 FORMAT (72H1 BCD INFORMATION
 1)
 2 FORMAT (9I4,2I2)
 3 FORMAT (31H0TOTAL NUMBER OF ELEMENTS =1I4/)
 4 FORMAT (31H TOTAL NUMBER OF NODAL POINTS =1I4/)
 5 FORMAT (31H NO. OF ANALYSES TO PERFORM =1I4/)
 6 FORMAT (31H CYCLE PRINT INTERVAL =1I4/)
 7 FORMAT (31H OUTPUT INTERVAL OF RESULTS =1I4/)
 8 FORMAT (31H CYCLE LIMIT =1I4/)
 9 FORMAT (22H TOLERANCE LIMIT =E10.3)
 10 FORMAT (22H RELAXATION FACTOR =F6.3)
 11 FORMAT (27H1EL. I J K E)
 12 FORMAT (4I4,E12.4)


```

13 FORMAT (80H1      NP      X-ORD      Y-OPD      X-LOAD      Y-LOA
1D      X-DISP      Y-DISP)
14 FORMAT (114,2F8.1,2F12.2,2F12.8)
15 FORMAT (40HONO. OF TERMS IN TOTAL STIFFNESS ARRAYS =16 )
16 FORMAT (43H1RESULTS FOR ELEMENTS IN PLACE-ANALYSIS NO.14/22HONO. O
1F ELEMENTS      =14/22H NO. OF NODAL POINTS =14/22H NO. OF B.C.
2      =14)
17 FORMAT (3I4,3E12.4)
18 FORMAT (4I4,F8.3,3E10.4,F8.4)
19 FORMAT (31H TOTAL NUMBER OF B.C.      =114/)
20 FORMAT (118,4F12.1,2F12.8)
21 FORMAT (2I4,1F8.3)
22 FORMAT (20H0BOUNDARY CONDITIONS)
23 FORMAT (32H0      CYCLE      FORCE UNBALANCE)
24 FORMAT (1I12,1E20.6)
25 FORMAT (42HONODAL POINT X-DISPLACEMENT Y-DISPLACEMENT)
26 FORMAT (1I12,2F15.6)
27 FORMAT(120H1 ELEMENT      X-STRESS      Y-STRESS      XY-STRESS
1      MAX.STRESS      MIN.STRESS      MAX.SHEAR      DIRECTION)
28 FORMAT (1I10,3F15.4,5X,4F15.2)
29 FORMAT (25H1RESULTS FOR ANALYSIS NO. 14/22HONO. OF ELEMENTS      =
114 /22H NO. OF NODAL POINTS =14/ 22H NO. OF B.C.      =14)
30 FORMAT (1H1)
31 FORMAT (37H-MODIFIED VERTICAL LOADS AT ELEVATION F8.2/13H NP.      YL
LOAD )
32 FORMAT (15H-TOTAL STRESSES /56H ELEMENT      X-STRESS      Y-S
1TRESS      XY-STRESS )
33 FORMAT (22H POISSONS RATIO      =F6.3/22H DENSITY      =E10
1.3)
34 FORMAT (22H1ANALYSIS OF THE FIRST 13,8H LAYERS )
35 FORMAT (39H MATERIAL IS REMOVED AND LOADS MODIFIED /20H NP.      XLOA
1D      YLOAD )
36 FORMAT (36H PIT IS FILLED WITH ORGANIC MATERIAL/9H DENSITY=E12.4/
19H E      =E12.4)
37 FORMAT (20I4)
38 FORMAT (18,2F12.4)
39 FORMAT (32H-      NP.      XLOAD      YLOAD      )
41 FORMAT (E12.4)
42 FORMAT(1H0,24HELEMENT REPLACEMENT DATA)
43 FORMAT(1I17,E15.6)
44 FORMAT(4I4)
497 FORMAT(24H NODES ON PIPE. (NRMPNT))
499 FORMAT(59H1 RADIUS      XCENTR      YCENTR      NRMPPTS      EPIPE      THP
1PIPE)
501 FORMAT(20I4)
711 FORMAT (32H0ZERO OR NEGATIVE AREA, EL. NO.=114)
712 FORMAT (36H0MORE THAN 7 POINTS CONNECTED TO NP. 14)
800 FORMAT(3F10.1,1I10,E11.4,F10.5)
801 FORMAT(F4.2)
C
C      READ AND PRINT INPUT DATA
C
1000 PRINT 30
      READ 1
      PRINT 1

```



```

      IF (NAL-1) 125,122,125
122  NNUMEL=1
      PRINT 16,NAL,NUMEL,NUMNP,NUMBC
      GO TO 127
125  NNUMEL=NMEL(NAL-1)+1
      PRINT 29,NAL,NUMEL,NUMNP,NUMBC
127  PRINT 10,XFAC
      PRINT 33,XU(NAL),RO(NAL)
      PRINT 9,TOLER
      IF (NMNP2) 145,145,139

      UNIT LOAD MODIFICATION

139  PRINT 31 ,ELEV(NAL)
143  DO 142 N=NMNP1,NMNP2
      IF (N-NMNP2 ) 140,141,141
140  UNITL=ABS ((XORD(N+1)-XORD(N)) /2.0)
      YLOAD(N)=YLOAD(N)-UNITL
      YLOAD(N+1)=YLOAD(N+1)-UNITL
141  PRINT 14,N,YLOAD(N)
142  CONTINUE
      IF (NMNP3) 145,145,144
144  NMNP1=NMNP3
      NMNP2=NMNP4
      NMNP3=0
      GO TO 143
145  IF (NMNP2) 146,146,129

      DEAD LOAD MODIFICATION

146  NFEL=NNUMEL
      NLEL=NUMEL
      RORG=RO(NAL)
147  DO 161 M=NFEL,NLEL
      IF (NMNP2) 156,157,156
156  N=NELOUT(M)
      GO TO 158
157  N=M
      IF (N-NELP1)158,148,148
148  IF (N-NELP2)161,161,158
158  I=NPI(N)
      J=NPJ(N)
      K=NPK(N)
      AJ=XORD(J)-XORD(I)
      AK=XORD(K)-XORD(I)
      BJ=YORD(J)-YORD(I)
      BK=YORD(K)-YORD(I)
      ARFA=(AJ*BK-AK*BJ)/2.0
159  DL=AREA*RORG /3.0
160  YLOAD(I)=YLOAD(I)-DL
      YLOAD(J)=YLOAD(J)-DL
      YLOAD(K)=YLOAD(K)-DL
161  CONTINUE
      PRINT 39
      PRINT 38,(M,XLOAD(M),YLOAD(M),M=1,NUMNP)

```

```

129 NCYCLE=0
   NUMPT=NCPIN
   NUMOPT=NOPIN
   DO 130 L=1,NDIM
     SXX(L)=0.0
     SXY(L)=0.0
     SYX(L)=0.0
130 SYY(L)=0.0

```

THE TAG ARRAY FOR MAPPING OF TOTAL STIFNESSES IS FORMED

```

162 DO 170 N=1,NUMEL
   LM(1)=NPI(N)
   LM(2)=NPJ(N)
   LM(3)=NPK(N)
   DO 170 II=1,3
     MS=LM(II)
     NP(MS,1)=MS
     DO 170 JJ=1,3
       IF (MS-LM(JJ)) 165,170,170
165 DO 168 LS=2,NCTAG
166 IF (NP(MS,LS)-LM(JJ)) 167,170,167
167 IF (NP(MS,LS)) 163,169,163
163 IF (LS-NCTAG) 168,164,164
164 IFLAG=1
   PRINT 712,MS
168 CONTINUE

```

```

   IF NP IS ZERO,STORE LM(JJ)
169 NP(MS,LS)=LM(JJ)
170 CONTINUE

```

```

   IF(I2)1001,1002,1001
1001 PRINT 350
   PRINT 351,((NP(I,J),J=1,8),I=1,NUMNPT)
   350 FORMAT(13H11ST NP ARRAY//)
   351 FORMAT(8I6)

```

```

1002 IF (IFLAG) 442,153,442

```

CONSECUTIVE NUMBERING OF NODAL POINT LABELLING ARRAY

```

153 L=0
   DO 155 N=1,NUMNPT
     IF (NP(N,1)) 155,155,154
154 L=L+1
     MNP(L)=NP(N,1)
155 CONTINUE
     MNP(NUMNP+1)=MNP(NUMNP)+1

```

```

   IF(I2)1003,1004,1003
1003 PRINT 352
   PRINT 353,(MNP(I),I=1,L),MNP(NUMNP+1)
   352 FORMAT(10H1MNP ARRAY//)

```

```

353 FORMAT(I6)
*****
C
C   COUNTING ADJACENT NODAL POINTS,THE COUNT IS STORED
C   IN THE FIRST COLUMN OF THE TAG ARRAY
C
1004 NP(1,1)=1
      DO 175 M=1,NUMNP
        I=MNP(M)
        IN=MNP(M+1)
        N=1
171  N=N+1
        IF (NP(I,N)) 174,174,172
172  IF (N-NCTAG) 171,173,173
173  NP(IN,1)=N+NP(I,1)
        GO TO 175
174  NP(IN,1)=N+NP(I,1)-1
175  CONTINUE
*****
      IF(I2)1005,1006,1005
1005 PRINT 354
      PRINT 351,((NP(I,J),J=1,8),I=1,NUMNPT)
354 FORMAT(13H12ND NP ARRAY)
*****
C
C   PRINTOUT OF NUMBER OF CONNECTED NODAL POINTS.THIS SHOULD EQUAL THE
C   NUMBER OF TERMS IN EACH OF THE TOTAL STIFFNESS ARRAYS AND NOT
C   EXCEED NDIM.
C
1006 N=MNP(NUMNP)
      NUMTOT=NP(N,1)
      PRINT 15,NUMTOT
      IF (NDIM-NUMTOT) 442,176,176
C
C   FORMATION OF STIFFNESS ARRAY
C
176 M=0
      NNELP1 = NELP1
178 M=M+1
      NLST=NMEL(M)
C INITIALIZATION FOR PIPE STIFFNESS CALCULATION
      NNPP1 = NPP1
      KIK=0
      IN = 0
      PSI=0.0
      IF (M -1) 180,179,180
179 NFST=1
      GO TO 181
180 NFST=NMEL(M-1)+1
181 DO 199 N=NFST,NLST
      N=N
      IF(NELP1-N) 521,522,521
522 CALL PYP
      GO TO 531
521 I=NPI(N)

```

```

J=NPJ(N)
K=NPK(N)
AJ=XORD(J)-XORD(I)
AK=XORD(K)-XORD(I)
BJ=YORD(J)-YORD(I)
BK=YORD(K)-YORD(I)
AREA=(AJ*BK-AK*BJ)/2.0

```

```

C
C*****
IF(12)1007,1008,1007
1007 PRINT 507,N
507 FORMAT( 9H0ELEMENT ,I3,31H   PROCESSED BY OLD PSIT ONLY )
C*****
C PRINT OF ERRORS IN INPUT DATA
1008 IF (AREA) 701,701,700
701 IF (IFLAG) 702,702,199
701 PRINT 711,N
IFLAG=1
GO TO 199
702 COMM=0.25*ET(N)/((1.-XU(M)**2)*AREA)
A(1,1)=BJ-BK
A(1,2)=0.0
A(1,3)=BK
A(1,4)=0.0
A(1,5)=-BJ
A(1,6)=0.0
A(2,1)=0.0
A(2,2)=AK-AJ
A(2,3)=0.0
A(2,4)=-AK
A(2,5)=0.0
A(2,6)=AJ
A(3,1)=AK-AJ
A(3,2)=BJ-BK
A(3,3)=-AK
A(3,4)=BK
A(3,5)=AJ
A(3,6)=-BJ
IF (NFST-NLST) 703,520,703
703 B(1,1)=COMM
B(1,2)=COMM*XU(M)
B(1,3)=0.0
B(2,1)=COMM*XU(M)
B(2,2)=COMM
B(2,3)=0.0
B(3,1)=0.0
B(3,2)=0.0
B(3,3)=COMM*(1.-XU(M))*0.5
C
DO 182 JJ=1,6
DO 182 II=1,3
S(II,JJ)=0.0
DO 182 KK=1,3
182 S(II,JJ)=S(II,JJ)+B( II, KK)*A(KK, JJ)
DO 183 JJ=1,6

```

```

DO 183 II=1,3
183 B(JJ,II)=S(II,JJ)
DO 184 JJ=1,6
DO 184 II=1,6
S(II,JJ)=0.0
DO 184 KK=1,3
184 S(II,JJ)=S(II,JJ)+B(II,KK)*A(KK,JJ)
531 CONTINUE
C*****
IF(I2)1009,1010,1009
1009 PRINT 506, N, ((S(K,J),J=1,6),K=1,6)
506 FORMAT(26H05 MATRIX FOR ELEMENT,I4/(6E12.2))
C*****
C
C SEARCHING FOR AND STORING NONZERO TERMS OF THE
C TOTAL STIFNESS ARRAY
C
1010 LM(1)=NPI(N)
LM(2)=NPJ(N)
LM(3)=NPK(N)
DO 198 II=1,3
KS=LM(II)
DO 198 JJ=1,3
NS=NP(KS,1)
LS=LM(JJ)
IF (KS-LS) 186,195,198
186 DO 188 MS=2,NCTAG
187 NS=NS+1
IF (NP(KS,MS)-LS) 188,195,188
188 CONTINUE
195 SXX(NS)=SXX(NS)+S(2*II-1,2*JJ-1)
SXY(NS)=SXY(NS)+S(2*II-1,2*JJ )
SYX(NS)=SYX(NS)+S(2*II ,2*JJ-1)
SYY(NS)=SYY(NS)+S(2*II ,2*JJ )
IF(NELP1-NELP2) 198,198,532
532 NELP1 = NELP1-1
198 CONTINUE
199 CONTINUE
C*****
IF(I2)1011,1012,1011
1011 PRINT 802
802 FORMAT(44H1 SXX SXY SYX SYY)
PRINT 803,((SXX(K),SXY(K),SYX(K),SYY(K),K=1,NUMTOT)
803 FORMAT(4E12.2)
C*****
1012 IF (M-NAL) 178,200,200
200 CONTINUE
IF (IFLAG) 442,201,442
C
C INITIALIZATION OF DISPLACEMENTS
C
201 DO 205 I=NFROM,NUMNP
N=MNP(I)
IF (NID-1) 204,202,203
202 DSY(N)=DORG

```

```

GO TO 205
203 DSY(N)=-DSY(N)
GO TO 205
204 DSY(N)=DISPL
205 DSX(N)=0.0

```

```

C
C   INVERSION OF NODAL POINT STIFNESSES
C

```

```

DO 210 I=1,NUMNP
M=MNP(I)
N=NP( M,1)
COMM =SXX(N)*SYY(N)-SXY(N)*SYX(N)
IF (COMM) 208,209,208
208 TEM =SYY(N)/COMM
SYY(N)=SXX(N)/COMM
SXX(N)=TEM
SXY(N)=-SXY(N)/COMM
SYX(N)=-SYX(N)/COMM
209 FRX(M)=XLOAD(M)
210 FRY(M)=YLOAD(M)

```

```

C *****
IF (I2)1013,1014,1013
1013 PRINT 802
PRINT 803,(SXX(K),SXY(K),SYX(K),SYY(K),K=1,NUMTOT)

```

```

C *****
C
C   MODIFICATION OF BOUNDARY FLEXIBILITIES
C

```

```

1014 DO 240 L=1,NUMBC
M=NPB(L)
N=IABS (NP(M,1))
NP(M,1)=-NP(M,1)
IF (NFIX(L)-1) 225,220,215
215 C=(SXX(N )*SLOPE(L)-SXY(N ))/(SYX(N )*SLOPE(L)-SYY(N ))
R=1.-C*SLOPE(L)
SXX(N )=(SXX(N )-C*SYX(N ))/R
SXY(N )=(SXY(N )-C*SYY(N ))/R
SYX(N )=SXX(N )*SLOPE(L)
SYY(N )=SXY(N )*SLOPE(L)
DSY(M)=0.0
GO TO 240
220 SYY(N )=SYY(N )-SYX(N )*SXY(N )/SXX(N )
DSX(M)=0.0
GO TO 230
225 SYY(N )=0.0
DSY(M)=0.0
DSX(M)=0.0
230 SXX(N )=0.0
235 SXY(N )=0.0
SYX(N )=0.0
240 CONTINUE

```

```

C *****
IF (I2)1015,1016,1015
1015 PRINT 802
PRINT 803,(SXX(K),SXY(K),SYX(K),SYY(K),K=1,NUMTOT)

```



```
1016 IF(I2 .EQ. 0) GO TO 243
      I2=I2-1
```

```
C *****
```

```
C ITERATION OF NODAL POINT DISPLACEMENTS
```

```
C
243 PRINT 23
245 SUM=0.0
      DO 290 I=1,NUMNP
          N=MNP(I)
          NN=MNP(I+1)
```

```
C NODAL POINT N IS RELAXED
```

```
C NM=IABS ( NP(N,1))
      IF (SXX(NM)+SYY(NM)) 249,290,249
249 NAP=IABS (NP(NN ,1))-IABS (NP(N,1))-1
      IF (NAP) 260,260,250
250 DO 255 LL=1,NAP
          NB=NP(N,LL+1 )
          M =LL+NM
          FRX(N)=FRX(N)-SXX(M)*DSX(NB)- SXY(M)*DSY(NB)
255 FRY(N)=FRY(N)-SYX(M)*DSX(NB)- SYY(M)*DSY(NB)
260 DX=SXX(NM)*FRX(N)-DSX(N)+SXY(NM)*FRY(N)
          DY=SYX(NM)*FRX(N)-DSY(N)+SYY(NM)*FRY(N)
          DSX(N) =DSX(N) +XFAC*DX
          DSY(N) =DSY(N) +XFAC*DY
          IF (NP(N,1)) 265,262,262
262 SUM=SUM+ABS (DX/SXX(NM))+ABS (DY/SYY(NM))
```

```
C NODAL POINTS CONNECTED TO NODAL POINT N ARE RELAXED
```

```
C IF (NAP) 280,280,265
265 DO 275 LL=1,NAP
          NB=NP(N,LL+1)
          M=LL+NM
          FRX(NB)= -SXX(M)*DSX(N )- SYX(M)*DSY(N )+FRX(NB)
275 FRY(NB)= -SXY(M)*DSX(N )- SYY(M)*DSY(N )+FRY(NB)
280 FRX(N)=XLOAD(N)
          FRY(N)=YLOAD(N)
290 CONTINUE
```

```
C CYCLE COUNT AND PRINT CHECK
```

```
C
NCHECK=0
NCYCLE=NCYCLE +1
      IF (NCYCLE-NUMPT)301,300,300
300 NUMPT=NUMPT+NCPIN
      PRINT 24,NCYCLE,SUM
301 IF (SUM-TOLER)305,305,302
302 IF (NCYCM-NCYCLE)305,305,303
303 NCHECK=1
          IF (NCYCLE-NUMOPT)245,304,304
304 NUMOPT=NUMOPT+NOPIN
```

```
C PRINT OF DISPLACEMENTS AND STRESSES
```

```

305 PRINT 25
DO 307 I=1,NUMNP
M=MNP(I)
307 PRINT 26, M, DSX(M),DSY(M)
PRINT 27
DO 421 M=1,NAL
NLST=NMEL(M)
IF (M -1) 311,310,311
310 NFST=1+NBLOCK
GO TO 312
311 NFST=NMEL(M-1)+1
312 DO 421 N=NFST,NLST
IF (N-NNELP1) 407,406,406
406 IF (N-NELP2) 421,421,407
407 I = NPI(N)
J=NPJ(N)
K=NPK(N)
AJ=XORD(J)-XORD(I)
AK=XORD(K)-XORD(I)
BJ=YORD(J)-YORD(I)
BK=YORD(K)-YORD(I)
EPX=(BJ-BK)*DSX(I)+BK*DSX(J)-BJ*DSX(K)
EPY=(AK-AJ)*DSY(I)-AK*DSY(J)+AJ*DSY(K)
GAM=(AK-AJ)*DSX(I)-AK*DSX(J)+AJ*DSX(K)+(BJ-BK)*DSY(I)+BK*DSY(J)-BJ
1*DSY(K)
COMM=ET(N)/((1.-XU(M)**2)*(AJ*BK-AK*BJ))
X=COMM*(EPX+XU(M)*EPY)
Y=COMM*(EPY+XU(M)*EPX)
XY=COMM*GAM*(1.-XU(M))*0.5
IF (NCHECK) 321,317,321
317 IF (NMNP2) 319,328,319
319 IF (NNN-1) 320,328,328
320 IF (NAL-M) 322,322,323
322 CG=(YORD(I)+YORD(J)+YORD(K))/3.0
SIGYY(N)=-1.0
GO TO 324
323 CG=ELEV(NAL-1)
324 TMUL=(ELEV(NAL)-CG)*RO(NAL)/2.0
SIGYYT(N)=SIGYYT(N)+(SIGYY(N)+Y)*TMUL
SIGXXT(N)=SIGXXT(N)+(SIGXX(N)+X)*TMUL
SIGXYT(N)=SIGXYT(N)+(SIGXY(N)+XY)*TMUL
SIGXX(N)=X
SIGYY(N)=Y
SIGXY(N)=XY
GO TO 321
328 SIGXXT(N)=SIGXXT(N)+X
SIGYYT(N)=SIGYYT(N)+Y
SIGXYT(N)=SIGXYT(N)+XY
321 C=(X+Y)/2.0
R=SQRT (((Y-X)/2.0)**2+XY**2)
XMAX=C+R
XMIN=C-R
TMAX=(XMAX-XMIN)/2.0
IF (Y-X) 325,326,325
325 PA=0.5*57.29578*ATAN ( 2.* XY/(Y-X))

```

```
GO TO 327
326 PA=90.0
327 IF (2.*X-XMAX-XMIN) 405,420,420
405 IF (PA) 410,420,415
410 PA=PA+90.0
GO TO 420
415 PA=PA-90.0
420 L=N-NBLOCK
PRINT 28,(L,X,Y,XY,XMAX,XMIN,TMAX,PA)
421 CONTINUE

C
IF (NCHECK) 431,431,243
431 PRINT 32
NFST=NBLOCK+1
DO 433 N=NFST,NUMEL
L=N-NBLOCK
IF (N-NNELP1) 425,429,429
429 IF (N-NNELP2) 433,433,425
425 PRINT 28, L,SIGXXT(N),SIGYYT(N),SIGXYT(N)
433 CONTINUE
NELP1 = NNELP1
NPP1 = NNPP1

C
LOADS SET TO ZERO

C
DO 435 I=1,NUMNP
M=MNP(I)
XLOAD(M)=0.0
YLOAD(M)=0.0
FRX(M)=0.0
FRY(M)=0.0
435 CONTINUE
N=MNP(NUMNP+1)
NP(N,1)=0
IF (NAL -NTO) 440,500,440

C
MODIFICATION OF LOAD DUE TO REMOVAL OF MATERIAL

C
500 NN=0
IF (NNN-1) 505,580,502
502 NNN=0
NID=0
DO 503 I=1,NFROM
DSY(I)=0.0
503 DSX(I)=0.0
GO TO 440
505 PRINT 34, NAL
PRINT 35
510 NN=NN+1
LL=NELOUT(NN)
ET(LL)=0.0
NFST=LL
NLST=LL
M=NTO
GO TO 181
```

```
520 DL=AREA*RO(NT0)/3.0
    SIG(1)=SIGXXT(LL)
    SIG(2)=SIGYYT(LL)
    SIG(3)=SIGXYT(LL)
    LM(1)=NPI(LL)
    LM(2)=NPJ(LL)
    LM(3)=NPK(LL)
    DO 530 JJ=1,3
    M=LM(JJ)
    FRY(M)=FRY(M)+DL
    DO 530 II=1,3
    FRX(M)=A(II,2*JJ-1)*SIG(II)/2.0+FRX(M)
    FRY(M)=A(II,2*JJ)*SIG(II)/2.0+FRY(M)
530 CONTINUE
    IF (NN-NOUT) 510,540,540
540 DO 570 M=1,NFREE
    N=NPFREE(M)
    XLOAD(N)=FRX(N)
    YLOAD(N)=FRY(N)
570 PRINT 14, N,XLOAD(N),YLOAD(N)
    NNN=1
    NID=1
    GO TO 129
```

C
C
C

REPLACING MATERIAL

```
580 DO 590 N=1,NOUT
    L=NELOUT(N)
590 ET(L)=ETORG
    RORG=ROR
    PRINT 34,NAL
    PRINT 36,RORG,ETORG
    NID=2
    NNN=NNN+1
    NFEL=1
    NLEL=NOUT
    GO TO 147
C
440 IF(NANAL-NAL) 444,444,120
444 READ 801, NEXT
    IF(NEXT .EQ. 0) GO TO 1000
442 STOP
    END
```

```

$IBFTC PYPO    DECK
SUBROUTINE PYP
DIMENSION NRMPNT(20), YORD(262), XORD(262), ELFLEX(3,3), ELRIG(3,3
1), ELA(3,6), ELATRN(6,3), ATK(6,3), BARDK(6,6), S(6,6), MNP(265),
2 DSX(262), DSY(262)
COMMON      12,NLLP1,N,KIK,IN,NRMPNT,NRMPTS,YORD,YCENTR,XORD,
1 XCENTR,THPIPE,RADIUS,EPIPE,S, NNPP1,NUMNP,NPPI,MNP,DSX,DSY,NPPZ
EQUIVALENCE (ELRIG,ELFLEX)
522 IF(KIK)523,527,523
527 IN = IN+1
C
C   FOR EACH ELEMENT OF PIPE
C
C
C   CALCULATE ANGLE PHI SUBTENDING EACH ELEMENT OF PIPE
C
C *****
C   IF(I2)2001,2002,2001
2001 PRINT 492,IN
492 FORMAT(14H1PIPE ELEMENT I2)
C *****
2002 NRI = NRMPNT(IN)
IF(IN-NRMPTS) 618,617,618
618 NRI1 = NRMPNT(IN+1)
GO TO 615
617 NRI1 = NRMPNT(1)
615 YI1 = YORD(NRI) - YCENTR
XI1 = XORD(NRI) - XCENTR
FI1 = ATAN2 (YI1,XI1)
619 YI2=YORD(NRI1)-YCENTR
XI2 = XORD(NRI1) - XCENTR
FI2 = ATAN2 (YI2, XI2)
616 PHI=FI2-FI1
IF (PHI) 620,621,621
620 IF(FI1)623,622,623
622 PHI=PHI+3.14159265
GO TO 621
623 IF(FI2)624,622,624
624 PHI=PHI+6.2831853
621 PHION2=PHI/2.0
PHIBY2 = 2.0*PHI
C *****
C   IF(I2)2003,2004,2003
2003 PRINT 1006,FI1
1006 FORMAT( 8HFI      ,F10.4)
PRINT 1006,FI2
ANPHI=PHI*180.0/3.142
PRINT 1496,ANPHI
1496 FORMAT( 6H0ANPHI/F10.5)
C *****
C
C   CALCULATE INCLINATION OF EACH PIPE ELEMENT
C
2004 IF(IN-1) 650,651,650
651 PSI = FI1

```

```

650 PSI = PSI+PHION2
C *****
  IF(I2)2005,2006,2005
2005 ANPSI=PSI*180.0/3.142
  PRINT 1495,ANPSI
1495 FORMAT( 6H0ANPSI/F10.5)
C *****
C
C CALCULATE MOMENT OF INERTIA OF PIPE, = PIPEI
C
C
2006 PIPEI =(THPIPE**3.0)/12.0
C
C COMPUTE PIPE ELEMENT FLEXIBILITY MATRIX ELFLEX
C
  ALFA = 1.0/(2.0*SIN (PHION2))
  ELFLEX(1,1)=PHI-PHI*COS (PHI)/2.0-SIN (PHION2)
  ELFLEX(1,1) = ELFLEX(1,1)*ALFA*ALFA
  ELFLEX(1,2)=-PHI*COS (PHI)/2.0+SIN (PHI)/2.0
  ELFLEX(1,2) = ELFLEX(1,2)*ALFA*ALFA
  ELFLEX(1,3)=SIN (PHI)*PHI/2.0-1.0+COS (PHI)
  ELFLEX(1,3) = ELFLEX(1,3)*RADIUS*ALFA
  ELFLEX(2,1) = ELFLEX(1,2)
  ELFLEX(2,2) = ELFLEX(1,1)
  ELFLEX(2,3) = ELFLEX(1,3)
  ELFLEX(3,1) = ELFLEX(1,3)
  ELFLEX(3,2) = ELFLEX(2,3)
  ELFLEX(3,3)=PHI+PHION2*COS (PHI)-1.5*SIN (PHI)
  ELFLEX(3,3) = ELFLEX(3,3)*RADIUS*RADIUS
  DO 604 J=1,3
  DO 604 K=1,3
604 FLFLEX(J,K) = ELFLEX(J,K)*RADIUS/(EPIPE*PIPEI)
C *****
  IF(I2)2007,2008,2007
2007 PRINT 1494,((ELFLEX(J,K),K=1,3), J=1,3)
1494 FORMAT( 7H0ELFLEX/(3E12.2))
C *****
C
C INVERT ELFLEX TO GET PIPE ELEMENT STIFFNESS, = ELPIG
2008 CALL SYMINV(ELFLEX,3)
C *****
  IF(I2)2009,2010,2009
2009 PRINT 1491,((ELRIG(J,K),K=1,3),J=1,3)
1491 FORMAT(6H0ELRIG/(3E12.2))
C *****
C
C CONSTRUCT DISPLACEMENT TRANSFORMATION MATRIX TO FIXED AXES, = ELA
C
2010 ELA(1,1) = COS (PSI)/(2.0*RADIUS*SIN (PHION2))
  ELA(2,1) = -ELA(1,1)
  ELA(3,1) = -SIN (PSI)
  ELA(1,2) = SIN (PSI)/(2.0*RADIUS*SIN (PHION2))
  ELA(2,2) = -ELA(1,2)
  ELA(3,2) = COS (PSI)
  ELA(1,3) = -ELA(1,1)

```

```

      ELA(2,3) = -ELA(2,1)
      ELA(3,3) = -ELA(3,1)
      ELA(1,4) = -ELA(1,2)
      ELA(2,4) = -ELA(2,2)
      ELA(3,4) = -ELA(3,2)
      FLA(1,5) = 0.0
      ELA(2,5) = -1.0
      FLA(3,5) = 0.0
      ELA(1,6) = 1.0
      ELA(2,6) = 0.0
      ELA(3,6) = 0.0
C *****
      IF(I2)2011,2012,2011
2011 PRINT 1007, ((ELA(J,K),K=1,6),J=1,3)
1007 FORMAT( 4H0ELA/(6E12.2))
C *****
C
C   CONSTRUCT TRANSPOSE OF ELA, =ELATRN
C
2012 DO 603 J=1,3
      DO 603 K=1,6
      603 ELATRN(K,J) = ELA(J,K)
C *****
      IF(I2)2013,2014,2013
2013 PRINT 493, ((ELATRN(K,J),J=1,3),K=1,6)
      493 FORMAT( 7H0ELATRN/(3E12.2))
C *****
C
C   CONSTRUCT PIPE ELEMENT STIFFNESS IN FIXED COORDINATES, = BARDK
C
2014 DO 710 I=1,6
      DO 710 J=1,3
      ATK(I,J)=0.0
      DO 710 KK=1,3
      710 ATK(I,J) = ATK(I,J) + ELATRN(I,KK)*ELRIG(KK,J)
      DO 709 I=1,6
      DO 709 J=1,6
      BARDK(I,J) = 0.0
      DO 709 KK=1,3
      709 BARDK(I,J) = BARDK(I,J)+ATK(I,KK)*ELA(KK,J)
      PSI=PSI+PHION2
C *****
      IF(I2)2015, 523,2015
2015 PRINT 1008, ((ATK(K,J),J=1,3),K=1,6)
1008 FORMAT( 4H0ATK/(3E12.2))
      PRINT 503, ((BARDK(K,J),J=1,6),K=1,6)
      503 FORMAT(31H0BARDK MATRIX FOR PIPE ELEMENT ,/(6E12.2))
C *****
C   STORING CURVED BAR STIFFNESS IN ELEMENT FORM P, Q, R
523 DO 533 JJ=1,6
      DO 533 II=1,6
      533 S(II,JJ)=0.0
      IF(KIK-1)524,525,526
524 S(1,1)=BARDK(5,5)-1.0
      S(1,3)=BARDK(5,1)

```

```
S(1,4)=BARDK(5,2)
S(1,5)=BARDK(5,3)
S(1,6)=BARDK(5,4)
S(2,2)=1.0
S(3,1)=BARDK(1,5)
S(3,3)=BARDK(1,1)-1.0
S(3,4)=BARDK(1,2)
S(3,5)=BARDK(1,3)
S(3,6)=BARDK(1,4)
S(4,1)=BARDK(2,5)
S(4,3)=BARDK(2,1)
S(4,4)=BARDK(2,2)-1.0
S(4,5)=BARDK(2,3)
S(4,6)=BARDK(2,4)
S(5,1)=BARDK(3,5)
S(5,3)=BARDK(3,1)
S(5,4)=BARDK(3,2)
S(5,5)=BARDK(3,3)-2.0
S(5,6)=BARDK(3,4)
S(6,1)=BARDK(4,5)
S(6,3)=BARDK(4,1)
S(6,4)=BARDK(4,2)
S(6,5)=BARDK(4,3)
S(6,6)=BARDK(4,4)-2.0
KIK=1
NELP1=NELP1+1
GO TO 531
525 DO 537 II=1,6
537 S(II,II)=1.0
S(1,5)=BARDK(1,6)
S(2,5)=BARDK(2,6)
S(3,5)=BARDK(3,6)
S(4,5)=BARDK(4,6)
S(5,5)=BARDK(6,6)-1.0
S(5,4)=BARDK(6,4)
S(5,3)=BARDK(6,3)
S(5,2)=BARDK(6,2)
S(5,1)=BARDK(6,1)
KIK=2
NELP1=NELP1+1
GO TO 531
526 DO 538 II=1,6
538 S(II,II)=1.0
S(1,5)=BARDK(5,6)
S(5,1)=BARDK(6,5)
KIK=0
NELP1=NELP1+1
531 CONTINUE
RETURN
END
```