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Uncertainty in Modeling Natural Phenomena

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Introduction: Model Uncertainty affects our Experimental Design and Decision

Process of Modeling and Designing Experiments

- A model is a representation of a system Independence assumptions between the variables, the functional form of relationships between the variables, utility functions, constraints, etc.
- Experimental Design and Decision making are based on the model assumed

An Incorrect Model affects Decisions and Designs

- Many sensor network applications deal with the detection of events.
- Each deployment is done in a new environment, and thus a precise model of the events is unknown.
- · Sensor network design should be robust to model errors.

Detection under incorrect models

· Each event of interest can be represented by a hypothesis

Sensor networks require low-complexity algorithms

Presence of an object in the field, location of a target (humans, cars), etc.

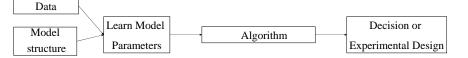
· The model-based detection problem is a hypothesis testing problem.

• The nature of the problem makes the modeling process inaccurate

The hypotheses models assumed may be different from the true models of the

Analysis of the probability of error in the system when the incorrect

models are used will inform us on the robustness of our detection.



Problem Description: Sensitivity Analysis and Robustness to Model errors

Uncertainty in Experimental Design

- Experimental design problems can be written as optimization problems.
- Sensitivity analysis is an important area of optimization which allows us to know how perturbations in the model assumed will affect the outcome.
- If a model parameter is very sensitive, then the result of the optimization changes drastically when the parameter is slightly perturbed.
- This would require our learning process to be extremely accurate, which is not very often the case.

Proposed Solution:

Sensitivity Analysis for Experimental Design

• The standard form of an optimization problem:

min
$$f_0(x)$$

subject to $f_i(x) \le 0$ $i = 1,..., n$
 $h_i(x) = 0$ $i = 1,..., n$

• Perturbations can be introduced in the utility function or in the constraints to analyze the behavior of the solution

Example: For the perturbed constraints problem i.e.

 $f_i(x) \le u_i$ $h_i(x) = v_i$

The optimal value can be lower bounded: $p^*(u,v) - p^*(0,0) \ge -\lambda^{*T}u - v^{*T}v$

• A simple Experimental Design: Sensor Palcement

 $y_1,...,y_m$ are measurements, $x_1,...,x_m$ are locations (experiments), and

 $v_1, ..., v_n$ are all possible locations (candidates) (n > m)

The measurements and the locations are related by the following linear model :

$$y_i = w^T x_i + \varepsilon_i$$
 where $\varepsilon_i \sim N(0, \sigma^2)$ $i = 1,...,$

w can be estimated by solving a LS problem : $\hat{w} = \arg\min_{w} \{J(w) = \sum_{i=1}^{m} (w^T x_i - y_i)^2 \}$

The error $e = w - \hat{w}$, $e \sim N(0, \sigma^2 C_w)$ where $C_w = (\sum_{i=1}^m x_i x_i^T)^{-1}$

We can see that C_w (and the error covariance) depends on the choice of x_i An optimization problem can now be formulated to minimize the error covariance (in some sense)

Example : A - optimal design (relaxed)

$$\min_{l_1,\ldots,l_n} \quad Tr\left[\left(\sum_{j=1}^n l_j v_j v_j^T\right)^{-1}\right]$$

subject to
$$l \ge 0, 1^T l = 1$$

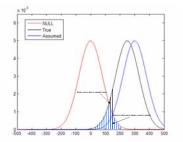
• A sensitivity analysis of the experiment design helps in evaluating the confidence in the design of the networks.

Robustness of Detection

- Hypothesis testing is a classical problem in Detection theory
- Performance is measured by probability of error given the assumed model.
- Model errors affect the detection performance When the hypotheses assumed do not include the correct model of the source, the classical error probability does not reflect the true performance.
- Results about the reliability of detections exist for simple hypothesis testing problems under incorrect models.

• A simple illustration:

events of interest.



- Results about the robustness of detection algorithms in sensor networks help in the design of the networks.
- Robustness of the algorithm used determines the fidelity required in modeling the events of interest When the algorithm is robust to model errors, a lower fidelity is acceptable
- The fidelity required in the modeling process affects the number of sensors and the measurement frequency needed