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Non-uniformly under-sampled multi-dimensional spectroscopic imaging *in vivo*: maximum entropy versus compressed sensing reconstruction

Brian Burns^{a,b}, Neil E. Wilson^{a,c}, Jon K. Furuyama^{a,c} and M. Albert Thomas^{a,b,c,*}

The four-dimensional (4D) echo-planar correlated spectroscopic imaging (EP-COSI) sequence allows for the simultaneous acquisition of two spatial (k_y , k_x) and two spectral (t_2 , t_1) dimensions *in vivo* in a single recording. However, its scan time is directly proportional to the number of increments in the k_y and t_1 dimensions, and a single scan can take 20–40 min using typical parameters, which is too long to be used for a routine clinical protocol. The present work describes efforts to accelerate EP-COSI data acquisition by application of non-uniform under-sampling (NUS) to the k_y – t_1 plane of simulated and *in vivo* EP-COSI datasets then reconstructing missing samples using maximum entropy (MaxEnt) and compressed sensing (CS). Both reconstruction problems were solved using the Cambridge algorithm, which offers many workflow improvements over other l_1 -norm solvers. Reconstructions of retrospectively under-sampled simulated data demonstrate that the MaxEnt and CS reconstructions successfully restore data fidelity at signal-to-noise ratios (SNRs) from 4 to 20 and 5× to 1.25× NUS. Retrospectively and prospectively 4× under-sampled 4D EP-COSI *in vivo* datasets show that both reconstruction methods successfully remove NUS artifacts; however, MaxEnt provides reconstructions equal to or better than CS. Our results show that NUS combined with iterative reconstruction can reduce 4D EP-COSI scan times by 75% to a clinically viable 5 min *in vivo*, with MaxEnt being the preferred method. Copyright © 2013 John Wiley & Sons, Ltd.

Keywords: EP-COSI; maximum entropy; compressed sensing; non-uniform under-sampling; spectroscopy; spectroscopic imaging

INTRODUCTION

Changes in metabolite concentrations as a result of the altered metabolism of cancer can be detected non-invasively using one-dimensional (1D) MRS *in vivo* (1–3). However, the overlap of spectral peaks in 1D MRS is a major impediment to the identification of individual metabolites. Two-dimensional (2D) MRS has increased spectral dispersion over 1D MRS and can disentangle overlapping complex spectral peaks (4). Single-voxel 2D MRS has been shown to increase the specificity and sensitivity of tumor grade classification when used with dynamic contrast-enhanced MRI in the breast (5). However, the acquisition of multiple t_1 increments per voxel to form the second spectral dimension limits its ability to provide multi-voxel coverage because of the long scan times needed to combine two spectral and two spatial dimensions.

With the advent of echo-planar spectroscopic imaging (EPSI), MRSI scans with one spectral and two spatial dimensions can be completed within clinically acceptable times by interleaving the acquisition of a spatial and spectral dimension within the EPSI readout (6–8). The four-dimensional (4D) echo-planar correlated spectroscopic imaging (EP-COSI) (9) sequence allows the acquisition of two spatial (k_y , k_x) and two spectral (t_2 , t_1) dimensions in a single recording to form 4D MRSI. The sequence interleaves the acquisition of the k_x and t_2 dimensions within the EPSI readout, but k_y and t_1 are incrementally acquired as indirect dimensions during each TR. The EP-COSI sequence has the benefits of increased spectral dispersion and multi-voxel support, which improves metabolite identification over multiple spatial

regions simultaneously; however, its scan time is directly proportional to the number of increments in the k_y and t_1 dimensions. An EP-COSI scan using typical parameters of TR/TE = 1.5 s/30 ms and $k_y/t_1 = 16/100$ can take 40 min, which is too long to be used within a routine clinical protocol.

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Abbreviations used: 1D/2D/3D/4D, one-/two-/three-/four-dimensional; Asp, aspartate; COSY, correlated spectroscopy; Cr, creatine; CS, compressed sensing; EP-COSI, echo-planar correlated spectroscopic imaging; EP-JRESI, echo-planar J-resolved spectroscopic imaging; EPSI, echo-planar spectroscopic imaging; FFT, fast Fourier transform; FMETD, methyl fat; FWHM, full width at half-maximum; Glx, glutamate and glutamine; MaxEnt, maximum entropy; NUS, non-uniform under-sampling/under-sampled; PSF, point spread function; RMSE, root-mean-square error; SNR, signal-to-noise ratio; tCho, total choline (choline + glycerophosphocholine + phosphocholine); TGFR, triglyceryl fat; UFD, olefinic fat; UFL, unsaturated fatty acid left; UFR, unsaturated fatty acid right.

When the Fast Fourier Transform (FFT) is used to transform uniformly sampled 4D MRSI data (k_y, k_x, t_2, t_1) to the spatial, spectral domain (Y, X, F_2, F_1) , decreasing scan times require a reduction in either the k_y spatial or t_1 spectral dimension through truncation or lower sampling rates, and a corresponding unwanted reduction in resolution or bandwidth. However, non-uniform under-sampling (NUS) of the spatial, spectral k_y - t_1 plane, in combination with iterative non-linear reconstruction, can be used to accelerate the collection of 4D MRSI data *in vivo*, whilst preserving the spatial and spectral resolutions and bandwidths (10).

Earlier work has demonstrated the feasibility of under-sampling the mixed-domain k_y - t_1 plane of a 4D echo-planar J -resolved spectroscopic imaging (EP-JRESI) dataset and reconstructing the missing points with compressed sensing (CS) (10), a popular method of non-linear iterative image reconstruction which promotes data sparsity in the reconstruction domain and data fidelity in the sample domain (11,12). The nature of spatial, spectral NUS artifacts in the k_y - t_1 plane was explored, and it was shown that l_1 -norm-based CS reconstruction is a viable means of reducing the scan times of 4D EP-JRESI *in vivo* through NUS. In recent years, CS reconstruction has been successfully applied to NUS MRI (13,14), three-dimensional (3D) MRSI (15), dynamic MRI (16,17), and multi-dimensional Nuclear Magnetic Resonance (NMR) (23).

Maximum entropy (MaxEnt) image reconstruction is an alternative non-linear iterative reconstruction technique to CS. Rather than minimizing transform sparsity, it maximizes the entropy of the data in the reconstruction domain, whilst preserving data fidelity in the sample domain (18,19). MaxEnt has been successfully used to reconstruct under-sampled images in astronomy and multi-dimensional spectra in NMR (19–21). However, MaxEnt has not been applied to the mixed-domain k_y - t_1 plane of a 4D MRSI dataset *in vivo*.

The use of entropy as a regularizer in image reconstruction predates l_1 -norm-based CS reconstruction and continues to be used extensively in the reconstruction of under-sampled NMR spectra in spite of the popularity of CS in other fields. It was first suggested by Frieden (18) in the early 1970s after Jaynes (22) proposed the idea of the Principle of Maximum Entropy, which describes the MaxEnt distribution as the ‘maximally non-committal distribution with regard to unavailable data’. This principle presents the MaxEnt prior as one that assumes nothing about the unavailable data; by assuming nothing about those points, their possible values are all equally likely to occur, and the reconstruction is that which most closely conforms to the uniform distribution, i.e. is flat. Peaks in the reconstruction domain are the result of signals from the sampled data, and any artifacts from the missing data points are removed because they represent states of low entropy that are not the result of k -space or time-domain signals.

In this article, we compare the MaxEnt and l_1 -norm-based CS reconstructions of NUS 4D EP-COSI data and show that MaxEnt is a viable alternative to CS for reducing scan times 4× in human breast *in vivo*. We quantitatively characterize the MaxEnt and CS reconstructions by comparing results for retrospectively NUS-simulated 4D EP-COSI data at varying levels of signal-to-noise ratio (SNR) and NUS rates. We show that retrospectively 4× NUS 4D EP-COSI *in vivo* breast data reconstructed using either MaxEnt or CS show a comparable spatial, spectral resolution to the fully sampled data. In addition, we show that MaxEnt and CS reconstructions of prospective 4× NUS 4D EP-COSI scans from the same breast study as the retrospective data, using the same mask and sequence parameters, compare favorably with the retrospective and fully sampled data.

Throughout this article, the NUS dataset that has not been reconstructed and has zeros in place of missing samples is referred to as the zero-augmented dataset to distinguish it from the MaxEnt and CS reconstructions.

EXPERIMENTAL DETAILS

4D MaxEnt and CS reconstruction: theory

MaxEnt and l_1 -norm-based CS were used to reconstruct the NUS k_y - t_1 plane of the 4D EP-COSI datasets.

l_1 -norm-based CS image reconstruction of 4D MRSI data is formulated as a constrained convex optimization problem (10–12):

$$\text{minimize } \|\psi m\|_1 \quad \text{s.t. } \|K\mathcal{F}m - d\|_2^2 \leq C_0 \quad [1]$$

where $m = (y, x, F_2, F_1)$ is the reconstructed spatial, spectral-domain data, \mathcal{F} is the 4D Fourier operator, K is the NUS mask that determines which samples were acquired in the k_y - t_1 plane, $d = (k_y, k_x, t_2, t_1)$ is the k -space, time-domain sampled data, C_0 is the standard deviation of the noise in d and ψ is a known sparse transform. ψ was chosen to be the identity transform because m was already self sparse as shown in ref. (10).

MaxEnt image reconstruction of 4D MRSI data solves a similar problem to CS, but uses $S_{1/2}$ entropy instead of the l_1 -norm (19–21):

$$\text{maximize } S(m)_{1/2} \quad \text{s.t. } \|K\mathcal{F}m - d\|_2^2 \leq C_0 \quad [2]$$

where $S(m)_{1/2}$ is the entropy of the estimated spectrum, and the remaining terms are identical to those in the CS problem. $S_{1/2}$ entropy is a concave function with a global maximum and no local extrema, and so there is a single solution that satisfies the problem within the feasible set of solutions defined by the data fidelity constraint as shown in Fig. 1 (24). As can be seen, $S_{1/2}$ entropy has a global extremum and has slightly more curvature than the l_1 -norm, but has far less curvature than the l_2 -norm.

The entropy used in the MaxEnt reconstruction was not the often used $-\sum p \log(p)$ entropy introduced by Shannon (25), but the $S_{1/2}$ entropy derived by Daniell and Hore (20) specifically

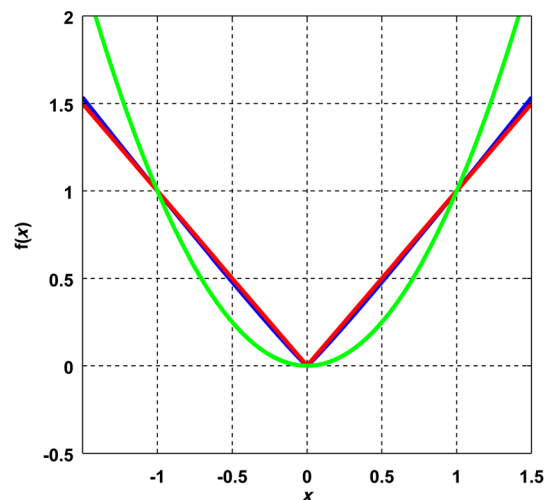


Figure 1. Plot showing $-S_{1/2}$ entropy (blue), l_1 -norm (red) and l_2 -norm (green). Each function has been normalized to equal unity at $|x| = 1$.

for NMR spectra originating from spin $1/2$ nuclei, such as ^1H , used in MRSI:

$$S(m)_{1/2} = -\sum_{i=1}^{i=N} \frac{|m_i|}{def} \log \left(\frac{|m_i|/def + \sqrt{4 + (|m_i|/def)^2}}{2} \right) - \sqrt{4 + \left(\frac{|m_i|}{def}\right)^2} \quad [3]$$

where *def* is a scaling parameter related to the sensitivity of the scanner and is calculated for *m* of length *N* as $\sqrt{C_0/N}$ (21). $S_{1/2}$ is used because the underlying physical processes that produce an MR spectrum are not based on discrete particle events and so cannot be modeled by simple Poisson-distributed processes as required for the derivation of Shannon entropy (26). They are governed by the density matrix of the spin system under investigation, and so the statistical distribution is different. Equation [3] was derived from first principles using both a classical spin model and a quantum mechanical model. Neither model made any assumptions on the initial state of the spin system nor the pulse sequence used. This equation can be applied to any MR spectrum originating from spin $1/2$ nuclei, and addresses previous concerns regarding the use of entropy in MRS and MRI reconstruction (27).

In order to remove any differences between the MaxEnt and CS reconstructions caused by differences in the solvers used, both problems were solved by a Matlab implementation of the Cambridge algorithm (19). This recasts the image reconstruction problem into an unconstrained convex optimization problem and uses a variant of the conjugate gradient method to iteratively find the extrema in two phases; the first phase minimizes the fidelity constraint and the second phase minimizes or maximizes the objective function, while keeping the fidelity constraint minimized. The stopping criterion for the problem is reached when the gradients of the objective $O(m)$ and the fidelity constraint $C(m)$ are parallel: $\left| \frac{\nabla O}{\|O\|_2} - \frac{\nabla C}{\|C\|_2} \right| < 0.001$. Specific details on the algorithm and modifications to accommodate multi-dimensional MR data can be found in ref. (21).

The Cambridge algorithm calculates the gradient $\nabla \|m\|_1 \in \mathbb{C}^N$ and Hessian $\nabla^2 \|m\|_1 \in \mathbb{C}^{2N \times 2N}$ of the objective function, which are not defined for $\|m\|_1$ when $m_i=0$. Therefore, in order to solve the l_1 -norm-based CS reconstruction problem, $\|m\|_1$ was redefined as:

$$\|m\|_1 = \sum_{i=1}^{i=N} \sqrt{\mathcal{R}(m_i)^2 + \mathfrak{I}(m_i)^2 + \epsilon} \quad [4]$$

where \mathcal{R} and \mathfrak{I} were the real and imaginary components of m_i , and ϵ is a small non-zero value to prevent $m_i=0$. The gradient and Hessian were then defined as:

$$\nabla \|m\|_1 = W^{-1} m \quad [5]$$

$$\nabla^2 \|m\|_1 = \begin{bmatrix} |m_i|^{-1}(1 - \mathcal{R}(m_i))|m_i|^{-2} & -\mathfrak{I}(m_i)\mathcal{R}(m_i)|m_i|^{-3} \\ -\mathfrak{I}(m_i)\mathcal{R}(m_i)|m_i|^{-3} & |m_i|^{-1}(1 - \mathfrak{I}(m_i))|m_i|^{-2} \end{bmatrix} \quad [6]$$

= 2×2 block diagonal matrix

where $W \in \mathbb{C}^{N \times N}$ is a diagonal matrix with $w_{ii} = |m_i|$, and element m_i is associated with the i^{th} 2×2 block in the Hessian. The gradient and Hessian of $S(m_i)_{1/2}$ are defined in ref. (21). Only the 2×2

diagonal blocks of the $\|m\|_1$ and $S(m_i)_{1/2}$ Hessians were stored in memory during reconstruction, not the full matrices.

Sample mask generation

The k_y - t_1 plane of the 4D EP-COSY datasets used in these experiments was under-sampled using 2D Poisson-gap sample masks that were generated using a modified 1D Poisson-gap process (28). In 1D Poisson-gap sample masks, the gaps between samples follow a Poisson distribution, whereas the 2D extension follows the convention that gaps between spaces follow a Poisson distribution. However, both conventions result in the spaces and sample points following Poisson distributions. Poisson-distributed masks avoid large gaps between samples, which are detrimental to the reconstruction, while ensuring that the samples are randomly distributed (29). Compared with other distributions, Poisson-distributed masks create the fewest aliasing artifacts in the Fourier domain and preserve the SNR of the under-sampled data (30).

The effects of the sample mask on the peak amplitude and lineshape of spectral reconstructions are well documented (29,31,32). Sample mask densities that follow the time-domain NMR signal envelope and sample more points at higher SNR have spectral reconstructions with lower root-mean-square errors (RMSEs) and less non-linearity compared with sample masks that do not. The t_1 dimensions of the EP-COSY datasets in this work were apodized with a sine-squared filter to enhance the cross-peaks (9), but, because of T_2^* decay, the filtered EP-COSY data had a skewed sine-squared signal envelope; therefore, the 2D Poisson-gap sample mask density was modulated along t_1 with a skewed sine-squared function (33). The k_y dimension was modulated by an exponential decay function similar to that used previously to maximize spatial SNR (34).

The sample density of a Poisson-gap mask can be modulated by the rate parameter λ which determines both the mean and variance of a Poisson distribution. The probability of generating a gap g from a Poisson distribution is characterized by:

$$p(g, \lambda) = (\lambda^g \cdot e^{-\lambda}) / g! \quad [7]$$

For large λ , large values of g are more likely, and for small λ , small values of g are more likely. Therefore, the probability of g can be modulated by varying the value of λ according to a sine or exponential decay function, and the probability of large gaps between spaces can be increased where the SNR is highest in the MR signal envelope (28). To generate g as a function of λ , a Poisson process can be simulated using various techniques that do not depend on an *a priori* knowledge of g as above (35). For these experiments, the *poissrnd*(λ) function in Matlab was used to generate g as a function of λ . It takes as input an array of λ and returns an array of gaps with local mean and variance λ .

2D Poisson-gap sample masks were iteratively generated in Matlab by combining the 1D distributions of t_1 and k_y until the desired NUS rate was reached.

Examples of the 2D λ , gap and mask arrays generated by 2D Poisson-gap are shown in Fig. 2; as the size of λ and the spacing gaps increase, the sample density increases in that area of the mask. The magnitude point spread function (PSF) of the mask is shown and demonstrates the viability of this approach; the single dominant central peak with small side-lobes, surrounded by low-amplitude, incoherent artifacts, is the desired profile of

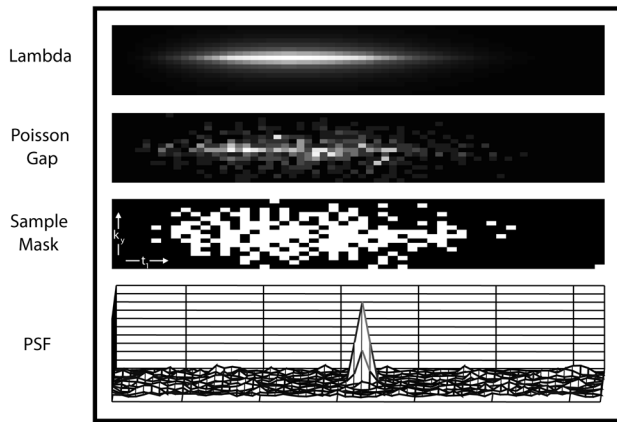


Figure 2. Poisson sample mask creation along the k_y - t_1 plane for echo-planar correlated spectroscopic imaging (EP-COSI). Top: modulated values of λ . Upper middle: Poisson-distributed values for each λ indicating the gap between spaces in the sample distribution. Lower middle: resulting two-dimensional (2D) Poisson-gap sample mask. Bottom: magnitude point spread function (PSF) of the 2D sample mask.

a NUS mask PSF (36,37). Incoherent sampling artifacts will have low amplitudes and spurious peaks caused by coherent aliasing will be negligible.

MR simulations

The effects of SNR and under-sampling rate on the reconstructions were quantitatively assessed using a noise-free simulated 4D EP-COSI dataset that contained choline + glycerophosphocholine + phosphocholine (total choline, tCho), glutamate + glutamine (Glx), creatine (Cr), aspartate (Asp) or nothing in each voxel, as represented in the top of Fig. 3 by a diagonal peak from each metabolite. Each metabolite was simulated using the GAMMA NMR libraries (38) from a 3T localized 2D correlated spectroscopy sequence (39) with the following parameters: 100 t_1 increments, 1024 points in t_2 , TR/TE = 1.5 s/30 ms, and spectral bandwidths of 1250 and 2000 Hz along F_1 and F_2 , respectively. Each 2D spectrum was line broadened by 10 Hz and apodized by a sine-squared filter along t_1 and a skewed sine-squared filter with skew parameter 0.5 along t_2 . No baseline corrections were performed on the spectra.

They were then copied into an 8x8 spatial grid to simulate spatially distributed metabolites as follows: the upper left quadrant contained 2x2 voxels of tCho, the upper right quadrant contained 2x2 voxels of Cr, the lower left quadrant contained 2x2 voxels of Glx and the lower right quadrant contained 2x2 voxels of Asp.

As a result of under-sampling the k_y - t_1 plane, the spatial, spectral artifacts caused the tCho and Glx voxels to alias into each other and the Cr and Asp voxels to alias into each other, as illustrated by the zero-augmented data at the bottom of Fig. 3. This changed the integrated peak area contained within each metabolite as the spatial, spectral separation between the metabolites broke down.

Noise was added to the simulated noise-free 4D EP-COSI dataset to model the SNRs of 2–20 in increments of 2. It was under-sampled 5x, 2.5x, 1.67x and 1.25x, and then separately reconstructed by MaxEnt and CS. The SNR was varied by simulating different levels of thermal noise in the dataset by adding univariate Gaussian noise to the noise-free real and imaginary channels of the 4D EP-COSI dataset (40). The desired SNR was achieved by ensuring that the additive noise signal power (σ^2) was equal to 1/SNR of the noise-free dataset signal power (ω^2), such that:

$$\text{noisy data} = \text{noise free data} + \frac{\omega^2}{\sigma^2 \times \text{SNR}} \times \text{noise} \quad [8]$$

Because the additive noise was random, each SNR was simulated and reconstructed 20 times per sample mask to account for random fluctuations in the reconstruction. The sampling masks were created using the 2D Poisson-gap method described earlier.

MRSI

The breasts of three healthy volunteers were scanned using the 4D EP-COSI sequence on a Siemens (Siemens AG, Erlangen, Germany) 3T Trio scanner with the following parameters: voxel size, 1x1x1 cm³, 50 t_1 increments, TR/TE/averages = 1.5 s/30 ms/1, field of view, 16x16 cm² FOV, and spectral bandwidths of 1250 Hz and 1190 Hz along F_1 and F_2 , respectively. Each breast was scanned twice: a 4x prospective NUS scan and a fully sampled scan using the same field of view and shim. The NUS scan took 5 min to complete and the

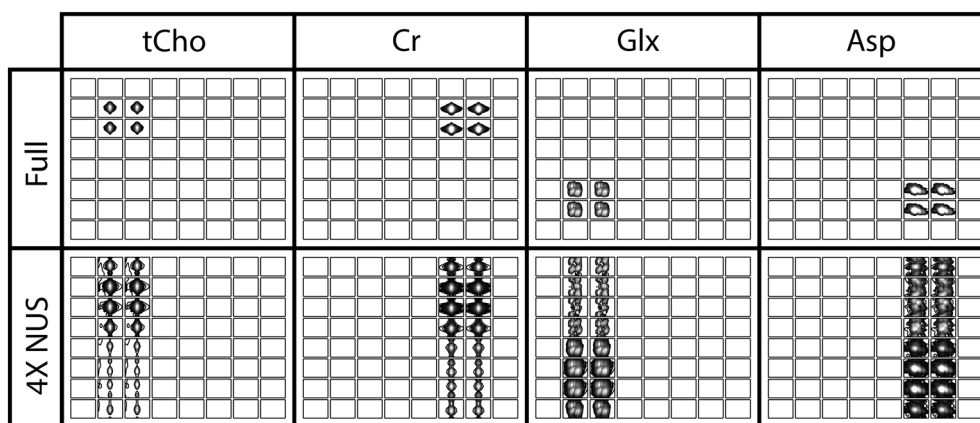


Figure 3. Simulated quad phantom illustration. Top: spatial distribution of tCho [total choline (choline + glycerophosphocholine + phosphocholine)], Cr (creatine), Glx (glutamate and glutamine) and Asp (aspartate) diagonal peaks when fully sampled. Bottom: spatial distribution of the same tCho, Cr, Glx and Asp diagonal peaks of the 4x non-uniform under-sampled (NUS) zero-augmented dataset.

fully sampled scan took 20 min. Both scans were first apodized using a sine-squared filter along t_1 and a skewed sine-squared filter with skew parameter 0.5 along t_2 . No baseline corrections were performed on the *in vivo* breast data. The fully sampled scans were then retrospectively under-sampled 4× using the same mask as employed in the prospective scan shown in Fig. 4, and both NUS datasets were then reconstructed using MaxEnt and CS.

RESULTS

MR simulations

Quantitative results for the MaxEnt and CS reconstructions of the simulated 4D EP-COSI dataset at different NUS rates and SNRs are shown in Fig. 5. The top panel shows the mean RMSE *versus* SNR for zero-augmented and reconstructed datasets at each NUS rate. The RMSE provides an estimate of the reconstruction



Figure 4. Non-uniform under-sampling (NUS) mask used to under-sample the k_y - t_1 plane 4× in Figs 8 and 9.

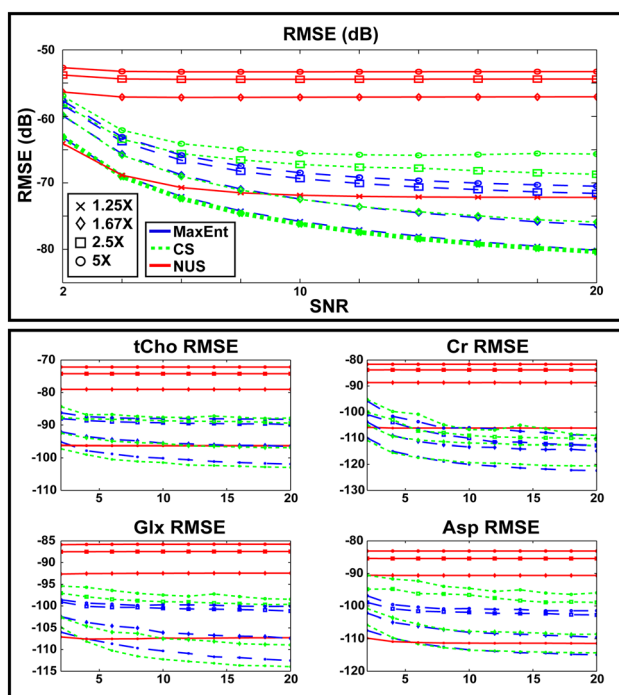


Figure 5. Metrics comparing the zero-augmented, maximum entropy (MaxEnt)-reconstructed and compressed sensing (CS)-reconstructed four-dimensional (4D) echo-planar correlated spectroscopic imaging (EP-COSI) simulated data. Top: overall root-mean-square errors (RMSEs) of each dataset *versus* signal-to-noise ratio (SNR) for 5×, 2.5×, 1.67× and 1.25× non-uniform under-sampling (NUS) rates. Bottom: tCho [total choline (choline + glycerophosphocholine + phosphocholine)], Cr (creatine), Glx (glutamate and glutamine) and Asp (aspartate) metabolite-specific RMSEs for each dataset *versus* SNR for 5×, 2.5×, 1.67× and 1.25× NUS rates.

accuracy with respect to a fully sampled reference dataset that increases as the two datasets become more dissimilar. The RMSE was calculated in the spatial, spectral domain as:

$$RMSE = \frac{1}{N} \sqrt{\sum (|data| - |full|)^2} \quad [9]$$

where N is the number of data points, ‘full’ is the fully sampled dataset and ‘data’ is the zero-augmented or reconstructed dataset. Error bars are not shown because the standard deviations were three to four orders of magnitude smaller than the mean RMSEs and did not vary noticeably over the NUS rate or SNR. As can be seen, the RMSE of the zero-augmented dataset increases as the NUS rate increases, but does not vary considerably with SNR, except at low NUS rates. Both the CS and MaxEnt reconstructions show large decreases in RMSE at each SNR and NUS rate, but, at low SNRs, RMSE begins to rise. At low NUS rates, CS and MaxEnt have comparable RMSEs at each SNR; however, at higher NUS rates, the RMSEs for the MaxEnt reconstruction are lower than for CS, and this difference increases with SNR.

The bottom panel of Fig. 5 shows the average RMSE of the diagonal and cross-peaks of tCho, Glx, Cr and Asp *versus* SNR of the zero-augmented and reconstructed datasets. The RMSEs were calculated over the metabolite peaks at the ppm locations listed in Table 1. Each RMSE was calculated only over the four spatially distributed voxels for each metabolite. For example, the tCho RMSEs were calculated over voxels (2, 2), (2, 3), (3, 2) and (3, 3), as illustrated in Fig. 3. Therefore, these RMSEs reflect local changes to the metabolite peak lineshape and amplitude caused by the spatial, spectral aliasing along the k_y - t_1 plane from the NUS and reconstruction.

All of the metabolite RMSEs in the bottom panel of Fig. 5 show similar trends over SNR as the overall RMSEs in the top panel of Fig. 5 at each NUS rate. The MaxEnt and CS reconstructions have lower RMSEs than the zero-augmented datasets, indicating that the metabolite peak lineshapes and amplitudes are being properly reconstructed. The MaxEnt reconstructions have lower RMSEs for many metabolites than the CS reconstructions at higher NUS rates, but, at lower rates, their RMSEs are roughly equivalent.

Figure 6 shows a 1D cross-section of the fully sampled, zero-augmented and reconstructed spectra for high and low SNR simulated spectra at 1.25× and 5× NUS, respectively. The 1D cross-section is indicated by the broken line across F_2 at $F_1 = 3.65$ ppm in Fig. 7, and any NUS artifacts are from aliased peaks above and below the line, not peaks shown in the cross-section. The high SNR, 1.25× NUS zero-augmented spectrum shows only small deviations from the fully sampled spectrum, but they are clearly visible in the inset. Both reconstructions restored the baseline to the level of the fully sampled spectrum and preserved the amplitude and lineshapes of the peaks in the full cross-sections. The artifacts in the low SNR, 5× NUS zero-augmented spectrum show significantly reduced peak amplitudes, broader linewidths and Gibbs ringing along the baseline. Both reconstructions successfully restored the linewidths of the peaks in the full cross-sections and removed the Gibbs ringing shown in the insets; however, MaxEnt was generally better at restoring the peak amplitude as indicated by the red arrows. Many of the real and imaginary peak amplitudes in the CS reconstructions were lower than those of the MaxEnt reconstructions, and the baseline for CS was also slightly lower.

Table 1. Two-dimensional peak locations (ppm) for selected metabolites

	tCho	Glx	Cr	Asp
Diagonals (ppm)	(3.2,3.2), (3.5,3.5), (4.0,4.0), (4.3,4.3)	(2.3,2.3), (3.7,3.7)	(3.0,3.0), (3.9,3.9)	(2.8,2.8), (3.9,3.9)
Cross-peaks (ppm)	(3.5,4.0), (3.5,4.3), (4.0,3.5), (4.3,3.5)	(2.3,3.7), (3.7,2.3)	N/A	(2.8,3.9), (3.9,2.8)

Asp, aspartate; Cr, creatine; Glx, glutamate and glutamine; N/A, not applicable; tCho, total choline (choline + glycerophosphocholine + phosphocholine).

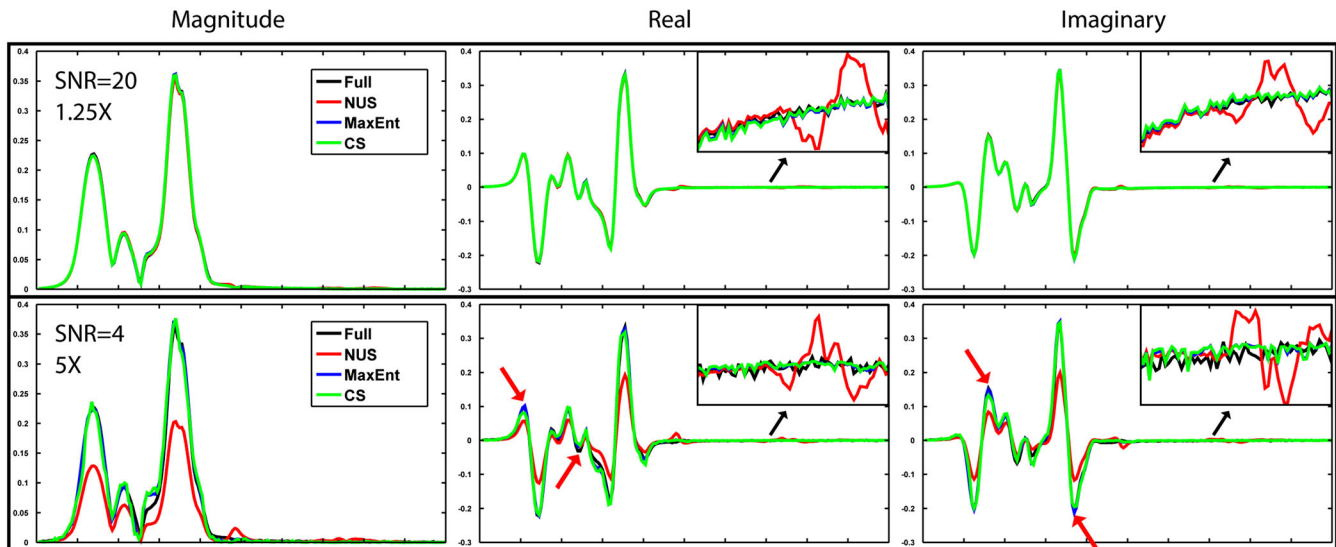


Figure 6. One-dimensional (1D) magnitude, real and imaginary cross-sections of fully sampled, zero-augmented and reconstructed Glx (glutamate and glutamine) spectra. Top: cross-sections from high-signal-to-noise ratio (SNR) spectra 1.25 \times non-uniform under-sampled (NUS) zero-augmented and reconstructed using maximum entropy (MaxEnt) or compressed sensing (CS). Bottom: cross-sections from low-SNR spectra 5 \times NUS zero-augmented and reconstructed using MaxEnt or CS. Insets: magnified cross-sections of spectral baselines.

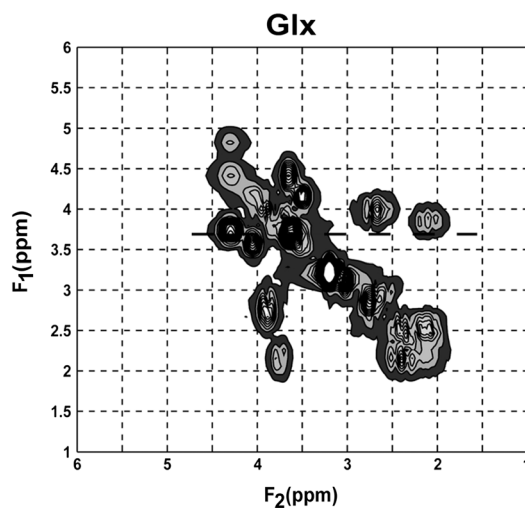


Figure 7. Fully sampled two-dimensional (2D) correlated spectroscopy (COSY) Glx (glutamate and glutamine) spectrum, with the broken line across F_2 at $F_1 = 3.65$ ppm indicating the one-dimensional (1D) cross-section shown in Fig. 6.

NUS of 4D EP-COSY in human breast

The results from a prospective 4 \times NUS EP-COSY scan of a 31-year-old healthy human breast that was MaxEnt- and CS-reconstructed are

shown in Fig. 8A, B, respectively, with the zero-augmented data shown in Fig. 8C. The contour levels employed in the fully sampled results in Fig. 9A were used in Fig. 8. The mask used to under-sample the k_y - t_1 plane is shown in Fig. 4, together with the signal envelopes for each dimension, and was generated using the 2D Poisson-gap method described earlier in this article.

Figure 8A1, B1 shows 2D correlated spectroscopy (COSY) spectra extracted from the MaxEnt and CS reconstructions, respectively. They were taken from the fatty breast regions highlighted in Fig. 8A2, B2. They clearly show the lipid diagonal peaks, olefinic fat (UFD), methyl fat (FMETD) and fat (FAT/FAT2/FAT3), and the cross-peaks, unsaturated fatty acid right (UFR), unsaturated fatty acid left (UFL), and triglyceryl fat (TGFR) (5). The spatial distribution of the UFL/UFR cross-peaks from the reconstructions is shown in Fig. 8A2, B2 with the MaxEnt reconstruction's spatial distribution overlaid on the anatomical MR image.

Figure 8C1 shows the same 2D COSY spectrum as in Fig. 8A1, B1 with 4 \times NUS applied to the k_y - t_1 plane using the mask in Fig. 4; however, no MaxEnt or CS reconstruction was used. The spatial, spectral incoherent artifacts from NUS manifest as smeared peaks along F_1 , which is illustrated by the collapse of the peaks in the 1D projection of the F_1 dimension on the right. The aliasing of the large diagonal fat peaks around ($F_2 = 2$ ppm, $F_1 = 2$ ppm) obscures the much smaller UFL/UFR cross-peaks around ($F_2 = 2.1$ ppm, $F_1 = 5.4$ ppm). Figure 8C2 shows the spatial distribution of the UFL/UFR cross-peaks and how spatial artifacts from the under-sampling of k_y - t_1 manifest as errant peaks in adjacent voxels.

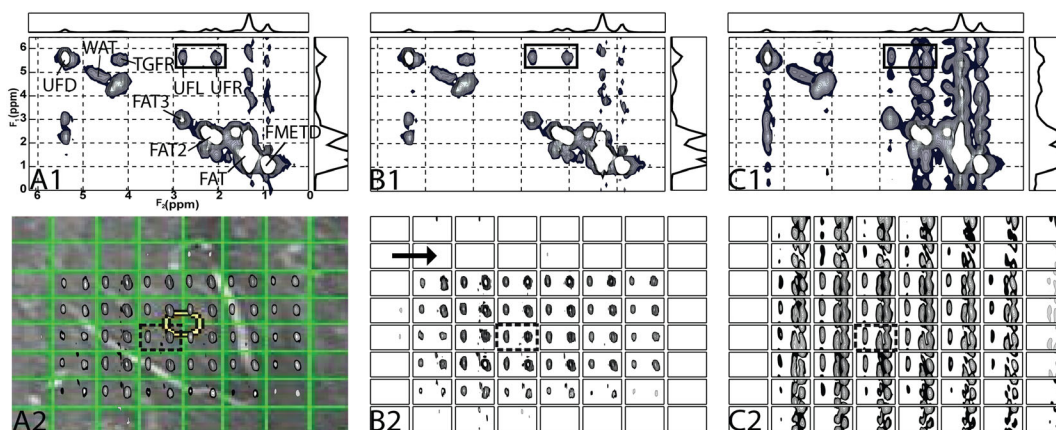


Figure 8. Prospective four-dimensional (4D) echo-planar correlated spectroscopic imaging (EP-COSI) results. Top: selected two-dimensional (2D) correlated spectroscopy (COSY) spectrum from a 4D EP-COSI scan of healthy, fatty breast highlighted in the bottom images for maximum entropy (MaxEnt)-reconstructed (A1), compressed sensing (CS)-reconstructed (B1), and 4× non-uniform under-sampled (NUS) zero-augmented (C1) data. Bottom: spatial distribution of the unsaturated fatty acid left/unsaturated fatty acid right (UFL/UFR) cross-peaks highlighted in the 2D COSY spectrum for MaxEnt-reconstructed (A2), CS-reconstructed (B2), and 4× NUS zero-augmented (C2) data. FAT/FAT2/FAT3, fat; FMETD, methyl fat; TGFR, triglyceryl fat; UFD, olefinic fat.

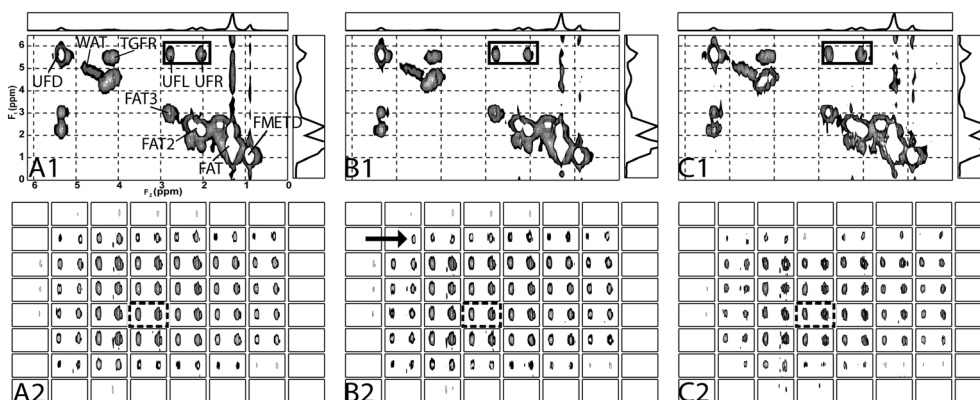


Figure 9. Retrospective four-dimensional (4D) echo-planar correlated spectroscopic imaging (EP-COSI) results. Top: selected two-dimensional (2D) correlated spectroscopy (COSY) spectrum from a 4D EP-COSI scan of healthy, fatty breast highlighted in the bottom images for fully sampled (A1), maximum entropy (MaxEnt)-reconstructed (B1), and compressed sensing (CS)-reconstructed (C1) data. Bottom: spatial distribution of the unsaturated fatty acid left/unsaturated fatty acid right (UFL/UFR) cross-peaks highlighted in the 2D COSY spectrum for fully sampled (A2), MaxEnt-reconstructed (B2), and CS-reconstructed (C2) data. FAT/FAT2/FAT3, fat; FMETD, methyl fat; TGFR, triglyceryl fat; UFD, olefinic fat.

Comparing the MaxEnt- and CS-reconstructed spectra in Fig. 8A1, B1, all of the significant diagonals and cross-peaks are fully resolved in both datasets with qualitatively similar linewidths and amplitudes. The only major differences between them are that the amplitudes of the t_1 ridges centered at ($F_2 = 1.3$ ppm, $F_1 = 1.3$ ppm) and ($F_2 = 1.0$ ppm, $F_1 = 1.0$ ppm) for CS are lower than for MaxEnt.

The results from a fully sampled EP-COSI scan of the same healthy breast as shown in Fig. 8, which was retrospectively 4× under-sampled using the same mask and MaxEnt and CS reconstructions, are illustrated in Fig. 9. Figure 9A shows the fully sampled data and Fig. 9B, C shows the MaxEnt and CS reconstructions, respectively. As the same field of view was used for both scans, the spectra at the top of Fig. 9 show the same 2D COSY spectra as those at the top of Fig. 8, and the bottom shows the spatial distribution of the UFL/UFR cross-peaks. The same contour levels used for the fully sampled data in Fig. 9A were also employed for the MaxEnt- and CS-reconstructed results in Fig. 9B, C.

As can be seen, all of the peaks in the fully sampled spectrum in Fig. 9A1 are completely resolved in both the prospective and retrospective reconstructions shown in Figs 8B1, C1, 9B1, C1; their positions, linewidths, amplitudes and spectral resolutions are all qualitatively comparable. However, the spatial distributions of the fully sampled and retrospective NUS results show better agreement than the prospective NUS results in the upper region of the breast; the excited volume of the prospective NUS results is one row smaller than that of the retrospective NUS results, as indicated by the arrows in Figs 8 and 9. This change was also observed in the non-water-suppressed scans taken prior to the prospective NUS and fully sampled scans, and therefore cannot be an artifact of the reconstruction.

Table 2 shows the F_1 full width at half-maximum (FWHM) and peak amplitudes of the zero-augmented and reconstructed dataset magnitude peaks in Figs 8 and 9. For comparison, they are normalized by the fully sampled peak amplitudes and FWHM from Fig. 9, so that values greater than unity are larger than the fully sampled value. As can be seen, there are quantitative

Table 2. Relative full width at half-maximum (FWHM) along F_1 and amplitude of metabolite peaks for zero-augmented, maximum entropy (MaxEnt)-reconstructed and compressed sensing (CS)-reconstructed data from the voxel shown in Figs 8 and 9. Values are normalized by the fully sampled peak FWHM and amplitudes

	Prospective amplitude							
	FAT	FAT2	FAT3	FMETD	TGFR	UFD	UFL	UFR
MaxEnt	1.249	1.342	1.232	1.614	0.951	1.125	1.060	1.078
CS	1.427	1.372	1.263	1.665	0.982	1.142	1.150	1.161
	Prospective FWHM							
	FAT	FAT2	FAT3	FMETD	TGFR	UFD	UFL	UFR
MaxEnt	0.818	0.909	0.818	1.000	0.818	1.000	0.900	0.727
CS	0.727	0.909	0.818	0.900	0.909	1.000	0.900	0.727
Zero-augmented	Retrospective amplitude							
	FAT	FAT2	FAT3	FMETD	TGFR	UFD	UFL	UFR
	0.634	0.701	0.662	0.639	0.639	0.627	0.518	0.845
MaxEnt	1.061	1.026	1.090	1.010	1.019	1.029	0.942	0.989
CS	1.237	1.138	1.017	0.961	1.077	0.995	1.071	1.043
Zero-augmented	Retrospective FWHM							
	FAT	FAT2	FAT3	FMETD	TGFR	UFD	UFL	UFR
	1.273	1.273	1.182	1.30	1.00	1.30	1.40	1.010
MaxEnt	0.818	0.909	0.818	1.00	0.818	1.00	1.00	0.818
CS	0.727	0.818	1.010	1.00	0.727	1.10	0.80	0.727

FAT/FAT2/FAT3, fat; FMETD, methyl fat; TGFR, triglyceryl fat; UFD, olefinic fat; UFL, unsaturated fatty acid left; UFR, unsaturated fatty acid right.

differences between the CS- and MaxEnt-reconstructed peak lineshapes. The zero-augmented dataset has broader, shorter peaks as expected, and both the CS- and MaxEnt-reconstructed peak lineshapes are closer to the fully sampled data; however, the MaxEnt peak lineshapes are almost all closer to the fully sampled data than are the CS peak lineshapes, which are narrower and taller than both the MaxEnt and fully sampled data. The increase in peak amplitudes in the CS reconstruction is greater in the larger peaks (FAT, FAT2 and FAT3) than in the smaller peaks (UFD, UFL, UFR) when compared with MaxEnt.

Additional quantitative differences between the MaxEnt and CS reconstructions are illustrated in Table 3, which shows the range of values for the $(UFL + UFR)/(FAT3 + FAT2)$ integrated peak area ratios and average errors from the fully sampled ratios for the central 6×6 voxels of the three healthy human breasts. As can be seen, NUS caused the ratios to vary considerably from the fully sampled ratios with a high mean ratio error. The reconstructed ratios show much better agreement with the fully

sampled ratios and have a much smaller mean ratio error in all three scans than do the zero-augmented data. However, the mean ratio errors for the MaxEnt reconstruction are almost all smaller than their CS counterparts, indicating that the peak ratio was more accurately reconstructed by MaxEnt. The retrospective reconstruction results are only slightly better than the prospective results, which is not surprising, given the excitation volume differences seen in Figs 8 and 9.

DISCUSSION

The simulated 4D EP-COSY dataset results in Fig. 5 demonstrate how the MaxEnt and CS reconstructions perform at different SNRs and NUS rates. Both reconstructions decrease the RMSE significantly at each SNR and NUS rate, compared with the zero-augmented dataset, but begin to increase at very low SNR, which indicates that they are unable to fully reconstruct

Table 3. Range and mean error of $(UFL + UFR)/(FAT3 + FAT2)$ integrated peak area ratios for fully sampled, zero-augmented, maximum entropy (MaxEnt)-reconstructed, and compressed sensing (CS)-reconstructed data from three healthy breasts

	Ratio range	Mean ratio error	Ratio range	Mean ratio error	Ratio range	Mean ratio error
	Breast 1		Breast 2		Breast 3	
Full	0.1277–0.0456	N/A	0.1984–0.0656	N/A	0.3542–0.0277	N/A
Zero-augmented	0.2162–0.1496	0.0823 ± 0.0198	0.4699–0.3082	0.2640 ± 0.0734	1.0077–1.1785	0.2047 ± 0.0916
Retrospective MaxEnt	0.1061–0.0281	0.0244 ± 0.0071	0.1576–0.0413	0.0254 ± 0.0142	0.4134–0.0291	0.0215 ± 0.0149
Prospective MaxEnt	0.1049–0.0216	0.0326 ± 0.0083	0.1215–0.0420	0.0415 ± 0.0164	0.3422–0.0414	0.0404 ± 0.0463
Retrospective CS	0.1103–0.0275	0.0246 ± 0.0073	0.1781–0.1004	0.0357 ± 0.0235	0.4114–0.0269	0.0268 ± 0.0175
Prospective CS	0.1084–0.0211	0.0334 ± 0.0082	0.1276–0.0425	0.0397 ± 0.0140	0.3594–0.0374	0.0434 ± 0.0487

FAT2/FAT3, fat; N/A, not applicable; UFL, unsaturated fatty acid left; UFR, unsaturated fatty acid right.

the data when features and sampling artifacts are obscured by high levels of noise. The data fidelity constraint in Equations [1] and [2] determines how closely the reconstructed points must be to the sampled points within the standard deviation of noise, which increases as the noise floor increases. This increase in the noise floor effectively 'loosens' the fidelity constraint, which allows the reconstructed points to deviate from their sampled counterparts and increases the entropy or sparsity of the reconstructed spectrum by narrowing the peak linewidths and de-noising smaller features. This, in turn, increases the non-linearity and RMSE of the reconstruction because of the loose fidelity constraint (41). The data fidelity constraint can be 'tightened' beyond the standard deviation of the noise in an effort to reduce the RMSE and reconstruction non-linearity, but this prevents the Cambridge algorithm from completely removing the spatial, spectral NUS artifacts close to the noise floor, which could potentially obscure small features (21).

The metabolite RMSEs in Fig. 5 show that the reconstructions offer significant improvements in the amplitude and lineshape of individual peaks over the zero-augmented data, even without using methods to reduce the reconstruction non-linearity (32). CS and MaxEnt produce very similar results at low NUS rates, but MaxEnt generally has a lower RMSE at higher NUS rates than this implementation of CS. As demonstrated by Figs 6 and 7, both reconstruction methods successfully restored the peaks and removed the Gibbs ringing artifacts; however, CS had a tendency to over-smooth smaller features close to the noise floor and narrow peak linewidths. It was this over-smoothing that reduced the amplitude of the CS-reconstructed fat tails at ($F_2 = 1.3$ ppm, $F_1 = 1.3$ ppm) and ($F_2 = 1.0$ ppm, $F_1 = 1.0$ ppm) in Fig. 8. The differences in peak linewidths between MaxEnt and CS contributed to the disparity in RMSE values at higher NUS rates, but the main contributing factor was the change in the noise floor in the non-peak regions of the spectra. The noise floor was slightly reduced over the entire 4D dataset in the CS reconstructions, which was the vast majority of points in the volume; therefore, small changes in the noise floor had large effects on RMSE. The over-smoothing in the CS reconstructions may have been caused by choosing $\epsilon = \text{def}/1000$ in Equation [4], and will be investigated in the future, although previous work has used similar values with success (13).

The healthy human breast results in Figs 8 and 9 show that CS and MaxEnt reconstructions work well for prospective and retrospective NUS, filtered, *in vivo* EP-COSY scans. There were minor differences between the prospective and retrospective reconstructions; however, these can be attributed to intra-scan variations in the excitation volumes, as these differences were reflected in the MaxEnt and CS reconstructions, as well as in the non-water-suppressed scans. The greater SNR loss caused by T_2^* decay which was not present in the simulated 4D EP-COSY dataset did not reduce the efficacy of the reconstructions. There was still sufficient SNR in the time domain to reconstruct the *in vivo* diagonal and cross-peaks in the spectral domain.

Although the MaxEnt and CS reconstructions of healthy human breast were qualitatively similar, Tables 2 and 3 illustrate quantitative differences between them. Both reconstruction methods improved the ratios of the lipid peaks in Table 3 and the amplitudes and FWHM of major peaks in Table 2, which shows that they were able to reconstruct the large, aliased diagonals, as well as the smaller cross-peaks that were obscured by the diagonals aliasing over the k_y - t_1 plane. However, as shown in Table 2, the CS-reconstructed peaks were narrower with higher amplitudes than their MaxEnt counterparts. This discrepancy increased with

peak amplitude, indicating a higher degree of non-linearity in the CS reconstruction relative to MaxEnt. Using the relative peak amplitudes and FWHM values from Table 2 to calculate the peak area, instead of the integrated peak area that was used for Table 3, the relative (UFL + UFR)/(FAT3 + FAT2) ratios for MaxEnt and CS for the retrospective reconstructions are 0.960 and 0.825, respectively. Because the FAT3 and FAT2 peaks from the CS reconstruction are relatively larger than the MaxEnt peaks from the increased non-linearity, their relative ratio with the UFL and UFR peaks is smaller. This increased non-linearity was a contributing factor in the larger mean ratio errors in Table 3 for the CS reconstructions relative to the MaxEnt reconstructions.

The under-sampled data in Fig. 8C1, C2 show artifacts spread along F_1 and Y , as well as reduced spectral resolution along F_1 and larger FWHMs in Table 2, caused by convolution with the broad NUS PSF. The homogeneous nature of healthy fatty breast spectra, coupled with the inherently low spatial resolution of 4D EP-COSY, made it difficult to determine from the figures whether the spatial resolution along Y decreased as a result of the NUS PSF. However, it is clear that the effects of the NUS PSF along F_1 were removed by MaxEnt and CS by the narrower FWHM values in Table 2 and the lack of NUS artifacts in Figs 8A1, B1, 9A1, B1. The errant spectral peaks in the spatial distribution were removed in Figs 8A2, B2, 9A2, B2, suggesting that the spatial PSF along Y was also improved. Any spectral bleed from the spatial PSF of the EP-COSY pulse sequence along X was orthogonal to the effect of the NUS PSF along Y , and was not affected by the MaxEnt and CS reconstructions.

The results in Figs 5–9 indicate that MaxEnt and CS produced qualitatively similar reconstructions; however, the MaxEnt results were quantitatively better by a small margin as discussed above. This is not surprising, given that the objective functions of CS and MaxEnt are similar, but there are minor differences between them as shown in Fig. 1. CS uses the l_1 -norm of the reconstructed spectrum in some transform domain, and MaxEnt uses entropy, which is a log-sum function that can be rewritten as a reweighted l_1 -norm, $\sum w_i \cdot |m_i|$, where w_i is $\log[f(m_i)]$, the log of a function of the reconstructed spectrum. Previous work has shown that reweighted l_1 -norm objective functions can outperform l_1 -norm-based CS reconstruction (42), and direct comparisons between MaxEnt and l_1 -norm-based CS reconstruction have shown them to be qualitatively equivalent (43). This is the first known work to show quantitative comparisons between these techniques, however, and further research into their relative performance is ongoing.

The Cambridge algorithm used to solve the MaxEnt and CS reconstruction problems was demonstrated to be robust against different levels of SNR and NUS rates for the simulated and *in vivo* datasets. There are other l_1 -norm solvers available for the CS reconstruction problem; however, many require parameter tuning for different datasets in order to find the optimal reconstruction parameters (44,45). The Cambridge algorithm does not have any tuning parameters that must be adjusted to find the optimal reconstruction for a dataset, which offers a substantial workflow improvement over other solvers. Although the Cambridge algorithm can be modified to solve the CS l_1 -norm reconstruction problem, it takes, on average, 5–10 times longer to converge as the MaxEnt problem, which took 7–10 min, on average, using a 64-bit dual-core, 3.4-GHz Core i7 processor with 16GB RAM. Therefore, we do not recommend its use as an l_1 -norm solver; it was only used for the current work in order to compare results for MaxEnt and CS reconstruction that were not biased by different solver implementations. However,

because it is relatively fast, robust to SNR changes, does not require parameter tuning, and provides MaxEnt results that were equal to or better than those of CS, the Cambridge algorithm is well suited as a MaxEnt solver.

The Poisson-gap sampling masks used in these experiments were generated by a random Poisson distribution, which injects a degree of uncertainty into the reconstruction. It has proven to be a reliable technique that generates masks with desirable PSFs, as shown in Fig. 2, and the RMSEs of the reconstructed datasets using different Poisson-gap sample masks are stable (28). Previous attempts by our group to use deterministic masks that were not randomly generated were difficult to optimize and suffered from coherent aliasing, which cannot be removed by MaxEnt or CS reconstruction (32,46). Recent work in NUS multi-dimensional NMR datasets using deterministic sample masks has shown promise and could be adapted to 4D MRSI (47).

Because of the random nature of the Poisson-gap sampling masks, they were chosen by an empirical heuristic that minimized the width of the central peak, the total power of the incoherent artifacts, and the ratio of the largest artifact peak to the central peak in the mask PSF. They followed a skewed-sine bell modulation function to maximize the reconstruction SNR, but were not optimized for specific metabolites or post-processing spectral filters. In our experiments, we observed that mismatches between a sample modulation function and the filtered signal envelope of a metabolite results in failure to sufficiently sample the high-SNR points along t_1 and prevents the full metabolite peak area from being reconstructed (31,32,48). Therefore, it should be emphasized that the sample mask is crucial to the SNR of each reconstructed metabolite for 4D EP-COSY data, and there is a dependence on the shape of standard spectral filters applied prior to reconstruction (33).

Further research into reducing the non-linearity of the reconstructed peaks to make accurate quantification possible, and comparisons with additional CS methods, is ongoing. In addition, future papers will address the use of Poisson-gap versus deterministic sample masks, and the optimization of the modulation functions for specific metabolites and different spectral filters.

CONCLUSIONS

This work has demonstrated that MaxEnt is a viable alternative to l_1 -norm-based CS reconstruction for accelerating the acquisition of 4D EP-COSY data *in vivo*. MaxEnt provided reconstructions equal to or better than those of CS, and the robust nature of the Cambridge algorithm without the need for parameter tuning makes it a good candidate for clinical use. The CS and MaxEnt reconstructions throughout this work were qualitatively similar; however, the quantitative results indicated increased non-linearity in the CS reconstruction when compared to MaxEnt. Simulated 4D EP-COSY data provided a quantitative characterization of both reconstruction methods at different NUS rates and SNRs, and the 4× NUS *in vivo* EP-COSY breast data showed that a clinically viable 5-min breast scan is possible.

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