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XtalCAMP: a comprehensive program for the analysis and visualization of scanning Laue X-ray micro-/nanodiffraction data

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1 **Equation Chapter 1 Section 1XtalCAMP: a**
2 **comprehensive software for the analysis and**
3 **visualization of scanning Laue X-ray micro/nano-**
4 **diffraction data**

5
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16

17 **Abstract**

18 XtalCAMP is a software package based on Matlab platform, which is **competent**
19 **adequate** for, but not limited to, the analysis and visualization of ~~the~~ scanning
20 Laue X-ray micro/nano-diffraction data. The main objective of the software is to
21 provide complementary functionalities ~~for to the current~~ Laue indexation
22 software ~~packages prevailing among used at different several~~ synchrotron
23 beamlines. The graphical user interfaces allow the easy analysis of characteristic
24 microstructure features, including real-time intensity mapping for a quick look of
25 phase, grain and defects distribution, 2D color-coded mapping of microstructural
26 properties ~~in from~~ the outputs of other Laue indexation software, grain boundary
27 characterization based on orientation/misorientation calculation, principal strain/
28 stress analysis and strain ellipsoid representation, as well as a series of
29 additional toolkits. As an example, XtalCAMP is applied to the microstructural
30 investigation ~~on of~~ a solution heat treated Ni-based superalloy manufactured
31 using laser 3D-printing technique.

32 **Keywords:** Scanning Laue X-ray micro/nano-diffraction, computer program, crystal
33 orientation map, strain/stress analysis

34 **1. Introduction**

35 Taking advantage of brilliant synchrotron sources, the scanning Laue X-ray

36 micro/nano-diffraction (μ XRD) technique has ~~been~~ become an indispensable
37 high-throughput approach ~~to the linkage between~~ for linking multi-scale
38 microstructures ~~and to~~ physical properties in ~~a large area~~ statistically
39 large areas of samples with excellent spatial (as good as tens of nm) and angular
40 resolutions ($\sim 0.001^\circ$) (Chen *et al.*, 2016; Zhou *et al.*, 2018). With the μ XRD
41 technique, ~~a raster scan on the specimen~~ the specimen is raster scanned under
42 by the a focused polychromatic X-ray beam and the diffraction ~~beams~~ patterns at
43 each scan spot are recorded using a 2D detector (i.e. Laue pattern) with a short
44 exposure time (< 0.5 s). ~~Then the~~ The spatial distributions of phases, crystal
45 orientation, elastic strains/stresses and microstructural defects ~~are~~ can then be
46 extracted after analyzing the Laue patterns. Consequently, data analysis
47 software, which is capable of indexing thousands of diffraction patterns
48 automatically, has been a major necessity for the popularization of the μ XRD
49 technique.

50 Previous computer programs, such as LAUEGEN (Campbell, 1995), LaueX
51 (Soyer, 1996) and OrientExpress (Ouladdiaf *et al.*, 2006), have been designed
52 for Laue diffraction data analysis, ~~while they aim but aimed~~ at isolated Laue
53 pattern (LP) indexation and crystal orientation determination. This brings forth
54 the development of in-house software at synchrotron beamlines to sequentially
55 analyze thousands of LPs, ~~including such as the~~ X-Ray Microdiffraction Analysis
56 Software (XMAS) (Tamura, 2014) at beamline 12.3.2 of Advanced Light Source
57 (ALS) and ~~also applied at~~ beamline 21A of Taiwan Photon Source (TPS), LaueGo
58 (Tischler) at beamline 34-ID-E of Advanced Photon Source (APS) and LaueTools
59 (Micha, 2017) at the CEA-CNRS BM32 beamline of European Synchrotron
60 Research Facility (ESRF). Although structured into different computer formats,
61 the core outputs of these software packages are similar, comprising a matrix of
62 the same dimension and size ~~of the scanning step~~ than the performed scan.
63 Each element of the matrix ~~contain~~ contains the crystal and microstructural
64 information obtained from the analysis of the corresponding LP, for example the
65 local crystal orientation, strain/stress tensor, LP background intensity, diffraction
66 peak number and shape, and so on. The crystal orientation is usually expressed
67 by in one or several of the following ways: ~~such as~~ orientation matrix, Euler
68 angles, Rodrigues' rotation axis/angle pair and quaternions. The background
69 intensity is an average value of all pixels on the 2D LP. The average full width at
70 half maximum (FWHM) of all indexed Laue peaks in the angular space is taken to
71 describe the diffraction peak shape. With these powerful software packages,

72 | μ XRD has been applied ~~into to~~ the investigation of phase identification and
73 structural evolution of micro/nano-crystals (Guo *et al.*, 2011; Strelcov *et al.*,
74 2012; Dejoie *et al.*, 2014), orientation mapping of single- or poly-crystalline
75 materials (Chen *et al.*, 2010; Ma *et al.*, 2015), transient and residual strain/stress
76 measurement in engineering and natural materials (Chen *et al.*, 2009, 2015; Li *et*
77 *al.*, 2018; Chen *et al.*, 2020), and defect density mapping (Lupinacci *et al.*, 2015;
78 Li *et al.*, 2018). In these typical applications of the μ XRD technique, it is found
79 that the functionalities, such as 2D map plotting, misorientation computing, grain
80 boundary characterization and strain/stress distribution visualization, need to be
81 further explored and enhanced for general users.

82 | Therefore, we introduce a custom-developed comprehensive software,
83 Crystal Computing and Mapping Program (XtalCAMP), ~~for~~ the in-depth analysis
84 of the outputs of ~~the~~ μ XRD data indexation, which incorporates a variety of easy-
85 to-use features including diffraction intensity study, basic 2D map plotting,
86 crystal orientation and misorientation analysis, grain boundary characterization,
87 strain/stress distribution visualization and other useful tools. As mentioned
88 above, the core information generated from indexation software packages such
89 as XMAS, LaueGo, and LaueTools is essentially the same; thereby we take the
90 XMAS outputs as the example in this article for the convenience of statement.

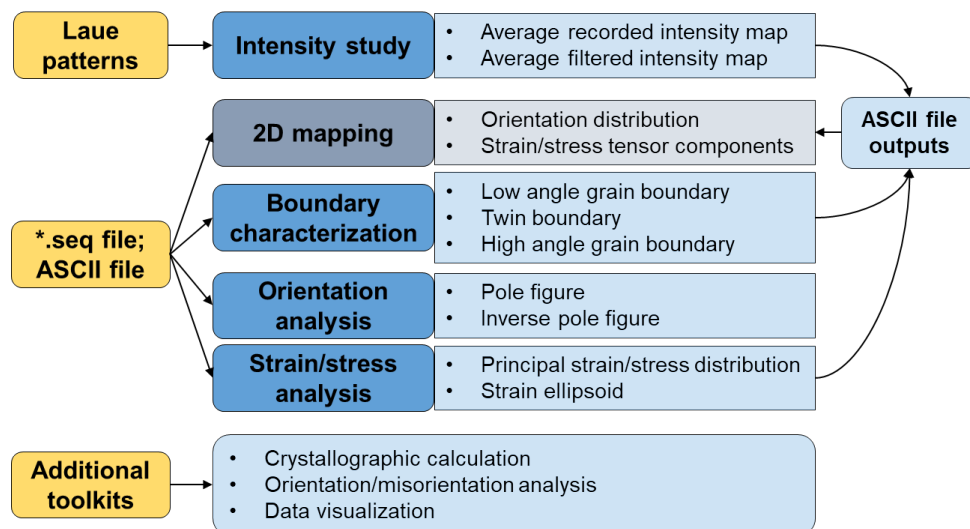
91 **2. Technical description, availability and requirements**

92 | XtalCAMP is coded ~~based on~~through the MATLAB graphical user interface
93 (GUI) module ~~in Matlab~~ and can be executed on Matlab-MATLAB R2014b ~~or and~~
94 higher versions installed on Windows 7 and 10 operating systems (32 bit or 64
95 bit). It has been registered at the Copyright Protection Centre of China
96 (Registration No. 2016SR060878).

97 **3. Program functionality and features**

98 | The ~~primary-general~~ architecture and principal functions of XtalCAMP are
99 ~~designed as~~ shown in Fig. 1. First of all, the diffraction intensity can be calculated
100 extracted and mapped for qualitative microstructure imaging ~~without any assist~~
101 independently of from XMAS or any other LP indexation/analysis software.
102 Secondly, the outputs of ~~the~~ LP indexation software packages, ~~in the~~
103 general(either in ASCII formats (*.txt) or specific binary *.seq formats generated
104 by XMAS), can be inputted-directly imported into into XtalCAMP, ~~and then~~
105 2D2D maps can then be plotted for microstructure imaging ~~with using~~ various

106 | ~~color styles color bars~~ and user defined threshold filters. Thirdly, further data
 107 | mining can be ~~carried out performed~~, including the plotting of pole figures,
 108 | inverse pole figures, ordinary grain boundaries, twin boundaries, misorientation
 109 | distributions, and so on. Finally, some ~~of the toolkits are have easy-to-use~~
 110 | ~~developed with easy-to-use user interface user-friendly interface~~.



111

112

Figure 1 The architecture of XtalCAMP.

113 | To ~~elucidate readily demonstrate~~ the basic data processing functions of
 114 | XtalCAMP, a μ XRD study of a heat treated DZ125L Ni-based superalloy
 115 | manufactured by laser 3D-printing is adopted as an example. A precipitation
 116 | hardened superalloy fabricated by directional solidification was selected as the
 117 | substrate. ~~There are mainly three kinds of phases containing in this alloy~~ ~~Three~~
 118 | ~~kind of phases exist in this alloy; that is,~~ γ austenite matrix, $L1_2$ ordered γ' -
 119 | $Ni_3(Al, Ti, Ta)$ precipitates and MC-type carbides. Powders of the same
 120 | compositions ~~with than~~ the substrate were laser cladded on the (001) plane of
 121 | substrate. With the aid of high thermal gradient antiparallel to the building
 122 | direction, columnar grains ~~in the with~~ width of $\sim 500 \mu m$ grew in epitaxy with the
 123 | bottom substrate, extending to multiple cladding layers. Due to ~~the dense high~~
 124 | dislocation ~~densitiess~~ and ~~high~~-residual strain/stress, complete recrystallization
 125 | occurred in the heat affected zone (HAZ) after post-manufacturing solution heat
 126 | treatment at $1240 \text{ }^\circ\text{C}$ for 2 h. ~~Then the~~ ~~The~~ μ XRD experiment was carried out at
 127 | ~~ALS the ALS on beamline 12.3.2~~ (Kunz *et al.*, 2009). An ~~area of~~ $570 \times 300 \mu m^2$
 128 | ~~area~~ on the longitudinal section of the ~~heat treated~~ ~~heat-treated~~ sample was
 129 | raster scanned using the micro-focused X-ray beam with $3 \mu m$ step size,
 130 | covering ~~from the~~ substrate ~~to and the~~ cladding layers. Finally, ~~the a~~ total 19000
 131 | LPs were automatically indexed using XMAS taking advantage of the newly

132 developed peak position comparison (PPC) indexing algorithm (Kou *et al.*, 2018)
 133 and the indexation outputs were imported into XtalCAMP for further analysis. It
 134 should be noted that all LPs were indexed by using the crystal structure of nickel,
 135 due to the small misfit and cube-on-cube orientation relationship between γ and
 136 γ' phases (Li *et al.*, 2018). The detailed sample preparation and μ XRD
 137 experiment are described in Appendix A.

138 3.1. Diffraction intensity analysis and mapping

139 As indexing thousands of Laue patterns in a scan is time-consuming, we
 140 developed a novel approach to collect the intensity of each LP without
 141 indexation, facilitating a quick view of the characteristic microstructure features,
 142 including cracks, voids, dendrite structures, precipitates, grain boundaries in a
 143 real-time manner. The following lists the main steps of this approach:

144 (1) Read a LP and get the dimensions ($n \times m$ pixels) and **graygrey** value
 145 array. For the i^{th} Laue pattern, the summation of **the graygrey** values **of from** all
 146 pixels is averaged, **which. This** is called average recorded intensity I_R of i^{th} LP **and**
 147 **is defined as:**

$$I_R = \frac{\sum_{k=1}^{n \times m} I_r^k}{n \times m} \quad 22 \setminus * \text{MERGEFORMAT } ()$$

149 where the I_r^k is the **graygrey** value of k^{th} pixel.

150 (2) To enhance the microstructural contrast, treatment is required to
 151 distinguish the LPs with different peak shape. The approach adopted here is to
 152 set a threshold intensity (I_t) for each LP, which is defined as $I_t = C_f \cdot I_R$. C_f is the
 153 **filtered** factor, which is **a** constant for all the LPs taken in the whole scanned
 154 area, and by default C_f is **take a equal to** 4. The detailed reason why this method
 155 works has been explained in our previous publication (Zhou *et al.*, 2016).

156 (3) Then the filtered intensity I_f^k of k^{th} pixel is defined as:

$$I_f^k = \begin{cases} 0, & \text{when } I_r^k \leq I_t \\ I_r^k - I_t & \text{when } I_r^k > I_t \end{cases} \quad 33 \setminus * \text{MERGEFORMAT } ()$$

158 Afterwards, the averaged filtered intensity I_F of i^{th} Laue pattern is obtained by
 159 averaging the filtered intensity of all the pixels in the Laue pattern:

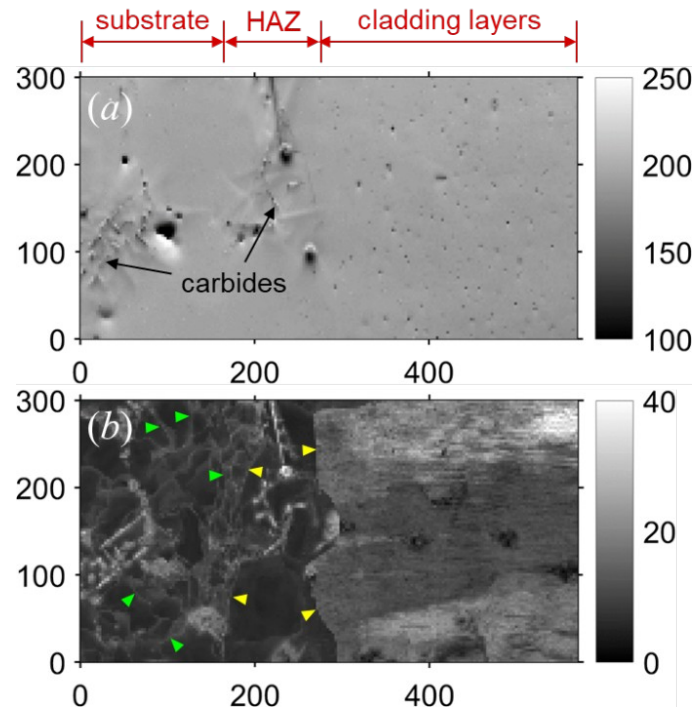
$$I_F = \frac{\sum_{k=1}^{n \times m} I_f^k}{n \times m}$$

44* MERGEFORMAT ()

160

161 (4) Finally, the average recorded intensity I_R and averaged filtered intensity
 162 I_F of all the Laue patterns are output as a *.txt file, which can be imported into
 163 XtalCAMP and visualized ~~by the as a~~ 2D map plot. The detailed import and plot
 164 operations are introduced in Section 3.2 and 3.3, respectively. Here an example
 165 is given to demonstrate how the microstructure features are studied from the
 166 maps of the average recorded and filtered intensities (Fig. 2).

167 ~~The lower-left corner of~~ Fig. 2b shows the averaged filtered intensity map of
 168 the Ni-based superalloy specimen. Due to the enrichment of heavy elements and
 169 sharp diffraction peaks, MC-type carbides (M = W, Ta, Ti) in the substrate and
 170 the HAZ give stronger intensity signals. Besides, some boundary features, which
 171 are identified as low angle grain boundaries (LAGBs) in section 3.5, are observed
 172 in the substrate as darker contrast, because of the peak splitting of the LPs
 173 collected in these regions. As for the completely recrystallized area in the heat
 174 affected zone (HAZ), the crystal orientation (and thus Laue peak indices and
 175 intensity) becomes significantly different from the substrate and the cladding
 176 layers, ~~and thus the Laue peak indices and intensity also in remarkable contrast,~~
 177 resulting through contrast in the clear visualization of high angle grain
 178 boundaries (HAGBs). The non-uniform contrast in the cladding layers is
 179 attributed to the local orientation gradient and microstructural defects. ~~It is~~
 180 ~~noticed~~ The that the contrast of both images can be adjusted by setting the range
 181 (minimum and maximum) of the grey scale values with proper values.

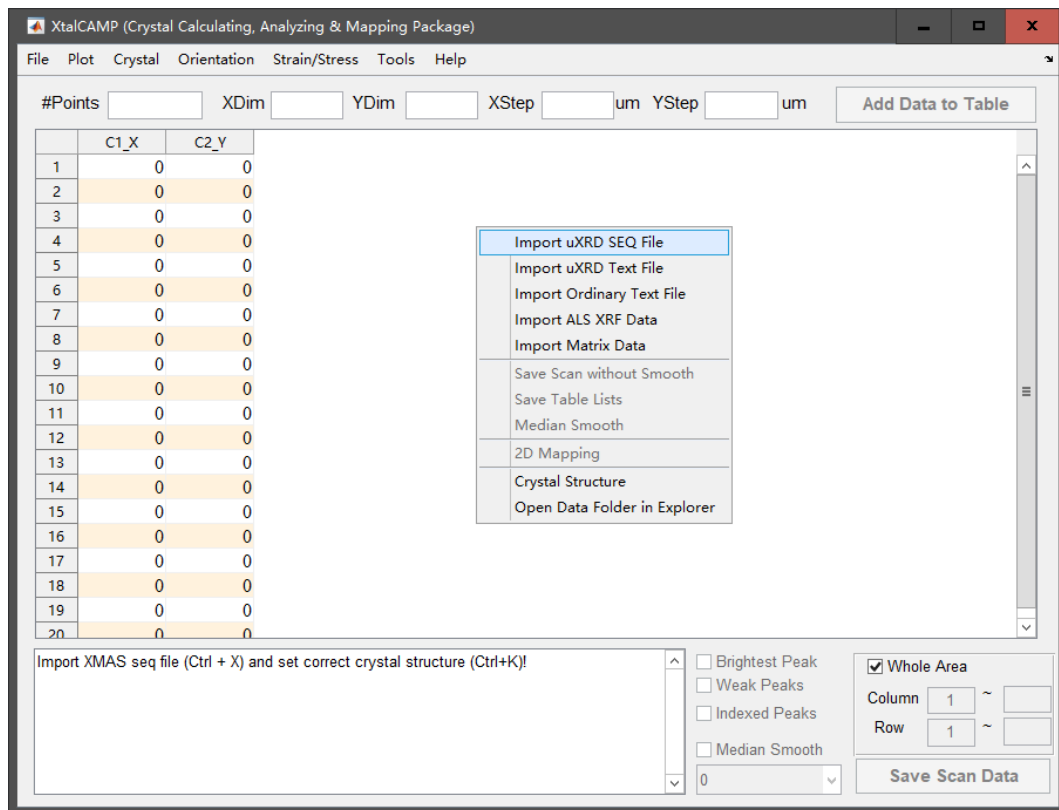


182

183 **Figure 2** The diffraction intensity maps collected before Laue pattern indexation. (a)
 184 Average recorded intensity map; (b) Average filtered intensity map is obtained by a
 185 default filtered factor 4. The LAGBs and HAGBs are denoted by green and yellow
 186 triangles, respectively.

187 **3.2. Data input**

188 The file input function is realized-achieved on the main window of XtalCAMP,
 189 as displayed in Fig. 3. The input data can be the μ XRD results, diffraction
 190 intensity analysis output, and other ASCII files such as fluorescence data which
 191 are usually collected when μ XRD experiments are performed. The μ XRD results
 192 are the most frequently used on XtalCAMP so we will take it as the example.
 193 They can be in either textthe *.txt format of the output matrix from the Laue
 194 pattern indexation software packages or the binary .seq file generated
 195 specifically by XMAS after automatically processing the thousands of Laue
 196 patterns collected in raster scan mode. After loading either format through "File"
 197 menu or right-click context menu, a table shows-upappears on the screen with
 198 the same number of rows as the-amount-of the LPs. Each row is a 156-column
 199 entry, including scan spot coordinates, pattern number, diffraction geometry
 200 parameters, orientation matrix values, strain/stress tensor components,
 201 equivalent strain/stress, average peak width, and so on, which then allows the
 202 construction of 2D maps denoting-of the distribution of a certain microstructural
 203 feature.



204

205

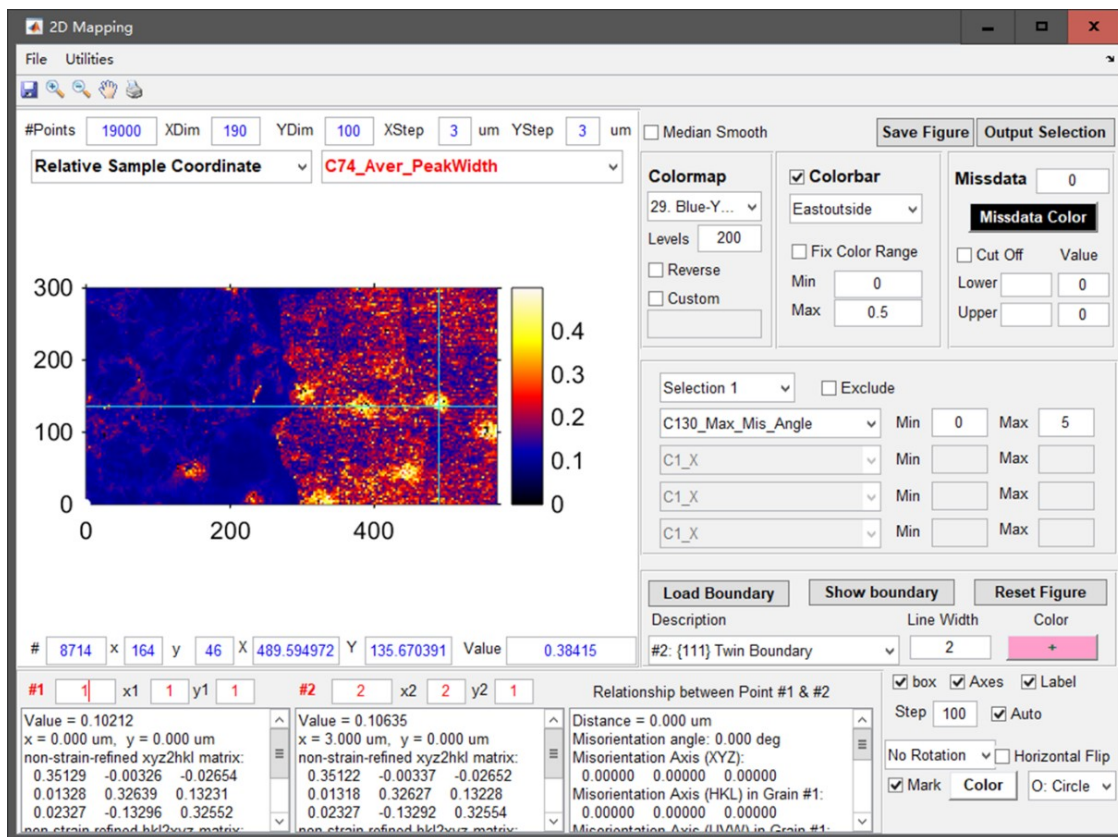
Figure 3 Main window of XtalCAMP with showing right-click options.

206 3.3. 2D color-coded mapping

207 As shown in Fig. 2, the X- and Y-coordinates of each scanning position are
 208 automatically calculated according to the scanning stage positions shown in the
 209 4th and 5th columns and by default displayed in the first two columns when the
 210 data are loaded into XtalCAMP, and then a certain aspect of microstructure
 211 characters at the location of rectangular grid sites can be visualized by plotting
 212 the 2D color-coded (including the grey scale) map using the corresponding
 213 column entry. On the 2D color-coded mapping interface, ~~plentiful-many~~
 214 are available to self-define the map appearance, such as ~~more than 40 kinds of~~
 215 color styles, ~~alterable~~-color range, not-indexed pixels visualized in different color
 216 from the colorbar, filter selections for data colored in the map, and axis label
 217 settings, etc. Moreover, data cursor is designed to read the pixel value from the
 218 map.

219 As shown in Fig. 4, the average peak width, which is the averaged FWHM of
 220 all Laue peaks indexed in a single Laue pattern, is taken as an example. As the
 221 peak width reflects the local dislocation concentration, the inhomogeneous
 222 distribution indicates a relatively larger population of dislocations stored in the
 223 cladding layers, in spite of the ~~disappeared-disappearance of~~ dendrite structure

224 after solution heat treatment.



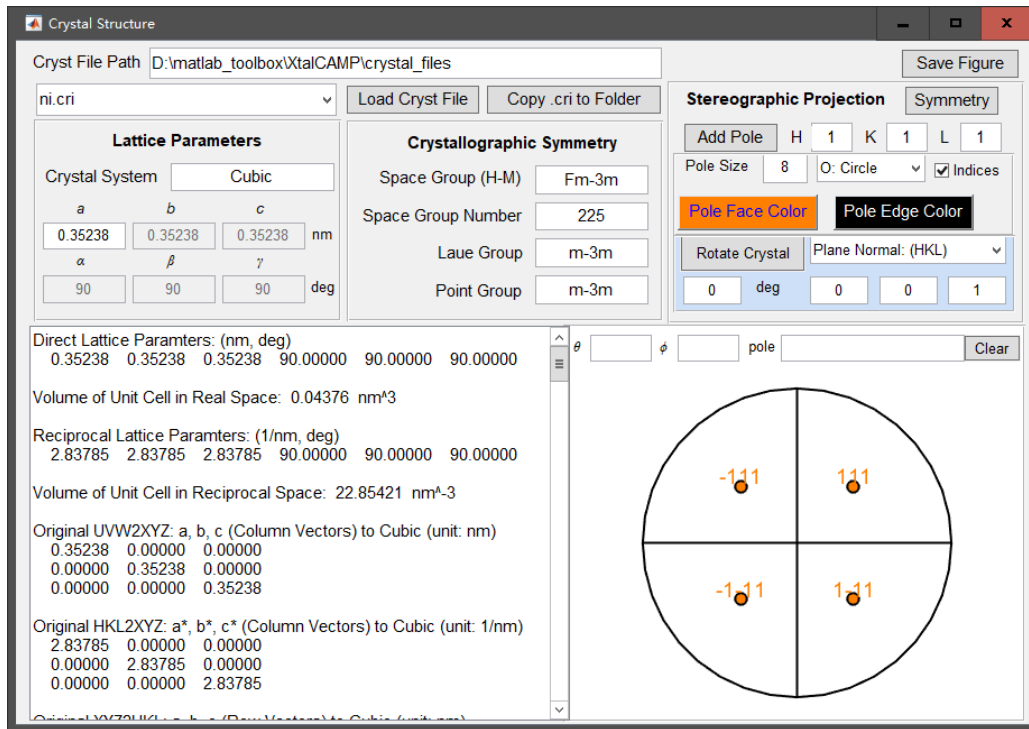
225

226

Figure 4 Snapshot of the 2D color-coded mapping interface.

227 3.4. Crystal selection

228 As no crystal information is contained in the *.seq file or other *.txt files, one
229 needs to pre-set the crystal structure for the crystal orientation/misorientation
230 analysis. In this case, one can access to the “Crystal” menu in the main window
231 (Fig. 3) and select the correct crystal file via the window shown in Fig. 5.
232 XtalCAMP supports both the standard crystallographic information file (*.cif) and
233 the crystal file (*.cri) defined by XMAS, from which the lattice and basis
234 information can be obtained. Both format can be converted to each other using
235 XtalCAMP. Once a certain crystal structure is selected, the space group and point
236 group annotations are displayed and the crystal symmetry is represented by the
237 stereographic projection of (001) pole center in the lower-right corner of Fig. 5.



238
239 **Figure 5** Crystal structure selection interface of XtalCAMP.

240 For crystallographic calculations (e.g. the angle between two crystal vectors)
241 in a certain (cubic or non-cubic) crystal structure, it is convenient to **build**
242 **up** define a Cartesian coordinate system $\mathbf{a}^\circ \mathbf{b}^\circ \mathbf{c}^\circ$, in which \mathbf{a}° , \mathbf{b}° , \mathbf{c}° are unit
243 vectors perpendicular to each other and adherent to the original crystal lattice
244 coordinate system \mathbf{abc} . Based on the common definition, the relationship
245 between the two coordinates follows (Matthies *et al.*, 1988):

246
$$\mathbf{c}^\circ \parallel \mathbf{c}, \mathbf{b}^\circ \parallel \mathbf{c} \times \mathbf{a}, \mathbf{a}^\circ \parallel \mathbf{b}^\circ \times \mathbf{c} \quad 55 \setminus * \text{MERGEFORMAT } ()$$

247 where the \times denotes the cross production of two vectors. Therefore, there exists
248 a coordinate transformation matrix \mathbf{L} (Liu & Liu, 2012):

249
$$\mathbf{L} = \begin{bmatrix} a \sin \beta & b(\cos \gamma - \cos \alpha \cos \beta) / \sin \beta & 0 \\ 0 & b \sqrt{1 - \cos^2 \alpha - \cos^2 \beta - \cos^2 \gamma + 2 \cos \alpha \cos \beta \cos \gamma} / \sin \beta & 0 \\ a \cos \beta & b \cos \alpha & c \end{bmatrix} \quad 66 \setminus *$$

250 MERGEFORMAT ()

251 where a , b , c , α , β and γ are lattice parameters. It is apparent that the
252 coordinates of lattice vectors \mathbf{a} , \mathbf{b} , \mathbf{c} are corresponding to the columns of \mathbf{L} .
253 Similarly, the rows of \mathbf{L}^{-1} (inverse matrix of \mathbf{L}) denote are the coordinates of
254 lattice vectors \mathbf{a}^* , \mathbf{b}^* , \mathbf{c}^* in reciprocal space, respectively. Therefore, the
255 arbitrary indices of a crystal direction or plane in the coordinate system \mathbf{abc} can

256 | be readily converted into the coordinate system $\mathbf{a}^\circ\mathbf{b}^\circ\mathbf{c}^\circ$ by using \mathbf{L} matrix, and
 257 | vice versa, where the conversion equations can be found in ref (He & Jonas,
 258 | 2007). Moreover, the determinants of \mathbf{L} and \mathbf{L}^{-1} represent the volumes of unit cell
 259 | in real and reciprocal spaces, respectively. As shown in Fig. 5, \mathbf{L} and \mathbf{L}^{-1} matrices
 260 | and other crystal information are displayed in the text box oin the lower-left
 261 | corner.

262 | 3.5. Orientation & misorientation analysis

263 | In XMAS *.seq file, the crystal orientation is represented by the $\mathbf{xyz2hkl}$
 264 | matrix, and its transpose matrix is denoted as \mathbf{G} , which describes the rigid
 265 | rotation from the Cartesian coordinate system $\mathbf{a}^\circ\mathbf{b}^\circ\mathbf{c}^\circ$ to the specimen coordinate
 266 | system \mathbf{xyz} by a rotational operation \mathbf{R} :

$$\mathbf{G} = \mathbf{xyz2hkl}^T = \mathbf{RL} = \begin{bmatrix} a_x & b_x & c_x \\ a_y & b_y & c_y \\ a_z & b_z & c_z \end{bmatrix}, \quad 77 \setminus * \text{MERGEFORMAT } ()$$

267 |
 268 | where the elements of \mathbf{G} matrix represent the projections of lattice vectors \mathbf{a} , \mathbf{b} ,
 269 | \mathbf{c} on the \mathbf{x} , \mathbf{y} and \mathbf{z} axes in the specimen coordinate system. The, and the \mathbf{R}
 270 | matrix is a pure rotation matrix, which is equivalent to a set of 3 Euler angles
 271 | widely adopted in the electron backscatter diffraction (EBSD) software. Similar to
 272 | transformation matrix \mathbf{L} , the vectors and Miller indices in coordinate system \mathbf{abc}
 273 | can be converted into coordinate system \mathbf{xyz} by using \mathbf{G} matrix, and vice versa.
 274 | The misorientation matrix \mathbf{M} between two crystal orientations \mathbf{G}_1 and \mathbf{G}_2 is
 275 | derived as

$$\mathbf{M} = \mathbf{G}_1\mathbf{G}_2^{-1} = \mathbf{R}_1\mathbf{L}\mathbf{L}^{-1}\mathbf{R}_2^{-1} = \mathbf{R}_1\mathbf{R}_2^{-1}, \quad 88 \setminus * \text{MERGEFORMAT } ()$$

276 |
 277 | where \mathbf{R}_1 and \mathbf{R}_2 are the corresponding rotation matrix of \mathbf{G}_1 and \mathbf{G}_2 , respectively.
 278 | The misorientation matrix \mathbf{M} is also a rotation matrix, which can be represented
 279 | as a misorientation angle-axis pair. By checking the misorientation between
 280 | adjacent scan spots, the boundary configurations, such as LAGB, twin boundary
 281 | (TB) and HAGB, in the scan area can be identified.

282 | In XtalCAMP, the boundary configurations are identified by calculating the
 283 | misorientation angle-axis pair between the current spot P with its right neighbor
 284 | P_r as well as $\{\theta_u, \mathbf{v}_u\}$ between P and its upper neighbor P_u , respectively and
 285 | sequentially (Fig. 6a). It is explained below to demonstrate theThe procedure on
 286 | how the boundaries are characterized (as schematically illustrated by Fig. 6b) is
 287 | explained below:

288 (1) A LAGB is formed if the misorientation angle θ_r is smaller than a threshold
289 angle ω_g (user-defined ~~while-but~~ commonly set as 15°), while the lower bound of
290 θ_r lacks rigorous definition and is usually dependent on the angular resolution.
291 For μ XRD technique, the lower bound of θ_r can be set as 0.1° , which is 100 times
292 larger than its angle resolution.

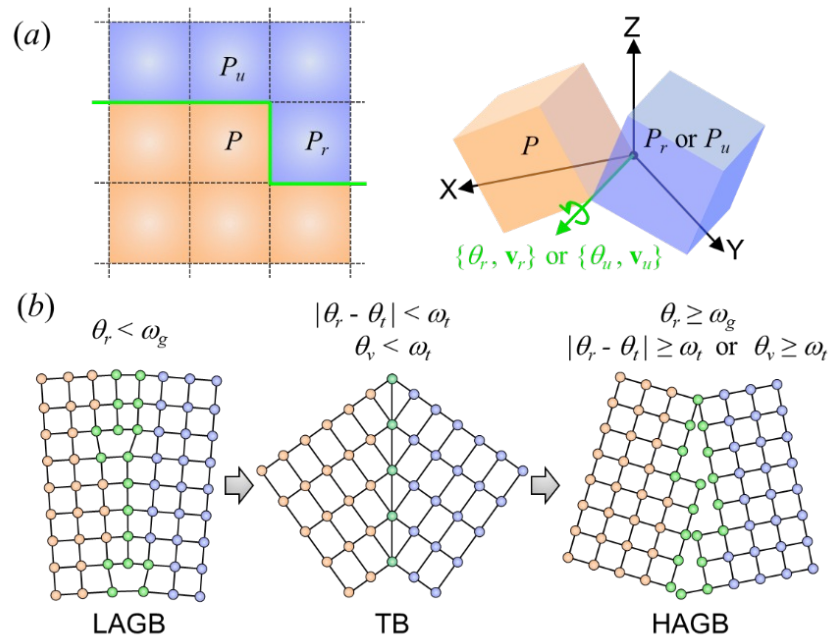
293 (2) If ~~the~~ misorientation angle θ_r is larger than ω_g , the boundary is
294 characterized as a HAGB, but in many cases it is of curiosity whether it is a
295 special boundary, such as TB, or an ordinary HAGB. We have reported a look-up
296 table based approach to ~~realize-achieve~~ this function (Li *et al.*, 2015). Firstly, a
297 look-up table which lists all the misorientation angle-axis pairs $\{\theta_t, \mathbf{v}_t\}$ is
298 established considering the given twin law (either plane or twin axis/angle) and
299 the rotational symmetry operations associated with the selected crystal
300 structure. Then the boundary is identified as a TB if the measured misorientation
301 meets the following two conditions simultaneously:

$$302 \quad |\theta_r - \theta_t| < \omega_{t1} \text{ and } \theta_v < \omega_{t2}, \quad 99 \backslash * \text{MERGEFORMAT } ()$$

303 where ω_{t1} and ω_{t2} are user defined threshold angles ~~compromising-taking into~~
304 ~~account~~ the inherent uncertainties of orientation measurement and plastic
305 deformation effect, and θ_v is the angle between \mathbf{v}_r and \mathbf{v}_t . Otherwise, if θ_r is larger
306 than ω_g and the conditions in equation Error: Reference source not found is not
307 satisfied, the boundary is identified as a HAGB.

308 (3) The same analysis procedure is repeated to check the boundary between
309 P and P_u .

310 By extending the process to the ~~whole-scan-spotsentire scan~~, the measured
311 misorientation angle-axis pairs and boundary information are output as two *.txt
312 files.



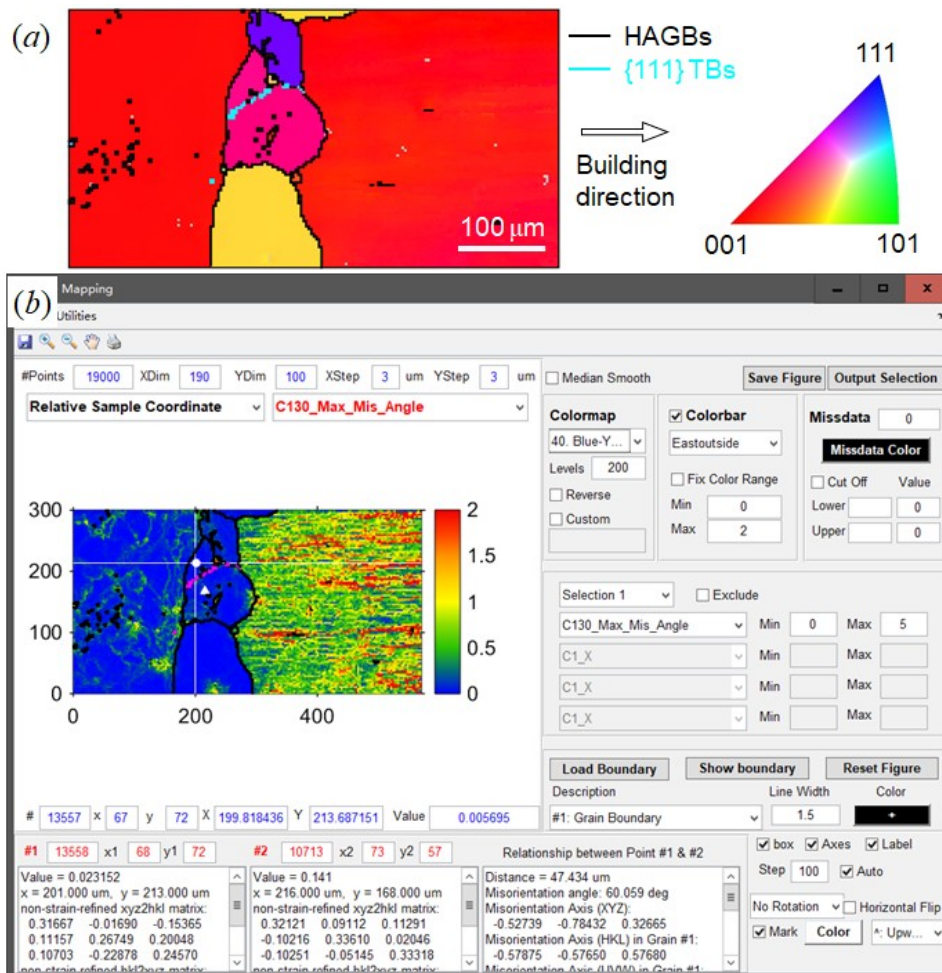
313

314 **Figure 6** Schematic illustration the grain boundary characterization algorithm. (a) Grain
 315 boundary determination strategy; (b) Schematic showing the LAGB, TB and HAGB.

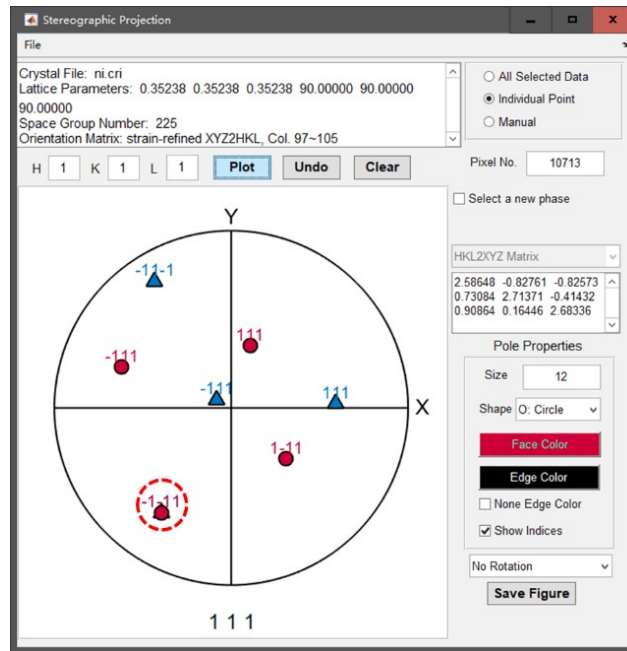
316 Here we also use the 3D-printed Ni-based superalloy data as an example.
 317 After re-loading the two *.txt files into XtalCAMP after boundary identification
 318 process, RGB inverse pole figure map (without showing the program interface)
 319 and misorientation map are plotted with TBs and HAGBs superimposed in
 320 different colors. As shown in Fig. 7(a), HAZ grains in different colors from the
 321 substrate and cladding layers, demonstrating the occurrence of recrystallization
 322 in the HAZ after solution heat treatment due to the large stored energy
 323 ~~contributed by from the~~ high density of dislocations (Chen *et al.*, 2020). It is
 324 observed in Fig. 7(b) that dislocation density becomes low and a {111} twin
 325 forms with the recrystallization. Besides, LAGBs in the substrate are consistent
 326 with the contrast found in the average filtered intensity map in Fig. 3(b), while
 327 more LAGBs with higher misorientation angles are detected in the cladding
 328 layers, consistent with previous study (Xue *et al.*, 2015).

329 It is convenient to read the orientation matrix using the data cursor in the 2D
 330 color-coded map. As seen in Fig. 7, by clicking the two grains next to the TB
 331 (marked by white circle and triangle in the figure, respectively), their orientation
 332 information is listed in the bottom textboxes, and the misorientation between
 333 them is automatically calculated and shown in the third textbox, which is close to
 334 $[60^\circ, [1\bar{1}1]]$, ~~elucidating validating our the validity of our~~ TB identification
 335 algorithm. The {111} twin relationship can be further confirmed from the {111}

336 pole figure, which is implemented on the interface shown in Fig. 8. The 111 poles
 337 of these two orientation are displayed in red and blue, respectively. The
 338 overlapped $\bar{1}\bar{1}\bar{1}$ poles of the two grains manifest-show that they share the same
 339 ($\bar{1}\bar{1}\bar{1}$) plane, which serves as the mirror plane between the twin and parent
 340 domains.



341
 342 **Figure 7** Orientation and misorientation map obtained by XtalCAMP. (a) RGB inverse pole
 343 figure map along building direction, which is rotated by 90° counter-clockwise. (b)
 344 2D color-coded mapping interface showing HAGBs (dark lines) and {111} TBs (pink lines)
 345 superimposed on the misorientation angle map.



346

347 **Figure 8** {111} stereographic projection of the two scan spots marked in Figure 7(b).

348

The overlapped poles are marked by the red circle.

349 3.6. Strain/stress analysis

350 For polychromatic X-ray Laue diffraction, the precise wavelength of each
 351 peak is unknown and the volumetric change of unit cell is thus indeterminable.
 352 However, the lattice distortion can be detected based on the hypothesis of
 353 constant volume of unit cell, and thus the deviatoric strain tensor ϵ_{ij} (3×3) can
 354 be measured accurately from the slight shift of Laue peak position relative to the
 355 unstrained crystal after crystal orientation is determined. By knowing thelf the
 356 stiffness tensor (6×6) tensor is known, the deviatoric stress tensor can be
 357 further calculated according to the generalized Hooke's law. The deviatoric
 358 strain/stress tensor components are contained in the output from the μ XRD data
 359 processing software file and can be visualized by aforementioned 2D color-coded
 360 mapping interface.

361 With respect to a strained/stressed crystal, there are three mutually
 362 perpendicular planes where the shear strain/stress components are 0 but only
 363 normal strain/stress components exist. The three normal strains/stresses are
 364 termed principal strains/stresses, and the corresponding strain/stress directions
 365 are normal to these three principal planes. Under the "Strain/Stress" menu in the
 366 main window of XtalCAMP (Fig. 3), the functionality to calculate the principal
 367 strains/stresses and their directions are stored as a *.txt file, which can also be
 368 re-loaded into XtalCAMP. The magnitudes and directions of principal strains of

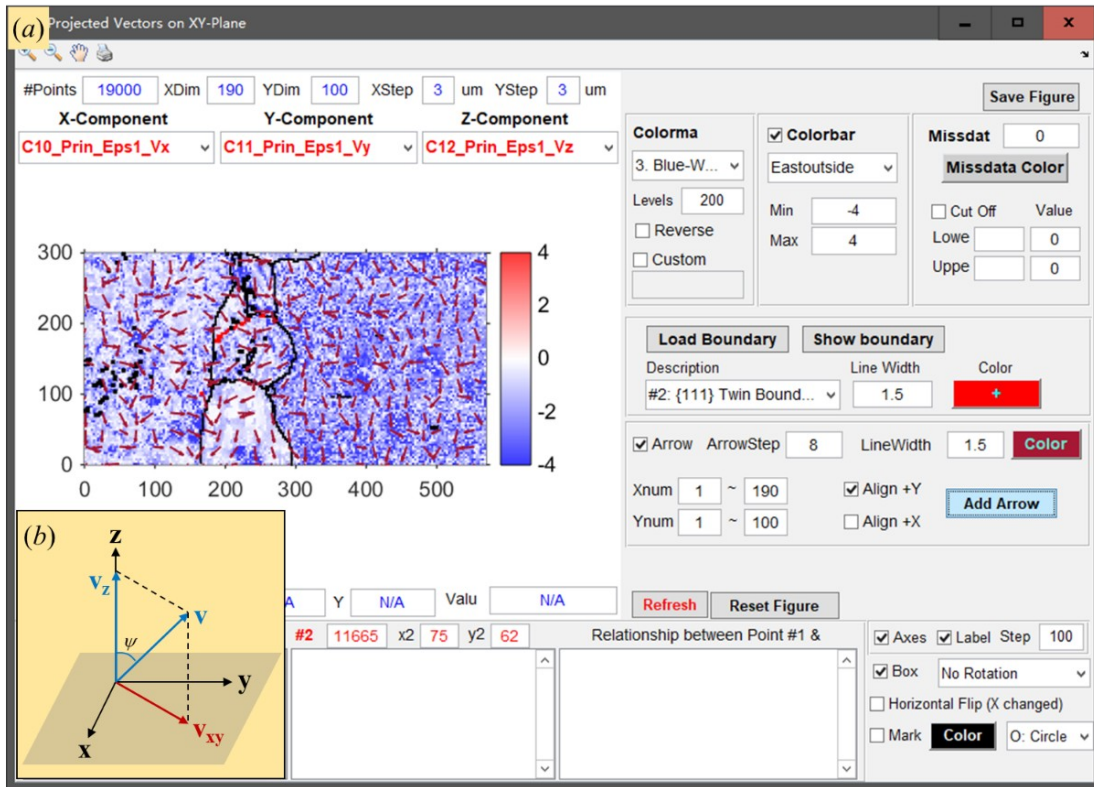
369 the 2nd rank strain tensors, expressed by symmetric 3 × 3 matrices, can be
 370 obtained by calculating the eigenvalues and eigenvectors (Noyan & Cohen,
 371 2013):

$$\boldsymbol{\varepsilon}_p = \begin{bmatrix} \varepsilon_{p1} & 0 & 0 \\ 0 & \varepsilon_{p2} & 0 \\ 0 & 0 & \varepsilon_{p3} \end{bmatrix} = \mathbf{T}^T \boldsymbol{\varepsilon}_j \mathbf{T} \quad , \quad 1010 \setminus * \text{MERGEFORMAT } ()$$

372
 373 where $\boldsymbol{\varepsilon}_p$ represents the principal strain tensor, ε_{p1} , ε_{p2} and ε_{p3} the three principal
 374 strains in ascending order, \mathbf{T} the rotation matrix composed of 3 column
 375 eigenvectors, and $\boldsymbol{\varepsilon}_j$ the deviatoric strain tensor. In the case of deviatoric strain
 376 tensor, the summation of ε_{p1} , ε_{p2} and ε_{p3} (trace of $\boldsymbol{\varepsilon}_p$) is 0, which means ε_{p1} is
 377 always compressive while ε_{p3} is always tensile (except when all components are
 378 0). This method and conclusion are valid for stresses as well.

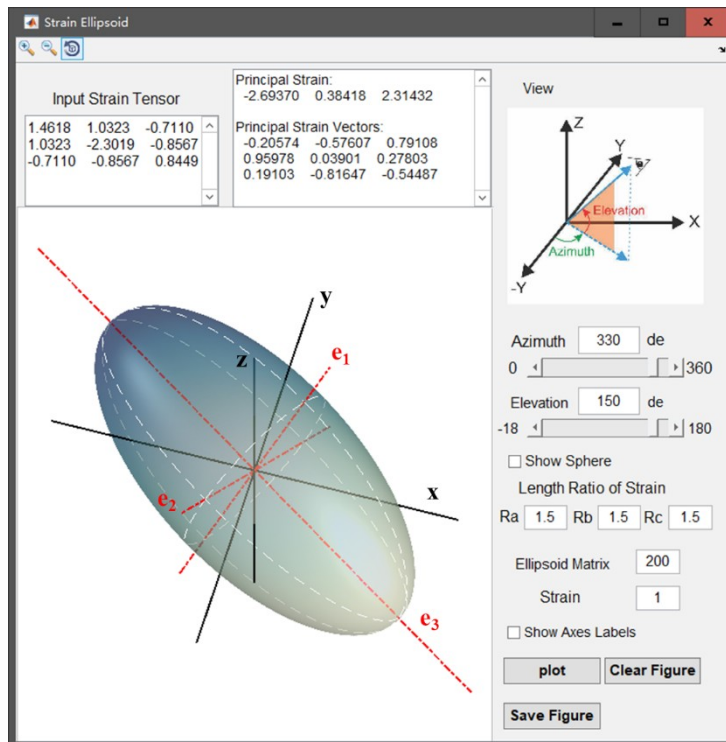
379 In order to show the magnitude and direction of principal strain
 380 simultaneously, the superimposition of strain direction projection on the 2D
 381 color-coded principal strain map is adopted, as seen in Fig. 9(a). As schematically
 382 displayed in Fig. 9(b), for the projection vector \mathbf{v}_{xy} of an arbitrary strain direction
 383 \mathbf{v} , the length of \mathbf{v}_{xy} can reflect the magnitude of z-component of \mathbf{v} . For an
 384 overview of the strain direction distribution, the \mathbf{v}_{xy} of every n^{th} (n is a user-
 385 defined viable which is 8 in this example) scan spot is denoted by the arrow. This
 386 approach has been successfully applied to explain the residual strain distribution
 387 in alloys and minerals (Li *et al.*, 2015; Chen *et al.*, 2016).

388 Additionally, strain ellipsoid is used to demonstrate the magnitude and
 389 orientation of the strain field. As seen in Fig. 10, \mathbf{e}_1 , \mathbf{e}_2 and \mathbf{e}_3 denote the
 390 principal strain directions and the dashed ellipses delineate the corresponding
 391 principal planes. It is clear that the rotation matrix \mathbf{T} in equation Error: Reference
 392 source not found represents the rotational operation between $\mathbf{e}_1\mathbf{e}_2\mathbf{e}_3$ coordinates
 393 to sample coordinates \mathbf{xyz} .



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Figure 9 The principal strain visualization interface. (a) The arrows denoting the compression strain axes direction superimposed on the magnitude distribution map of principal compression strain. (b) Schematic showing an arbitrary vector projected on the **xy**-plane.



398
399

Figure 10 Strain ellipsoid interface.

400 **3.7. Additional tools**

401 In addition to the functionalities introduced above, XtalCAMP also provides a
 402 ~~batch of many other~~ useful tools, which are straightforward to use, ~~as and~~ listed
 403 in Table 1.

404 **Table 1** Additional tools in XtalCAMP.

Applicati on	Crystallographic study	Orientation/ misorientation calculation	Data visualization
Tools	1. Equivalent directions and Miller indices; 2. Conversion between 3-digit indices to 4-digit indices in hexagonal lattice vector; 3. Angle between two vectors; 4. Conversion between plane indices and the plane normal direction; ...	1. Conversion of different orientation representations; 2. Misorientation between two xyz2hkl matrices by considering the rotational symmetry; 3. Construction of look-up table for twinning identification; ...	1. Contour plot; 2. 3D surface plot; 3. Inverse pole figure; 4. Misorientation profile along a line; 5. Frequency statistics of microstructural property ...

405 **4. Conclusions and future outlook**

406 We have described the major structure and functionalities of XtalCAMP, a GUI
 407 program dedicated to μ XRD data mining and visualization. More detailed
 408 information ~~it~~ can be obtained ~~by click from the~~ "Help" ~~menu~~ on the main
 409 interface.

410 XtalCAMP ~~is like to undergo continuous upgrade~~ ~~is continuously updated~~ and
 411 more functionalities will be added based on the suggestion ~~by of~~ users. Future
 412 additions to the software will include the following two aspects:

413 (1) Currently, Matlab needs to be installed before running XtalCAMP. To
 414 extend its application, executable files for Windows and Mac OS systems
 415 will be developed. After achieving this, only MATLAB Runtime ~~is will be~~
 416 required, which can be downloaded from the website
 417 (<https://mathworks.com/products/compiler/matlab-runtime.html>) free of
 418 charge.

419 (2) The μ XRD technique has been merging with other advanced
 420 crystals/materials characterization techniques such as EBSD and high
 421 resolution powder diffraction, μ XRD orientation measurements can be
 422 transformed into the data format compatible with EBSD data analysis
 423 software such as MTEX toolbox (Bachmann *et al.*, 2010) and other

424 crystallographic analysis programs such as BEARTEX (Wenk *et al.*, 1998).
425 The data formation conversion functionality will be introduced in
426 XtalCAMP and extend μ XRD techniques to more users.

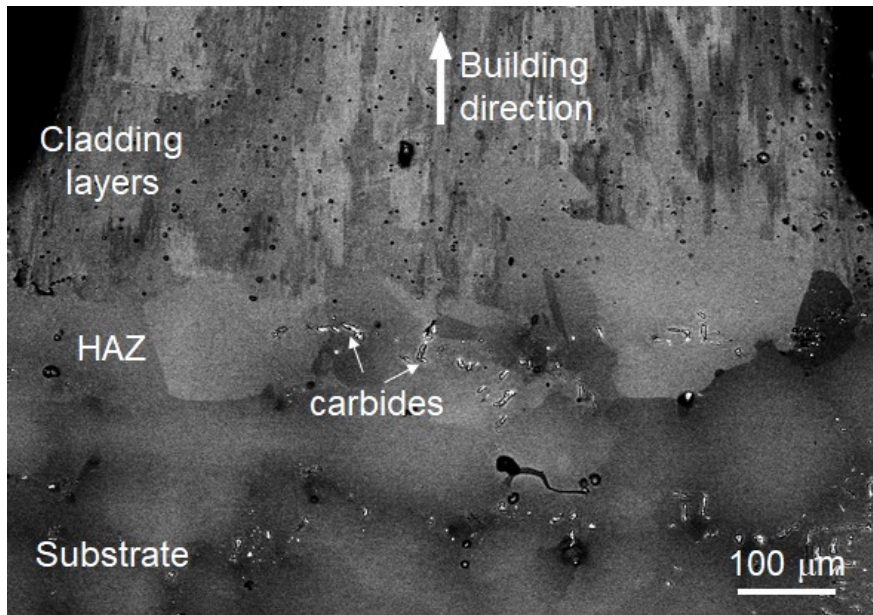
427 |

428 |

429 **Appendix A. Sample preparation and μ XRD experiment.**

430 The thin-wall Ni-based superalloy sample was 3D printed using an in-house
431 developed co-axial laser cladding apparatus equipped with a 1 kW Nd:YAG laser
432 source (Do *et al.*, 2013). The substrate was cut from a directionally solidified Ni-
433 based superalloy DZ125L ingot. The DZ125L powders, ~~in the diameter with~~
434 particle diameters ranging from 40 μm to 120 μm , were used as the feedstock
435 and deposited on the (001) plane of the substrate with a fixed laser power of 180
436 W and a scan rate of 10 mm/s protected with Ar atmosphere. The Ar gas carried
437 powders were injected into the melt pool at a feeding rate of $\sim 9 \text{ mm}^3/\text{s}$ and the
438 layer thickness was controlled about 100 μm . After post-processing solution heat
439 treatment at 1240 $^\circ\text{C}$ for 2 h, a slice in the thickness of $\sim 1.5 \text{ mm}$ was cut
440 longitudinally and investigated under the scanning electron microscopy (SEM) in
441 backscattered electron (BSE) mode (Fig. S1) after mechanical grinding and
442 electro-polishing.

443 The solutionized sample was then further examined with the synchrotron
444 Laue μ XRD experiment on beamline 12.3.2 at the Advanced Light Source in
445 Lawrence Berkeley National Laboratory (California, USA). The sample was
446 mounted 90° rotated around the surface normal with respect to the SEM image
447 on a high-precision XY-stage (so that the building direction is towards right), with
448 a 45° incline angle between the sample surface normal and incident X-ray beam.
449 By using the focused polychromatic X-ray beam in size of $\sim 1 \mu\text{m}$ with an energy
450 bandpass between 5 and 24 keV, a total number of 19000 Laue patterns were
451 collected using a 2D detector (Pilatus 1M, 1043×981 in pixels) from an area of
452 $570 \times 300 \mu\text{m}^2$, which covered the substrate, HAZ, and cladding layers, with 3
453 μm step size on the sample surface. Subsequently, all the Laue patterns were
454 sequentially indexed by XMAS software taking advantage of the newly developed
455 peak position comparison indexing algorithm.



456

457 **Figure S1** BSE SEM investigation on the laser 3D-printed Ni-based superalloy DZ125L
 458 after solution heat treatment.

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