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1 Causal Analysis in Control-Impact Ecological Studies with Observational Data

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11
12 *Abstract*

13 1: Randomized experiments have long been the gold standard in determining causal effects in
14 ecological control-impact studies. However, it may be difficult to address many ecologically and
15 policy-relevant control-impact questions-such as the effect of forest fragmentation or protected
16 areas on biodiversity-through experimental manipulation due to scale, costs and ethical
17 considerations. Yet, ecologists may still draw causal insights in observational control-impact
18 settings by exploiting research designs that approximate the experimental ideal.

19 2: Here we review the challenges of making causal inference in non-experimental control-impact
20 scenarios as well as a suite of statistical tools specifically designed to overcome such challenges.
21 These tools are widely used in fields where experimental research is more limited (i.e., medicine,
22 economics), and could be applied by ecologists across numerous sub-disciplines.

23 3: Using hypothetical examples, we discuss why bias is likely to plague observational control-
24 impact studies in ways that do not surface with experimental manipulations, why bias is
25 generally the barrier to causal inference, and different methods to overcome this bias.

26 4: Satellite-, survey- and citizen-science data hold great potential for advancing key questions in
27 ecology that would otherwise be prohibitive to pursue experimentally. However, to harness such
28 data to understand causal impacts of land, environmental and policy changes, we must expand
29 our toolset such that we can improve inference and more confidently advance ecological
30 understanding and science-informed policy.

31 Keywords: before-after-control-impact, causal analyses, econometrics

32 *Introduction*

33 The methodological gold standard in ecology, as in many scientific disciplines, is the
34 randomized control trial, also known as the control-impact experiment. The random assignment
35 of subjects (or sites) into treatment (or impact) and control groups with pre-determined treatment
36 levels has been used to uncover innumerable fundamental findings in ecology. For example,
37 common garden experiments seek to compare the effect of a fixed treatment (fertilizer
38 supplements, fungal inoculations, predator exclusions, genetic strains) using two or more groups
39 that are otherwise exposed to the same environmental conditions. Since we cannot observe the
40 exact same site both treated and not treated simultaneously, we must compare between sites to
41 identify the effect of treatment. The key to valid comparison is to assign treatments to sites at
42 random. In such randomized experiments, only the treatment should differ systematically
43 between treatment subjects and control subjects; this allows researchers to interpret the average
44 difference between treatment and control groups as the average causal effect of treatment at the
45 population-level.

46 Ecologists are increasingly interested in taking advantage of survey, remote-sensing and
47 citizen-science data to address ecologically and policy-relevant questions in systems that do not
48 easily lend themselves to experimental manipulation. For example, the placement of protected
49 areas is rarely under the control of the researcher and they are generally not randomly placed on
50 a landscape. In such cases, how can one identify the causal effect of protected areas on the
51 abundance of, say, an economically or ecologically important species? To do so, the researcher
52 must overcome the fundamental challenge present in non-experimental settings: the inability of
53 researchers to have full control over treatment assignment (i.e. protected and not protected sites),
54 which opens up the possibility that the outside forces that influence observed treatment are doing
55 so in a non-random manner. Naively applying regression, anova or other statistical approaches
56 without accounting for the non-experimental nature of observational data can lead to
57 inappropriate conclusions due to overlooked bias from improper comparisons between areas
58 chosen and not chosen for treatment. In other words, the common mantra of “correlation does
59 not imply causation” applies. However, not all is lost. Ecologists can establish causal inference
60 with observational data in a control-impact framework if we incorporate careful research design
61 and rigorous statistical approaches expressly designed for the purpose.

62 Here we discuss the challenge and promise of inferring causality from non-experimental
63 data in control-impacts studies. We begin by discussing frameworks for causal inference. We
64 then expand on the nature of why observational data present specific challenges not encountered
65 in randomized experiments, which provides paths forward. To that end, we review several
66 statistical approaches often associated with econometrics that can potentially overcome bias in
67 control-impact analyses with observational data. To the extent possible, we seek to build
68 intuition rather than to delve into the technical details. We use hypothetical examples to do so,

69 since few real data sets are amenable to all methods discussed and the true population parameter
70 is indiscernible in real data.

71 *Frameworks of Causal Inference*

72 In control-impact studies, causal inference is achieved through explicit comparison across
73 units that are treated and units that serve as controls. In such settings, the key concept is that of a
74 counterfactual: what would outcomes for the treated units look like in the absence of the
75 treatment? If control units differ from treated units in the absence of the treatment, then a causal
76 interpretation is not feasible.

77 There are several different frameworks for conceptualizing causal relationships in order
78 to facilitate causal inference. Two of the most well-known are Pearl's structural causal model
79 (SCM; Pearl 2000, 2010) and Rubin's potential outcomes model (PO; Rubin 2005). SCM is a
80 powerful framework for assessing causal relationships between variables. It integrates nonlinear
81 structural equation modeling (SEM), graphical representation of causal pathways, and potential
82 outcomes analysis (Pearl 2010). SEM, first developed in the early decades of the 20th century
83 (Wright 1921), has been used in ecological systems to generate and test complex hypotheses
84 about direct and indirect species interactions and system processes (Grace *et al.* 2010; Fan *et al.*
85 2016). SCM extended SEM to more flexible distributional assumptions, and links the equations
86 embodied in the causal diagram (or directed acyclic graph, DAG) to the concept of
87 counterfactuals.

88 In contrast, the PO framework is based on a notion of causality which places an emphasis
89 on what researchers can and cannot observe, and an emphasis on isolating the effect of usually a
90 single explanatory variable of interest (i.e. treatment variable) on a single outcome rather than on
91 disentangling complex relationships within a network. Thus, PO is a particularly amenable

92 framework for conceptualizing randomized and non-randomized control-impact studies. A
93 specific insight illustrated by the PO framework is that causal interpretations are stymied by the
94 fundamental truth that a subject cannot be both treated and not treated simultaneously (Holland
95 1986). As we will see below, randomization allows for the estimation of an average treatment
96 effect in the population, while the absence of randomization requires additional understanding of
97 the data-generating mechanism to develop a credible comparison. While part of the richness of
98 SCM is the development of a new mathematical language describing causal relationships
99 without reliance on probability math, it is not our goal to summarize this for ecologists. We point
100 the interested reader to Pearl (2010). Our goals are to first illustrate why statistical bias presents a
101 particular challenge for observational studies and then introduce some practical tools from
102 econometrics to improve causal inference in observational control-impact studies. As such, we
103 build on the potential outcomes framework as a simple way to relate to ecology's foundations in
104 randomized experiments. Nonetheless, bias can also be described using the mathematical and
105 graphical representations of SCM, which we include in our illustrations. Finally, we emphasize
106 that by employing the specific control-impact notion of causality, this review will not cover the
107 notion of causality found in coupled dynamical systems, such as those pertaining to models of
108 coupled predator-prey interactions. That notion of causality, sometimes referred to as "Granger"
109 causality (Granger 1969) in time-series econometrics and recently advanced for nonlinear
110 dynamical settings (Sugihara *et al.* 2012), examines how several interacting time series variables
111 may be coupled over time. Because our aim is to inform research in control-impact studies, this
112 review will exclude this dynamical notion of causality.

113 *Potential Outcomes Framework*

114 To be concrete, take for example, a study that is interested in estimating the effect of
115 forest thinning (e.g. through US Forest Service Collaborative Forest Landscape Restoration
116 Program) on songbird abundance. Which forest stands are chosen for thinning treatment is not
117 under the manipulation of the researcher where treatment and control sites could be assigned
118 randomly at precisely known levels of treatment. Rather, as is common with observational data,
119 the decision of where to thin is likely determined by a tangle of possibly unknown or unobserved
120 environmental (e.g. climate, soil), social (e.g. land values) and policy factors that cannot be
121 manipulated by the researcher. As such, here and throughout we model the treatment as a
122 random, rather than fixed, variable. The implication of this distinction will become clear later on
123 (see *Treatment as a Random Variable* below).

124 The US Forest Service's priorities often include improving ecosystem function and
125 reducing fire risk, and thus we can imagine that more degraded sites or sites closer to human
126 habitation are more likely to be given resources than intact forests far from the Wildland-Urban
127 Interface. In that case, a survey of songbird abundance across thinned and unthinned sites is
128 likely to find lower mean songbird abundance in thinned sites. A similar result might occur if
129 there were different levels of thinning treatments based on proximity to surrounding
130 development or fire risk. In both scenarios, we would be remiss to conclude that thinning reduces
131 songbird abundance based on a simple comparison of means because sites chosen for treatment
132 (or sites chosen for higher levels of treatment) differed systematically from those not chosen (or
133 those chosen for lower levels of treatment). This systematic difference between the sites assigned
134 treatment (or different treatment levels) results in inaccurate estimation of the effect of treatment.
135 More formally, the mean or expected value of the estimated effect of the treatment, $E[\hat{\beta}]$, is
136 different from the true value, β . This is known as statistical bias. The challenge is therefore

137 overcoming bias stemming from non-random treatment assignment so we can isolate the effect
138 of the treatment on bird abundance.

139 For simplicity we start by formalizing the above scenario with a binary treatment
140 (thinned, unthinned forest stands). For any site, there are two outcomes that can potentially be
141 observed—songbird abundance if the site was selected for the thinning treatment and songbird
142 abundance if the site was not selected for the thinning treatment. Formally,

$$143 \quad \text{Potential outcome} = \begin{cases} Y_{1i} & \text{if } T_i = 1 \\ Y_{0i} & \text{if } T_i = 0 \end{cases} \quad (1)$$

144 where Y_{0i} is songbird abundance in site i had that site not been chosen for treatment ($T_i = 0$),
145 and Y_{1i} is songbird abundance in site i had it been chosen ($T_i = 1$)¹. The observed outcome Y_i
146 can be related to the potential outcomes by,

$$147 \quad Y_i = Y_{0i} + (Y_{1i} - Y_{0i})T_i. \quad (2)$$

148 The causal effect of thinning for site i is $Y_{1i} - Y_{0i}$. For many empirical applications, the
149 question of interest, or estimand, is the population average treatment effect (ATE). Let $E[\cdot]$
150 represent the expectation operator, or the population mean of a random variable. By the law of
151 large numbers, the sample mean converges to the population mean so $E[\cdot]$ can also be thought of
152 as the sample average in very large samples. The ATE can be written as

$$153 \quad \beta = E[Y_{1i}] - E[Y_{0i}] = \left(\frac{1}{N}\right) \sum_{i=1}^N (Y_{1i} - Y_{0i}) \quad (3)$$

154 where N is the population size. β is the causal effect we would like to be able to estimate if it
155 were possible to observe, for every site i , its outcome both when it is thinned (Y_{1i}) and when it is

¹ The formal notation for potential outcomes was introduced by Neyman (1923, translated and reprinted in 1990) in the context of randomized experiments. It wasn't until the work of Rubin (1974) that the potential outcomes framework was considered for observational data settings. The term "Rubin Causal Model" first appears in Holland (1986).

156 not thinned (Y_{0i}). Since this is impossible, we must learn about the effect of forest thinning
157 through comparisons across untreated units that can serve as valid counterfactuals.

158 If we took the simple observed differences in mean songbird abundance between treated
159 and untreated sites, we may capture more than we intended. The simple difference in means
160 between sites that were and were not treated is equivalent to

$$\begin{aligned} 161 & E[Y_i|T_i = 1] - E[Y_i|T_i = 0] \\ 162 & = E[Y_{1i}|T_i = 1] - E[Y_{0i}|T_i = 0] \\ 163 & = \underbrace{E[Y_{1i}|T_i = 1] - E[Y_{0i}|T_i = 1]}_{\text{Average treatment effect on the treated (ATT)}} + \underbrace{E[Y_{0i}|T_i = 1] - E[Y_{0i}|T_i = 0]}_{\text{Selection bias}}. \end{aligned} \quad (4)$$

164

165 The first composite term on the right-hand side of equation (4) represents the average
166 effect of treatment on sites that were thinned (“average treatment on the treated”, ATT). The
167 second term captures the systematic difference between sites that are and are not treated in the
168 absence of treatment (e.g., if the thinning program was cancelled after site selection but before
169 thinning occurred, would average bird abundance differ between selected and not selected
170 sites?). Thus, the second term captures the “selection” bias stemming from non-random
171 treatment assignment. Selection bias would arise if sites chosen for thinning were less isolated or
172 otherwise in less pristine condition than sites not chosen. In that situation the estimated effect of
173 thinning would capture both the true effect of the thinning treatment on bird abundance and the
174 pre-treatment difference in site quality. Quasi-experimental approaches including BACI designs
175 seek to remove selection bias so we can isolate the causal effect of the treatment from observed
176 differences in outcomes between treatment and control groups.

177 *A key assumption*

178 Regardless of whether treatment is randomly assigned, deriving causal inference based on
179 counterfactuals invokes the assumption that there is no treatment spillover or interference
180 between sites. This is known as the Stable Unit Treatment Value Assumption (SUTVA; Rubin
181 1980; 2005). SUTVA also assumes there are not different versions of the same treatment. This
182 would be violated if, for example, some sites are only treated on paper, but action never happens
183 on the ground.

184 SUTVA is required for potential outcomes to be well defined and is built into the
185 potential outcomes definition in equation (1). However, one can envision conditions in
186 ecological systems that violate SUTVA. For example, if population growth in a non-treated site
187 is so high that there is net dispersal away from the site and into a treatment site, there would be
188 treatment spillover, which would obfuscate the effect of the treatment alone. Treatment spillover
189 would generally occur with spatial dependence between outcomes, where treatment of one site
190 *caused* higher abundance at a nearby site. However, spatial correlation of the standard errors (a
191 common feature of ecological data) would not violate SUTVA.

192 At first glance, SUTVA seems overly restrictive. However, studies can often be designed
193 such that SUTVA is reasonable. For example, researchers can aggregate to larger units (e.g.
194 individual to population, patch to landscape; Imbens & Wooldridge 2009). Lack of interference
195 between observations underlies many statistical analyses trying to ascertain treatment effects in
196 randomized trials as well as observation studies. If one is to relax SUTVA, additional
197 information is needed to specify the exact extent and intensity of interactions across individuals
198 (e.g. Deschenes and Meng, 2018). This is an active area of research (e.g. Manski 2013).

199 *Randomized Experiments*

200 If we are willing to make the SUTVA, causal inference becomes a problem associated
201 with assignment of treatment. If treatment status, T_i , is independent of potential outcomes as it
202 theoretically would be in a random experiment, the second composite term of equation (4) drops
203 out since $E[Y_{0i}|T_i = 0] = E[Y_{0i}|T_i = 1]$. Further, the conditional expectation simplifies to the
204 unconditional expectation in the first term, $E[Y_{1i}|T_i = 1] - E[Y_{0i}|T_i = 1] = E[Y_{1i}] - E[Y_{0i}]$
205 because potential outcomes are independent of treatment status ($Y_{1i}, Y_{0i} \perp T_i$, where \perp denotes
206 statistical independence). Thus, the simple difference in population means, the left-hand side of
207 equation (4), is equal to ATE, equation (3), if treatment status is randomly assigned. This
208 highlights why experimental manipulations are the gold standard for causal inference. Replacing
209 the population means with the corresponding sample analogs results in a consistent estimate of
210 the ATE.

211 In observational analyses, we must remove selection bias associated with non-random
212 assignment of treatment as bias precludes the identification of causal relationships. How we do
213 so depends on what we know about how treatment is assigned and whether we can observe
214 relevant covariates that determine treatment assignment. Below we transition from potential
215 outcomes to regression, and from there to different regression-based methods for deriving
216 causality for treatment selection based on observable and unobservable characteristics. See SI for
217 example code and table 1 for a summary of data requirements and key assumptions for each
218 method.

219 *Regression Analysis*

220 Equation (2) can be rewritten in terms of a regression model. To build intuition in the
221 most straightforward manner, we omit covariates for now. For simplicity, we also assume that

222 treated sites respond the same way to thinning (i.e. constant treatment effects) and the model is
223 linear in parameters. In this case, we can write equation (2) as,

$$224 \quad Y_i = \alpha + \beta T_i + \varepsilon_i, \quad (5)$$

225 where $\alpha = E[Y_{0i}]$, $\beta = Y_{1i} - Y_{0i}$ is the treatment effect, and ε_i is the site-specific random error
226 term.

227 Evaluating equation (5) for treated and untreated sites yields,

$$228 \quad E[Y_i|T_i = 1] - E[Y_i|T_i = 0] =$$
$$229 \quad = (\alpha + \beta + E[\varepsilon_i|T_i = 1]) - (\alpha + E[\varepsilon_i|T_i = 0]) \quad (6)$$

$$230 \quad = \beta + E[\varepsilon_i|T_i = 1] - E[\varepsilon_i|T_i = 0] \quad (7)$$

231 This illustrates that the bias that prevents us from isolating the causal effect (β) from the
232 simple difference in the treatment and control sites ($E[Y_i|T_i = 1] - E[Y_i|T_i = 0]$) stems from a
233 correlation of the treatment with the error term. In other words, if the site-specific, random error
234 term were not related to treatment status, $E[\varepsilon_i|T_i = 1] = E[\varepsilon_i|T_i = 0]$, the average treatment
235 effect, β , is all that remains. Though we used the population regression for ease of illustration, by
236 the law of large numbers, the sample regression coefficients are a consistent estimate of the
237 population coefficients.

238 *Treatment as a Random Variable*

239 It is worth noting that throughout, we have been considering the treatment as a random,
240 rather than a fixed, variable. This distinction, which is less essential in the context of randomized
241 experiments, is the basis for why bias may arise in observational data settings.

242 In theory, a randomized experiment enables the researcher to fully manipulate which
243 units are assigned to treatment or control, and for non-binary treatments, to determine the
244 specific levels of treatment. The ability to fully manipulate treatment means that the researcher

245 may be willing to assume, as Sokal & Rohlf (2012) describe in their seminal Biometry text (p
246 475), “the independent variable X is measured without error. We therefore say that the X ’s are
247 “fixed,” which means that whereas the dependent variable Y is a random variable, X does not
248 vary at random, but rather is under the control of the investigator”. If X is assumed to be fixed,
249 the correlation between the treatment variable and the error that we have been discussing at
250 length is zero, by assumption². This point is not often emphasized because in a perfectly
251 executed randomized experiment, treatment (as a random variable) is uncorrelated with the
252 errors anyway. Of course, in practice, assuming X is obtained without error may not hold due to
253 naturally occurring variation, and randomization may not inherently provide bias-free estimates
254 if randomization is incomplete (e.g. due to unknown individual variation in study units).

255 Yet, in observational data there is a clear distinction with regard to the treatment variable.
256 By definition, treatment (e.g. location and extent of deforestation, protected areas, hunting
257 pressure etc.) is determined by “outside” and potentially unknown forces that are beyond a
258 researcher’s control. Treating explanatory variables as random variables acknowledges the
259 possibility of a correlation between the treatment variable and the unmodeled determinants of the
260 outcome (i.e. model errors), and thus various sources of bias that preclude causal interpretations
261 of correlations. We next discuss these sources of bias before turning to various research designs
262 that potentially enable causal inference with observational data.

263 *Sources of Bias*

² Mathematically, this stems from the “exogeneity assumption” required for unbiased estimators. Exogeneity implies zero correlation between the treatment and the true model error, $E[T_i \varepsilon_i] = 0$. If treatment is considered fixed, it can be removed from the expectation such that $E[T_i \varepsilon_i] = T_i * E[\varepsilon_i]$. Since the latter term equals zero by assumption, assuming treatment is fixed implicitly assumes away any potential correlation between the explanatory variables and the error term, and thus the possibility of many forms of statistical bias.

264 Bias implies that the expected value of the sample estimator does not reflect the true
265 population parameter, $E[\hat{\beta}] \neq \beta$ (Fig. 1a). While the correlation between the hypothetical model
266 errors and treatment ($E[T_i \varepsilon_i] \neq 0$) is broadly referred to as **endogeneity bias**, there are a couple
267 of specific scenarios that are widely observed in observational studies.

268 Any covariate that is excluded from the model ends up in the error term. Thus, any
269 variable that is correlated with the treatment and drives the outcome would result in a correlation
270 between the errors and the treatment if not explicitly included in the model. For example, if
271 forest stand age was correlated with the treatment (e.g. thinning) and bird abundance (e.g.
272 through habitat availability), omitting forest age as a covariate would induce a correlation
273 between the errors and the treatment and result in a biased estimator of the effect of thinning on
274 bird abundance due to the **selection bias** problem illustrated earlier (which is also referred to as
275 omitted variable bias and can be illustrated via a DAG, fig. 2). This contrasts with variables that
276 drive the outcome but are not correlated with the treatment. Failing to control for these variables
277 adds noise (i.e. increases the standard error of the parameter estimate) but does bias regression
278 coefficients.

279 The second major source of endogeneity bias occurs when there is a feedback between
280 the outcome variable back to explanatory variables, known as **reverse causality**. In other words,
281 if thinned sites were chosen to avoid areas with high bird abundance, then abundance drives
282 thinning and thinning drives abundance. In this case, it is impossible to estimate either
283 directional relationship without addressing the feedback because of the induced correlation
284 between the errors and the treatment going in either direction (bird abundance \rightarrow thinning,
285 thinning \rightarrow bird abundance).

286 Lastly, a persistent challenge for observational studies is the presence of **measurement**
287 **error** in the explanatory variables. While measurement error of the outcome variable results in
288 noise, it does not cause bias unless the measurement error is correlated with the explanatory
289 variables. In contrast, measurement error in the explanatory variables causes what is known as
290 Classical Errors-in-Variables, which biases the slope estimates towards zero.

291 *Methodological Approaches*

292 This section details five empirical approaches that, under different statistical assumptions, enable
293 causal interpretations when examining observational data.

294 1. Difference-in-Difference (DiD): In the absence of experimental manipulation, it is difficult to
295 parse apart the effect of the treatment from background changes in environmental conditions.

296 Luckily, many survey data sources are collected over multiple years. When “panel” (or
297 “longitudinal”) data are available, the analyst can sometimes leverage repeated observations over
298 time to address bias due to omitted, time invariant confounders.

299 Like BACI paired (Stewart-Oaten et al. 1986), DiD is a paired design where treatment
300 and control sites are observed at the same time before and after the treatment occurs (Angrist &
301 Pischke 2009). We introduce the basic DiD despite its similarities to BACI to introduce readers
302 to another methodological literature and as an entryway to the panel data models discussed
303 below.

304 With repeated observations of the same groups over time a DiD is estimated using the
305 below model,

$$306 \quad Y_{igt} = \alpha + \delta_1 treat_g + \delta_2 after_t + \beta(treat_g * after_t) + \varepsilon_{igt} \quad (8)$$

307 where i denotes an individual observation, g denotes group, and t denotes the time period. Here
308 “treat” is a dummy variable that is equal to one for sites that eventually received treatment

309 (treatment group) and “after” is a dummy variable that is equal to one “after” the treatment
310 occurs. By conditioning on these dummy variables in an ordinary least squares (OLS)
311 framework, the average differences between treatment and control (before treatment) and
312 average differences between pre-treatment control sites and post-treatment control sites are
313 removed. Thus, the coefficient on the interaction term, β , indicates the change in outcome due to
314 the treatment after differencing away persistent difference between groups and shared time
315 trends. Normality of the errors is not required for OLS to be unbiased. While the basic model
316 could be estimated with a repeated measure ANOVA if normality of the errors is assumed, a
317 regression approach is advantageous with complex models, missing or unbalanced data, and
318 when assuming normality or homoscedasticity of the errors is overly restrictive.

319 The simplest setup is when outcomes are observed in two periods for both groups where
320 one group’s treatment status changes from the first period to the next. However, the fundamental
321 assumption of DiD (and other BACI designs) is that if not for the treatment, the two groups
322 would have parallel time trends (Angrist & Pischke 2009). As an indirect test of this assumption,
323 one can see if there are common time trends across groups before the treatment by using
324 additional pre-treatment time periods, when available. DiD can be extended to include
325 covariates, different timing of treatment (“staggered” DiD) and an additional control group
326 (“triple difference”).

327 2. Within-estimator Panel Data Model: The within-estimator panel data model is a generalization
328 of DiD models to multiple groups and time periods.

329 Let us say we are again interested in song bird abundance, but this time as a function of
330 forest fragmentation. With repeated observation of the same sites over time, we can exploit year-
331 to-year deviations from the mean forest fragmentation of a site to estimate how fragmentation

332 affects bird abundance, under certain conditions, even if we do not have measurements of all the
333 covariates.

334 The within-estimator (also called the least-squares dummy variable model) is often and
335 confusingly termed a “fixed effects” panel data model, but we continue with “within-estimator”
336 to avoid confusion with “fixed effects”, as defined in biostatistics (i.e. a non-random variable).
337 The within-estimator model could be represented as follows,

$$338 \quad Y_{it} = \alpha + \beta \text{Fragmentation}_{it} + c_i + \gamma_t + \varepsilon_{it} \quad (9)$$

339 where Y_{it} indicates bird abundance in site i and time t , α is the intercept, β is the coefficient of
340 interest, and ε_{it} is the random error term. As elsewhere in this manuscript, we ignore covariates
341 for notational convenience.

342 Here c_i represents unobserved heterogeneity that is unique to each site i but time
343 invariant over the study period (e.g. climate, soil quality) and γ_t represents unobserved
344 heterogeneity that is unique to each year (e.g. weather, technology) that is shared by all sites. If
345 either c_i or γ_t is ignored, it ends up in the error term, potentially creating endogeneity as
346 described above. Ecologists are familiar with using site or year random effects in mixed effects
347 models. Random effects models, such as random intercept models, assume that the unobserved
348 site- or year-specific heterogeneity is uncorrelated with the treatment (Wooldridge 2002). In
349 many cases this is a strong assumption. For example, climate, soil quality, proximity to urban
350 centers are all likely to be correlated with fragmentation. If these variables were measured and
351 included directly, there would be no issue. However, if they are not, a site random effect would
352 not avoid omitted variable bias because, although the correlation of observations at the same site
353 is modeled, the correlation between covariate (fragmentation) and the error term is not removed.
354 Instead, the within-estimator can be used. The effect of the within-estimator is that observations

355 are differenced from their site-specific mean and thus identified by “within” site (or year)
356 variation. If the site-specific (time-specific) unobserved heterogeneity is correlated with
357 fragmentation does not matter because it is effectively removed from the model in the
358 differencing. In the case where the site-specific (time-specific) heterogeneity was indeed
359 uncorrelated with the covariates (the random effects assumption), the within-estimator would
360 remain unbiased but would be less statistically efficient, or in other words have a larger variance,
361 than the random effects estimator (Fig. 1). However, if the site-specific (time-specific)
362 heterogeneity was correlated with the observed covariates, only the within-estimator model
363 would remain unbiased. Though we only discuss site and year above, the same logic and applies
364 to other group characteristics as well. We point the reader to Larsen & Noack (2017) for an
365 example of using the within-estimator to understand how crop diversity affects agricultural
366 pesticide use, after controlling for year-specific, crop-specific and region-specific unobserved
367 heterogeneity.

368 3. Instrumental Variables: The within-estimator requires panel data and generally does not solve
369 reverse causality bias (Table S1; for an exception see Larsen *et al.* 2014). However, the
370 instrumental variables (IV) approach can jointly solve selection bias, measurement error, and
371 reverse causality, provided certain assumptions are met. To isolate causal effects of a treatment
372 on an outcome, the IV approach requires the researcher to select an “instrument” that (1) is
373 sufficiently correlated with the endogenous treatment variable and (2) does not affect other
374 determinants of the outcome (i.e. does not belong in the main regression). These two
375 assumptions ensure that the variation in the treatment variable driven by the instrumental
376 variable is also uncorrelated with other determinants of the outcome, thus removing the source of
377 endogeneity bias.

378 As an illustration of how IV works, consider predator-prey relationships which are classic
 379 examples of reverse causality as predator abundance drives prey abundance, but the reverse is
 380 also true (Kendall 2015). If we were, for example, interested in estimating the effect of wolf
 381 abundance on moose abundance using a linear regression, our linear coefficients may instead
 382 capture the reverse effect. To estimate the effect of wolf on moose abundance, we need to sever
 383 the reverse causality pathway by isolating a driver of wolf abundance that has no direct effect on
 384 moose abundance. One possible instrument would be the prevalence of canine distemper, which
 385 drives wolf abundance, but should not affect moose abundance (except through changes in wolf
 386 abundance). Note, we are assuming here that this predator-prey system is not closely coupled. If
 387 it were closely coupled such that there were offset boom-and-bust cycles, our estimates of the
 388 causal effect using cross-sectional data at any point in time would fail to capture the cyclical
 389 nature of the relationship (e.g. Sugihara *et al.* 2012).

390 Turning to how an IV approach would work in this setting, we can use the exogenous
 391 change in wolf abundance due to canine distemper to estimate the effect of wolf abundance on
 392 moose abundance. Conceptually, an IV approach occurs over a two-stage regression process.
 393 The first stage regression relates canine distemper prevalence to wolf abundance via,

$$394 \quad \text{PredAbundance}_i = \delta + \gamma \text{Distemper}_i + u_i. \quad (10)$$

395 In the second stage regression, moose abundance is then regressed on the wolf abundance
 396 predicted by canine distemper from the first stage,

$$397 \quad \text{PreyAbundance}_i = \alpha + \beta \widehat{\text{PredAbundance}}_i + \varepsilon_i \quad (11)$$

$$398 \quad = \alpha + \beta(\hat{\delta} + \hat{\gamma} \text{Distemper}_i) + \varepsilon_i. \quad (12)$$

399 As equations 10-12 show, the variation in wolf abundance used to estimate the effect on moose
 400 abundance comes only from canine distemper. Provided that canine distemper is not correlated

401 with other drivers of moose abundance, contained in the error term ε_i , then an IV model
402 estimates a causal effect.

403 In practice, the IV approach entails two further details. First, IV is usually implemented
404 with two-stage least squares, where equations 10 and 11 are jointly estimated. This is to account
405 for sampling variability in the predicted endogenous variable. Second, as a diagnostic of whether
406 the instrumental variable is strongly correlated with the endogenous variable, one often examines
407 variants of the F-statistic from the first-stage regression in equation 10. Such tests reveal whether
408 there is a “weak instrument” problem, the presence of which introduces a bias in the IV estimate
409 that can be as large as the endogeneity bias in the initial linear regression model (Bound *et al.*
410 1995). For a more in-depth discussion of IV in an ecological context, we direct the reader to
411 Kendall (2015). For an ecological application which uses the IV approach to the effect of forest
412 fragmentation on Lyme disease incidence, we direct the reader to MacDonald *et al.* (2018).

413 4. Regression Discontinuity: In some settings, the assignment of treatment may depend on an
414 arbitrary rule arising from policy or institutional features. Modifying our earlier land-use
415 example, let’s say forest stands were eligible for thinning if they were within 15 km of at least
416 one developed area and were at least 3 ha in size. As is often the case with such cutoff rules, both
417 the 15 km distance and 3 ha size criteria may have been arbitrarily specified by some policy.
418 However, it may not be desirable to implement a difference-in-difference method if finding
419 control units that satisfy these criteria requires a researcher to expand the data setting into places
420 that are unlikely to be similar. For example, a forest stand in Minnesota is unlikely to be a valid
421 control for a forest parcel in California even if both have the same distance to a developed area
422 and size. Similarly, using instrumental variables may not be feasible in some cases due to a lack
423 of a satisfactory instrument.

424 In such settings, a researcher may exploit the arbitrary nature of the cutoff rule. Here, one
425 can try to compare stands above 3 ha in size that are just less than 15 km from a developed area
426 (treatment) with similarly sized stands that are just more than 15 km from a developed area
427 (control). Alternatively, for all parcels that are less than 15 km from a developed area, one can
428 compare stands that are just above 3 ha in size (treatment) with those that are just below 3 ha
429 (control). Such comparisons implement the regression discontinuity (RD) design. Specifically,
430 the RD method exploits a discontinuity in treatment assignment around some threshold value of
431 a “forcing” variable, which in our example would be either distance to a developed area or parcel
432 size.

433 The key statistical assumption for the RD method to be valid is that only the probability
434 of receiving the treatment jumps discontinuously as the forcing variable crosses the threshold.
435 All other factors that determine the outcome must be continuous around the threshold. That is,
436 going back to our example, only thinning eligibility changes at the 15 km distance threshold so
437 that any outcome differences across the threshold can be attributed solely to thinning eligibility.
438 Under these conditions, the RD method estimates the local average treatment effect only for the
439 subpopulation close to the threshold. In practice, this means that the RD method is very data
440 demanding, and requires a sufficient density of observations within narrow bandwidths around
441 the threshold of the forcing variable. Interested readers can learn more about this issue and many
442 other RD implementation considerations in Lee and Lemieux (2010).

443 5. Propensity score. Finally, in some settings, it may be argued that a researcher can observe all
444 known determinants of an outcome that is correlated with the treatment of interest. In that case,
445 known as “selection on observables”, simply controlling for those covariates in a standard
446 regression setting would enable a causal interpretation. However, for many ecosystems, the list

447 of covariates may number in the hundreds, with possible combinations of covariates observed for
448 a treated unit not appearing for a control unit.

449 Propensity scores avoid this high-dimensionality problem by matching or weighting the
450 probability that a site receives treatment based on a function of observable characteristics. The
451 propensity score is the probability a site receives treatment given its baseline characteristics,
452 $p(X_i) = Pr(T_i = 1 | X_i)$ where $0 < p(X_i) < 1$. It follows from the treatment ignorability
453 assumption that $T_i \perp (Y_{0i}, Y_{1i}) | p(X_i)$ (Rosenbaum & Rubin 1983). Thus, conditional on the
454 propensity score, treatment is independent of potential outcomes. Rosenbaum & Rubin (1983)
455 also show that treatment and control observations with the same value of the propensity score
456 balance in the distribution of baseline characteristics.

457 Propensity scores are estimated using a regression model for binary outcome variables
458 (e.g. logit or probit) where probability of treatment is estimated as a function of baseline
459 characteristics with highly flexible functional form. The specification should balance the
460 distribution of baseline characteristics across the distribution of propensity scores.

461 There are several ways propensity scores can be used including matching on propensity
462 scores, inverse probability weighting the estimator, using propensity scores in a weighted
463 regression, and using propensity scores as a covariate adjustment in linear regressions. A
464 thorough discussion of different methods can be found elsewhere (Austin 2011). We simulate
465 propensity score matching and propensity scores as a covariate adjustment in a linear regression
466 (SI), and point the reader to Pearson *et al.* (2016) for an ecological application focused on
467 agricultural land cover and aquatic ecosystem impacts.

468 *Discussion*

469 A multitude of environmental and ecological challenges facing natural systems in the
470 coming decades can be informed by observational data. Leveraging the data-rich landscape of
471 the twenty-first century for impact studies necessitates incorporating statistical tools specifically
472 developed for disentangling causal relationships in the absence of randomized experiments. Here
473 we discussed how observational data differ from experimental data, why this difference is of
474 crucial statistical importance, and introduced some assumptions and approaches that can be used
475 to recover a causal interpretation of treatment effects in the absence of randomly assigned
476 treatment.

477 In particular, we emphasized the fundamental importance of zero correlation between the
478 covariate of interest and a model's error term. The presence of such a correlation leads to what is
479 known as endogeneity bias and thus, incorrect coefficient estimates. Though we avoided
480 discussing specific estimation methods, all common regression methods (ordinary least squares,
481 maximum likelihood, generalized least squares, etc.) will generally produce biased estimates of
482 the causal effect in the presence of endogeneity bias.

483 The symptoms of endogeneity bias can present as spatial or temporal autocorrelation in
484 the residuals. However, if autocorrelation is due to omitted variables that are spatially or
485 temporally correlated (e.g. climate, soil quality) and correlated with the treatment variable,
486 methods that only adjust for autocorrelation of the errors will fail to produce unbiased slope
487 estimates for the treatment of interest. Similarly adding random effects of site or year may not
488 reduce bias. If site characteristics are correlated with the covariate of interest, random effects
489 estimators will remain biased. Rather, recognizing and applying methods to overcome the
490 underlying source of endogeneity bias are fundamental to reliable point estimates.

491 This paper's main contribution is to provide basic intuition for developing causal
492 inference using observational data for different types of control-impact analyses. We necessarily
493 could not provide a full treatment of such approaches, nor comprehensive treatment of causality
494 in all observational settings. For instance, our maintained assumption throughout this manuscript
495 that a random sample could be drawn from the population (at least in the cross-section
496 dimension; Wooldridge 2002), extends to more complicated sampling designs such as stratified
497 or clustered sampling (Wooldridge 2002). Further, we ignored concerns regarding the efficiency
498 of estimators. Lastly, our focus on control-impact analyses does not include all notions of
499 causality relevant to ecologists. In particular, while many of the methods discussed can be
500 extended to nonlinear models where the marginal effect of the treatment variable is not constant
501 over its entire range (e.g. logistic regressions), we excluded discussion of dynamic notions of
502 causality involving coupled variables (e.g. Granger 1969; Sugihara *et al.* 2012). For coupled
503 systems such as coupled predator-prey cycles, the methods discussed here would misspecify the
504 nature of relationship as such systems cycle among positive, negative and neutral correlation
505 between predator and prey. As observational data expand to provide sufficiently expansive
506 species-specific time series observations, dynamic forms of causality will become increasingly
507 relevant.

508 Nevertheless, many global environmental challenges of today and tomorrow will take the
509 form of control-impact studies, where treatment evaluation is of primary interest. It is for those
510 questions that a focus on unbiased statistical estimates of the treatment effect will be invaluable
511 for addressing important ecological questions. Though we relied on hypothetical examples to
512 streamline discussion, these methods discussed herein are not entirely new to ecologists. We
513 point the reader to Gross & Rosenheim (2011), Bonds *et al.* (2012), Larsen (2013), Larsen and

514 Noack (2017), and MacDonald *et al.* (2018) for empirical ecological studies using these
515 methods, to Kendall (2015) and Butsic *et al.* (2017) for additional methodological discussion
516 aimed at the ecology audience, and to Wooldridge (2002) or Angrist & Pischke (2009) for
517 advanced and introductory texts, respectively, on econometric methods. Ecologists have a strong
518 tradition of causal inference in experimental research. Here we encourage a similarly strong
519 interest in causality in observational control-impact studies such that we can better leverage
520 novel data sources to inform ecological understanding and environmental policy.

521

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526 *Author contributions:* AEL conceived of the study, AEL & BK wrote simulation code, AEL, KM
527 & BK wrote the manuscript.

528

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607 Table 1. Data requirements and key assumptions of different methodology discussed.

Method	Addresses	Situation	Data requirements	Key Assumptions
Difference-in-difference	Selection bias stemming from which group gets treatment.	Time trends and group specific averages differ between treatment and control groups.	At least two periods of data, before and after, observed for both a treatment and control group.	Parallel time trends between the treatment and control group prior to treatment.
Within-estimator	Selection bias stemming from unobserved or not included variables that are correlated with the covariate of interest and the outcome.	Time shocks shared by all observations (time dummies), time-invariant characteristics unique to individual observations or groups (individual, group dummies)	Panel data where covariates of interest and outcome variable vary over time and/or within individuals (i.e. within the dummy variable group(s)).	Strict exogeneity.
Instrumental Variables	Reverse causality. Can also be used to address other endogeneity bias.	There exists a feedback between the magnitude of outcome variable and the treatment variable	Requires an “instrumental” variable that is correlated with the endogeneously determined treatment variable, but otherwise does not drive the outcome.	Instrument is “relevant” (i.e. correlated with endogenous variable) and uncorrelated with the errors.
Propensity Scores	Selection bias, if selection is determined by observable characteristics.	Reduces the high dimensionality problem associated with including all variables that could determine treatment vs control status.	Data on variables that determine selection into treatment and control groups.	Treatment ignorability assumption. Common support between treatment and control groups. Additional assumptions depending on how p-scores are used.
Regression Discontinuity	Selection bias	Discrete treatment assignment as a function of some threshold in a “forcing” variable.	Because treatment is assumed to be as good as random only near the threshold, there needs to be sufficient mass of data within narrow bandwidths of the forcing variable on either side of the threshold.	Assignment of treatment is as good as random across the threshold of the forcing variable. Units are unable to sort across the threshold.

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612 Figure Legends

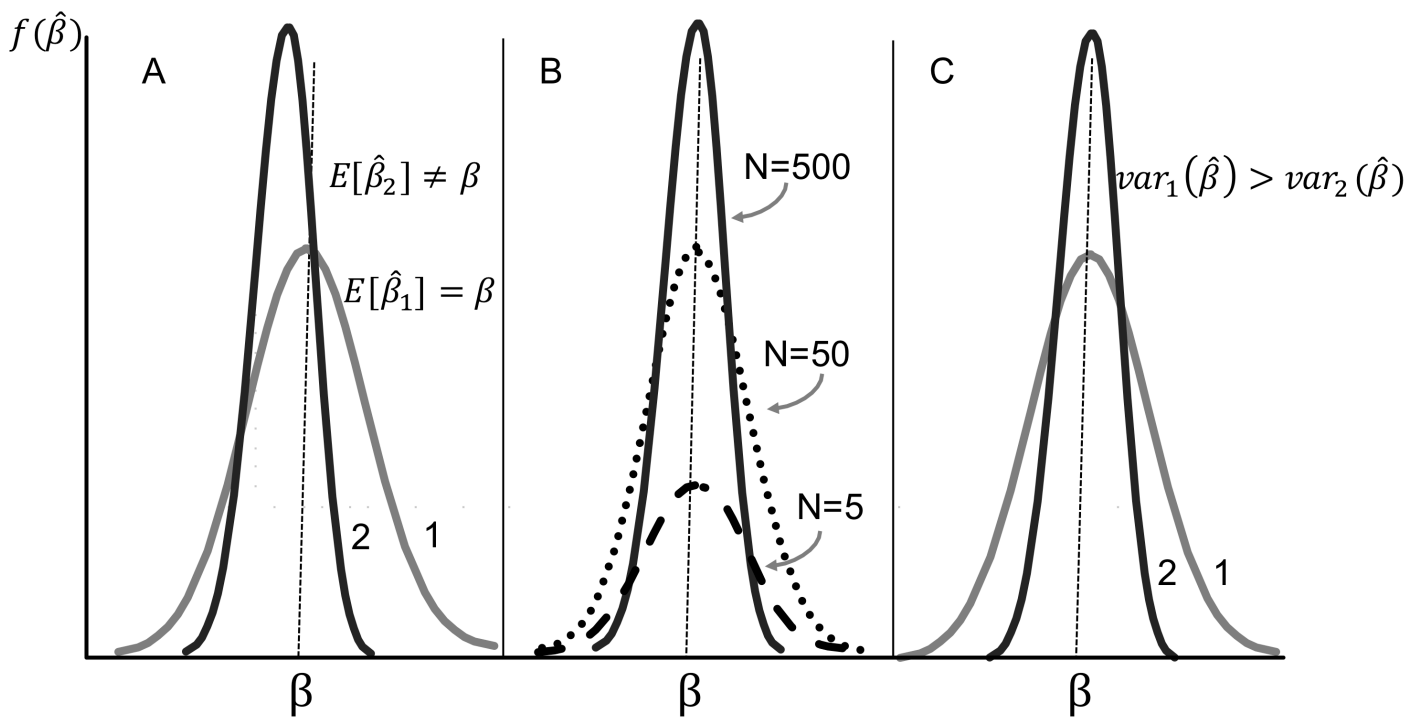
613

614 Figure 1. Properties of Linear Estimators. The desirable properties of linear estimators are that
615 the estimator is unbiased (A,1), consistent (B) and efficient (C). Unbiasedness is a finite sample
616 property. An estimator is unbiased, if the average (or expected value) of the sampling
617 distribution is equal to the true parameter value (B, gray line). If there is a correlation between
618 the model errors and treatment variables, the estimator will generally be biased (A,2).
619 Consistency, like unbiasedness, is related to identification of the true relationship (i.e. the
620 frequency distribution of estimated coefficients is centered on the true value, β). However,
621 consistency is an asymptotic property. We focus on unbiasedness, which is most relevant to
622 finite samples, however, instrumental variables, due to its two step process, is a consistent but
623 biased estimator. Efficiency is related to the spread of the distribution of the estimator. An
624 efficient estimator has the minimum variance of all estimators in its class of estimators (e.g.
625 linear estimators).

626

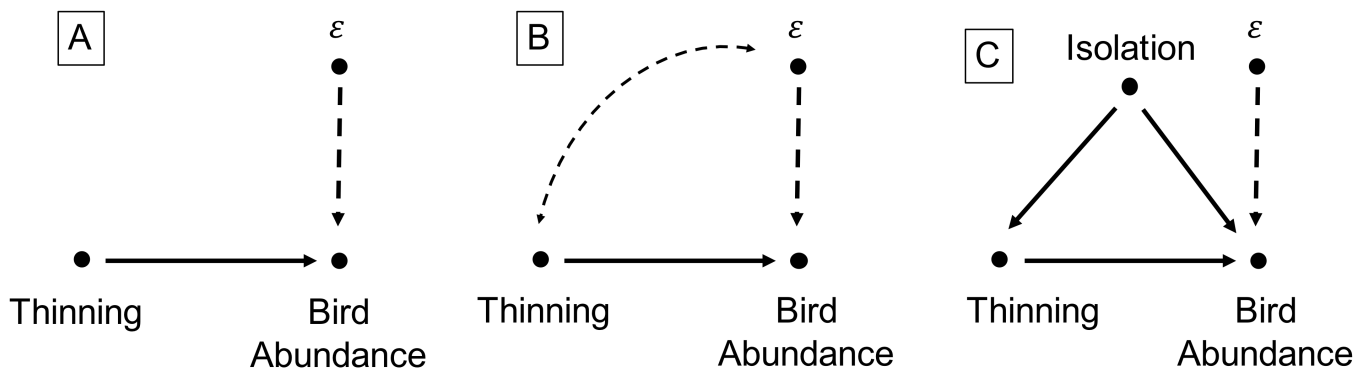
627 Figure 2. Causal diagram or Directed Acyclic Graph. Nodes represent variables, arrows
628 represent possible causal effects in the direction of the arrow (a drives b, $a \rightarrow b$), bi-directional
629 arcs represent possible confounding relationships, and solid and dashed lines represent observed
630 and unobserved variables, respectively. Importantly, causal assumptions are represented by the
631 lack of connections, thus (A) assumes model 1 is correct, that there is no omitted variable
632 confounding the estimate of the causal effect of thinning. If there was and it was unobserved (B),
633 estimating model 1 would produce biased estimates of the effect of thinning on bird abundance
634 due to the correlation between the errors (which include the unobserved confounding variable)
635 and the treatment. If the researcher knew and could measure the confounding variable (C), the

636 researcher could find unbiased estimate for the effect of thinning on bird abundance by modeling
637 it explicitly; estimating model 2 rather than model 1.



Model 1: $Birds_i = \alpha + \beta Thinning_i + \varepsilon_i$

Model 2: $Birds_i = \alpha + \beta Thinning_i + \gamma Isolation_i + \varepsilon_i$



Supplementary Information

To illustrate how selection bias and reverse causality bias influence common estimators, we compare the OLS, within- and IV estimators under different scenarios. In each case, the true relationship is $Abundance_{it} = 2 + 1 * fragmentation_{it} + 1 * distance_i + u_{it}$. We simulate panel data with 100 units, each observed four times.

First, we estimate the above model for OLS to illustrate that if there are no omitted variables and no feedbacks, the OLS will be unbiased. For the selection bias example, we imagine the researcher does not measure distance to nearest development, but that there is a correlation between distance and fragmentation. The OLS is a biased estimator in this case (Table S1). However, if we use the within estimator to remove time-invariant characteristics unique to a site through de-meaning, we see our coefficient estimates are close to the true slope. If we instrument for fragmentation, we see the coefficients are greatly improved relative to OLS, but are not as close to the true slope as for the within-estimator. This reflects the notion that IV is biased, but approaches the true slope as the sample size increases towards infinity.

For simultaneous causality, we now imagine the researcher includes distance, but that there is a feedback between songbird abundance and fragmentation. Note, distance, being time invariant, is dropped during the estimation process for the within estimator. In the case of reverse causality, both the OLS and within estimator yield coefficients that are far from the true slope, while estimated coefficients using IV remain close.

	Correctly specified OLS	Selection Bias			Reverse Causality Bias		
		OLS	Within estimator	IV	OLS	Within estimator	IV
Fragmentation							
100 iterations	1.003 (0.050)	1.459 (0.110)	1.010 (0.063)	1.052 (0.107)	1.370 (0.107)	1.356 (0.138)	1.010 (0.114)
500 iterations	1.001 (0.049)	1.455 (0.110)	1.000 (0.063)	1.049 (0.107)	1.375 (0.107)	1.367 (0.136)	1.001 (0.112)
1000 iterations	1.001 (0.050)	1.459 (0.110)	1.000 (0.064)	1.052 (0.106)	1.383 (0.106)	1.354 (0.138)	1.000 (0.113)
True slope = 1.0							
Site dummy variable	N	N	Y	N	N	Y	N
Time periods (t)	4	4	4	4	4	4	4
Observations (t*n)	400	400	400	400	400	400	400

Table S1. Outcome from simulated code where the true slope is 1.0. With omitted variable bias stemming from time-invariant site-specific characteristics (e.g. distance, patch size), either the within-estimator or IV estimator can substantially reduce bias relative to OLS. However, if there is a feedback between the outcome and covariates, the within estimator will generally fail to reduce bias. Rather instrumental variables can be used in cases of reverse causality. See `SimulatedBias.do` for the simulation code for this table and `RSimulationCode.R` or `StataSimulationCode.do` for basic example code for the methods described in the text.