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Seismic Performance of Dissipative, Biaxially loaded and Embedded Column Base Connections

By

AHMAD S. HASSAN

DISSERTATION

Submitted in partial satisfaction of the requirements for the degree of

DOCTOR OF PHILOSOPHY

in

Civil and Environmental Engineering

in the

OFFICE OF GRADUATE STUDIES

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UNIVERSITY OF CALIFORNIA

DAVIS

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Committee in Charge

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ABSTRACT

This dissertation investigates the seismic response of Column Base Connections in Steel Moment Frames, a critical structural component used to transfer forces from the steel superstructure to the supporting concrete foundation. The research presented is intended to highlight and address various unresolved issues on the seismic performance of column base connections, and develop methods and criteria for their design resulting in economical and reliable connections.

Column bases are arguably the most important connections in steel structures, transferring forces from the entire building to the foundation. A variety of details are commonly used for these connections ranging from exposed type with anchor rods, to embedded type. Current design/construction practices for base connections result in major conservatism in material requirements (deeper embedments or large anchor rods) and other inefficiencies stemming from the following: (1) Column base connections are generally capacity-designed to be stronger than the adjoining column presuming that the connections will be less ductile than the column, (2) Embedded Column Base connections have been designed for years without direct experimental support, such that current methods assume them to be similar to coupling beams in shear walls; disregarding many physical mechanisms that contribute to the strength of the actual connections. These include, the effect of reinforcement welded/attached to the column, and the beneficial effect of a slab-on-grade that overtops exposed-type connections, resulting in a shallowly embedded (blockout) connection. Consideration of these effects has the potential to greatly reduce costs by decreasing required embedment depth, minimizing other detailing (such as heavy anchor rods), and reducing logistical challenges.

Four studies are presented, investigating (1) the seismic response of dissipative exposed-type base connections, (2) the strength characterization of biaxially-loaded column bases, (3) the seismic performance of blockout column base connection, as well as (4) embedded-type base connection with reinforcement attachments. The first study presents full-scale tests on Exposed Column Base Plate Connections with ductile anchors, with the aim to examine the seismic performance of these connections for their prospective use as dissipative/weak bases. These connections feature upset thread anchor rods, providing a stretch length over which inelastic deformations may be distributed. The tested specimens (with varying parameters) survived, with no anchor rod failure, the application of two back-to-back lateral deformation protocols (each to drift amplitudes of 5%), followed by additional cycles to 6.5% drift amplitude. Complementary line element-based and continuum finite-element simulations are conducted to examine to what extent the experimentally observed response may be generalized to untested configurations.

The second study demonstrates a new method to characterize the internal stress distribution and anchor rod forces in Exposed Column Base Plate Connections subjected to biaxial bending and axial compression. The method is based on and validated against finite element simulations and available experimental data. The method is demonstrated to predict anchor force with good accuracy across a range of configurations (including column and base plate size) and loadings (level of axial force and bending angle).

The third study presents full-scale experiments for shallowly embedded “Blockout” base connections to investigate the effect of additional strength and stiffness provided by an overtopping slab cast over the conventional exposed base connection. The connections are subjected to

combinations of axial compression and cyclic lateral deformations. Significant increases in both stiffness and strength, with stable and ductile hysteretic response are noted. Results from this study are synthesized with results from previous studies on similar connections to propose a strength model and evaluate previously proposed stiffness models.

The final study involves large-scale tests on embedded column base connections with attached reinforcement, and analyzes the effect of common reinforcement detailing for connections under axial compression and cyclic lateral deformation representative of seismic loading. It is observed that the introduction of horizontal reinforcement attached to the embedded column flanges reduces the strength and stiffness of such connections, as compared to cases where no reinforcement is attached. This is because, the horizontal reinforcement introduces a tension field in the concrete area above the uplifting region of the embedded plate, resulting in a reduced vertical resistance and an overall net reduction in strength. Based on observations, a method is developed to predict the strength of Embedded Column Base connections with various detailing features. The method shows good agreement with test data when compared with available strength models. Implications on design, detailed analysis and discussion of limitations of each study are provided.

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The large-scale experiments described in this dissertation were conducted at the Structural Engineering Laboratory (Outdoor Strong Floor) at UC Davis. The author is grateful to Daret Kehlet, Chad Justice, and Victor Jones, the technical personnel at UC Davis for their assistance and support during all phases of planning and testing. The author is thankful to Mitch Reichardt for his immense help and incredible assistance with the test setup and planning. The author is hugely thankful to Greta Murtas, Eric Garcia, and Carlos Medina for their enormous help in constructing the test components. The author also thanks Sashi Kunnath and John Bolander, for their guidance and assistance in preparing this dissertation.

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CHAPTER 1

INTRODUCTION

1.1 INTRODUCTION

This dissertation investigates the behavior and design of Column Base Connections in Steel Moment Frames (SMFs) with various configurations, performance objectives, and loading conditions. The investigation comprises three large-scale testing programs, complemented by computational simulations and analytical developments to examine the seismic performance and design of commonly used, as well as newly proposed base connection details. In addition, the dissertation presents a supplemental study on the strength characterization of biaxially loaded base connections in Steel Moment Frames. The intent of this dissertation is to address knowledge gaps in the seismic performance of the connection between steel columns and concrete footings, and to develop predictive behavioral models currently unavailable in design practice.

1.2 MOTIVATION AND BACKGROUND

Column bases are arguably the most critical connections in Steel Moment Frames (SMFs), transferring the forces, and moments from the entire structure to the foundation. A variety of details are commonly used for these connections, which can be broadly classified into exposed type with anchor rods, to embedded type with various detailing and attachments. The role of these connections is even more critical in the seismic response of SMFs as their strength, rotational stiffness, and hysteretic characteristics interact with the frame, influencing force/moment distribution in the frame.

Research on column base connections is relatively limited compared to research on other types of steel connections (for example, beam-column connections). Further complicating factors include the following: (1) these connections take vastly different forms (i.e., exposed, embedded, and shallowly embedded) and (2) they lie at the interface of steel and concrete, which makes them challenging not only from a mechanics standpoint, but also from the standpoint of design guideline and standards development.

In light of these issues, and considering previous work on the topic of column bases (discussed in detail in the next chapters – as pertains to each study), the following priorities are identified and refined for research:

- 1- Development of ductile and dissipative column base connections that may be used in SMFs as “Weak/Dissipative Bases”, such that they may be designed more economically as compared to “Strong Bases” which are designed to yield the attached column. The aim is to propose methodologies for simulation and design of these connections (as well as the frames) that utilize weak-base connections.
- 2- Investigation of the mechanistic response of biaxially loaded Exposed Column Base Plate connections, and suggestion of approaches to characterize internal force distributions in such connections.
- 3- Experimental investigation of the seismic performance of “Blockout” or shallowly embedded base connections. This includes the consideration of untested parameters, and providing a realistic test setup (representative of the construction practice), and eventually propose a model for strength characterization that provides good accuracy across all available test data.

- 4- Examination of embedded base connections with various types of reinforcement through a program of large-scale testing reflecting commonly used and untested connection details. The goal is to develop fundamental understanding of the force transfer mechanisms, and consequently strength models of commonly used embedded base connections.

Each of the above topics and research priorities is a self-contained study. Consequently, relevant literature review, context, test data, conclusive remarks and other information are provided within each of the chapters. Some or all test data, models, and codes supporting the findings of these studies are available from the author upon request.

1.3 DISSERTATION OUTLINE

This dissertation consists of five chapters including the introductory chapter. Two of them are composed of peer-reviewed (published) journal articles. Two more are planned to be submitted to relevant scientific journals. Each chapter reproduced from a journal article includes detailed information of the article in the beginning of the corresponding chapter.

Chapter 2 presents the full-scale experiments and computational simulations on a novel dissipative exposed base connection with ductile anchors, ultimately culminating in procedures/criteria for designing weak/dissipative bases. Chapter 3 presents a strength characterization method for biaxially loaded base connections. Chapter 4 discusses the test program conducted to examine the seismic performance of breakout (shallowly embedded) base connections, along with a strength model development. Chapter 5 presents a test program investigating the seismic response of embedded column bases with attached reinforcement. Results are compared to existing guidelines and available strength characterization methods, and utilized for the development of a unified model to characterize the strength of such connections.

CHAPTER 2

SEISMIC PERFORMANCE OF EXPOSED COLUMN BASE PLATE CONNECTIONS WITH DUCTILE ANCHOR RODS

This chapter presents the post-print version of the article with the following full bibliographic details: Ahmad S. Hassan, Biao Song, Carmine Galasso, and Amit M. Kanvinde (2022). “Seismic Performance of Exposed Column–Base Plate Connections with Ductile Anchor Rods.” Journal of Structural Engineering, American Society of Civil Engineers (ASCE), Vol. 148, Issue 5, 04022028, DOI: [https://doi.org/10.1061/\(ASCE\)ST.1943-541X.0003298](https://doi.org/10.1061/(ASCE)ST.1943-541X.0003298)

2.1 INTRODUCTION

Current seismic design practice for Steel Moment Frames (SMFs) in the United States is intended to develop yielding in plastic hinges at the ends of the beams, while the columns, panel zones, and connections, which are presumed to have limited ductility, remain elastic (AISC 341-16 2016). This is accomplished by designing these non-ductile components for overstrength seismic loads (i.e., by amplifying the reduced base shear by the system-specific overstrength factor Ω_0) or by capacity-protecting the components (i.e., by designing them to withstand the expected strain-hardened strength of connected components). Connections are often designed as per the latter approach. For example, beam-to-column connections are typically designed to resist forces corresponding to the fully yielded and strain hardened moment ($M_{pr} = 1.1 R_y M_p$) in the adjacent beam plastic hinge (AISC-358 2016), in which M_p denotes the plastic moment and R_y denotes the ratio of expected to nominal yield strength. Plastic hinges are also expected to form at the base of the first story columns and are unavoidable from the standpoint of kinematics if a full-building sideway mechanism is desired. These plastic hinges may be accommodated in the column member itself or in the column base connection or the foundation. The former approach (i.e., a “Strong Base” design, forcing the plastic hinge into the column member) is the common practice (AISC

Seismic Design Manual 2018), and is achieved by capacity protecting the connection, i.e., requiring it to withstand $M_{pr} = 1.1 R_y M_p$ of the column in the presence of overstrength axial load. Designing connections in this manner is costly. Specifically, in the case of Exposed Base Plate (EBP) connections (see Figure 2.1a), the application of prevalent design methods (e.g., AISC Design Guide One - Fisher and Kloiber 2006; AISC Seismic Design Manual 2018) usually necessitates the use of multiple anchor rods and a thick plate to resist the large moment corresponding to M_{pr} . For larger column sizes in mid- to high-rise frames, the capacity design approach often favors the use of an embedded-type connection (Grilli and Kanvinde 2017). This is not only costly but also logistically challenging due to multiple concrete pours. The latter approach (i.e., a “Weak Base” design accommodating plastic deformations within the base connection) is allowed by AISC 341-16 (AISC 2016) Section D2.6c, using an overstrength seismic load to design base connections provided that “*a ductile limit state in either the column base or the foundation controls the design.*” However, this is not common because: (1) connection qualification data for column bases or detailing guidance to achieve ductile response is not readily available; and (2) until recently, there was limited understanding of the ductility demands in these connections, if designed as weak bases.

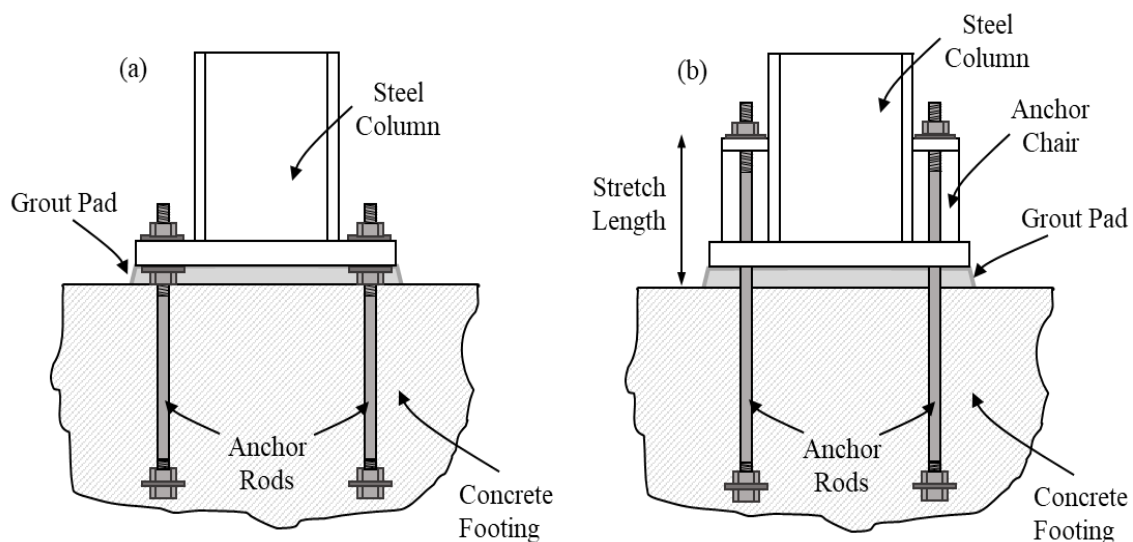


Figure 2.1 – (a) Schematic illustration of an Exposed Column Base Connection; (b) Exposed Base Connection with extended anchors (Soules et al., 2016).

Research conducted over the last 20 years provides motivation for developing high-ductility connections that may be used as weak bases in seismically-designed SMFs. Specifically, experimental studies by Gomez et al. (2010), Kanvinde et al. (2015), Trautner et al. (2017), Astaneh et al. (1992), Fahmy et al. (1999), Burda & Itani, (1999), Lee et al. (2008) and Wald et al. (2020) on EBP connections indicate a very high degree of rotation capacity (in the range of 6-10%). These capacities are observed even without intentional detailing for ductility, and are often as large as (if not greater than) rotation capacities for plastic hinges that form in wide-flanged column members (Elkady and Lignos 2016, 2018; Newell and Uang 2008), suggesting that the strong base approach may not only be expensive, but also counterproductive, forcing yielding into the possibly less ductile element (the column) rather than the base connection. Moreover, Nonlinear Response History Analysis (NLRHA) by Falborski et al. (2020) suggests that base rotation demands in moment frames designed with weak bases (designed for moments corresponding to Ω_o , rather than M_{pr}) are on the order of 4-5% (i.e., 0.04-0.05 rad). When compared to the observed rotation capacities of base connections from the various experimental programs mentioned above, this suggests that the effective development and mainstream adoption of base connections that reliably meet these demands is within reach.

Against this backdrop, this study presents a series of four full-scale experiments and associated computational analyses of EBP connections with yielding anchors. The study demonstrates EBP details that provide high rotation capacity, while also being convenient to fabricate in a practical setting in the United States. Figure 2.2 schematically illustrates the tested details developed in consultation with an oversight committee of fabricators and practitioners – see Acknowledgments. These details feature Upset Thread (UT) anchors, with a smooth shank to accommodate inelastic

cyclic deformations, while the base plate itself remains elastic. The shank is frictionally isolated from the surrounding concrete with polyethylene tape. The specimens are subjected to cyclic lateral loading under constant axial compression. The main variables are the axial load, rod diameter and grade. Complementary simulations of the base connections are conducted to generalize the test findings to untested configurations. The next section presents relevant background, followed by a description of the experimental program and the simulations.

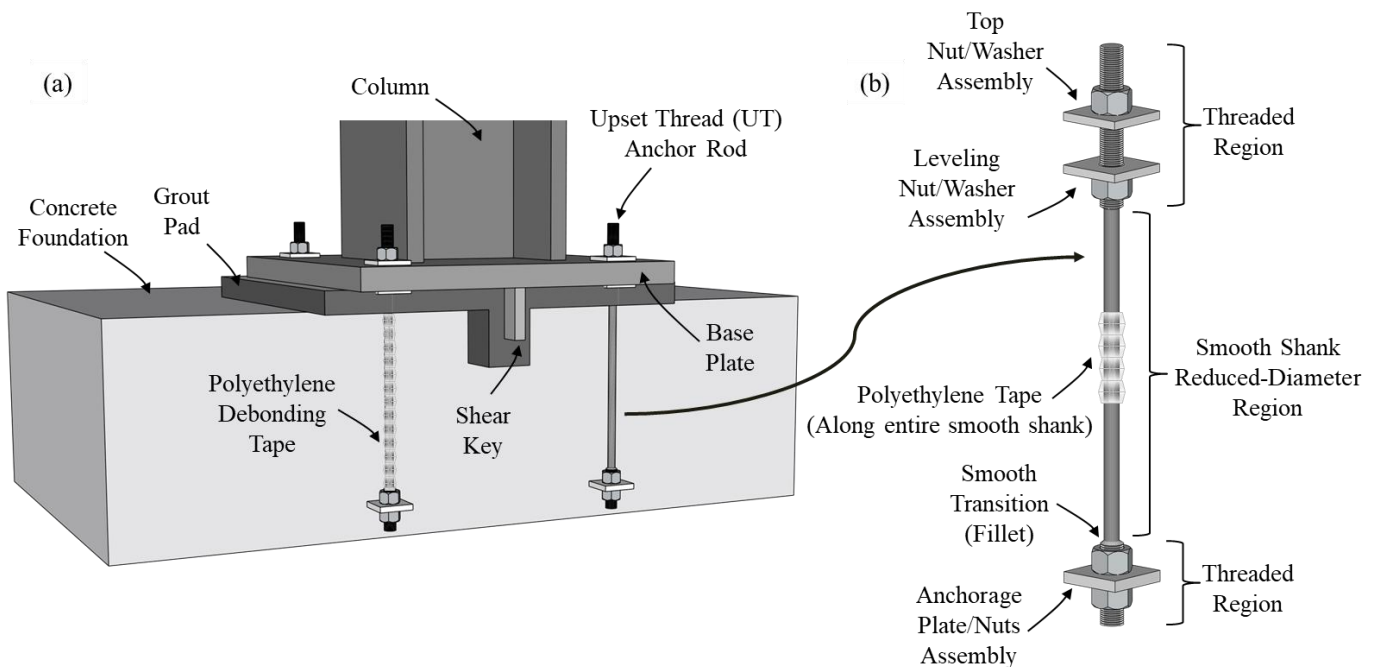


Figure 2.2 – (a) Exposed Base Plate Connection with Upset Thread (UT) anchor rods (Isometric section view); (b) Upset Thread (UT) anchor rod detail.

2.2 BACKGROUND AND SCOPE

Although EBP connections have been a subject of study for over three decades, the primary focus has been on developing strength models (Drake and Elkin 1999) leading to design guidelines (*AISC Design Guide One* - Fisher and Kloiber 2006) and manuals (*AISC Seismic Design Manual* 2018; *SEAOC Structural/Seismic Design Manual* 2015). Observations regarding their high ductility (Gomez et al. 2010; Trautner et al. 2017) have mostly been an outgrowth of studies

primarily focused on their strength characteristics. Conventional design methods for EBP connections consider various limit states, e.g., tensile yielding of the anchor rods or flexural yielding of the base plate on the tension or compression side of the connection, or bearing failure of the footing. Experimental research (including the studies cited above) suggests that concentrating the yielding in the anchors has the potential to maximize overall rotation capacity of the connections. Thus, EBP connections with yielding anchors have been utilized in shake table studies (Lignos et al. 2013; Hucklebridge 1977) with good performance. Nonetheless, the focus in these studies has been on the macro-mechanics of system performance rather than the development of a practically feasible ductile base detail.

Trautner et al. (2016, 2017) conducted comprehensive experimental studies to examine the seismic response of EBP connections with various types of yielding anchors. These experimental specimens reflected construction practice in the United States, with different anchor types (cast-in and post-installed), the use of leveling nuts, and different anchor stretch lengths. All these specimens showed excellent rotation capacity (6–15%) under cyclic loading protocols. Of these, the cast-in anchor detail that was able to distribute yielding over the largest length (longer effective stretch length), showed the greatest rotation capacity, whereas the strong-anchor detail that constrained the anchor yielding resulted in the lowest rotational capacity. In addition, reconnaissance studies conducted after the 2010 Maule earthquake in Chile (Soules et al. 2016) indicate that EBP connections with extended anchors (Soules et al. 2016, see Figure 2.1b) provided excellent seismic performance due to the greater stretch length, which allowed the accumulation of large plastic deformation. Collectively these (and other, e.g., Gomez et al. 2010) studies indicate

that: (1) ductile response of EBP connections may be achieved by concentrating yielding in the anchors; and (2) a large stretch length for distribution of plastic strains is beneficial.

Building on these insights, this study examines the UT detail (shown schematically in Figure 2.2) which has the following features:

1. A fairly long stretch length to distribute plastic strains over the anchor rods, without the use of additional fabrication – e.g., as shown in Figure 2.1b.
2. A smooth shank over this stretch length, to provide a greater resistance to fracture as compared to threaded rods.
3. Frictional isolation of the shank using polyethylene tape to ensure that plastic strains are mobilized over the entire shank.
4. A leveling nut-washer detail on the underside of the base plate (see Figure 2.2) to engage the rod in tensile as well as compressive yielding – in effect, this is similar to Buckling Restrained Braces which show excellent cyclic deformation capacity – e.g., see AISC 341-16.
5. A shear lug/key to transfer column shear.
6. The use of standard materials and fabrication practices, with the exception of the UT rods and the polyethylene tape to minimize additional expense, and facilitate adoption.

2.3 EXPERIMENTAL PROGRAM

This section outlines the experimental setup, test matrix, protocol, and instrumentation. Figure 2.3 illustrates the overall test setup, whereas Table 2.1 summarizes the test matrix. Table 2.1 also includes selected experimental results that are discussed later.

Test Setup and Instrumentation

Figure 2.3 shows the test setup, including the specimen, reaction frame for lateral loads, and the loading cross-beam to introduce compressive gravity loads. Key features of the test setup are:

1. All specimens were cantilever columns with a servo-controlled hydraulic actuator attached at the top. This location (3.4m above the base) was assumed to be the inflection point in a first story column. All columns were A992 Grade 50 ($F_y = 345$ MPa) and were designed to remain elastic to induce failure in the base connection.
2. The cross-beam indicated in Figure 2.3 introduced a constant compressive axial load through an assembly of tension rods and hydraulic jacks in Tests #1, 2, and 3. The lower end of the tension rods was connected to a freely rotating clevis, such that the axial forces were follower forces and did not introduce ($P - \Delta$) moment into the connection as the column displaced.
3. The footings having a length of 2.74 m (108 in.), a width of 1.83 m (72 in.) and depth of 0.5 m (20 in.) with a nominal compressive strength $f'_c = 27.5$ MPa (see Table 2.2 for measured values) were provided with minimal longitudinal and transverse reinforcement. The reinforcement featured an identical top and bottom mesh of #5 hooked bars (#16 metric size) placed longitudinally at 305 mm (12 in.) on center and transversely at 178 mm (7 in.) on center, with a 76 mm (3 in.) bottom cover.
4. The columns were welded to the base plates with Partial Joint Penetration welds and reinforcing fillet welds. The plate and welds were sized to remain elastic, forcing yielding into the anchors.

Figure 2.2 illustrates the UT detail. Referring to the figure, each anchor rod was milled using a lathe to a reduced diameter denoted d_{UT}^{rod} over a designated stretch length denoted L_{UT}^{rod} . The reduced diameter was chosen such that the fully yielded and strained hardened stretch region would

not induce any yielding in the threaded region. A smooth transition (with a 6.3 mm fillet radius) was provided between the smooth shank and the threaded regions at both ends. At the bottom, a nut and square plate washer assembly provided anchorage. A concrete cover of 13 mm (0.5 in.) was provided below this nut-washer assembly. At the top, nut and plate washer assemblies sandwiched the base plate with oversized holes. The nut immediately below the base plate functions as a leveling nut and also provides a mechanism for introducing compression into the anchor. The upper plate washer was tack welded to the base plate, consistent with construction practice. Oversized holes in the base plate were used to facilitate installation (*AISC Design Guide One*, 2006). The dimensions of the oversized holes and the plate washers, along with the rod dimensions for each of the experiments are summarized in Table 2.1 footnotes. A shear key with a thickness of 25.4 mm was fillet welded to the bottom of the base plate. The key protruded 82.5 mm (3.25 in.) from the bottom surface of the base plate and was accommodated in a pocket in the footing – see Figure 2.2a. A 50 mm (2 in.) layer of non-shrink grout with nominal compressive strength $f_{grout} = 55.1 \text{ MPa}$ was provided between the base plate and the top surface of the concrete footing. This grout was poured after the setting and leveling of the base plate on the leveling nuts (and shim stacks to avoid applying accidental forces to rods during setting). Thus, except for the upset thread rods and the polyethylene tape, the fabrication and erection procedure for the detail is identical to that of conventional EBP details.

The data collected from the experiments includes: (1) lateral force and displacement at the top of the column; (2) axial force in the column; (3) vertical and horizontal displacements of the base plate; (4) strain gage measurements from the anchor rods and the base plate surface; and (5) displacements to monitor rocking and sliding movement of the footing. Additional transducers

were installed to detect unanticipated response modes such as out of plane, and torsional response of the column. Figure 2.4 shows instrumentation schematics for the base plate and the column, identifying the location and purpose of each sensor.



Figure 2.3 – Experimental test setup.

Test Matrix

Referring to Table 2.1, the following test parameters were varied: (1) the axial load, (2) the anchor rod diameter, (3) stretch length, and (4) the anchor grade. The selected parameter values for each considered similarity to prevailing practice, and limitations of the test setup. Specifically:

1. The compressive axial loads were selected to produce significant variation in moment capacity by delaying plate uplift (as estimated by the *AISC Design Guide One* approach), while also not inducing yielding in the base plate on the compression side of the connection.
2. The anchor dimensions were chosen to ensure yielding in the UT region, while other components remained elastic. The embedment length of anchor rods was selected to ensure that the rods achieve their full tensile capacity prior to pullout/breakout concrete failure.
3. Two anchor rod grades, namely Grade 55 and 105, (380 and 724 MPa, respectively) of ASTM F1554, were used.
4. Subsets of tests interrogate effects of individual test variables. For example, Tests #1 and 2 provide an examination of the effect of anchor rod diameter (other variables are held constant), whereas Tests #3 and 4 provide a similar investigation of the effect of axial load.

Tables 2.2 and 2.3 summarize the results of ancillary tests for measurement of material properties. These measured properties are used to interpret results and calibrate analysis models.

Loading Protocol

In all specimens, the axial load was introduced first and held constant while the lateral displacement-controlled loading protocol was applied. Figure 2.5 illustrates the lateral loading protocol, expressed in terms of the column drift ratio. The loading protocol consists of two ATC-SAC (Krawinkler et al. 2000) loading histories applied consecutively (each with a maximum drift of 5%) followed by additional cycles till 6.5% drift amplitude. The ATC-SAC history was selected because it is also mandated for pre-qualification of beam-column connections in SMFs as per AISC-358 (2016); the goals of this study are similar, i.e., to demonstrate performance under high seismic demand. The additional loading cycles (beyond the first application of the ATC-SAC

history) were pre-planned in case failure was not observed during the first application and may represent extreme seismic demands or multiple earthquakes.

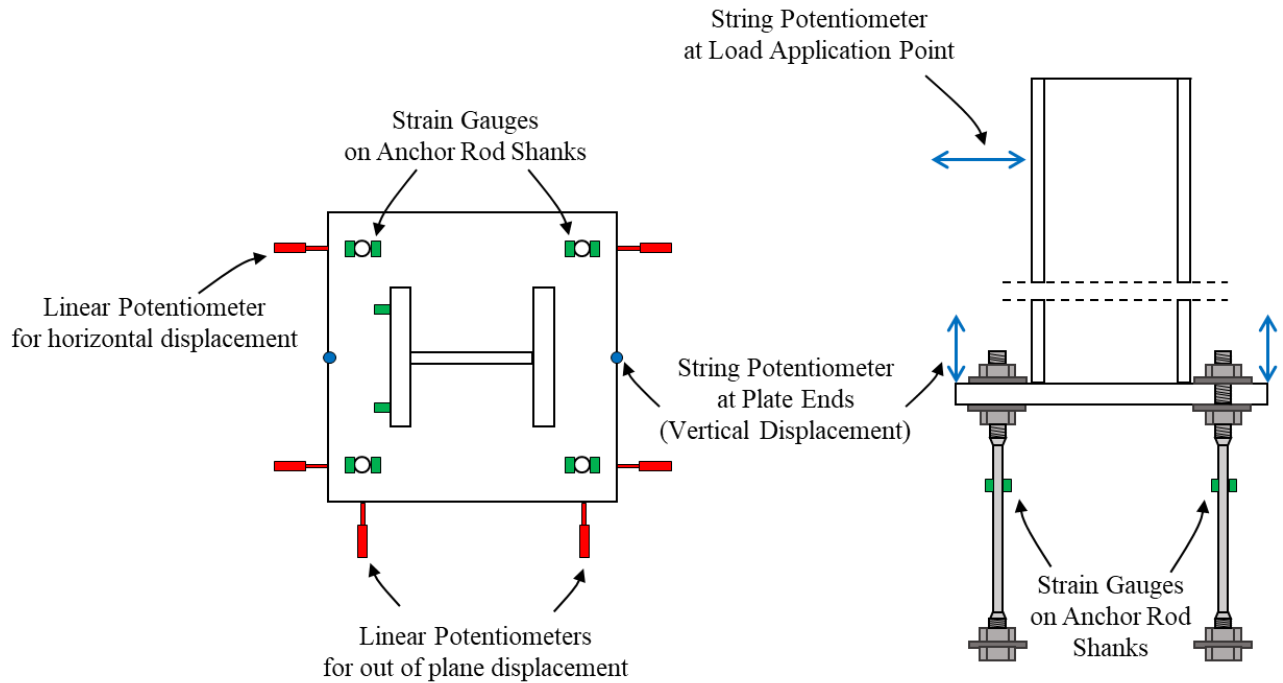


Figure 2.4 – Instrumentation schematics for the base plate and the column.

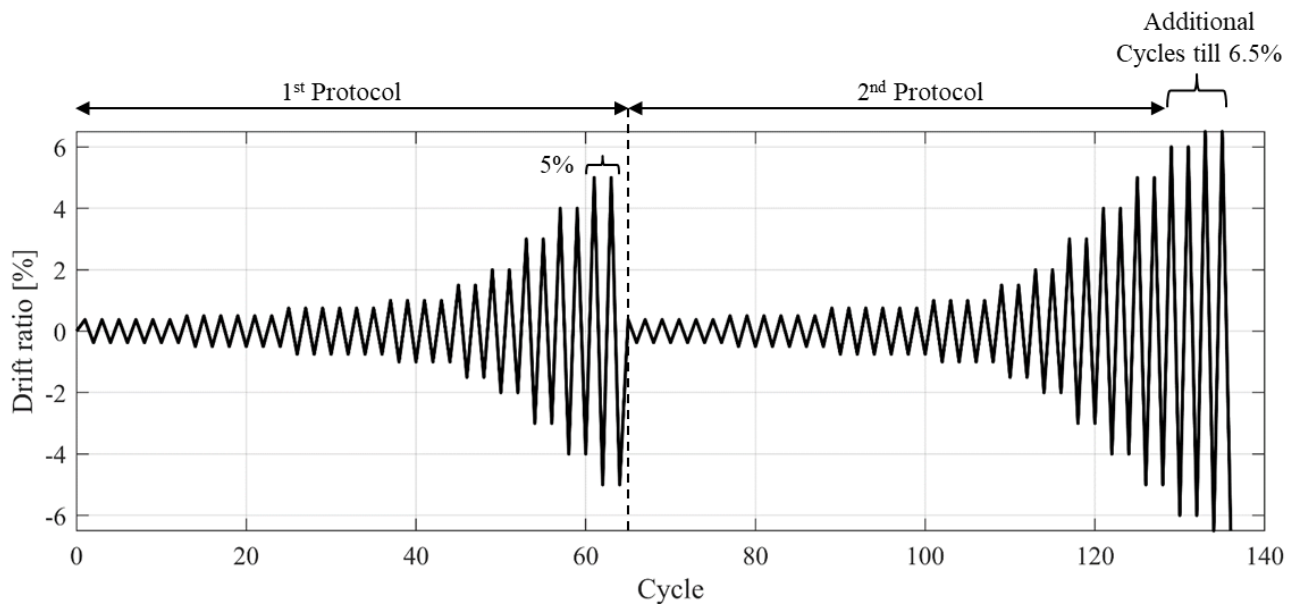


Figure 2.5 – Loading protocol with two consecutively applied ATC-SAC (Krawinkler et al. 2000) loading histories.

Table 2.1 – Tests Matrix and Results

Test ^{a, b}	Axial Load P [kN]	Rod Unthreaded d (Core) Diameter $d_{unthreaded}^{rod}$ [mm]	Rod ^c Threaded d Diameter $d_{threaded}^{rod}$ [mm]	Rod Reduced Diameter r d_{UT}^{rod} [mm]	Rod UT Length L_{UT}^{rod} [mm]	ASTM ^d F1554 Anchor Grade	M_{DG1}^e [kN.m]	$M_{max}^{test f}$ [kN.m]	$\frac{M_{max}^{test}}{M_{DG1}}$	$\frac{M_{4\%}^{test g}}{M_{max}^{test}}$
1	534 (120 kip)	19 (0.75")	16 (0.63")	12.7 (0.5")	419 (16.5")	55 (380 MPa)	356.7	506.8 (+)	1.42	0.82
								420 (-)	1.18	0.77
2							346.5	428 (+)	1.24	0.97
								467 (-)	1.35	0.94
3		25.4 (1")	22.3 (0.88")	19 (0.75")	381 (15")	105 (724 MPa)	451.7	552 (+)	1.22	0.90
								611 (-)	1.35	0.93
4	0						263.7	402.5 (+)	1.53	0.98
								378 (-)	1.44	0.93
								Mean	1.34	0.90
								COV	0.09	0.07

^a Tests featured $W14 \times 370$ (customary units) cantilever columns - ASTM A992 Grade 345 MPa.

^b Base plate dimensions: $N \times B \times t_p = 762 \times 762 \times 51$ mm; Edge distance between rod centerline and edge of plate = 101.5 mm. with 2 rods on each side; Oversized hole diameter in plate = 47.5 mm.

^c Square plate washers at top and bottom dimensions: $76 \times 76 \times 9.5$ mm and $76 \times 76 \times 12$ mm, respectively.

^d Values of anchor rod yield strength f_y^{rod} are nominal.

^e Moment calculated in accordance with current procedures outlines in AISC's Design Guide One - Fisher and Kloiber (2006).

^f Maximum moment measured for specimens in each direction of loading (positive and negative).

^g The ratio between the base moment at 4% drift (during the first application of SAC protocol) and the maximum moment.

Table 2.2 – Summary of measured material strengths from concrete/grout ancillary tests

Cure Age	# of Samples	Concrete Compressive Strength f'_c [MPa]	Grout Compressive Strength f_{grout} [MPa]
28 days	8	28.3	-
Day of full-scale test		31.0	58.6

Table 2.3 – Summary of measured material strengths from anchor rod ancillary tests (as per ASTM A370, 2020)

ASTM ^a F1554 Rod Grade	# of Samples	f_y^{rod} [MPa]	f_u^{rod} [MPa]	$\frac{\epsilon_{max}^{Test}}{\epsilon_{max}^{ASTM}}$ ^b
55 (380 MPa)	3	405.4	552.3	1.53
105 (724 MPa)		775.0	946.7	1.32

^a Measured yield stress for Grade 105 rods, is based on the 0.2% offset method.

^b The ratio between the average maximum strain for tested rods at fracture and the maximum strain provided by ASTM 1554 (2020) for a 8 in. (203 mm) gage length.

2.4 EXPERIMENTAL RESULTS

Figures 2.6a-d show the moment rotation plots for all four specimens. The rotation in these is determined by subtracting the elastic column rotations from the overall drift. For all specimens, the initial elastic response was observed until a base rotation of approximately 0.008-0.01 rad was reached; this corresponds to column drift of approximately 1-1.1 %. This was followed by non-linear response due to the yielding of the anchors with a gradual increase in resistance until a rotation of 0.04-0.05 rad. This was accompanied by gradual cycle-to-cycle degradation, as damage accumulated in the grout. After this point, the flexural resistance slowly decreased due to cycle-to-cycle degradation, although in-cycle degradation (i.e., negative slope) or failure was not observed in any of the experiments. For all specimens, the hysteretic response was pinched, owing to gapping and contact between the base plate and the footing. The hysteresis loops also showed an intermediate plateau of resistance (for tests with axial load). As noted previously by Gomez et al. (2010), this corresponds to the flexural resistance due to the prestressing effect from axial compression, wherein the connection resists moment without developing tension in the anchors. All tests exhibited extremely high deformation capacity, surviving both applications of the ATC-

SAC protocol as well as the subsequent 6.5% cycles, without rod fracture or any other form of catastrophic failure.

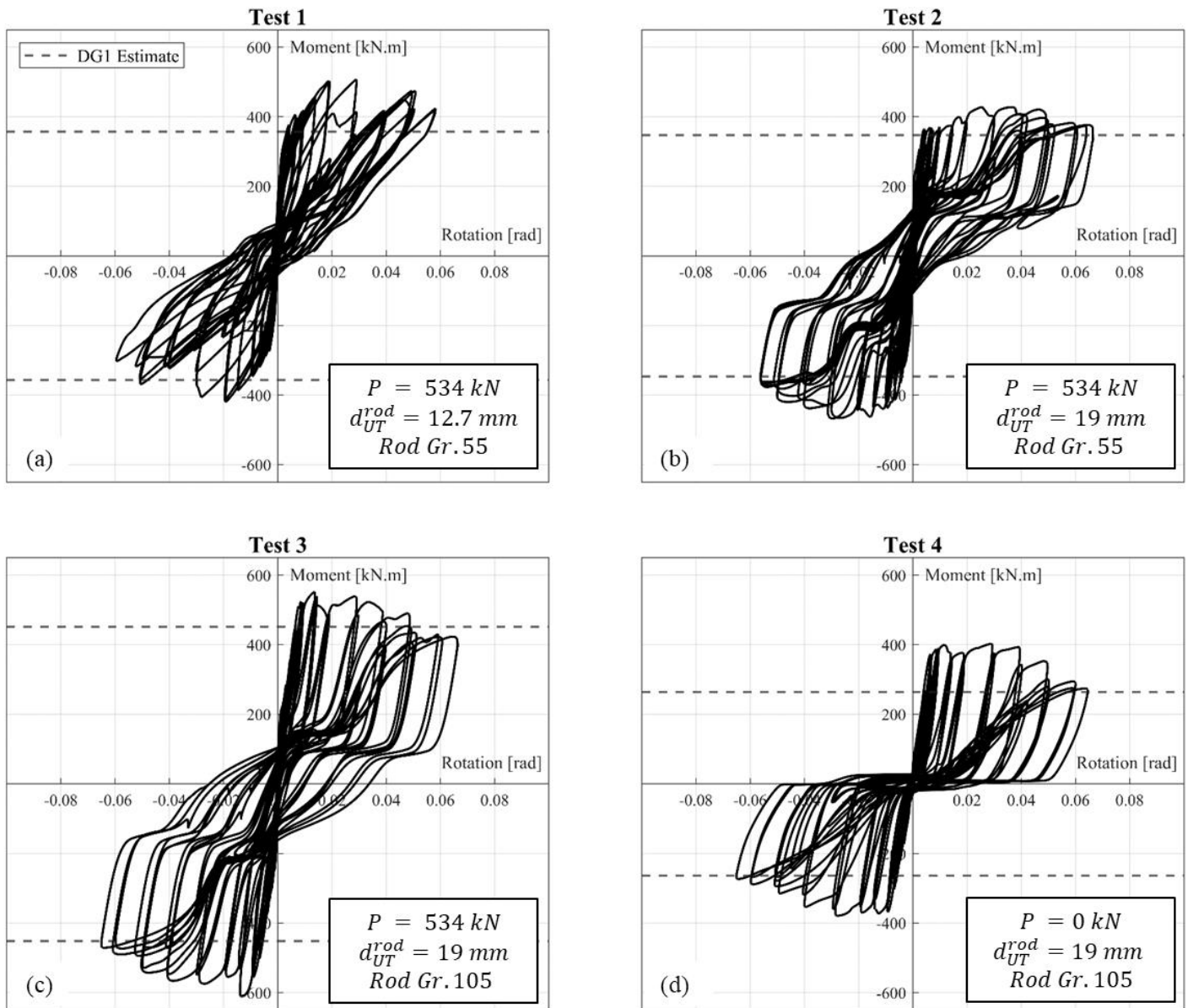


Figure 2.6 – Moment-Rotation plots for all tested specimens.

Figures 2.7a-d show damage progression photographs for one of the tests (Test #3) taken at various points during the cyclic loading history. The photographs illustrate typical response and failure modes of all test specimens. Referring to the photographs, the damage accumulation was gradual,

and observable mainly in the spalling of grout. Figure 2.7a illustrates damage observed during the initial stages of loading (at drifts $\leq 1\%$). Minor cracks began to form in the grout pad accompanied by surface flaking at the top of the pad surrounding the plate, with traces of plate separation from the pad at the plate/grout interface. However, this did not affect the load-deformation response, such that linear elastic response was observed until drifts of 0.8%. As loading progressed, the following damage modes were observed:

- Vertical cracks (Figure 2.7b) in the grout pad near the plate edges and cracks radiating from plate corners, followed by the breakage of the cold joint between grout and concrete.
- This damage progression continued until the end of the first SAC protocol (drift of 0.05 rad), leading to crushing/spalling of grout chunks at the plate corners with separation from the pad under the baseplate footprint. During the second application of the protocol, these chunks continued to crush and separate further from the base plate – see Figure 2.7c.
- No damage to the concrete footing was observed due to bearing. However in all specimens, punch-out of the anchor rods occurred through the bottom cover of the concrete, resulting in a gap below the bottom nut-washer assembly (Figure 2.7d). This gap was 13mm long (the thickness of the concrete cover), and allowed unrestrained vertical movement of the anchor through the gap. Implications of this are discussed in a subsequent section.
- Anchor rod yielding was observed in all tests. The yielding initiated in the stretch region between a drift of 1 and 1.5% for all tests (strain data from anchor rods confirmed this). As the grout pad deteriorated, compression force was transferred to anchor in compression through the leveling nut. At larger deformations ($> 4\%$ drift), dishing of the plate washer immediately below the base plate was observed, resulting in a small gap (~ 3 mm) at the top nut level (Figure 2.7c). This gap did not have any significant effect on the connection response.

Table 2.1 summarizes measured quantitative data. Two moment strength values are recovered for each specimen, one corresponding to the maximum moment measured in each direction of loading. These are denoted as M_{max+}^{test} and M_{max-}^{test} , where the positive sign denotes the direction of application of the first deformation cycle. The table includes the ratio between the maximum column base moment (M_{max+}^{test} and M_{max-}^{test}) observed during testing and the moment M_{DG1} calculated in accordance with current procedures outlined in *AISC's Design Guide One*, and measured material properties summarized in Tables 2.2 and 2.3. Referring to Table 2.1, the average value of M_{max}^{test}/M_{DG1} for all tests is 1.34 (with a Coefficient of Variation 0.09), indicating that the *AISC Design Guide One* approach is conservative. Table 2.1 also includes the ratio between the base moment observed at 4% drift (during the first application of the SAC protocol) and the maximum moment, i.e., $M_{4\%}^{test}/M_{max}^{test}$. This provides a direct point of reference to pre-qualification standards for beam-column connections (AISC 341-16 2016), wherein a resistance of 80% of the beam strength is required at 4% drift, when subjected to the ATC-SAC protocol. Referring to Table 2.1, the average value of $M_{4\%}^{test}/M_{max}^{test}$ across all experiments is 0.9, with a CoV of 0.07, indicating good performance in terms of maintaining strength for large deformations. The flexural resistance increases with the increase in compressive load (e.g., see Test #3 and 4 that are otherwise identical), as well as with an increase in anchor diameter (e.g., see Test #1 and 2) or steel grade (e.g., see Test #2 and 3). Other than these, the response was fairly consistent across the test variables.

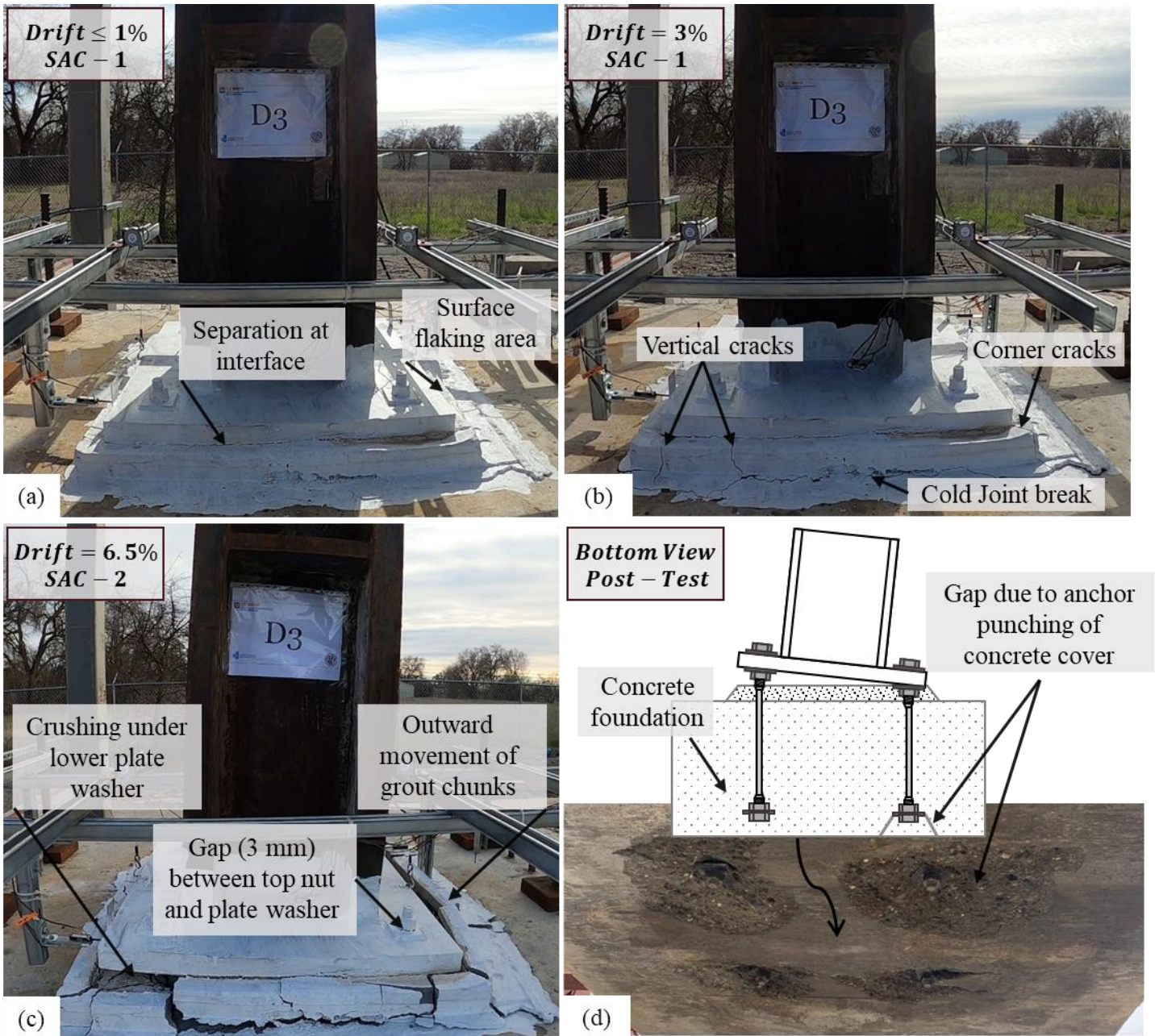


Figure 2.7 – Typical/observed damage progression for one of the tested specimens (Test #3).

2.5 SIMULATIONS TO ASSESS DEFORMATION CAPACITY OF UNTESTED CONFIGURATIONS

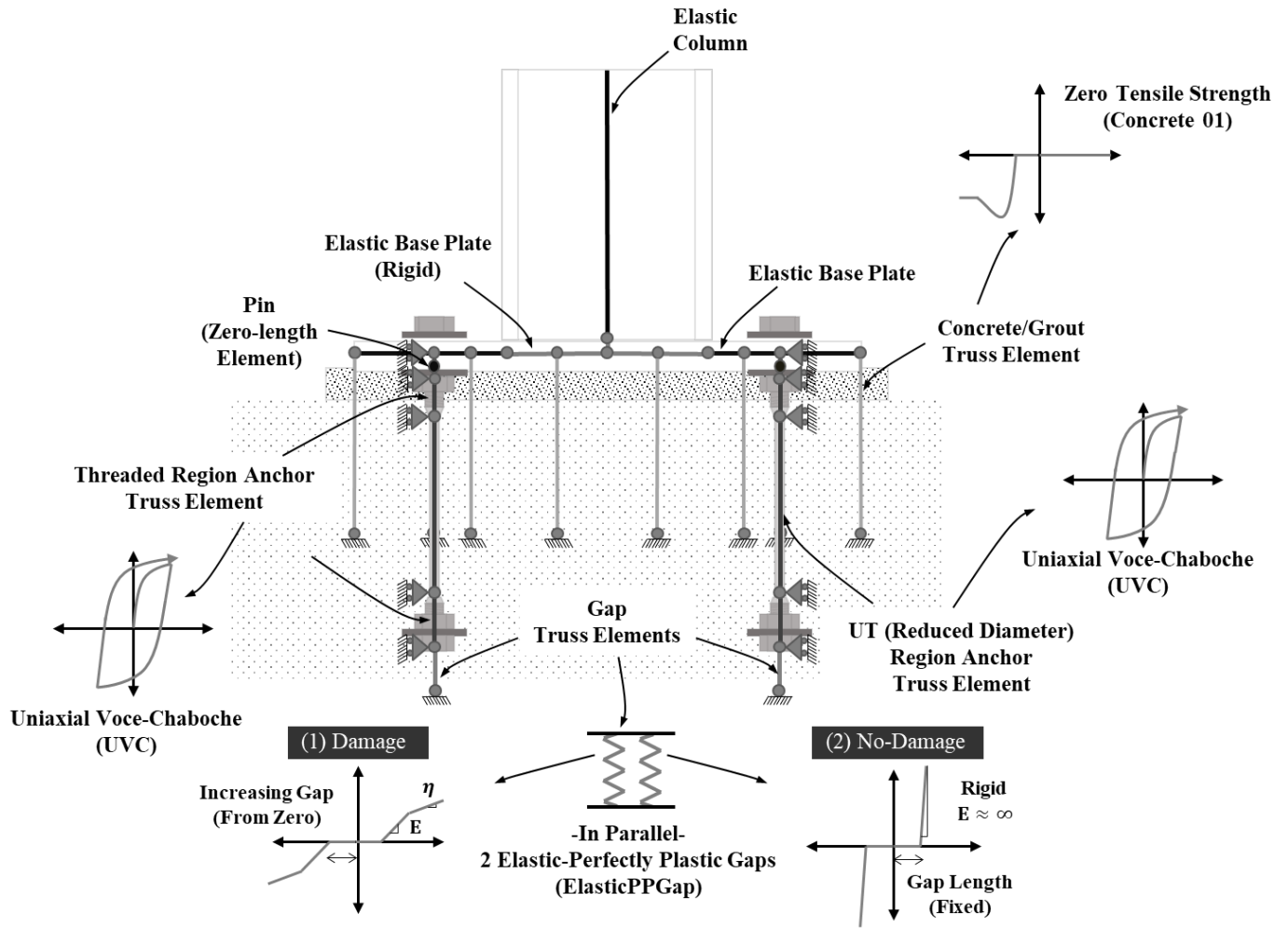
Simulations complementary to the experiments were conducted to examine the degree to which the high deformation capacity of the tested specimens may be generalized to untested

configurations. This included: (1) Line Element Based (LEB) models to infer the deformation histories in the anchor rods, (2) estimation of damage in the rods based on the deformation histories estimated from the LEB models; and (3) parametric assessment of this damage across various configurations.

Line Element Based simulations to characterize anchor deformation histories

Figure 2.8 schematically illustrates a representative two-dimensional Line-Element Based (LEB) model constructed using the OpenSees (v.3.2.1) platform (McKenna et al. 2012) to determine the deformation histories of the anchor rods. This model follows the methodology outlined by Inamasu et al. (2021). Referring to Figure 2.8, the base connection is represented through an assembly of uniaxial springs and beam-column elements; these include:

1. *Beam-column elements to represent the base plate as well the column:* These components are simulated as elastic recognizing that dissipative base connections will be designed to concentrate inelastic response only in the UT region of the anchor rods. The beam-column elements representing the plate in the flap region outside the W-section assume an effective width equal to the entire plate width, assuming that the high flexural rigidity of the plate minimizes bending in the out of plane direction. Within the W-section region, the beam-column elements representing the plate are modeled as rigid.
2. *Uniaxial spring elements to represent the bearing response of the footing:* A total of 20 such elements are used (not all shown in Figure 2.8 for clarity), each representing the response of a segment of the footing. The Zero Tensile Strength material model (Kent-Scott-Park Concrete Material (Kent and Park 1971; Scott et al. 1982) – implemented as “Concrete01” in OpenSees) is used to represent concrete/grout response. This model captures important aspects of footing



Parameters for Gap Element			
Parameter		Value	Rationale
Stiffness of gap material [kN/mm]	E_{gap-1}	175000	Calibrated to match test data
	E_{gap-2}	$\approx \infty$	Laboratory strong floor stiffness
Yield force of gap material [kN]	$F_{y_{gap-1}}$	106	Concrete end blowout strength as per the ACI 318-19 provisions (ACI 2019)
	$F_{y_{gap-2}}$	$\approx \infty$	Laboratory strong floor stiffness
Gap length [mm]	δ_{gap-1}	0	Initial condition (no gap)
	δ_{gap-2}	13	Gap length after test completion (concrete cover)
Material hardening ratio	η_{gap-1}	0	No hardening for gap growth (elastic perfectly-plastic)
	η_{gap-2}	1	Laboratory strong floor stiffness (almost elastic)

Figure 2.8 – Schematic illustration of the two-dimensional Line-Element Based (LEB) simulation model with element and material definitions.

behavior, including softening due to crushing, the absence of tensile strength (that results in gapping between the plate and concrete/grout), and strength degradation due to cyclic loading.

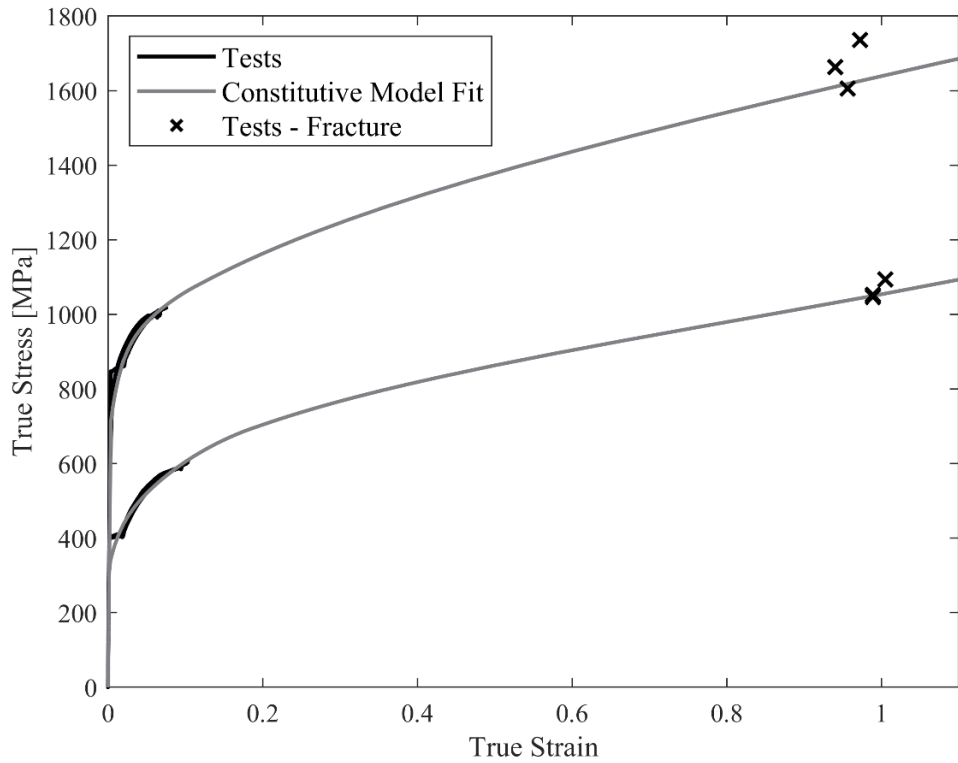


Figure 2.9 – Comparison of uniaxial coupon test data and constitutive model fit for the ASTM F1554 (Grade 55 and 105) rods.

The parameters of the concrete and grout were calibrated based on cylinder tests as follows: compressive strength, $f_{pc} = 58.6 \text{ MPa}$, compressive strain at maximum strength, $\varepsilon_{c0} = 0.003$, crushing strength, $f_{pcU} = 6.89 \text{ MPa}$ and compressive strain at crushing strength, $\varepsilon_U = 0.005$. It is important to note here that the softening properties of the concrete response imply a length scale over which softening (and hence localization) occurs (Bazant 1976). Consequently, the parameters controlling this (specifically f_{pcU} and ε_U) are calibrated to fit the load-displacement response of the test data.

3. *Uniaxial spring elements to represent the anchor rods:* Each anchor rod was simulated as an assembly of three springs (represented by uniaxial truss elements) in series. Of these, the element in the center represents the UT section over which the plastic deformations concentrate – the effective diameter for this element was set equal to the reduced diameter size from the tests (12.7 mm for Test #1 and 19 mm for Tests #2, 3 and 4). The two outer springs represented the threaded region of the rod outside this length. For these, the diameters were set equal to 16

mm for Test #1 and 22.3 mm for Tests #2, 3 and 4. The constitutive response of the steel material was represented through the Voce-Chaboche model (Voce 1948 and Chaboche et al. 1979), implemented in OpenSees as Updated Voce-Choboche “UVCuniaxial” (de Castro e Sousa et al. 2020). The parameters of this model (which includes combined isotropic and two-backstress kinematic hardening) were calibrated as the following: elastic modulus of steel, $E_{rod} = 200000 \text{ MPa}$; initial yield stress of steel, $f_y^{rod} = 405.5 \text{ MPa}, 775 \text{ MPa}$; maximum increase in yield stress due to isotropic hardening $Q_\infty = 0.07 \text{ MPa}$; isotropic hardening saturation rate $b = 0.54$; kinematic hardening parameters $C_1 = 6550 \text{ MPa}, 11721.1 \text{ MPa}$, $C_2 = 173.1 \text{ MPa}, 138 \text{ MPa}$; $\gamma_1 = 61.8, 72.8$ and $\gamma_2 = 13.5, 40.57$. The two values for some of these parameters are for the Grade 55 and 105 steels, respectively. The monotonic parameters (E_{rod} , f_y^{rod} , and f_u^{rod}) as well as the C_1 and C_2 parameters were calibrated to match the response of uniaxial coupon tests conducted on unthreaded rod material as shown in Figure 2.9, whereas the remaining parameters were adopted from the study of de Castro e Sousa et al. (2020). Referring to Figure 2.9 (see the X-markers), the complete true stress-strain response (which includes information even after necking and extensometer) was inferred by measuring the force at fracture, and the corresponding post-fracture necked diameter.

4. *Gap elements*: Referring to prior discussion, gapping was observed at the bottom of the anchor rod due to punch-out of the concrete cover in the footing (Figure 2.7d). This gapping accommodates overall deformations of the connection and has the potential to decrease the strain demands in the designated stretch length of the rod for a given magnitude of connection rotation. The gapping at the bottom was represented through an assembly of two springs in parallel attached in series with the bottom end of the anchor rod springs (as shown in Figure 2.8). Each spring is represented through a tension/compression Elastic-Perfectly Plastic Gap

material implemented in OpenSees as “ElasticPPGap”. When represented in this way, the spring arrangement activates the gap at a pre-determined level of compressive force (corresponding to the punch-out of the concrete), and then increases the gap dimension each time additional damage is accumulated during subsequent cycles. The maximum gap dimension in the downward direction corresponded to the distance at which the bottom of the rod would impinge the strong floor. Figure 2.8 includes an inset table in which the various LEB gap parameters are summarized, with the rationale for their selection.

Using the above approach, LEB models were constructed complementary to the four full scale experiments. These simulation models were subjected to the axial load and lateral loading protocols as applied to the experimental specimens. Figures 2.10a-d compare the load-deformation response for each test to the corresponding response as determined from the LEB models. Referring to the figures, the LEB models simulate the overall load-deformation response with accuracy, including the various transition points that correspond to contact/gapping between the plate and concrete and the anchor and strong floor (i.e., gap closure). The sharp kinks in the simulated curves arise due to the placement of bearing springs at discrete locations; this response is smoothed if more springs are added. Referring to Figure 2.10a, the higher values of moment from the test compared to the simulation results is possibly attributed to asymmetry in the direction of loading for this specific specimen (Test #1) – particularly some additional grout was deposited on one side versus the other. However, the model is able to simulate the moment values, as well as the hysteretic behavior (loading and unloading branches) on the negative side with good accuracy. As an additional source of validation, similar agreement was found for the evolution of other experimental quantities for all tests, including the vertical motion of the base connection at

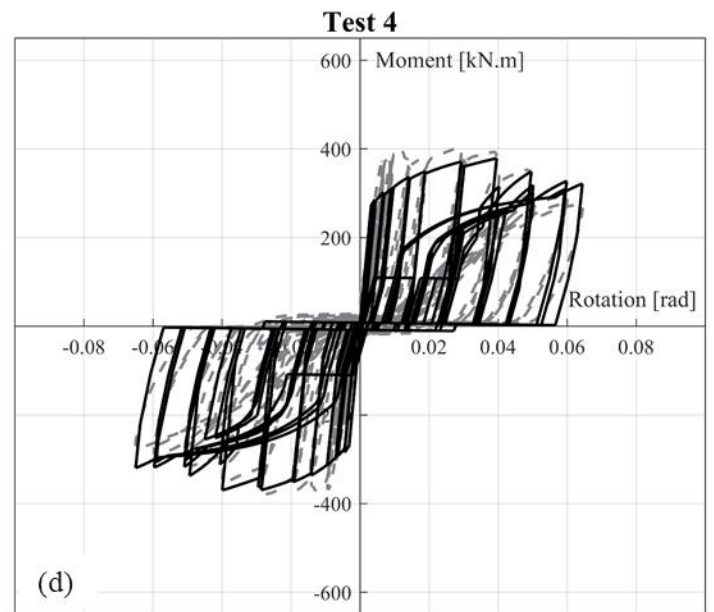
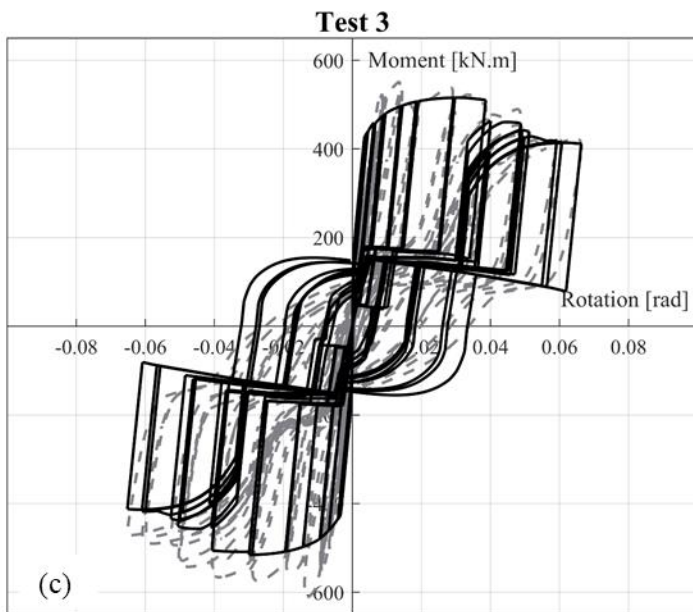
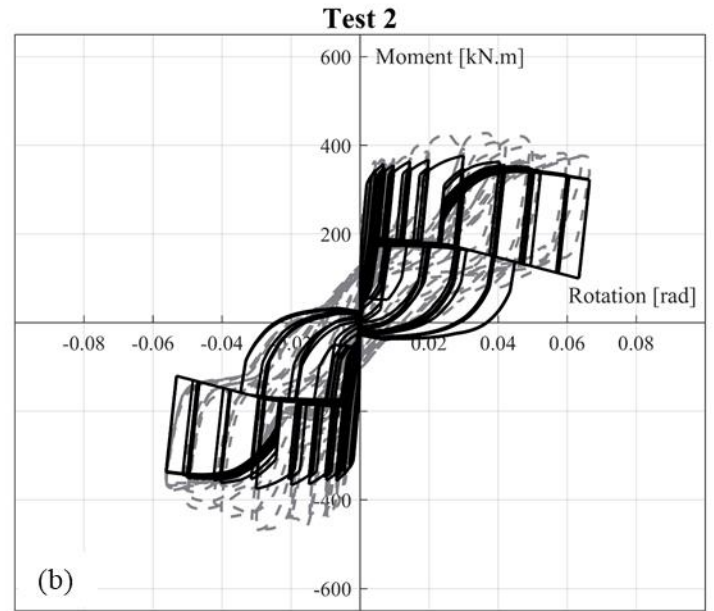
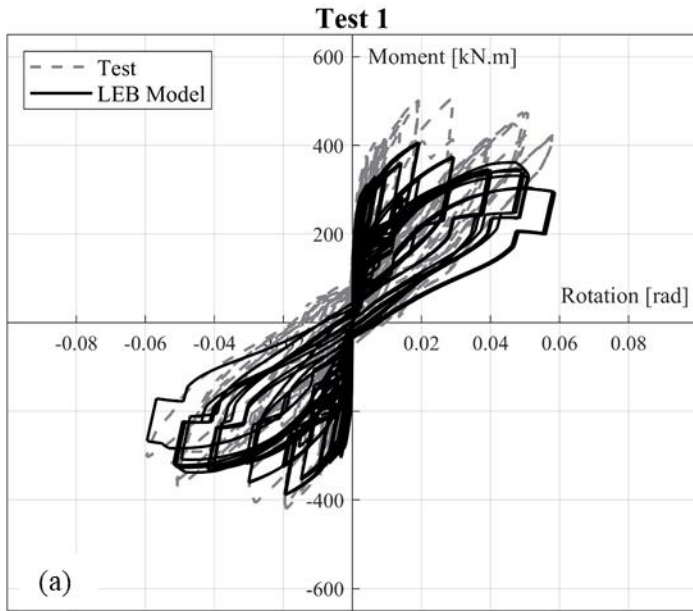


Figure 2.10 – Moment-Rotation curves for the 4 tested specimens and their corresponding curves recovered from LEB model.

the location of the anchor rods, as shown in Figures 2.11a-d. The vertical motion at this location is a direct indicator of the anchor rod deformations that are used for assessing their capacity. In this context, the vertical displacement, as predicted by the LEB model (corresponding to anchor rod tension at a drift of 4%) is within 7% of the experimental displacement.

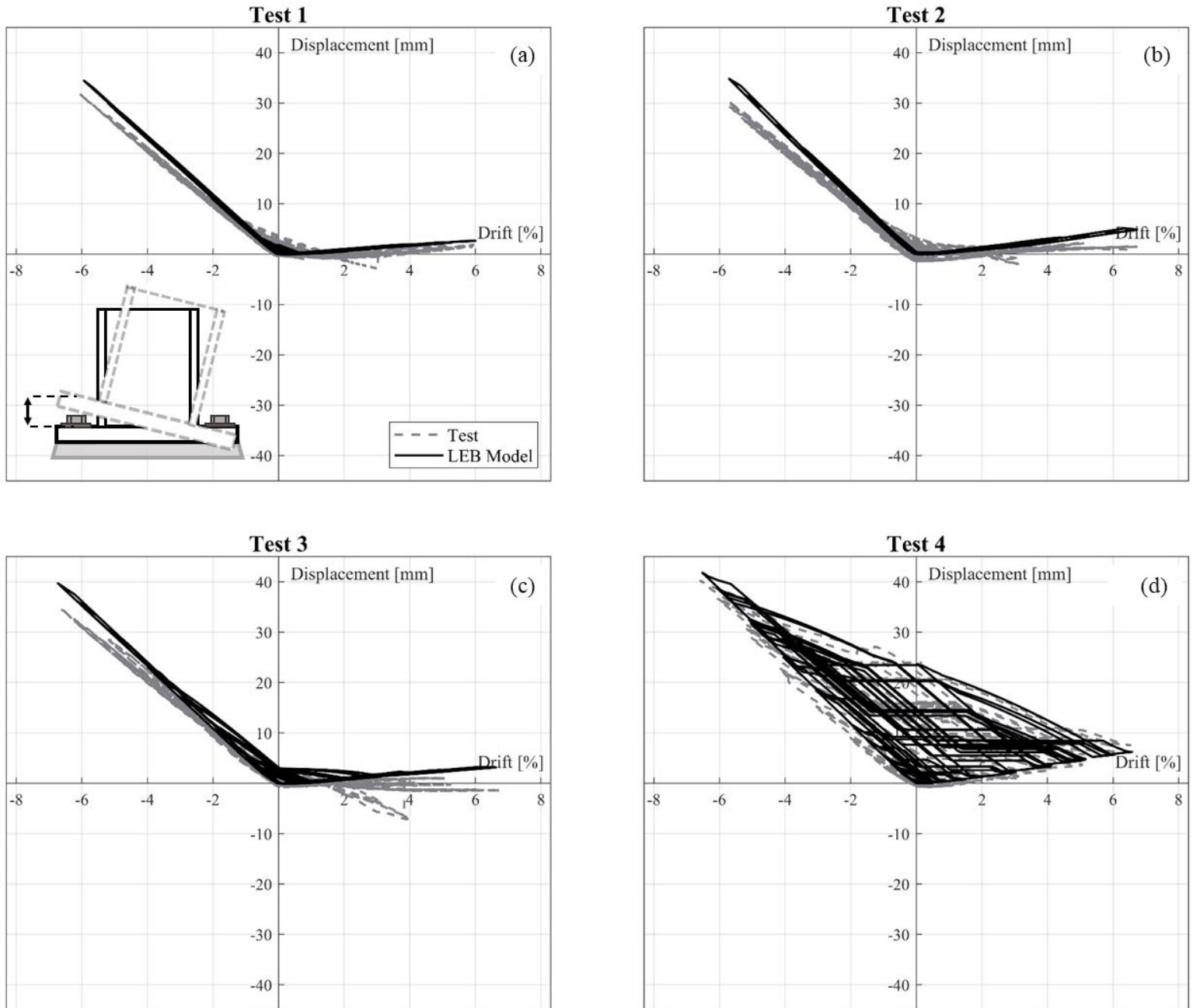


Figure 2.11 – Vertical displacement history of the base plate at anchor rod location plotted against column drift from tested specimens and LEB models.

This, along with the agreement in the load-deformation response suggests that the LEB models effectively represent the physics of connection response and may be used to characterize the load deformation response and anchor deformation histories. Once validated, the simulation approach was used for parametric simulation of configurations that were not tested physically. Table 2.4

summarizes all the parameter sets (including those complementary to the physical experiments) for which the LEB models were constructed. Referring to Table 2.4, these parameter sets include:

- Additional base plate sizes, since the base plate size (specifically the length N) directly influences the kinematic relationship between the connection rotation and rod deformation.
- Situations in which there is no gapping below the anchor, to examine a more conservative condition with respect to strain accumulation in the anchors. This may occur when a large concrete cover below the bottom end of the anchor prevents blowout. Two values of $\delta_{gap} = 13 \text{ mm}$ (similar to experiments) and $\delta_{gap} = 0 \text{ mm}$ (no gap) were examined.
- Additional values of the anchor rod diameters and the stretch length L_{UT}^{rod} .

Each of the LEB models in Table 2.4 was subjected to cyclic column lateral deformations consistent with two ATC-SAC protocols applied consecutively followed by additional cycles to 6.5% drift – identical to the drift histories applied to the experiments (illustrated previously in Figure 2.5). Anchor rod deformation histories were extracted from each run. Figure 2.12 shows two such deformation histories plotted against the cumulative drift applied at the top of the column. One history corresponds to Test #2 (i.e., Simulation #18 in Table 2.4). The other history is for an identical configuration, albeit with δ_{gap} set to 0 (Simulation #19). Both deformation histories show only the deformations of the anchor rod (UT region), excluding the gapping displacements – since only these deformations contribute to damage and eventual failure of the anchor rod. Referring to Figure 2.12, two observations may be made:

- Although the column deformations are symmetric, for Simulation #18 (with gap) during the initial cycles of loading, the rod elongations ratchet in the tensile direction. This may be attributed to the gradually opening gap below the anchor rod, which prevents full recovery of compressive deformations. In fact, as indicated in Figure 2.12, the saturation value of the gap

(i.e., $\delta_{gap} = 13 \text{ mm}$) is consistent with the irrecoverable deformation in the anchor. Referring to the “no-gap” deformation history (Simulation #19), it is apparent that all the deformation is recovered during compressive cycles, as expected.

- A consequence of the above behavior is that although the cumulative plastic strain in the no-gap situation is larger, the peak tensile plastic strain is virtually identical between the gap and no-gap situations; this observation is consistent across all the parameter sets studied.

Damage assessment in anchor rods

The anchor rod deformation histories recovered from each of the parametric simulations may be used to infer damage in the anchor rods. Based on observations of failure in previous EBP experiments (Gomez et al., 2010; Trautner et al., 2017), and of similar steel components subjected to cyclic loading (e.g., Kanvinde 2004 for steel rods; Terashima 2018 for buckling restrained braces) two relevant damage/failure modes are considered: (1) necking of the anchor rods in the UT section, which leads to strain accumulation and fracture, and (2) Ultra Low Cycle Fatigue (ULCF) fracture of the anchor rods which may occur without necking, due to plastic strains accumulated homogeneously over the UT length. Each of these is now discussed.

- *Necking induced failure:* Previous experiments on EBP connections as well as cyclically loaded steel rods indicate that necking (which occurs on a tensile excursion) results in loss of strength, and rapid localization of strains within the necked region, ultimately leading to fracture. It is well established (Considère 1885) based on volume conservation arguments that necking instability in axially loaded bars occurs when the instantaneous true longitudinal stress in the rod exceeds the instantaneous tangent modulus of the material, expressed mathematically as $\sigma_{true} \geq (d\sigma_{true}/d\varepsilon_{true})$. In this expression, the true stress and strain are functions of the

engineering values as $\sigma_{true} = \sigma_{eng} \times (1 + \varepsilon_{eng})$, and $\varepsilon_{true} = \ln(1 + \varepsilon_{eng})$. The main implication is that in cyclically loaded rods, history effects are not important, because only the instantaneous values of stress and the tangent modulus control the necking instability. To examine this further, Figure 2.13 plots the true stress-strain curves for two of the simulations whose deformation histories were shown earlier in Figure 2.12. Stress-strain curves for all parametric simulations are qualitatively similar. Referring to Figure 2.13, two points are evident. First, from the standpoint of predicting necking, which occurs at strains greater than 0.1, the hysteresis loops are fully stabilized for both the gap and no-gap situations. Due to this loop-stabilization, the tensile strain interpreted in a monotonic manner (disregarding history effects) is an accurate predictor of the instantaneous stress, as well as the tangent modulus. Second, for a given connection rotation, the tensile strain is virtually identical between the gap and no-gap situations, even if the accumulated strain is different. Based on the above observations, the following damage index is proposed for necking:

$$D_{neck} = \varepsilon_{max} / \varepsilon_{neck} \quad (2.1)$$

In the above, ε_{max} is the maximum tensile strain encountered until any point in the loading history of the UT section in LEB model, whereas ε_{neck} denotes the value of strain at which necking would initiate, such that $D_{neck} = 1$ predicts necking. For each steel grade, the value of ε_{neck} is inferred from the maximum elongation values in ASTM 1554 (2020). Specifically, the failure elongations implied in ASTM 1554 correspond to a standard tensile test. The failure elongation may be decomposed as follows:

$$\Delta_{failure} = \Delta_{neck} + \Delta_{post-neck} \quad (2.2)$$

In the above, Δ_{neck} represents the deformations up to the point of necking, and $\Delta_{post-neck}$ represents the post-necking deformations to fracture. Of these, Δ_{neck} corresponds to a state of

uniform strain over the gage length, whereas $\Delta_{post-neck}$ corresponds to localized deformations and has been shown to be independent of gage length for a given rod diameter (e.g., see Kolwankar et al. 2017). Consequently, Equation (2.2) above may be simplified to:

$$\varepsilon_{max} \times L_{gage} = \varepsilon_{neck} \times L_{gage} + \Delta_{post-neck} \quad (2.3)$$

For each steel grade, ASTM 1554 provides two values of ε_{max} , for two gage lengths. These values may be used in conjunction with Equation (2.3) above to eliminate $\Delta_{post-neck}$, and estimate ε_{neck} . The computed values of ε_{neck} are as follows: 0.17 for the Grade 55 anchor rod, and 0.11 for the Grade 105. Once ε_{neck} is thus calibrated, the damage index D_{neck} and its evolution may be determined for each of the simulations; see Figure 2.14 for an illustration of one such evolution of D_{neck} (for Simulation #18).

- *Ultra Low Cycle Fatigue Failure:* In situations where no single tensile cycle is large enough to trigger necking, Ultra Low Cycle Fatigue (ULCF) fracture may still occur due to cyclic plastic strains that accumulate in a homogenous manner over the entire UT region (rather than localize due to necking). Numerous continuum damage mechanics-based criteria have been proposed to predict ULCF fracture – Kanvinde (2017) provides a comprehensive review. In this work, ULCF damage was assessed based on the Stress Weighted Damage Fracture Model (SWDFM) proposed by Smith et al. (2021), which has been extensively validated against experimental data from structural steels. The original SWDFM model includes continuum stress invariants, including stress triaxiality and the Lode parameter – see Smith et al. (2021) for the detailed expression. However, for the uniaxial cyclic case with an axisymmetric state of stress (for which the triaxiality alternates between +1/3 and -1/3 for tension and compression, and the absolute value of Lode parameter equals 1), the fracture (or damage)

criterion corresponding to the SWDFM may be represented as the following damage index, which predicts ULCF when it exceeds 1:

$$D_{ULCF} = \int_0^{\varepsilon_p} C \times [2 \times \exp(1.3 T) - \exp(-1.3 T)] \times d\varepsilon_p \quad (2.4)$$

All terms in the above equation may be known or readily calculated from the stress-strain histories determined from the LEB simulations; specifically, T is the stress triaxiality that alternates between $\pm 1/3$ for tension and compression, $d\varepsilon_p$ is the incremental plastic strain, and C is a material parameter. Based on data reported for various materials by Smith et al. (in press), the parameter C is selected as 0.31 (the highest reported value in literature) to conservatively estimate the ULCF damage. Based on this, Figure 2.14 also shows the evolution of D_{ULCF} for Simulation #18, overlaid on the evolution of D_{neck} shown previously.

Both the LEB models and the above damage measures based on them assume that the anchors undergo purely axial deformations in tension and compression. However, the rotation of the base plate produces small lateral deformations at the top of the anchor rod (due to the arcing effect), resulting in bending strains and stresses. To examine whether this influences strains in the UT region, 6 Continuum Finite Element (CFE) simulations were conducted using the ABAQUS (v.6.14) simulation platform (2014). These simulations interrogated: (1) column sizes (W14x370 and W8x48); (2) base plate footprints (762x762 mm² and 356x356 mm²); (3) anchor rod grades (ASTM F1554 Grade 55 and Grade 105), diameters (25.4 mm with UT diameter of 19.1 mm and 19.1 mm with UT of 12.7 mm); and (4) axial loads (in the range of 0 to 534 kN) and loading heights (2.3 to 3.4 m). Each of the simulations was subjected to displacement-controlled lateral loadings until necking was observed in an anchor rod. The CFE models can simulate necking in the rods, because they use large-deformation continuum elements to represent the rods. Key aspects of connection physics were simulated following best-practices outlined previously by

Kanvinde et al. (2013); these include (1) all geometric aspects including nut-washer assemblies at the end of the rods, and the transitions at the ends of the UT; (2) appropriate constitutive properties of all materials – specifically the Armstrong Frederick model for steel (1966), which is the multiaxial analogue of the UVC model used in the LEB simulations, and an elastic model for the concrete; and (3) frictionless hard contact between the anchor and the concrete/grout. Figure 2.15 illustrates the plastic strain contours in one such model after necking initiation in the anchor rod. Referring to the figure, the maximum strains occur in the UT region of the rod, and the bending in this region is negligible.

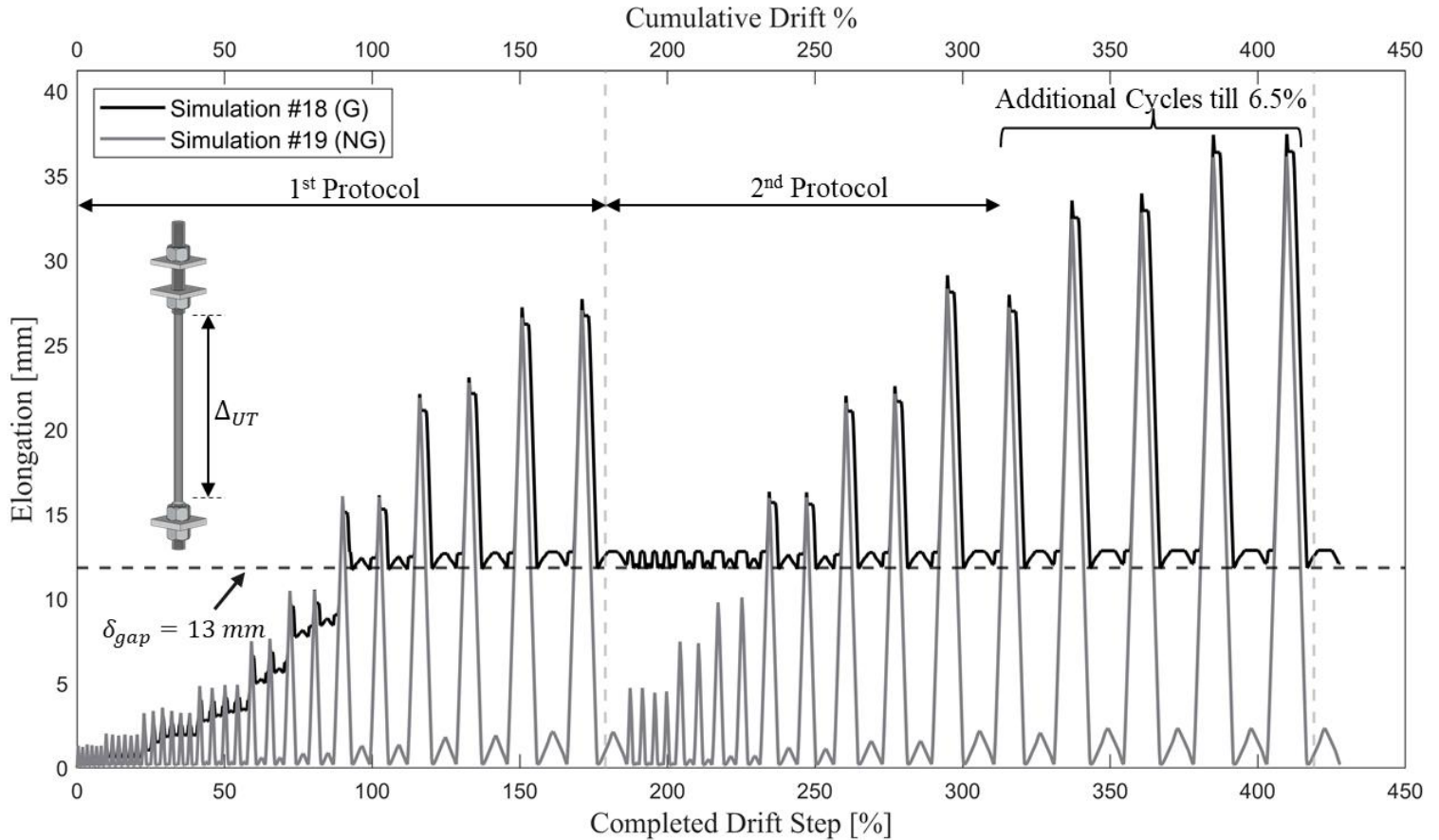


Figure 2.12 – Anchor rod elongation history plotted against cumulative drift.

Table 2.4 – Simulation Matrix and Results

Simulation ^a #		N ^d [mm]	P [kN]	L _{UT} ^{rod} [mm]	d _{threaded} ^{rod} [mm]	d _{UT} ^{rod} [mm]	Rod Gr. ^e	D ^{SAC-1} ^f _{neck}		D ^{SAC-2} ^g _{neck}		D ^{SAC-1} ^f _{ULCF}		D ^{SAC-2} ^g _{ULCF}		M _{4%} ^{simulation} M _{max} ^{simulation} ^h						
G	NG							G	NG	G	NG	G	NG	G	NG							
1	2	1016	890	508	35	31.8	105	0.65	0.65	0.88	0.87	0.10	0.20	0.33	0.63	0.96	1.00					
3	4							0.86	0.86	1.16	1.16	0.14	0.28	0.45	0.85	0.96	1.00					
5	6							0.92	0.91	1.22	1.22	0.13	0.33	0.29	0.95	0.98	0.98					
7	8			28.7	25.4	55	0.62	0.61	0.81	0.81	0.19	0.42	0.60	1.15	0.93	0.96						
9	10			35	31.8	105	0.82	0.82	1.13	1.13	0.13	0.27	0.43	0.83	0.94	0.98						
11	12		1779	381	28.7	25.4	105	55	0.57	0.57	0.77	0.77	0.17	0.36	0.54	1.03	0.92	0.96				
13	14							105	0.87	0.87	1.18	1.18	0.15	0.31	0.47	0.92	0.92	0.96				
15	16							55	0.59	0.59	0.79	0.79	0.18	0.39	0.57	1.09	0.90	0.93				
17 ^b	-							762	534	419	16.5	12.7	55	0.42	-	0.48	-	0.29	-	0.67	-	0.80
18 ^b	19	0.48												0.46	0.64	0.61	0.14	0.34	0.41	0.91	0.95	0.97
20 ^b	-	0	381	22.3	19	105	0.70							-	0.94	-	0.08	-	0.20	-	0.92	-
21 ^b	-					55	0.77		0.98	0.98	0.08	-	0.19	-	0.96	-						
22	23	890	381	16.5	12.7	105	55		0.68	0.67	0.89	0.89	0.09	0.25	0.29	0.71	0.91	0.96				
24	25						55		0.45	0.44	0.59	0.58	0.12	0.32	0.36	0.85	0.89	0.93				
26	27						105		0.69	0.69	0.91	0.90	0.18	0.27	0.39	0.75	0.88	0.90				
28 ^c	29						55		0.45	0.45	0.59	0.59	0.32	0.33	0.85	0.88	0.85	0.85				
30	31						508		223	508	22.3	19	55	0.24	0.23	0.31	0.30	0.04	0.13	0.10	0.38	0.95
32	33	0.31	0.30	0.41	0.40	0.06		0.18						0.14	0.51	0.97	0.98					
34	35	15.9	105	0.47	0.46	0.63		0.62						0.04	0.14	0.10	0.43	0.98	0.97			
36 ^c	37	667	381	22.3	19	105		55	0.31	0.30	0.41	0.40	0.18	0.19	0.51	0.54	0.97	0.98				
38	39							105	0.41	0.41	0.56	0.56	0.03	0.11	0.08	0.36	0.92	0.90				
40	41							55	0.28	0.28	0.38	0.37	0.05	0.16	0.13	0.46	0.81	0.83				
42	43							105	0.43	0.43	0.57	0.57	0.04	0.13	0.09	0.38	0.87	0.85				
44 ^c	45							55	0.29	0.29	0.38	0.38	0.16	0.17	0.46	0.49	0.78	0.79				
46	47	356	400	305	16.5	15.9		105	0.30	0.31	0.43	0.44	0.02	0.07	0.03	0.22	0.96	0.92				
48	49						0.25		0.26	0.35	0.36	0.02	0.05	0.03	0.17	0.96	0.92					
50	51						12.7		55	0.28	0.28	0.38	0.38	0.06	0.06	0.15	0.21	0.87	0.87			
52 ^c	53		667	381	16.5	15.9	105	55	0.19	0.19	0.25	0.25	0.09	0.09	0.27	0.29	0.78	0.78				
54	55							55	0.23	0.23	0.32	0.33	0.02	0.04	0.02	0.15	0.90	0.88				
56 ^c	57							55	0.17	0.17	0.23	0.23	0.07	0.07	0.22	0.24	0.80	0.80				
58	59							105	0.25	0.25	0.35	0.35	0.05	0.06	0.15	0.19	0.82	0.82				
60 ^c	61							55	0.17	0.17	0.23	0.23	0.08	0.08	0.25	0.26	0.73	0.73				

^a G = “with gap of length 13 mm”; NG = “with no gap”

^b Simulations represent the tested specimens (Tests #1,2,3 and 4 respectively).

^c Bottom gap was not fully activated for these simulations.

^d Base plate dimensions N × B × t_p and (column profile): 1016 × 610 × 102 mm (W24 × 176); 762 × 762 × 51 mm (W14 × 370); 508 × 508 × 51 mm (W12 × 96); 356 × 356 × 51 mm (W8 × 48) for N = 1016, 762, 508 and 356 mm, respectively.

^e ASTM F1554 Anchor rod grade with f_y^{rod}=405 and 775 MPa for grades 55 and 105, respectively.

^f The maximum necking and ULCF damage indices observed before the end (5% cycles) of the first application of the SAC protocol (SAC-1).

^g The maximum necking and ULCF damage indices observed before the end of the second application of the SAC protocol (SAC-2) and the additional cycles till 6.5%.

^h The ratio between the base moment at 4% drift during the first application of the SAC protocol (SAC-1) and the maximum moment, observed during the simulations.

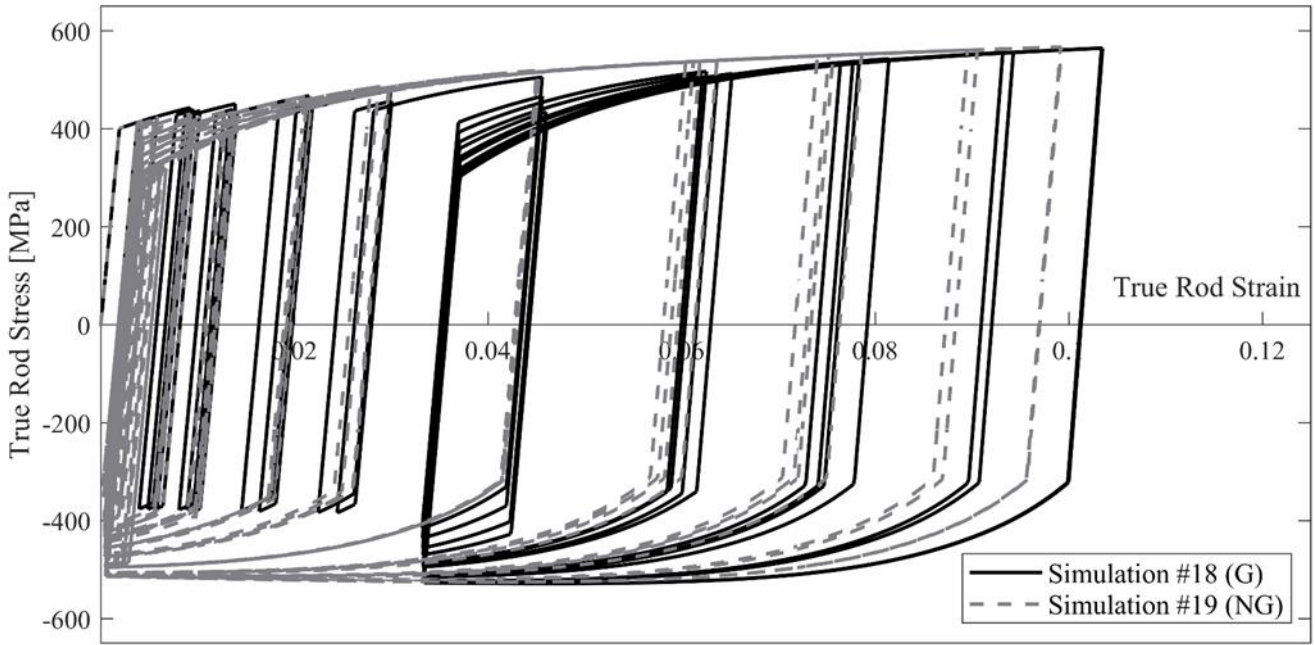


Figure 2.13 – Anchor rod true stress-strain curves, for Simulations #18 and 19 (G and NG).

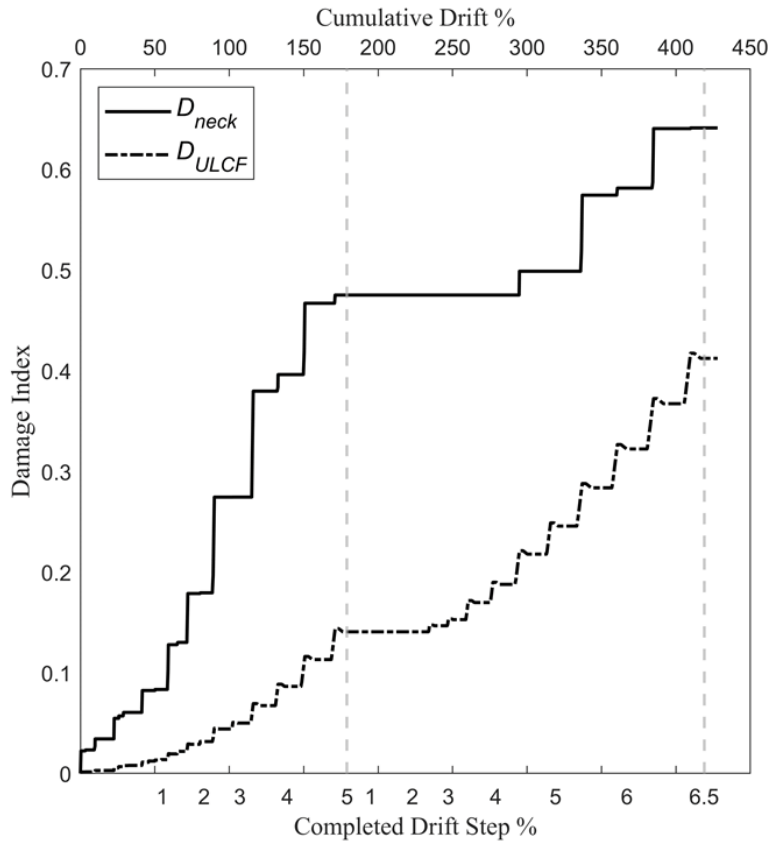


Figure 2.14 – Evolution of D_{neck} and D_{ULCF} for Simulation #18 (G); vertical dashed lines indicate completion of first and second loading protocol.

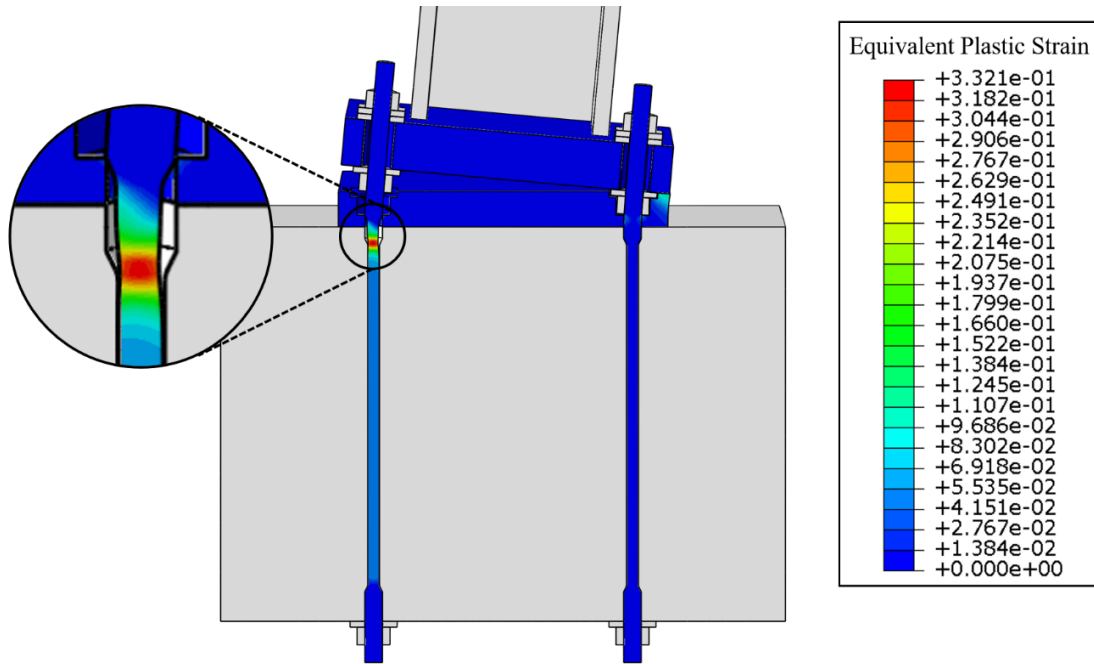


Figure 2.15 – Plastic strain contours from CFE simulation showing necking in the UT region of the rod.

Additionally, a series of 32 CFE component simulations (including the UT region of the anchor rod and the surrounding concrete – see Figure 2.16a) were conducted to examine the validity of the proposed necking damage index D_{neck} . The three-dimensional CFE models feature a frictionless interface between the rod and concrete surface, and are able to directly simulate necking in the rods following a well-established, and validated methodology for simulating tensile necking (e.g., see Terashima 2018) because they can represent the diametral reduction of the rods, and its interaction with constitutive response. Moreover, the models do not require the introduction of a diametral imperfection to initiate the necking instability, because mild gradients in the longitudinal stress field (owing to boundary condition effects at the end of the rods) are sufficient to initiate the instability.

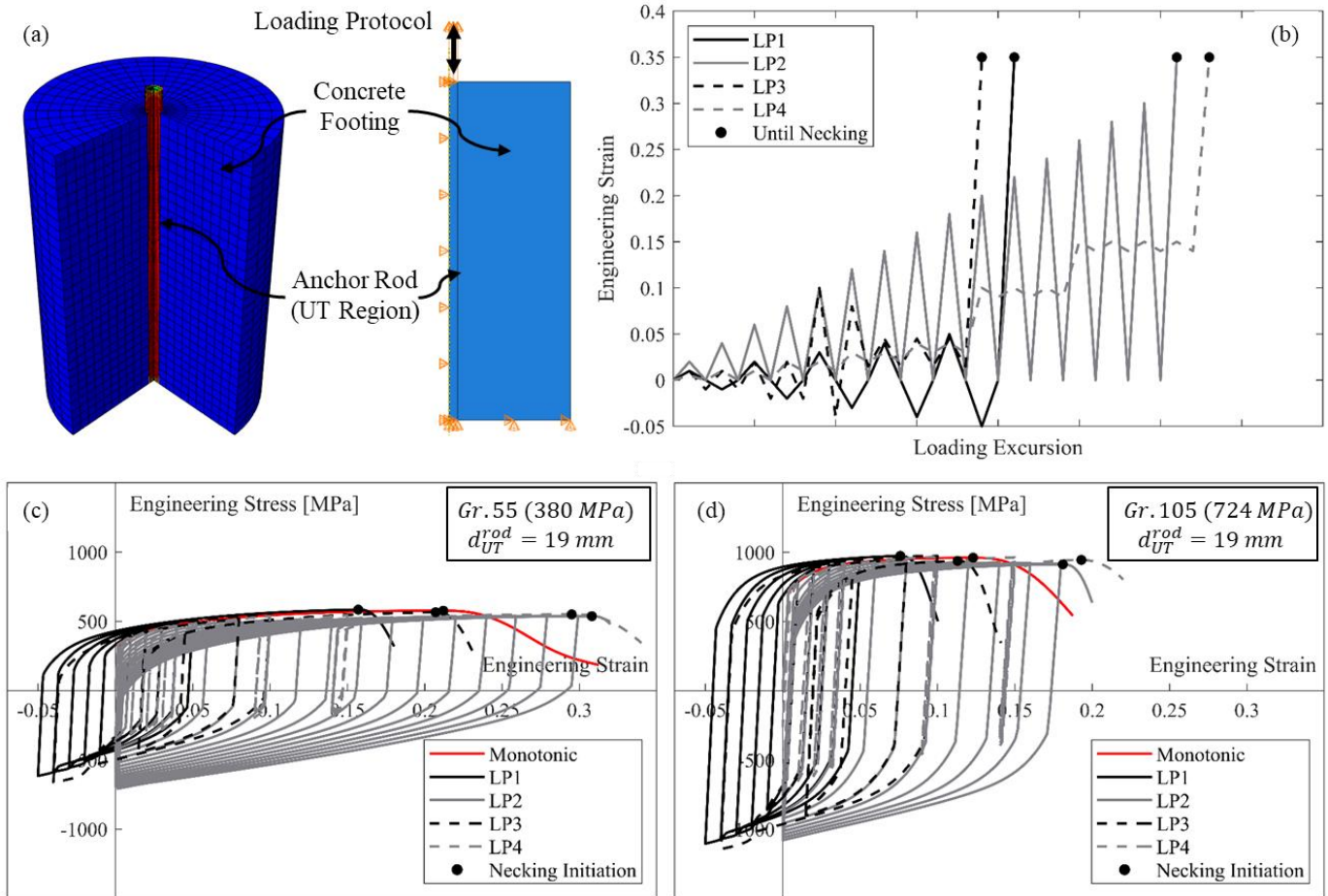


Figure 2.16 – CFE simulations for necking damage measure validation: (a) CFE model for anchor rod with surrounding concrete; (b) Loading protocols under investigation; (c) stress-strain curves for rods of same diameter size (19 mm), subjected to monotonic and cyclic loading protocols, for Grade 55; and (d) Grade 105

Necking instability is detected in the rods when the tensile force (or the effective engineering stress) begins to reduce; this is usually followed by visual observation of a neck in the rod. Using this simulation methodology, two rod grades (ASTM F1554 Grade 55 and Grade 105), four UT region diameters (12.7 mm, 19.1 mm, 25.4 mm, and 31.8 mm) and four cyclic deformation loading protocols/histories (see Figure 2.16b) were considered. For the purposes of illustration, Figures 2.16c-d plot representative engineering stress-strain curves for these rods as inferred from the CFE models. These are shown for one UT diameter (19.1 mm), and two different grades subjected to the cyclic and monotonic loading protocols. The values of strains at which necking initiates (indicated by a drop in engineering stress, and denoted as ϵ_{neck}^{CFE}) are recovered from all the simulations. A survey of these values reveals that the ϵ_{neck}^{CFE} as inferred from CFE simulations are

significantly larger than the previously computed/calibrated values from ASTM 1554 (denoted hereafter as $\varepsilon_{neck}^{ASTM}$) for both grades. The average $\varepsilon_{neck}^{CFE}/\varepsilon_{neck}^{ASTM}$ is 1.55 with a CoV of 0.17, and 1.44 with a CoV of 0.22 for Grades 55 and 105, respectively. This is not surprising, given that the ASTM values represent minimum values. This suggests that the proposed necking damage index is relatively conservative, i.e., for the rod materials tested herein, necking is likely to occur at significantly greater strains than implied by $\varepsilon_{neck}^{ASTM}$. It is relevant to note here that, lower values of necking strain ε_{neck}^{CFE} (albeit still close to the $\varepsilon_{neck}^{ASTM}$) are generally observed in loading protocols in which the rod undergoes significant negative strain cycles (e.g., LP1 and LP3). In the context of anchor rod in exposed base connections, these strain cycles are highly unlikely/unrealistic. Both these observations (negligible bending effect, and the conservatism in necking damage index) lend support to the use of LEB-based damage measures used in this study.

Results and Discussion

The damage measures D_{neck} and D_{ULCF} may be applied to examine the deformation capacity of base connection details other than those that have been tested (i.e., those introduced previously in Table 2.4). Consequently, for each of the simulations in Table 2.4, values of both damage indices were recovered at specific instants. Referring to Table 2.4, these indices are denoted D_{neck}^{SAC-1} , D_{ULCF}^{SAC-1} , D_{neck}^{SAC-2} , and D_{ULCF}^{SAC-2} . Of these, the former two (superscript SAC-1) denote the maximum necking and ULCF damage indices observed before the end (i.e., 5% cycles) of the first application of the SAC protocol, whereas the latter two (superscript SAC-2) denote the maximum damage indices observed before the end of the second application of the SAC protocol and the additional cycles till 6.5%. The former may be considered damage at demands consistent with connection pre-qualification, whereas the latter may be interpreted as damage at extreme demands or after

multiple high-intensity earthquakes. Figures 2.17a-b plot results graphically. Referring to Table 2.4 and Figures 2.17a-b, the following observations may be made:

- For a large majority of the simulation sets (43 out of 61), all damage indices are below 1.0, indicating that the anchor rods are unlikely to exhibit either necking or ULCF fracture in most of the scenarios, even after two applications of the SAC protocol and the 6.5% cycles.
- All instances where either D_{neck} or D_{ULCF} exceeds 1.0 (see bold values in Table 2.4) occur only during the second application of the SAC loading history and only for the longest plate ($N = 1016$ mm). These are extreme situations, both in terms of the applied demands and base plate geometry. In fact, the highest value of either D_{neck} or D_{ULCF} during the first application of the SAC loading history is $D_{neck,max}^{SAC-1} = 0.92$ (for Simulation #5), indicating that none of the examined configurations fails during the first application of the SAC protocol.
- In 47 out of 61 simulations (including both the SAC-1 and SAC-2) the D_{neck} value is greater than the corresponding D_{ULCF} value, indicating that failure by necking is the more likely failure mode. The exceptions to this all occur in the no-gap simulations. This is not surprising because the plastic strain accumulation is greater than that in the simulations with the gap.
- Referring to Figures 2.12-2.14 and associated discussion, D_{neck} values (for both SAC-1 and SAC-2) are similar between the gap and no-gap simulations because the maximum tensile elongation is virtually identical between the two. However, the D_{ULCF} values are, on average larger for the no-gap simulations, in which the cyclic strain accumulation is more significant.
- It is relevant to note here that although the introduction of the gap (which was incidental for the tested specimens, owing to the small concrete cover under the anchor rod end) reduced the cumulative plastic strain accumulation and hence enhanced the overall deformation capacity of the anchor rod; a punching shear failure at the bottom of the footing is typically undesired.

This should be avoided through providing an adequate concrete cover and potentially supplementary reinforcement below the anchor rod/assembly (anchorage plate and nut) in accordance with ACI 318-19 (ACI 2019).

- Table 2.4 (last two columns) summarizes the values $M_{max}^{simulation} / M_{max}^{test}$ for each of the simulations; these are determined for the SAC-1 condition and are analogous to the $M_{4\%}^{test} / M_{max}^{test}$ values presented previously for the experimental data, and indicate the ability of the given detail to maintain flexural strength. Referring to this column, these values range between 0.73-1.0 (average of 0.9, with a CoV of 0.07 – similar to the physical experiments) suggesting that the connections continue to carry significant moments at 4% drift.

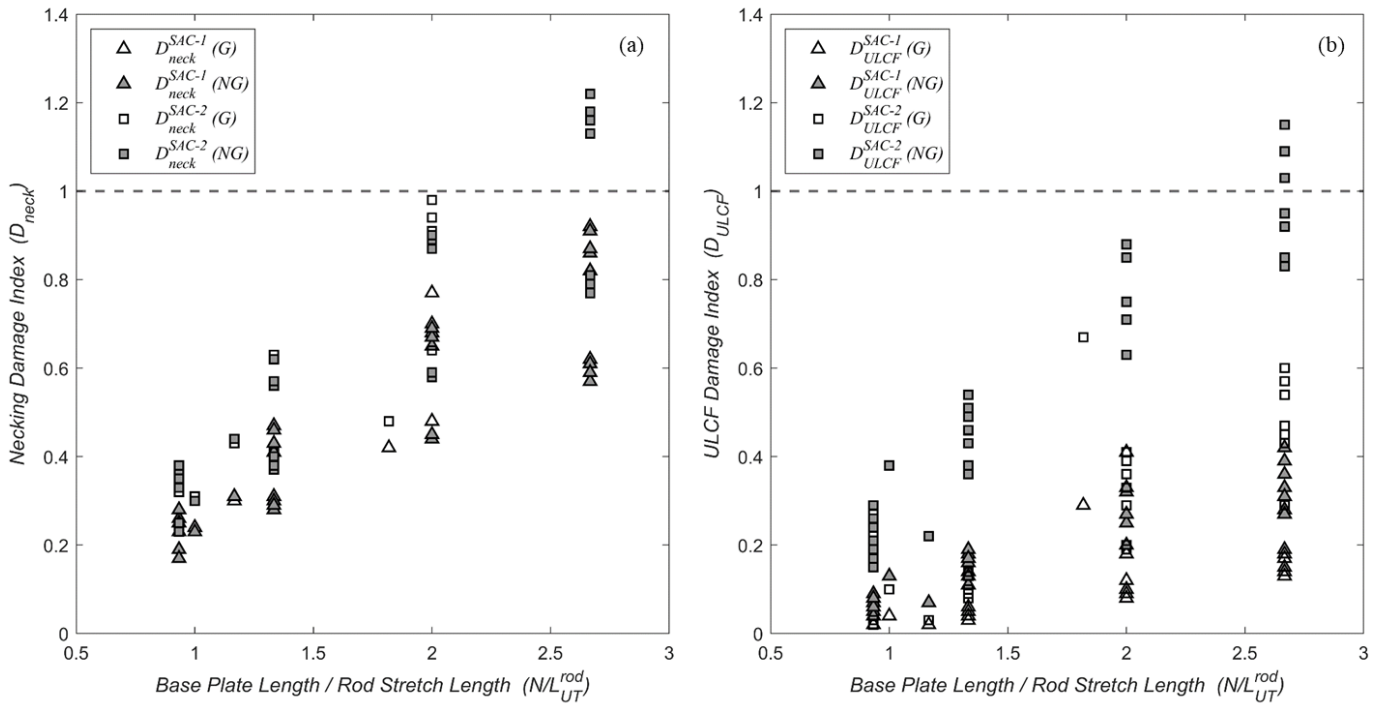


Figure 2.17 – Anchor rod damage measures (a) D_{neck} and (b) D_{ULCF} after each applied loading history versus N/L_{UT}^{rod} for all simulations.

Figures 2.17a and b plot all four values of the damage index, i.e., D_{neck}^{SAC-1} , D_{ULCF}^{SAC-1} , D_{neck}^{SAC-2} , and D_{ULCF}^{SAC-2} against the N/L_{UT}^{rod} . Referring to these figures, the following observations may be made.

First, a strong positive trend is observed between all the damage indices and the plate length N/L_{UT}^{rod} . This is not unexpected, because the term N/L_{UT}^{rod} approximately reflects the kinematic relationship between connection rotation and the rod strain, wherein a high value of N results in greater rod deformation (for a given base rotation), which is then distributed over the length L_{UT}^{rod} . Second, it is noted that for N/L_{UT}^{rod} values less than 2.0, all damage index values are significantly lower than 1.0, indicating safety for these connections even in the SAC-2 case. Collectively, these observations provide preliminary guidance for sizing of L_{UT}^{rod} relative to the base plate dimensions.

2.6 SUMMARY AND CONCLUSIONS

Recent studies indicate that concentrating inelastic rotations in ductile column base connections (i.e., a weak-base design) in steel moment frames, rather than in the attached column may result in safe as well as economic connection design. This is a significant departure from the prevailing approach of designing the base to be stronger than the column. This study examines an exposed column base plate detail that can provide significant inelastic rotation capacity without failure. The detail concentrates yielding in Upset Thread (UT) anchors that provide a designated stretch length for distribution of strains and are frictionally isolated from the footing through the use of polyethylene tape. Other than these modifications, the detail is identical to conventional exposed base plate connections. Four full-scale experiments were conducted on these connections. In these tests, the main form of observable damage was the cracking and spalling of grout, accompanied by yielding of the anchor rods. Concrete punch-out was observed at the bottom of the specimens at the conclusion of the tests. None of the tests showed anchor fracture or any other form of catastrophic failure. In terms of load-deformation response, the specimens showed an elastic response, followed by yielding and pinched hysteresis with cycle-to-cycle degradation due to the

aforementioned damage mechanisms. Notwithstanding this degradation, the specimens were able to maintain significant flexural capacity throughout the loading. The experiments suggest that the Upset Thread (UT) detail is highly promising and can provide extraordinarily ductile response even under very high seismic demands.

A comprehensive program of simulations was carried out to examine to what degree the response of the physical experiments may be generalized to untested configurations. These simulations were verified against the physical experiments and then used to parametrically examine the effect of base configurations on connection response – specifically anchor rod failure. The results of this parametric study indicate that for the large majority of the cases, damage in the anchor is below its critical value, suggesting that they are unlikely to fracture. The cases in which anchor failure is predicted all correspond to the second application of the ATC-SAC loading history (no failure is predicted in any of the cases for the first application), and configurations in which the base plate length is at least twice as long as the stretch length, i.e., the term $N/L_{UT}^{rod} \geq 2.0$. In summary, the test and simulation program indicates that the UT detail is likely to provide ductile response under a wide range of configurations. Moreover, the parametric analysis indicates that limiting the ratio of base plate length to stretch length may be an effective strategy for controlling anchor rod strains, and mitigating failure.

The study has some limitations that must be considered while evaluating its results and, more importantly, design development; these limitations are now outlined. First, the performance of connections (as implied by both the tests and simulations) cannot be extrapolated to details that are significantly different than those examined – for example, alternate anchor rod patterns, material grades, or nut-washer assemblies may influence the deformation capacity of the rods.

Perhaps most importantly, to achieve the observed performance, components of the base connection (i.e., base plate, welds) must be designed to concentrate yielding only in the anchor rods. Second, the tested details included a shear key that effectively transferred column shear to the foundation. The absence of such a mechanism may result in shear transfer through the anchors, compromising their deformation capacity. Regarding the simulations, it is important to recognize that they predict failure only in the anchor rods, and even for these, only two possible failure modes – assuming purely axial deformations. Moreover, the damage measures have not been independently verified against failure data of anchors, other than the observation that they predict no-failure in the configurations corresponding to the experiments. While these are supported by complementary CFE simulations and agreement with test data, it is not possible to rule out failure modes that may develop in untested configurations that are also not captured by the simulations. Thus, caution must be exercised in evaluating the results of the simulations. Finally, it is emphasized that the study focuses only on connection response, and does not consider its interactions with the frame. Designing connections to be weak may raise collateral issues, e.g., the concomitant decrease in flexural stiffness (see Falborksi et al. 2020) and a redistribution of forces and deformation demands in the connections.

CHAPTER 3

STRENGTH CHARACTERIZATION OF EXPOSED COLUMN BASE PLATES SUBJECTED TO AXIAL FORCE AND BIAXIAL BENDING

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3.1 INTRODUCTION

Column base connections are critical components in steel structures, transferring axial forces, shear forces, and moments from the entire building into the foundation. The focus in this study is on Exposed Column Base Plate (ECBP) connections that are commonly used in steel moment frames. Figures 1a and b show a photograph (from a testing program by Gomez et al. 2010) and a schematic illustration of such a connection, representative of construction practice in the United States. Referring to Figure 3.1, these connections include various components (i.e., the column, base plate, anchor rods, and concrete/grout foundation), which interact under a variety of loading conditions such as axial tension/compression, flexure, and shear. For axial force and flexure, the primary mechanism of resistance is also indicated in Figure 3.1b; this includes the development of axial tension in the anchor rods complemented by bearing stresses in the grout or concrete on the compression side of the connection. These stresses and forces induce various failure modes (grout/concrete crushing, yielding of the base plate on the tension or compression side, or yielding of the anchor rods) for which the connection must be designed. The behavior of ECBP connections has been studied extensively over the last four decades – Grauvilardell et al. (2005) provides a comprehensive review of studies that have led to the development of the American Institute of Steel Construction's (AISC) *Design Guide One* (Fisher and Kloiber 2006), and related provisions in the Seismic Design Manuals (SEAOC 2013, AISC 2015), as well as the AISC Specification

(AISC 2016) and Steel Manual (AISC 2017). Subsequent studies have focused on examining the assumptions of *Design Guide One* (Fisher and Kloiber 2006) through experimental (e.g., Gomez et al. 2010) and computational (Kanvinde et al. 2013) studies, as well as examining other issues pertaining to ECBP connections. These include characterizing the effect of an overtopping slab on grade (Richards et al. 2018), rotational stiffness of these connections (Kanvinde et al. 2012), and prospective design approaches that rely on the ductility or dissipative characteristics of these

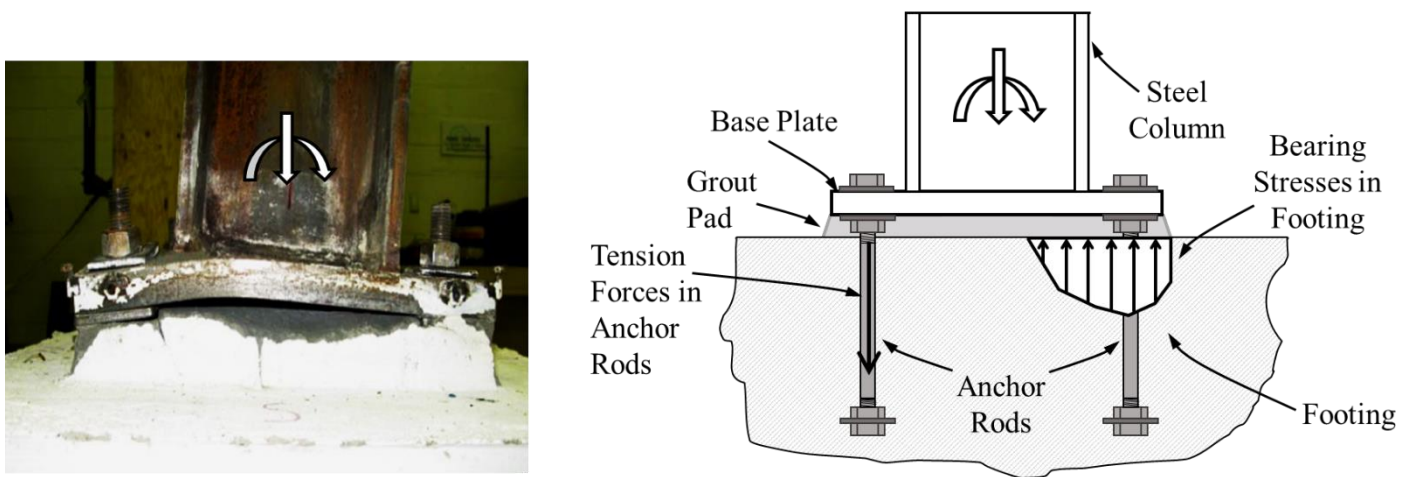


Figure 3.1 – Exposed column base connections: (a) photograph of loaded connection (Gomez et al. [1]); (b) schematic illustration of connection components

connections (Trautner et al. 2016; Falborski et al. 2020), and associated models for simulation of hysteretic response (Torres-Rodas et al. 2016).

These studies and design considerations almost exclusively focus on ECBP connections loaded in uniaxial bending (usually in the presence of axial compression). Within this, a large majority of studies have examined connections with W-section columns loaded in the major axis direction, with notable exceptions being Choi et al. (2005) (which experimentally studied square hollow section steel column bases under biaxial bending), Lee et al. (2008), Bajer et al. (2014), Fasaee et

al. (2018) and recently Da Silva Seco (2019) that address columns loaded in the minor axis direction. Consequently, current United States design practice for these connections disregards biaxial bending of ECBP connections, instead relying on design checks independently in orthogonal directions (SEAOC 2013, AISC 2015), or disregarding the minor axis check altogether, with the implicit assumption that flexural demands in the minor axis direction of moment frames are modest. These approaches are problematic for the following reasons:

1. Finite Element simulations by Kanvinde et al. (2013) as well as Choi et al (2005) and Fasaee et al. (2018) indicate that the presence of flexure in the minor axis direction significantly decreases the moment capacity in the major axis direction, and vice versa. The implication is that an interaction check (similar to that of beam-columns), rather than independent checks along either axis is necessary to assess connection safety. This interaction is not surprising because moments in both directions are resisted by the same components, i.e., the anchor rods, base plate, and grout/concrete.
2. Earthquakes and wind always cause multiaxial loads, resulting in biaxial bending at the base connection level. For example, in the seismic context (or in moment frames loaded laterally), building simulations (Menun and Der Kiureghian 1999; Burton et al. 2018 and Wang et al. 2019) indicate that minor axis moments at the base may not be modest either. From a physical standpoint, this occurs because the top end of the first story column undergoes deformations compatible with loading in both minor as well as major axis directions.
3. Collectively, the observations above suggest that the current approach for designing biaxially loaded ECBP connections may be unconservative. However, the current guidelines which constitute the United States construction practice do not provide an alternative, with the only available method as outlined in *Design Guide One* and demonstrated in the design manuals

(SEAOC 2013, AISC 2015) – this is referred to hereafter as the DG1 approach. The extension of the DG1 approach (which is originally based on the work of Drake and Elkin 1999) to biaxial bending is not straightforward either. This is because, as discussed in the next section, it requires solving for two variables to define the internal stress distribution and the forces in the anchor rods. As per the DG1 approach, illustrated schematically in Figures 3.2a and b, these two unknowns may either be: (1) the sum of the forces in one row of anchor rods (denoted T) and the width (denoted Y) of a rectangular stress block with a known stress f_{max} corresponding to the bearing strength of grout or concrete, in the case of “high-eccentricity” wherein the base plate uplifts, or (2) the width of the rectangular stress block Y and the induced stress f in the stress block, in the case of “low-eccentricity,” wherein the moment may be resisted by the prestress provided by the axial compression, without uplift of the base plate.

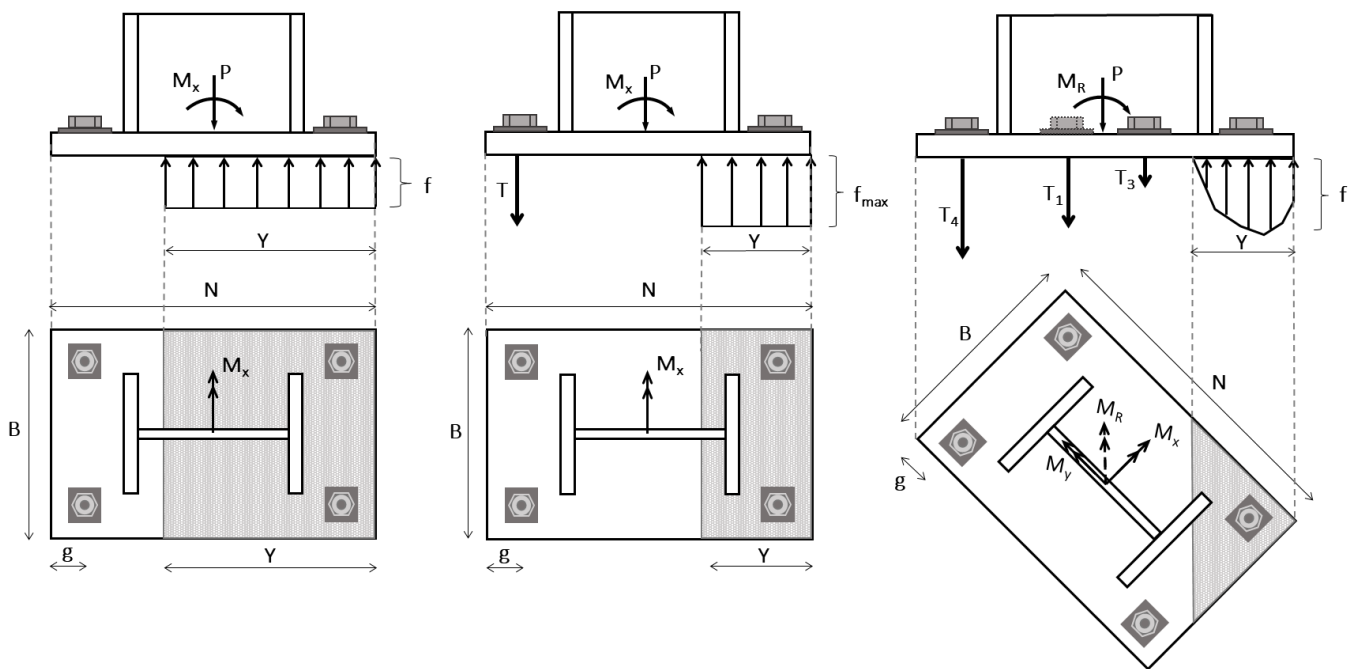


Figure 3.2 – Design Guide One interpretation of (a) Low eccentricity, (b) High eccentricity and (c) Biaxial bending

Under uniaxial bending, these unknowns may be conveniently determined using statics, since two equations of equilibrium (force and moment) are also available. Under biaxial bending, although an additional equation of equilibrium (i.e., moment equilibrium about the minor axis) becomes available, the number of unknowns increases disproportionately. To illustrate this, Figure 3.2c shows an elevation view in the plane of the resultant moment; referring to this figure: (1) additional rows of anchor rods may be engaged, each with a different tensile force, and (2) the orientation of the edge of stress block, in addition to its width is not known as well. In general, this edge may not be perpendicular to the direction of the resultant moment due to unsymmetric bending (Timoshenko 1940). Due to these factors, the application of the DG1 method to the biaxial bending of ECBP connections requires the resolution of static indeterminacy, which cannot be accomplished without introducing additional behavioral assumptions. Owing to such issues, prior studies on the topic such as Choi et al. (2005) and Fasaee et al. (2018) have proposed simplified strength models to characterize the capacity of ECBP subjected to biaxial bending in the presence of axial force. The former study presented an interaction surface based on experimental tests conducted on base plates with eight anchor bolts with a square hollow steel column, while the latter study proposed an elliptical interaction curve between the ECBP moment capacities in two orthogonal directions, each determined as per DG1. While expedient, such approaches do not explicitly articulate the mechanics or internal force distribution of the connection, and may not be convenient to generalize to configurational parameters that are significantly different from those used to calibrate the interaction curve. In summary, mechanics-based methods for strength characterization of ECBP connections under biaxial bending are not readily available.

Motivated by these problems, the main objective of this work is to study the mechanistic response of biaxially loaded ECBP connections, and to suggest approaches to characterize internal force distribution in biaxially loaded ECBP connections. The study uses a series of Continuum or Component-Based Finite Element simulations that interrogate a range of variables, including the base plate thickness, footprint dimensions and aspect ratio, number, size, and configuration of anchor rods, as well as the column section. These simulations (which, as discussed later, include various types of finite elements, including springs) are generically denoted as CFE simulations to distinguish them from frame-element based finite element models. Such simulations are sometimes referred to as Component-Based Finite Element Models (CBFEM), especially in Europe. These simulations provide quantitative and qualitative insights regarding the internal force distribution that may be used to resolve the indeterminacies outlined above. These insights are then used to develop a mechanics-based approach that may be used to design biaxially loaded ECBP connections. The model is formulated for convenient application within a practical setting, utilizing elements of the DG1 approach. The chapter begins by providing a brief overview of the DG1 approach, followed by a discussion of the CFE simulations on biaxially loaded connections, including their validation against experimental data. Key findings from the CFE simulations are then outlined. Building on these findings, the new approach is then formulated, and its results are examined against counterpart results from the CFE simulations and available experimental data. The chapter concludes by summarizing the limitations of the approach, along with areas for improvement.

3.2 BACKGROUND AND CURRENT APPROACH FOR STRENGTH CHARACTERIZATION

Models for strength characterization of ECBP connections may be broadly classified into three categories: (1) models that provide a full analytical solution to the problem, considering

interactions between the bending of the base plate, axial stretching of the anchors, and compressive deformations of the footing, along with gapping and contact between the plate and the footing – e.g., Ermopoulous and Stamatopoulos (1996), (2) models that assume a rigid base plate enforcing deformation compatibility between various components (e.g., assuming it to be rigid), and then use this deformation compatibility to estimate stresses in components such as the anchor rods – e.g., Wald (2000), and (3) models that use a predetermined stress block (or stress distribution) such as linear (triangular) or constant (rectangular) on the bearing side of the connection, and then determine forces in various components through equilibrium. The Drake and Elkin (1999) approach, currently adopted in DG1, falls in this third category.

Each approach has benefits and limitations. The first approach directly applies the principles of mechanics, but the resulting equations are too complex to apply within a practical setting. The second approach disregards the flexibility of the base plate, and in many cases, produces inaccurate results. In fact, Gomez et al. (2010), and Kanvinde et al. (2013) indicate that such methods may be non-conservative when assessed relative to test data. Models that rely on a predetermined form of the stress block do not enforce deformation compatibility explicitly but seek to balance accuracy and simplicity. As a result, these are preferred in current design practice. Since the model developed in this study for biaxial bending uses a stress-block based approach, essentially utilizing aspects of the DG1 method, it is useful to introduce key aspects of this method. The DG1 assumes that depending on the level of axial compression in the base connection, the moment may be resisted either by: (1) bearing stresses only – i.e., the “low-eccentricity” condition – Figure 3.2a, or (2) a combination of bearing stresses on the compression side, complemented by tension in the anchor rods – i.e., the “high-eccentricity” condition – Figure 3.2b. The method further assumes

that the stress block carries a constant stress (i.e., it is rectangular), and only one row of tension rods is present. The critical value of load eccentricity $e = M/P$, which distinguishes between these two conditions may be determined as:

$$e_{crit} = \frac{N}{2} - \frac{P}{2Bf_{max}} \quad (3.1)$$

The term f_{max} represents the bearing stress capacity on the compression side of the connection, whereas the terms P , B , and N refer to the axial compression, and the base plate width and length, as shown in Figures 3.2a and b. If $e < e_{crit}$, the bearing stress is less than or equal to its maximum value f_{max} , and the only possible mode of failure is flexural yielding of the base plate on the compression side of the connection, due to the upward bearing stresses – Figure 3.2a. The two unknowns, i.e., the bearing stress $f (< f_{max})$ and stress block length Y^{DG1} (to denote Design Guide One) are determined through simultaneously solving equations of vertical force and major axis moment equilibrium. When $e \geq e_{crit}$, the bearing stress is assumed to attain its maximum value f_{max} , such that the problem again has two unknowns, i.e., the stress block length Y^{DG1} and the tension in the row of anchor rods T^{DG1} – Figure 3.2b. These may be determined through force and moment equilibrium as follows:

$$Y^{DG1} = (N - g) - \sqrt{(N - g)^2 - \frac{2[M + P(\frac{N}{2} - g)]}{f_{max}^{DG1} B}} \quad (3.2)$$

$$T^{DG1} = f_{max}^{DG1} B \left((N - g) - \sqrt{(N - g)^2 - \frac{2[M + P(\frac{N}{2} - g)]}{f_{max}^{DG1} B}} \right) - P \quad (3.3)$$

The term g represents the distance between the anchor rod centerline and the edge of the base plate, as shown in Figure 3.2. The maximum bearing stress $f_{max}^{DG1} = \min(f_{grout}, f_{concrete})$, where

f_{grout} is the crushing strength of the grout, whereas $f_{concrete}$ may be determined to account for the confining effect of the footing size, which is usually larger than the base plate:

$$f_{concrete} = 0.85 \times f'_c \times \sqrt{\frac{A_2}{A_1}} \leq 1.7 \times f'_c \quad (3.4)$$

Where: f'_c = compressive strength of the concrete

A_1 = plate bearing area

A_2 = effective concrete area (typically plan area of footing – see DG1)

Once this force distribution is established, the connection may fail through either: (1) flexural yielding of base plate on the compression side, (2) flexural yielding of the base plate on the tension side due to downward forces in the anchor rods, or (3) axial failure of the anchor rods. Suitable design checks are then applied to size the plate and the rods. The DG1 assumes ECBP connections under uniaxial loading, and cannot address the indeterminacies (due to additional rows of anchor rods being engaged, or the additional variables required to characterize the orientation of the bearing block) that arise in biaxially loaded connections.

3.3 CONTINUUM OR COMPONENT-BASED FINITE ELEMENT SIMULATIONS OF ECBP CONNECTIONS

The CFE models were developed using the software PROFIS Engineering (2017) to provide an understanding of ECBP response under biaxial bending and axial compression. This section describes: (1) the simulation methodology, including features and theoretical underpinnings of the PROFIS Engineering software, (2) validation of the simulation methodology, against ECBP tests (loaded in uniaxial bending) by Gomez et al. (2010), and (3) application of the validated methodology to biaxially loaded ECBP connections.

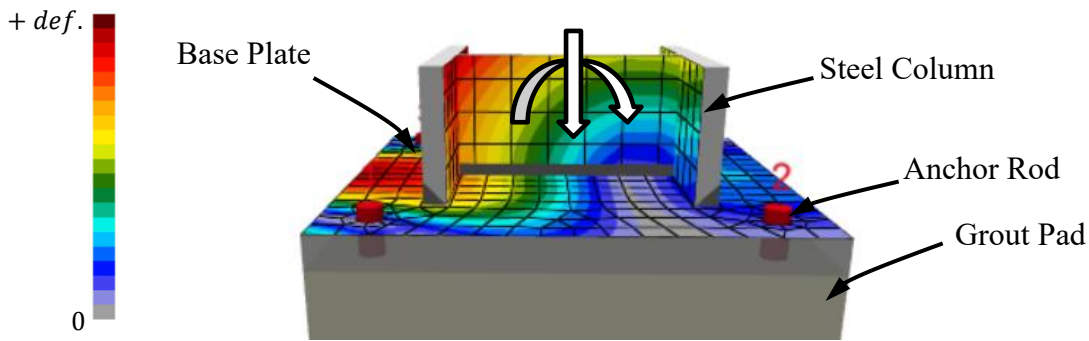


Figure 3.3 – Base plate simulation using PROFIS Engineering [26] showing contours of plate deformation (for one of the tests by Gomez et al [1])

Simulation Methodology

Figure 3.3 illustrates a CFE model constructed using the software PROFIS Engineering (2017). This model is complementary to one of the tests conducted by Gomez et al. (2010) used for validation of the methodology, discussed later. Key features of all CFE models are now summarized:

1. *General characteristics:* Referring to Figure 3.3, the CFE models consist of the various components present in the ECBP connection, including the base plate, anchor rods, and column section. Of these, the base plate and the column section are represented through four-node quadrilateral shell elements with shear deformations represented through the Mindlin formulation (MITC4 elements – see Dvorkin and Bathe 1984). A mesh density of roughly 16 elements per side for the plate provides convergent solutions. The rods are simulated as uniaxial springs assuming that the shear load is being transferred independently as is commonly done (e.g., through a shear lug). The concrete block is simulated analytically with

a uniaxial compressive stiffness, as described in the following point. Loading was applied in a nonproportional manner, i.e., axial compression followed by lateral moment.

2. *Component interaction and contact:* Hard, frictionless contact with gapping/separation in tension was simulated between the base plate and the concrete footing, whereas all other interactions (base plate to the column, base plate to the rod) were “tied,” or constrained.
3. *Material constitutive response:* The column, as well as the base plate, were simulated as elasto-plastic with a von Mises yield surface and linear isotropic hardening. The elastic constants were set as follows – the modulus of elasticity $E = 200,000 \text{ MPa}$, and Poisson’s ratio $\nu = 0.3$. The hardening modulus K of the steel material was set as 200 MPa . The concrete was simulated as an elastic medium, represented as a Winkler-Pasternak model (Pasternak 1954) whose stiffness may be determined as follows:

$$k = \frac{E_c}{(a_1 + \nu) \sqrt{\frac{A_{eff}}{A_{ref}}}} \left(\frac{1}{\frac{h}{a_2 B} + a_3} + a_4 \right) \quad (3.5)$$

Wherein k is the stiffness of concrete subsoil in compression, E_c modulus of elasticity of concrete, ν Poisson’s coefficient of the concrete block, A_{eff} effective area in compression, A_{ref} reference area taken as 1 m^2 , h and B are the height of the concrete block and the width of the base plate respectively and a_1 , a_2 , a_3 and a_4 are coefficients taken as 1.65, 0.5, 0.3 and 1.0 respectively – these are determined based on parameter fitting to continuum finite element simulations of the footing conducted using 3-d brick elements (IdeaStatiCa 2019). The formula is unit dependent, and the above version uses SI units. With respect to these constitutive model assumptions, two observations are important. First, none of the loading combinations stress the base plate or the anchors into the inelastic range; this is consistent with the primary objective of the study, which is to determine forces in the anchor rods and the base plate such

that they may be sized to ensure an elastic response. From a practical standpoint, this implies that the inelastic properties of the rods and base plate are of little consequence. Second, as suggested by experimental (e.g., Kanvinde et al. 2015) as well as nonlinear CFE simulations (Kanvinde et al. 2013), the footing response is linear with respect to deformation even at high loads (due to the high degree of confinement) such that representing it through an equivalent elastic response (as in Equation 3.5 above) is appropriate – previous work by Trautner et al. (2018) confirms this observation. The anchor rods were simulated as uniaxial springs with elastic response, based on the anchor dimensions. Note that since the approach presented herein focuses on determining the maximum forces in the anchor rods for the purposes of design, the post-yield response is not of consequence.

4. *Loading and response quantities monitored:* Numerous quantities were monitored in the CFE simulations; these include the lateral load, deformation, and anchor rod forces, and bearing stress profiles. These outputs were used in the appropriate context. Specifically, some CFE simulations (complementary to the Gomez et al. (2010) specimens subjected to uniaxial bending) were used for validation against counterpart experimental data, whereas others were used to obtain insights into ECBP specimens subjected to biaxial bending.

Validation of CFE Simulations

The CFE approach outlined above has been examined against numerous tests on ECBP connections by Trautner et al. (2018), indicating that it effectively predicts connection response, including internal force distribution. As part of this study, additional validation was conducted against in-house experimental data by Gomez et al. (2010). Specifically, 6 experiments conducted previously by Gomez et al. (2010) were used to validate the CFE simulations by comparing

quantities determined from the CFE to corresponding quantities from the experiments. Table 3.1 summarizes the parameters used in these tests. Referring to Table 3.1, the experiments interrogate a range of variables, including base plate thickness, the level of axial load, as well as variations in anchor rod strengths. The simulations were conducted for each of the experiments summarized in Table 3.1. Two types of experimental data were used for validation of the CFE; these are: (1) The lateral load-displacement curve, measured at the point of application of the lateral load, and (2) Anchor rod forces – specifically, the Gomez et al. (2010) specimens featured strain-gages attached to the anchor rods. These strains were converted to anchor rod forces based on force-strain curves obtained from independent tests of identical anchor rods (Gomez et al. 2010). Comparisons between these data streams and their counterparts from the CFE simulations are indicated in Figures 3.4a-f for the base-moment vs drift data, and Figures 3.5a-f for the anchor-force versus base-moment data. In the latter figure, the experimental anchor force shown is the average of the tension forces measured in the two active anchor rods. Except for Test #1 (see Table 3.1), all experiments are cyclic. However, the CFE models apply only monotonic loading. Thus, the CFE response quantities are compared to the envelope of the cyclic experimental data, as shown in Figure 3.4. This is justifiable for three reasons: (1) a comparison between Test #1 (monotonic) and Test #2 (cyclic, but nominally identical otherwise to Test #1) indicates negligible strength deterioration due to cyclic effects – see Gomez et al. (2010), (2) none of the cyclic tests (i.e., Tests #2-#6) show cycle-to-cycle deterioration in any of the quantities, and (3) all design methods assume monotonic response without consideration of cyclic or deterioration effects. Referring to Figures 3.4 and 3.5, the following observations may be made:

- The agreement between the load-deformation curves (Figures 3.4a-f) is striking in the linear elastic range, and also fairly good in the nonlinear range.

- Figures 3.5a-f illustrate the agreement between the applied base moment and the tension force in the anchor rods. These are more relevant from the standpoint of this study, whose primary aim is to characterize internal force distributions (chiefly, the rod forces). With the exception of Test #3 (Figure 3.5c), the agreement between the tests and simulations is excellent over the entire range of applied moments. For Test #3, it is surmised that the nuts on the rods were prestressed such that base plate lifted off slightly later than expected – the CFE does not simulate this prestress. However, after the lift-off of the base, the evolution of anchor rod forces (as determined by the CFE) closely parallels the experimental response.

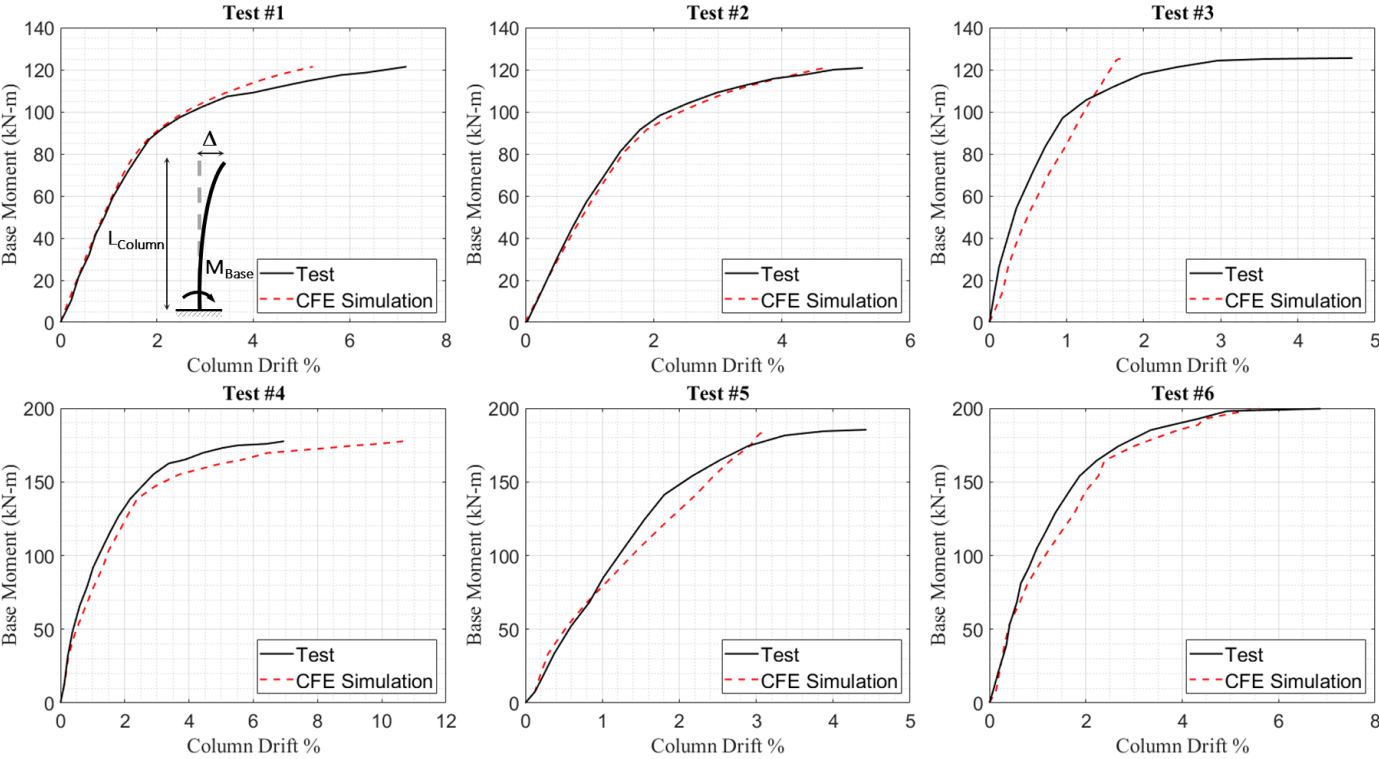


Figure 3.4 – Load-Drift response from experiments and simulations

Although the validation above is conducted for ECBP specimens loaded in uniaxial bending, it demonstrates that CFE models are able to reproduce key aspects of physical response, such as contact, gapping, and the interactions that are required for estimation of rod forces. Once validated

in this manner, the methodology is applied to ECBP connections subjected to biaxial bending and axial compression. This is the topic of the next subsection.

Table 3.1 – Tests from Gomez et al. (2010) experimental program used for CFE validation

Test # ^a	N (mm)	B (mm)	Plate thk. (mm) ^b	Anchor Rod Strength (Nominal) (MPa)	Compressive Axial Load (kN)	Lateral Loading Protocol
1	356	356	25.4	1010 (724.0)	0	Monotonic
2	356	356	25.4	1010 (724.0)	0	Cyclic
3	356	356	38.1	491.5 (248.0)	400.3	Cyclic
4	356	356	25.4	1010 (724.0)	400.3	Cyclic
5	356	356	50.8	1010 (724.0)	400.3	Cyclic
6	356	356	25.4	1010 (724.0)	667.2	Cyclic

^a All experiments used a W203x71 (W8x48) column section

^b Base plate material for all tests was ASTM A36 (measured $F_y=248.3$ MPa)

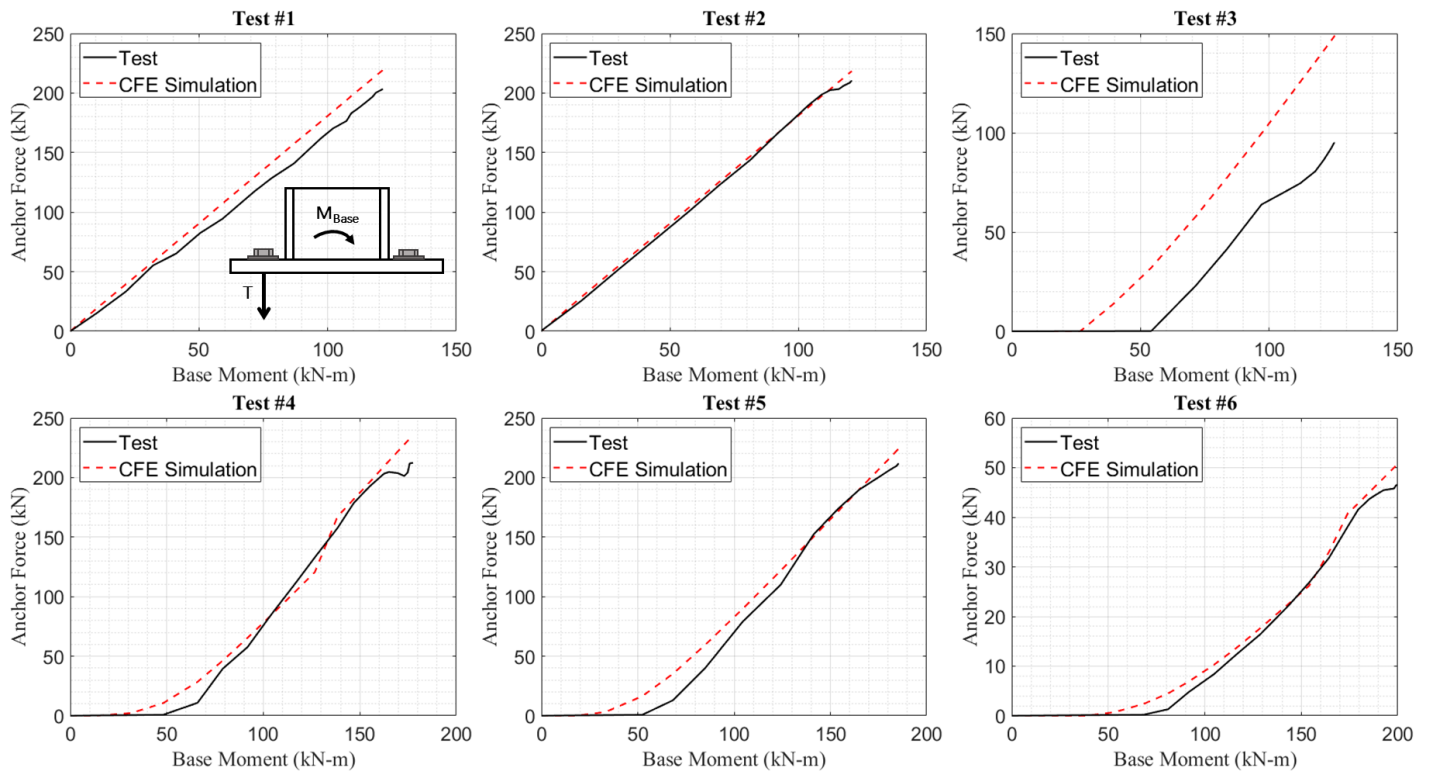


Figure 3.5 – Anchor Force – Moment response recovered from experiments and simulations. Referring to Table 3.2, these include a range of column section, base plate sizes, and thicknesses, as well as anchor rod sizes – these represent a range of realistic configurations similar to those

specified in practice. All the simulated configurations feature a 4-anchor rod layout similar to that illustrated in Figure 3.3, with edge distances as shown in Table 3.2. Each of these CFE models was subjected to a range of loadings, defined in the space of P , M_x , and M_y , where P is the axial compression, M_x is the bending moment about the column major axis, and M_y is the bending moment about the column minor axis. The values of axial force were selected in 6 increments ranging from 0 to 30% of the crushing load of the footing (i.e., $P_{crushing} = \phi \times f_{max} \times A_1$; $\phi = 0.65$) to reflect realistic values. For each of these axial loads, the moment values were selected to result in constant ratios of M_y/M_x . These ratios represent resultant moment directions such that $\theta_M = \tan^{-1} \left(\frac{M_y}{M_x} \right)$, wherein $\theta_M = 0^\circ$ represents uniaxial loading in the major axis direction, whereas $\theta_M = 90^\circ$ represents uniaxial loading in the minor axis direction. The angle θ_M was varied in 5° increments ranging from 0° to 90° . For each of these angles, the magnitude of the resultant moment $\sqrt{M_x^2 + M_y^2}$ is varied such that $0.2 \leq \frac{M_x}{M_{px}} + \frac{M_y}{M_{py}} \leq 0.7$ (the moments in the denominator reflect the plastic strengths of the column section). These variations result in a total of 136 (P , M_x , M_y) loading combinations applied to each of the configurations summarized in Table 3.2. For each of these simulations, the following quantities are recovered: (1) axial forces in each of the anchor rods, and (2) magnitude and distribution of footing compressive stresses. These quantities are retained and used to assess various strength models presented in the next section. Moreover, as illustrated in Figures 3.6 and 3.7, and the associated discussion, these quantities also provide insights for the development of these models. Two observations are of particular interest:

1. Figure 3.6 shows a representation of anchor rod forces in one of the loading cases (Corresponding to Configuration # 4 – see Table 3.2) for biaxial bending; observations are qualitatively similar for other loading cases. Referring to this figure, the ends of the lines

representing anchor forces appear to lie on a plane. This observation is consistent across a large majority of the simulated configurations and loading combinations, suggesting that the anchor forces increase linearly, about an imaginary axis of rotation, due to the compatible deformations enforced by the uplifting plate – such that the deformations of the plate are relatively minor. However, the location of the “neutral axis,” i.e., where this plane intersects the footing surface varies depending on the configuration and loading.

2. The stress profiles recovered from the CFE reflect bearing stresses that are (for the high eccentricity conditions) significantly lower as compared to f_{max}^{DG1} implied by DG1. Moreover, there is also significant variability in the bearing stress profile (i.e., its maximum value), depending on the applied loading – recall that for all high-eccentricity situations, the DG1 essentially disregards variation in the maximum stress. Figure 3.7 plots the ratio $f_{max}^{CFE}/f_{max}^{DG1}$ versus the $(P/A + M_x/S_x + M_y/S_y)/f'_c$, wherein A , S_x and S_y denote the area and section moduli of the plan dimensions of the base plate, such that the index $(P/A + M_x/S_x + M_y/S_y)/f'_c$ is a normalized, approximate indicator of the magnitude of combined loading. Note that the stress profile in the CFE specimens is not constant (or rectangular). Consequently, for consistent comparison with f_{max}^{DG1} , the term f_{max}^{CFE} represents the maximum stress derived by redistributing the CFE stress distribution into an equivalent rectangular stress block. Referring to Figure 3.7, the following observations may be made: (1) in all the cases examined, the ratio $f_{max}^{CFE}/f_{max}^{DG1}$ is significantly lower than 1.0 indicating that in general, the DG1 estimate of the rectangular block maximum stress is inaccurate, (2) a strong linear trend is noted between the loading index $(P/A + M_x/S_x + M_y/S_y)/f'_c$ and the stress-ratio $f_{max}^{CFE}/f_{max}^{DG1}$, (3) the data points on the scatter plot are grouped based on the θ_M angle (i.e., the direction of resultant moment) – the stress ratio $f_{max}^{CFE}/f_{max}^{DG1}$ does not seem to have a strong correlation with the angle of

loading. The dependence of the magnitude of the stress block on the applied loading is highly intuitive, although it is not considered in DG1.

Table 3.2 – Configurations simulated to examine biaxial bending

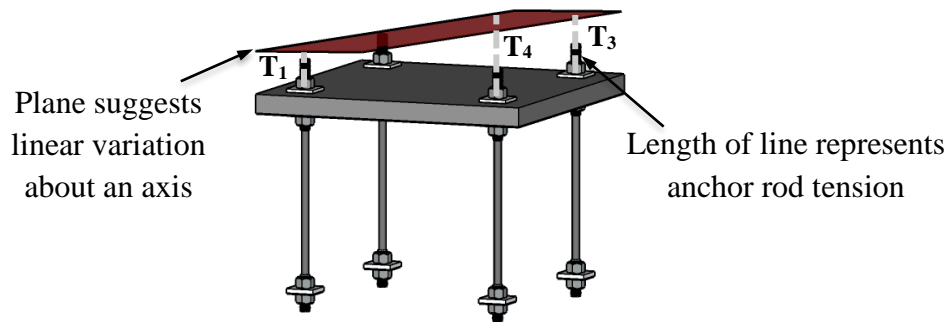


Figure 3.6 – Graphical representation of anchor rod forces

Config #	N (mm)	B (mm)	Edge Distance (mm)	Plate Aspect Ratio	Plate Thk. (mm)	Anchor Rod Diameter (mm)	Column Section (Imperial)
1	356.0	356.0	38.1	1.00	25.4	19.0	W203x71 (W8x48)
2	482.6	356.0	38.1	1.36	25.4	19.0	W203x71 (W8x48)
3	406.4	356.0	38.1	1.14	50.8	19.0	W203x71 (W8x48)
4	762.0	762.0	101.6	1.00	50.8	25.4	W356x551 (W14x370)
5	812.8	406.4	63.5	2.00	50.8	19.0	W610x125 (W24x84)
6	508.0	508.0	50.8	1.00	38.1	25.4	W305x143 (W12x96)

These observations are used in support of proposing approaches for characterizing the internal stress distribution; these approaches are discussed in the next section.

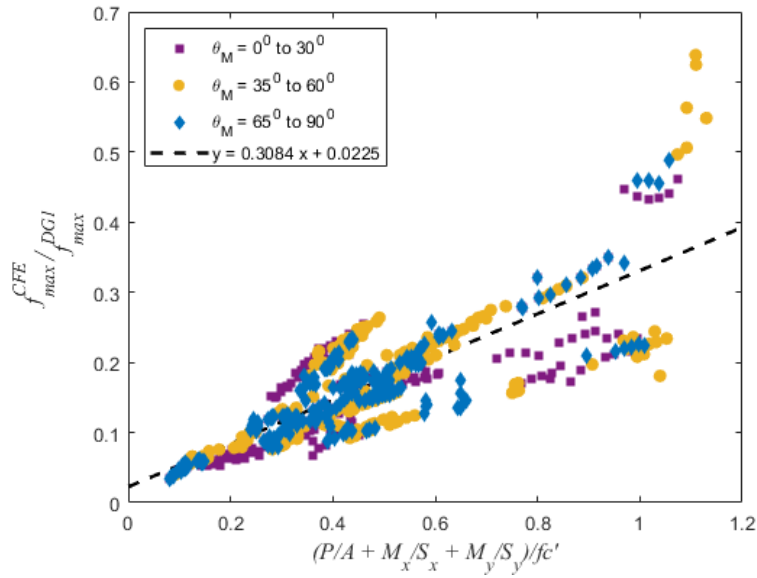


Figure 3.7 – The ratio $f_{max}^{CFE}/f_{max}^{DG1}$ versus the normalized measure of loading $(P/A + M_x/S_x + M_y/S_y)/f'_c$

3.4 PROSPECTIVE APPROACHES FOR CHARACTERIZING INTERNAL FORCE DISTRIBUTION

Referring to the preceding discussion, extending the DG1 approach to biaxial connections is challenging for two reasons: (1) the angle of the edge of the compression zone is not known *a priori* due to the possibility of unsymmetric bending of the cross section, and (2) this unknown angle, along with the greater number of rods that are engaged (see Figure 3.2c introduced previously) result in an increased number of unknowns that may not be solved using equilibrium equations alone. This is in contrast to the DG1 approach for uniaxial bending, which solves for the two unknowns, i.e., T^{DG1} , and Y^{DG1} based on force and moment equilibrium. Consequently, additional assumptions must be invoked to resolve this indeterminacy. Two general approaches are possible. The first is a “rigid-plate” analysis, which performs a section analysis of the base plate footprint, assuming that the plane section (defined by the base plate) remains plane, and the footing and the anchor rods deform compatibly with this section. Such an approach was not selected in this study for two reasons: (1) from a practical standpoint, requiring engineers to

perform a sectional analysis for ECBP design would be a significant departure from current practice, requiring additional information regarding the stress-strain response of various components, including the footing, and (2) it is highly desirable for prospective approach for biaxial loading to converge to the DG1 approach for uniaxial loading, i.e., for $\theta_M = 0^\circ$ and 90° to maintain consistency with current design practice; this is effectively precluded if a rigid plate analysis is used. The second approach involves using a prescribed stress distribution (in terms of its form and location) as is done in DG1 and supplementing it with insights derived from the CFE, specifically that the anchor rod forces increase in a linear fashion from an axis of rotation which is parallel to the edge of the compression block. In the absence of a coupled analysis that considers interactions between a flexible plate and concrete, with contact and gapping, such assumptions lack a mechanistic basis in themselves and are expediently selected to reproduce test or simulation data.

Following the above discussion, the proposed approach for characterizing internal stresses in ECBP connections subjected to biaxial bending and axial compression is now summarized. Similar to DG1, the approach assumes base plate plan dimensions, i.e., N and B , as well as the anchor rod layout and dimensions. Then, the method estimates forces in each component that may be compared to the capacities of those components. Based on these comparisons, the various components may be resized until all design checks are satisfied. Thus, the input variables for application of the method include the following: (1) dimensions of the plate; length N and width B and material strength (specified yield stress for the plate material f_y^p) (2) anchor rod layout, diameters and grade/material strength (specified ultimate stress for the rod material f_u^{rod}) (3) footing plan area and bearing strength f_c' . Figures 3.8a and b illustrate the assumptions of this

method., whereas Figure 3.9 schematically illustrates the process used for its implementation. Given these, the proposed approach assumes that:

1. A compression stress block with a constant bearing stress value f_{max} in the concrete (similar to the rectangular stress block method of DG1) is formed with a straight edge, whose location and orientation may be defined by d and θ , that represent the distance from the centroid and the angle with respect to the major axis of the column – see Figure 3.8a. Note that the f_{max} shown in Figure 3.8a denotes the stress, and not the force per unit length in the elevation section – in general, the latter will not be a constant value owing to the varying dimension of the plate in the out of plane direction.
2. The displacements of the anchor rods increase linearly in the direction perpendicular to the edge of the bearing block, i.e., in the direction of the principal moment, with the Instantaneous Axis of Rotation (IAR) located parallel to the edge of the stress block. The location of this axis may be quantified by the parameter $\beta = Y_{IAR}^{Method} / Y_{Block}^{Method}$ where Y_{IAR}^{Method} and Y_{Block}^{Method} represent the distances of the IAR and the edge of the compressive block from the extreme point of the base plate, in the direction of principal bending – see Figure 3.8b.
3. The anchor forces are determined in accordance with this IAR (orientation and position), increasing linearly with distance; this is consistent with the observations of the CFE simulations (see Figure 3.6 shown earlier).

In the above, the terms f_{max} and β are assumed to be fixed, and reflective of general base plate response. With these additional assumptions, two possible scenarios are possible, analogous to the original DG1 approach: (1) a low eccentricity situation, in which the applied loads may be resisted entirely by the bearing stress block without the development of tension in any of the anchors, and (2) a high eccentricity situation in which the applied loads are resisted through a combination of

bearing as well as the development of tension in various anchors. The first case results in three unknowns, i.e., d , θ , and f ; note that similar to DG1, the bearing stress is treated as a variable in the low-eccentricity condition; wherein f is less than f_{max} . These three unknowns may be solved using only the equations of equilibrium, i.e.,

$$\Sigma F_z = 0 \tag{3.6}$$

$$\Sigma M_x = 0 \tag{3.7}$$

$$\Sigma M_y = 0 \tag{3.8}$$

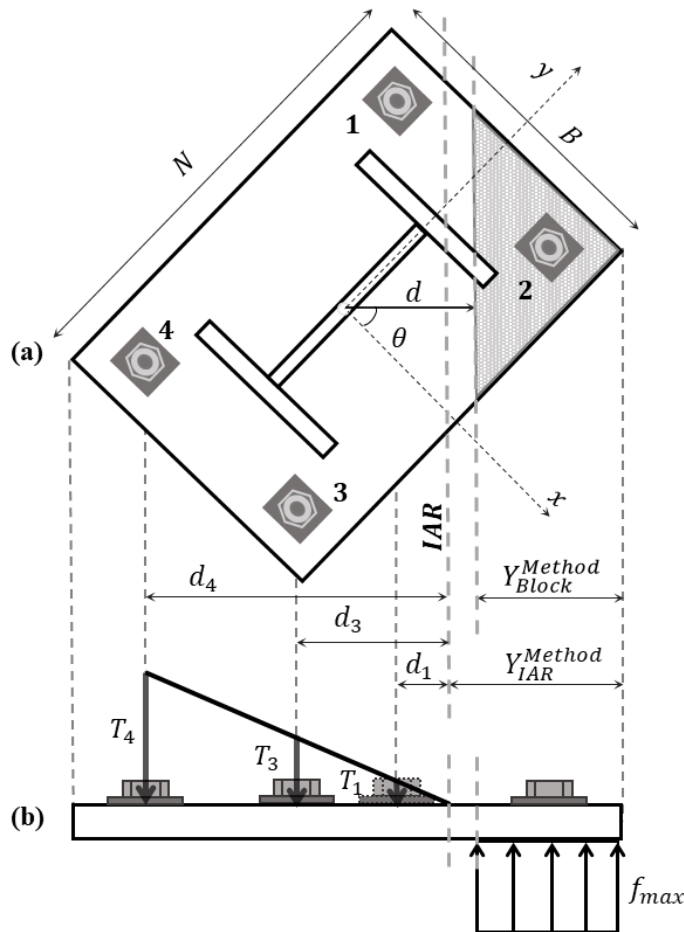


Figure 3.8 – Schematic illustration of the proposed method (a) Plan view and (b) Elevation

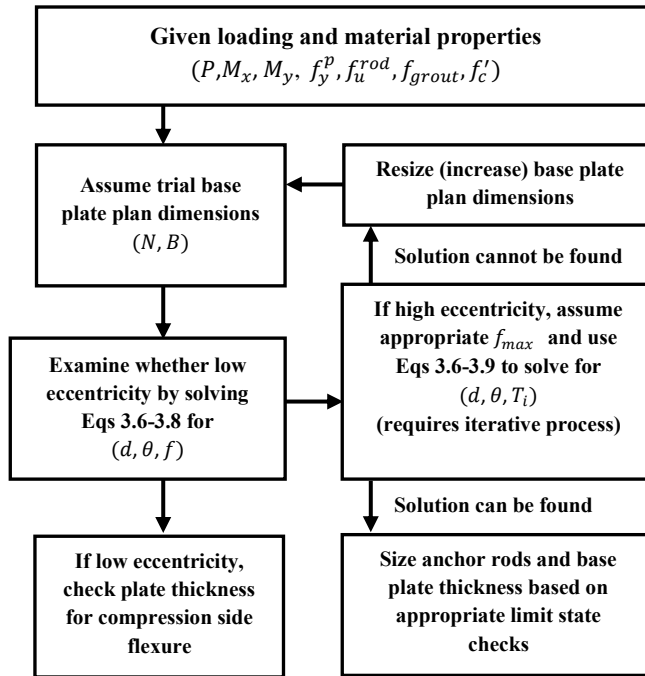


Figure 3.9 – Flowchart for implementation of proposed method

A computer program is developed to iteratively solve these equations. The solutions of these equations (i.e., computed values of d , θ , and f) are acceptable only if they represent a physically possible condition, i.e., (1) the compression block implied by d , θ does not extend beyond the dimensions of the base plate, and (2) the maximum stress f remains below the assumed material bearing stress capacity f_{max} . If such a solution cannot be found, the configuration is determined to be a high-eccentricity case (following the intent and process of DG1, but generalized to a biaxial bending situation). In this case, the maximum stress in the block is assumed a constant, predetermined value, following DG1 – this is denoted f_{max} . This results in a total of $n_{rods} + 2$ unknowns. These include d and θ , as well as the axial tension force in each of the n_{rods} anchor rods that lie on the tension side of the IAR (see Figure 3.8b). To solve these, a total of $n_{rods} + 2$ equations are available as well. These include the three equilibrium equations above Eqs. (3.6-

3.8), in addition to $n_{rods} - 1$ equations that arise from the compatibility relationship shown below:

$$\frac{T_1}{d_1} = \frac{T_2}{d_2} = \dots = \frac{T_n}{d_n} \quad (3.9)$$

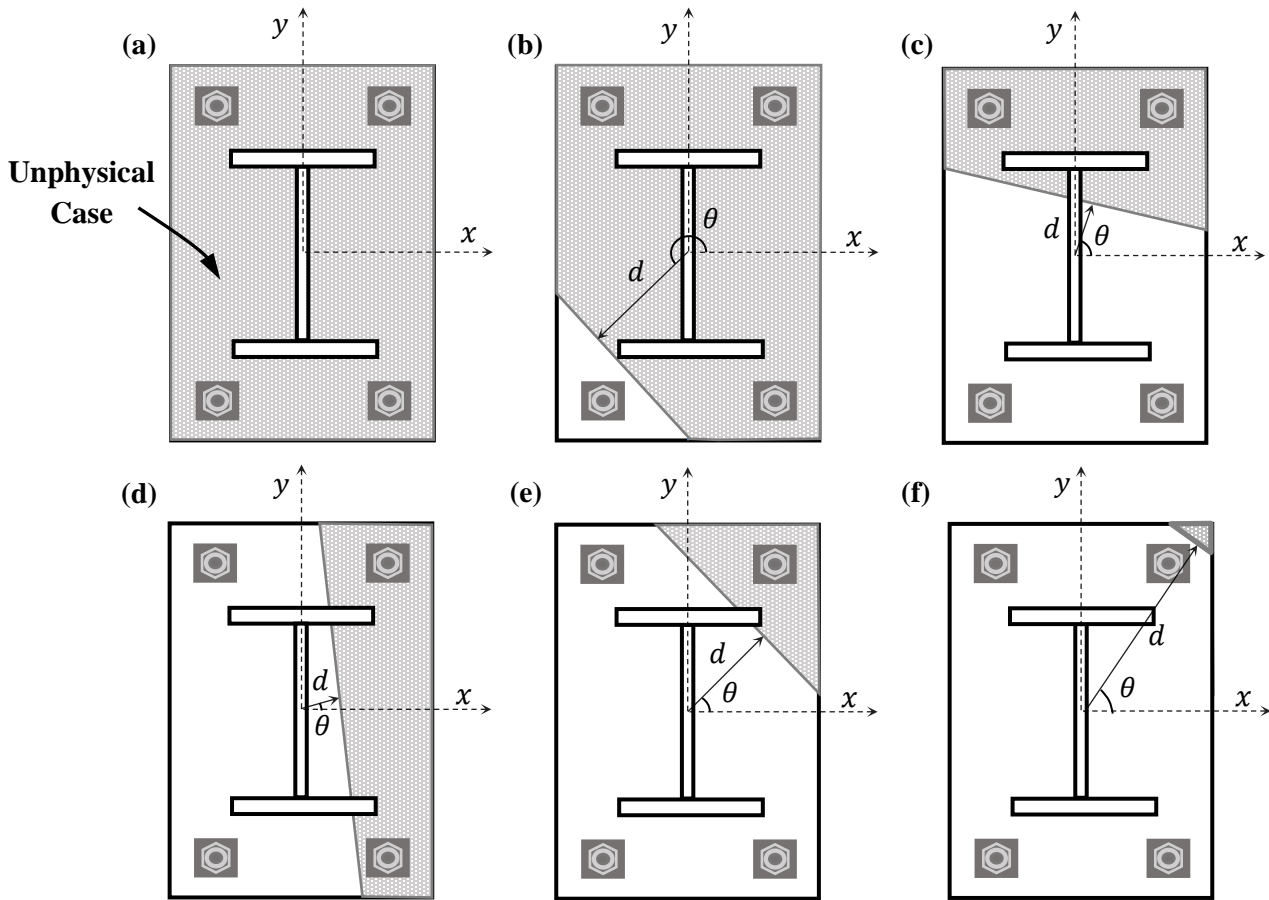


Figure 3.10 – Possible cases for engagement of anchor rods – shaded area indicates compression block

In the above equations, T_i represents the tension force in each anchor rod located at a distance d_i from the IAR (see Figure 3.8), in the direction perpendicular to it. Finding a solution to these (given the applied loads P , M_x , and M_y) entails the following steps that are automated through a computer program (see Figure 3.9):

1. The location of the edge of the compression stress block represented by a trial set of values for d and orientation θ are assumed along with the constant bearing stress value f_{max} .
2. Based on the assumed values of d and θ , the bearing block may represent one of the six cases identified in Figure 3.10a-f. Two additional considerations are relevant here. First, the case where the bearing block extends over all anchors is not physical (Figure 3.10a), except in the case of low-eccentricity (discussed earlier), in which $f < f_{max}$. Second, the cases correspond only to the number of rods engaged in tension, and not the geometric shape of the bearing block, which may vary for each case depending on the shape and edge distances of the anchor rods.
3. Once the applicable trial case is determined, the compression block area (and therefore the compressive force resultant and location – from geometry) as well as the number of rods in tension n_{rods} may be determined.
4. Next, the location of the IAR may be determined based on the assumed value of β . This enables calculation of the perpendicular distances from the IAR to the anchor rods ($d_1, \dots, d_{n_{rods}}$).
5. Equation (3.6) (which corresponds to force equilibrium in the vertical direction) along with the $n_{rods} - 1$ Equations (3.9) (which relate the forces in the anchor rods) may be used to estimate forces in each of the anchors ($T_i, \dots, T_{n_{rods}}$). Once these are determined, the resultant internal moments M_x^{trial} and M_y^{trial} may be determined through Equations (3.7) and (3.8). Note that these are denoted trial values because they correspond to an assumed combination of d and θ .
6. The trial values M_x^{trial} and M_y^{trial} are compared to the applied moments M_x and M_y . If they match (within a tolerance), then the assumed d and θ are retained as final estimates. If not, another value of d and θ is selected, and Steps 1-5 above are repeated. This problem is computationally inexpensive; thus, no special technique is required to select subsequent trial

values of d and θ . A process, which includes marching through all admissible values of d and θ is adopted. Even for the high-eccentricity case, meaningful solutions of d and θ are not guaranteed. This may happen when for any of the cases, the values of d and θ are not physically consistent with the assumptions of the case (e.g., the compression block extends underneath an anchor stressed in tension). In such cases, the footprint of the base plate (i.e., N and B) must be resized (see Figure 3.9).

Once solved, these equations result in forces in all anchor rods T_i , as well as the orientation and location of the bearing block defined by d and θ . Note that these calculations are contingent on a selection of the terms β (representing the location of the IAR with respect to the edge of the compression block), and the term f_{max} , representing the maximum stress in the compression block. Since these are constituents of the prospective design approach, various values were trialed for each, and resulting estimates of anchor rod forces were compared to their CFE counterparts for each of the simulations summarized previously in Table 3.2. These comparisons yield the following observations (detailed analysis is presented in the next section):

1. A value of $\beta = 1$ appears to work well across all the simulations, i.e., there is good agreement between the maximum anchor rod forces from the CFE and the method, for a range of trialed f_{max} values. Note that a value of $\beta = 1$ implies that the IAR lies at the edge of the bearing stress block.
2. Results of the method are (expectedly) sensitive to the selection of the maximum bearing stress value f_{max} . As illustrated previously in Figure 3.7, the stresses observed in the CFE simulations are significantly lower (on average by 75%) as compared to the stress implied by DG1 for the high eccentricity condition; note that for the low-eccentricity condition, the two methods are conceptually identical, since the compatibility relationship is not invoked. In the

proposed approach, three values of f_{max} are examined as possible candidates. One is $f_{max} = f_{max}^{DG1}$, that is consistent with DG1. As discussed in the next section, this does not provide the best agreement with simulation results. Consequently, another value of $f_{max}^{Constant} = 0.4f'_c$ (or $f_{max}^{Constant} = 0.24 f_{max}^{DG1}$) is suggested, to provide the best median agreement with CFE data. While anchor forces determined from these assumptions agree, on average, with CFE data, there is also a very high variability in the CFE-to-predicted ratios. To address this issue, a third estimate of $f_{max} = f_{max}^{Variable}$ is proposed in which $f_{max}^{Variable}$ depends on the magnitude of applied loading, reflecting the trend noted earlier in Figure 3.7.

It is relevant to note here that the above discussion assumes that the column rests directly on top of a concrete pad (often the case when the anchors are post-installed). However, the column may be often placed on top of a grout pad. As discussed earlier, in all these alternative approaches, f_{max}^{DG1} notionally indicates the minimum of the grout and concrete strength. With the above values set, the process outlined earlier (and illustrated in Figure 3.9) may be executed to determine all the unknowns, i.e., d , θ , f in the case of the low eccentricity condition, and d , θ , and the forces in all rods ($T_i, \dots, T_{n_{rods}}$) in the high eccentricity condition. The next section discusses the results and implications for design.

3.5 RESULTS AND DISCUSSION

The procedure outlined in the preceding section is applied to each of the $136 \times 6 = 816$ combinations of configuration and loadings studied herein. The primary output variable considered for analysis of the results is the largest anchor rod tensile force that is developed in the rod farthest from the IAR – this is denoted T_{max} . This is a suitable comparison for the following reasons: (1)

the largest anchor rod force typically governs the design of all anchors, i.e., size and grade in a connection, (2) the tension in the anchor may be used to estimate the bending moment in the base plate on the tension side of the connection. Moreover, research by Gomez et al. (2010) which is incorporated into the AISC 341-16 (AISC 2016) indicates that bending of the base plate on the compression side is unlikely to produce connection failure and may be disregarded. With this context, Figures 3.11a-c plot the estimated T_{max}^{Method} versus its counterpart from all 136×6 CFE simulations T_{max}^{CFE} . In Figure 3.11a, the estimated value T_{max}^{Method} is based on the assumptions of DG1, i.e., $f_{max} = f_{max}^{DG1}$. Figure 3.11b corresponds to T_{max}^{Method} estimated from the assumed value $f_{max}^{Constant} = 0.4f_c'$ (or $f_{max}^{Constant} = 0.24 f_{max}^{DG1}$). Finally, the T_{max}^{Method} values plotted in Figure 3.11c are based on the variable estimate of f_{max} as determined from the following Equation:

$$f_{max} = f_{max}^{Variable} = \left(0.3084 \times \frac{P/A + M_x/S_x + M_y/S_y}{f_c'} + 0.0225 \right) \times f_{max}^{DG1} \quad (3.10)$$

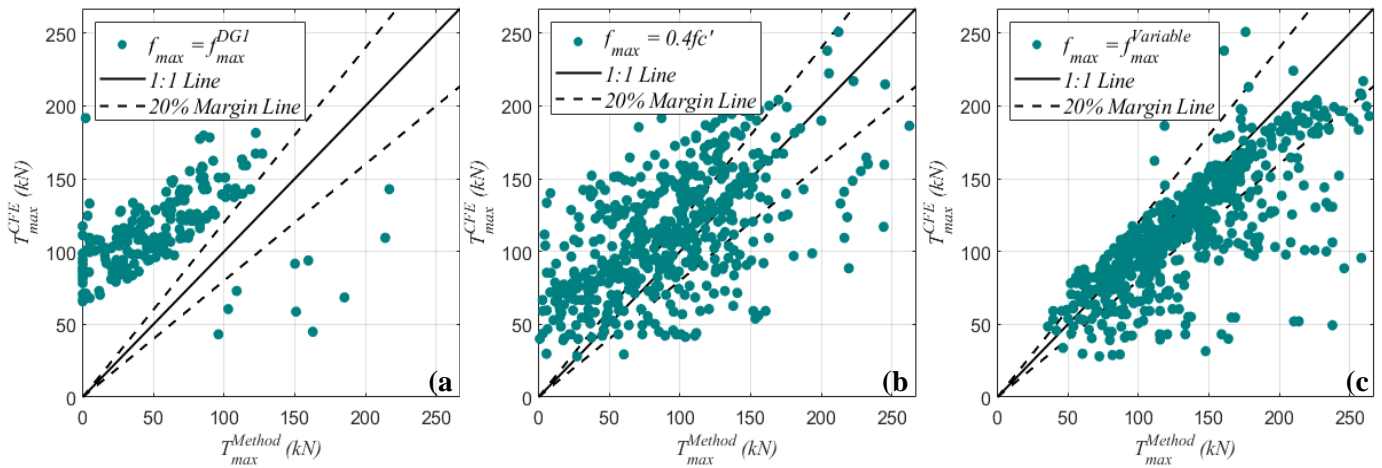


Figure 11 – T_{max}^{CFE} plotted against T_{max}^{Method} using different bearing stress f_{max} estimates: (a) $f_{max} = f_{max}^{DG1}$, (b) $f_{max} = f_{max}^{Constant} = 0.4f_c'$ and (c) $f_{max} = f_{max}^{Variable}$

This relationship, based on regression, reflects the trend previously illustrated in Figure 3.7. It is relevant to note here, that the points with departures from the observed linear trend between the loading index and the stress-ratio still provide strength predictions within the accepted range or are more towards the conservative side. Figures 3.12a-f examine the effect of two key parameters on the efficacy of the proposed method. Specifically, Figures 3.12a-c plot the ratio $T_{max}^{CFE}/T_{max}^{Method}$ (for all three approaches) versus the angle of applied loading θ_M (in which $\theta_M = 0^\circ$ corresponds to major axis bending, and $\theta_M = 90^\circ$ corresponds to minor axis bending). The data points represent all simulations, along with a moving average and standard deviation lines. Figures 3.12d-f plot the ratio $T_{max}^{CFE}/T_{max}^{Method}$ versus the aspect ratio N/B of the base plate. Referring to Figures 3.11 and 12, the following observations may be made:

1. Referring to Figures 3.11a-c, it is evident that a direct adaptation of the DG1 approach results in the poorest agreement between the predicted and simulated results. Specifically, the average $T_{max}^{CFE}/T_{max}^{Method}$ for the scatter points shown in Figure 3.11a are 1.87 with a Standard Deviation of 0.56. This suggests that not only is a direct adaptation of the DG1 approach inaccurate, but it is also unconservative. This is because the DG1 sets the concrete bearing stress to its maximum value, which is a gross overestimation in many cases, and does not reflect the internal stress distribution, as shown previously in Figure 3.7. Setting a lower value of f_{max} (i.e., $f_{max}^{Constant} = 0.4f'_c$) addresses this issue, partially (see Figure 3.11b) such that on average $T_{max}^{CFE}/T_{max}^{Method} = 1.24$. However, even such an empirical calibration (with a fixed f_{max}) cannot address the variability in the results, i.e., the Standard Deviation is 0.57. Figure 3.11c, which illustrates results based on $f_{max}^{Variable}$, shows significantly reduced variability and bias (average $T_{max}^{CFE}/T_{max}^{Method} = 0.95$ and Standard Deviation = 0.32).

2. The inaccuracy of the DG1 based approach is not specific to the cases with biaxial bending. For an examination of this issue, referring to Figure 3.12a, in which it is noted that even for the values of $\theta_M = 0^\circ$ and 90° (i.e., uniaxial bending about the major and minor axis respectively), the bias as well as the variation are significant. Note that for these situations, the proposed method is identical to the DG1 approach. Thus, it may be argued that the proposed approach inherits the limitations of the DG1 approach.
3. Figures 3.12b and c suggest that both the proposed approaches (with the constant and variable f_{max}) show roughly consistent performance across all angles of loading. However, the approach with the variable value of bearing stress $f_{max}^{Variable}$ show significantly lower, and consistent variability across all angles of loading.
4. Figures 3.12d-f examine trends of the DG1 extension and the two proposed methods with respect to the base plate aspect ratio N/B . In addition to the biases and inaccuracies of various methods reported in the previous points, these Figures 3.12d and e indicate that both the DG1 extension and the approach with the constant f_{max} ($f_{max}^{Constant}$) show a distinct trend with respect to the base plate aspect ratio, such that the accuracy decreases significantly as the base plate changes from square to rectangular. In contrast, the proposed approach with the variable $f_{max}^{Variable}$ does not show such a bias (see Figure 3.12f), providing further indication that it may more effectively represent the physics of the connection.
5. A Principal Component Analysis (PCA – Jolliffe 2002) was conducted to examine if combinations of input variables (rather than the primary input variables) influence its accuracy. The analysis examined how the primary output variable $T_{max}^{CFE}/T_{max}^{Method}$ varied with the input variables. The PCA indicated that the first principal component captured more than 90% of the variability, and the main variables contributing to this component were the geometric

attributes of the base plate S_x , S_y , and A , followed by the axial load, and moments in either direction. Moreover, these were negatively correlated with the $T_{max}^{CFE}/T_{max}^{Method}$. The angle of loading or the aspect ratio were not dominant. This suggests that the accuracy of the approach is influenced by the overall level of loading and the base plate dimensions. This is not surprising, given that the main element of subjectivity/empiricism in the approach arises from

the regression fit between $f_{max}^{Variable}$ and $\frac{P/A+M_x/S_x+M_y/S_y}{f'_c}$.

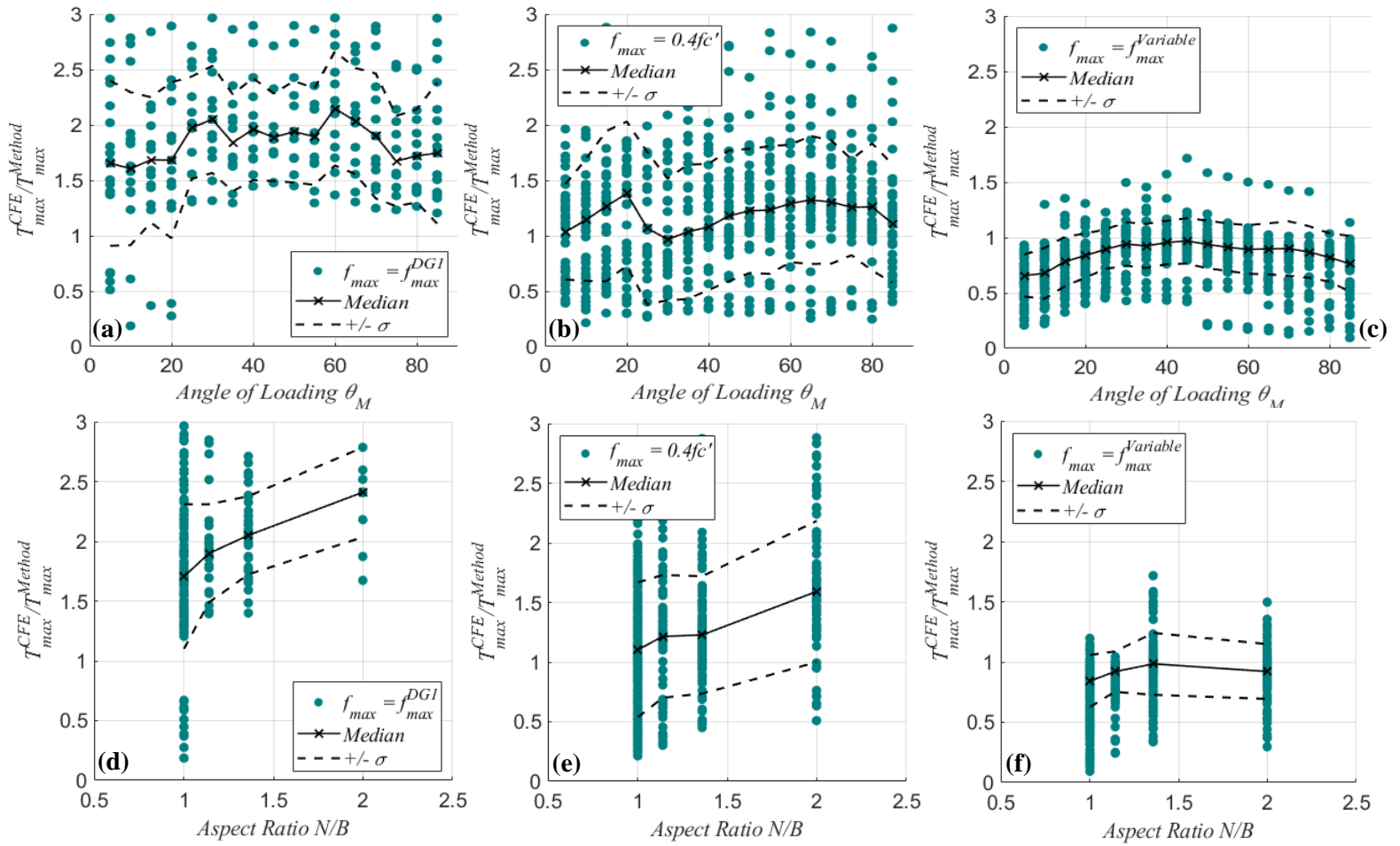


Figure 12 – The ratio $T_{max}^{CFE}/T_{max}^{Method}$ plotted against (a-c) angle of loading θ_M and (d-f) plate aspect ratio N/B for different bearing stress f_{max} estimates

In summary, a direct extension of the DG1 approach to biaxial bending suffers from a loss in accuracy. This may be partially addressed by selecting a fixed, lower value $f_{max}^{Constant}$, and more effectively addressed by estimating $f_{max}^{Variable}$ as a function of the applied loading. As noted earlier, the dependence of the bearing stress on the applied loading is not surprising, since the assumption of a constant bearing stress is an expedient one, developed for convenience. The refined, loading dependent estimate of $f_{max}^{Variable}$ is similarly empirical, but appears to reflect the mechanics of the base connection more closely. Once the tension forces in the rods and the compressive stress block are determined, various components of the connection may then be sized. For the anchor rods, this is usually straightforward, since it involves a direct comparison between the estimated anchor force and corresponding capacity. On the other hand, base plate yielding usually occurs in the form of yield lines on both the tension and compression sides of the connection. For the cases of uniaxial bending, the yield lines are often readily visualized (e.g., parallel to the compression flange – AISC Design Guide One, or diagonal between the anchors and the tension flange – OSHA 2001). However, such descriptions are not available for biaxial bending, in which case the yield lines are likely to be much more complex in form. While this is outside the scope of the current study, the force distributions (both anchor and compressive block) generated by this method may be used to formulate such yield line patterns.

The proposed approach is additionally evaluated against data from two biaxially loaded ECBP connections from two test programs (the only such data available): Bajer et al. (2014) at Brno University of Technology, Czech Republic (the BUT study), and Da Silva Seco (2019) at INSA Rennes, France (the INSA Rennes study). These studies did not report the force in anchors for the biaxially loaded specimens, but rather provided the moment-rotation diagrams (showing connection capacity); as a result, a direct comparison with the method is not possible.

Table 3.3 – Test parameters from Experimental studies (Bajer et al. 2014 and Da Silva Seco 2019) and evaluation with respect to Method

Test Program	Test Number ^a (Code)	N (mm)	B (mm)	Plate Thk. (mm)	Anchor Rod Diameter (mm)	Loading Angle θ_M (Degrees)	Axial Load (kN)	Column Profile	$\frac{M_{yield}^{Test}}{M_{yield}^{Method}}$
BUT	Joint 3	440	330	20	20 (M20 8.8)	26.5	400	HEB 240	1.61
INSA Rennes	SPE1-M45	330	300	10	16.0 (M16 5.6)	45.0	-	HEA 200	1.17

^a Selected experiments featured an anchor rod failure mode (rupture of anchors)

Consequently, for each of the test configurations (see Table 3.3) in which anchor rod failure was documented as the controlling mode, the quantity M_{yield}^{Method} is estimated. This reflects the resultant moment at which the anchor rod with the greatest force T_{max}^{Method} yields (as inferred from the proposed approach with $f_{max}^{Variable}$). Table 3.3 summarizes the test parameters along with the test-to-predicted ratios $M_{yield}^{Test}/M_{yield}^{Method}$, in which M_{yield}^{Test} reflects the experimental yield resultant moment for each of the considered tests. Note that this value too is indirectly inferred (by using the intersection point of the reported secant stiffness with the moment-rotation curve) since a clear yield point is not evident in the experimental data. Referring to Table 3.3, the average test-predicted ratio is 1.39, indicating a degree of conservatism in the approach.

3.6 SUMMARY, CONCLUSIONS, AND LIMITATIONS

This study presents a method to characterize internal forces in Exposed Column Base Plate connections subjected to biaxial bending in the presence of axial compressive force. This method is developed based on insights obtained from a series of Finite Element simulations that are validated against prior test data. These simulations interrogate numerous variables, including loading angle (for flexure) as well as the base plate aspect ratio, and column section. The proposed

method extends the current approach for ECBP connections under uniaxial bending (as outlined in the AISC Design Guide One) to biaxial bending. For the convenience of application, the method retains the general philosophy and key elements of the DG1 approach, including the assumption of a rectangular stress block on the compression side. Moreover, the method converges to the DG1 approach for uniaxial loading in major and minor axis bending. However, the proposed method also requires additional assumptions to address the indeterminacies that arise due to biaxial bending. These include enforcing a pattern of forces in the anchor rod based on an assumed Instantaneous Axis of Rotation (IAR).

A notable observation of the study is that the bearing stress used in the DG1 (i.e., f_{max}^{DG1}) overestimates the true bearing stresses as determined from the CFE simulations. Furthermore, there is also great variability in the CFE-to-predicted ratios of anchor force, suggesting that the DG1 fails to capture fundamental aspects of physical response, even in the uniaxial bending condition. Thus, two alternative estimates of bearing stress are proposed. One is a fixed value, $f_{max}^{Constant} = 0.4f'_c$ (which is roughly 25% of f_{max}^{DG1}) that eliminates the bias of the DG1 method. However, it cannot eliminate the variability in the results. To accomplish this, an alternate estimate $f_{max}^{Variable}$ is suggested. This is based on the observation (from CFE simulations) that the magnitude of the bearing stress block increases with an increase in loading – an expected trend, which is currently not incorporated in DG1. This eliminates the bias in results, and also significantly increases accuracy overall with respect to the simulated configurations that include a range of loading angles as well as base plate aspect ratios. The method is also assessed against a limited set of test data; the results are not quite as promising as the comparison against CFE, but are reasonable, nonetheless. This is attributed to challenges in interpreting the test data accurately.

While promising, the method has several limitations that must be considered in its interpretation and application. First, the method inherits the limitations of the DG1 approach, including the presumption of a predetermined rectangular stress block, rather than an explicit solution of equilibrium, compatibility, and constitutive response. Although this aspect of the method is based on practical considerations, it does limit the accuracy of the approach. In addition to this, other aspects of the method are semi-empirical as well. For example, the calibrated value of $f_{max}^{Constant} = 0.4f'_c$, as well as the regressed relationship for $f_{max}^{Variable}$ are not developed from first principles, although they appear to reflect the physics of connection response. This is particularly unsatisfying, presenting challenges in the interpretation of the regressed expression of $f_{max}^{Variable}$, and possible extrapolation/generalization. Specifically, it is recognized that the approach, in large part, compensates for the problems introduced by the DG1 method. Because of this, the criteria suggested herein for $f_{max}^{Variable}$ may lead to erroneous/inaccurate anchor rod force predictions for different base plate configurations than those examined (e.g. details that allow significant base plate/column profile yielding). Moreover, it is important to note that given the limited number of experiments for biaxial bending of ECBP connections, the method is based on insights and data from CFE simulations; these CFE simulations themselves are subject to error, especially in the simulation of the footing constitutive response as well as consideration of effects such as anchor rod prestress. Due to these various factors, extrapolation of the method to configurations significantly different than the ones interrogated in the simulations (e.g., alternate anchor rod configurations, base plate aspect ratios greater than 2.0), may be subject to additional error. Finally, determining yield line patterns in ECBP connections is outside the scope of this study, which focuses on anchor rod forces and internal stress distributions. These limitations may be addressed through additional testing of biaxially loaded connections, simulations, and associated model

development. Until such studies are complete, the proposed model provides a practical and reasonably accurate approach to aid the design of these connections.

CHAPTER 4

SEISMIC RESPONSE OF BLOCKOUT COLUMN BASE PLATE CONNECTIONS UNDER AXIAL COMPRESSION AND FLEXURE

4.1 INTRODUCTION

Exposed Column Base Plate (ECBP) connections are commonly used in steel construction to connect the column to the concrete footing (see Figure 4.1), and to transfer the forces from the entire frame into the foundation. Referring to Figure 4.1, these connections consist of a steel column welded to a base plate, which is then attached to a concrete footing using anchor rods. Given their prevalence and importance, they have been the subject of considerable study. These studies have included experimental (Astaneh et al. 1992; Burda and Itani 1999; Gomez et al. 2010; Kanvinde et al. 2015; Trautner et al. 2016; Hassan et al. 2022) as well as analytical (Ermopoulos and Stamatopoulos 1996) investigations, and have addressed strength models (Drake and Elkin 1999), stiffness models (Wald et al. 1995; Kanvinde et al. 2012), seismic performance (Trautner et al. 2017; Hassan et al. 2022), strength characterization of biaxially loaded (Hassan et al. 2021) details, as well as interactions with the frames (Falborski et al. 2020; Inamasu et al. 2021). Figure 4.1 also illustrates the mechanism through which these connections resist applied loads. The applied axial force and moment are resisted by the development of a bearing stress block on the compression side of the connection, complemented by tension in the anchor rods. Shear is resisted either by the anchor rods, a shear lug (not shown), or friction. Based on these mechanisms, the American Institute of Steel Construction's (AISC) *Design Guide 1* (Fisher and Kloiber, 2006), hereafter abbreviated as DG1, provides strength characterization methods, and design guidance for these connections.

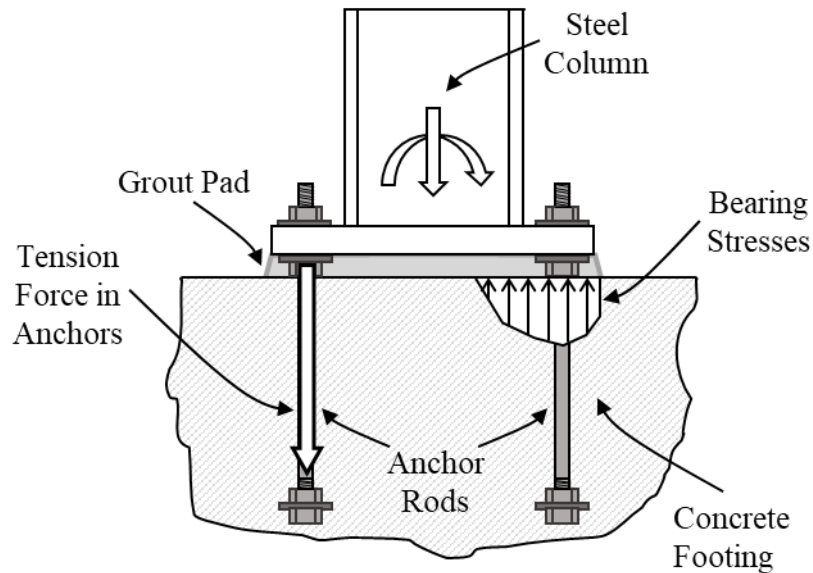


Figure 4.1 – Schematic illustration of an exposed column base plate connection subjected to axial compression and moment

In many situations (especially in commercial or residential buildings), a slab-on-grade is often cast on top of the base plate to provide a flat surface – see Figure 4.2. To achieve this, the column is connected to the footing as in a conventional ECBP connection, but through a diamond shaped “blockout” as shown in Figure 4.2. This blockout allows for the installation of the remainder of the slab-on-grade prior to the installation of any structural steel (minimizing the overlap of concrete and steel work on the job site). After the column is installed, the blockout is filled with unreinforced concrete or grout creating a cold joint between the blockout concrete and the remainder of the slab. The depth of the blockout is usually in the range of 200 mm – 400 mm. The diamond shape of the blockout (i.e., orientation at 45 degrees to the frame gridlines) encourages formation of shrinkage cracks in preferred directions aligning with construction control joints (i.e., along and perpendicular to the gridlines) as shown in Figure 4.2.

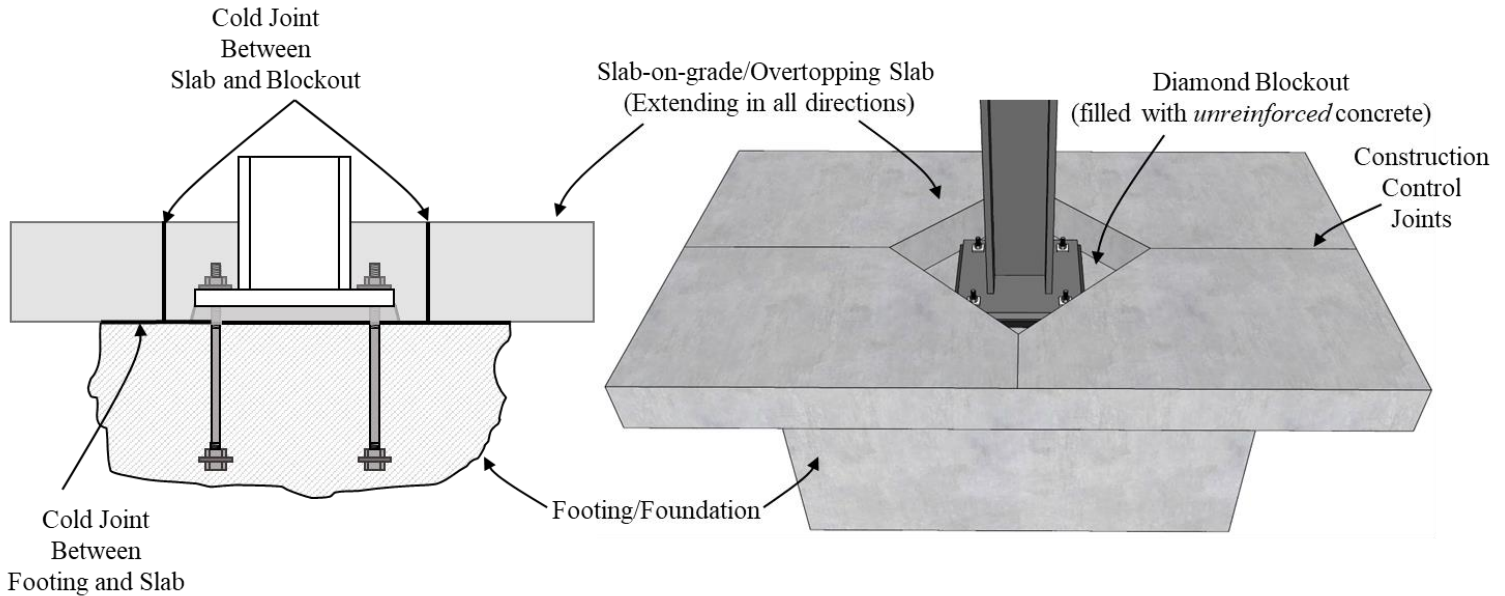


Figure 4.2 – Blockout column base connection

The blockout and the surrounding slab results in an embedded base connection, which provides supplemental flexural strength and stiffness to the mechanisms illustrated in Figure 4.1. This supplemental resistance is usually disregarded in the design of the ECBP connection itself, as well as in the simulation of the frame – both in the context of its design as well as seismic performance assessment. Previous experiments by Richards et al. (2018), Hanks and Richards (2019) on similar connections, as well as Grilli et al. (2017) on more deeply embedded connections indicate that the embedment provides significant additional strength (as much as 50% compared to ECBPs without the blockout) as well as stiffness, which cannot be disregarded without introducing major conservatism into design and seismic performance assessment. The latter (i.e., performance assessment) is particularly relevant because: (1) a large number of ECBP connections with blockout are often present, both in the seismic lateral load resisting system as well as the gravity system, (2) these are often simulated ECBP connections without the blockout, greatly

underestimating their contribution to the overall lateral resistance of the frame, and 3) the collapse capacity of the overall system has been shown (Flores et al. 2014) to be sensitive to the base condition.

Despite their importance, breakout as well as embedded connections (especially those consistent with United States construction practice) have attracted research attention only recently, such that the knowledge regarding their response is fairly immature. The only experimental studies featuring breakout connections are Richards et al. (2018); Hanks and Richards (2019), and the only study with embedded connections is by Grilli et al. (2017). While these studies provide valuable experimental data and an understanding of fundamental behavior and seismic response, none of the experimental specimens (on breakout connections) tested so far include axial compression, which is expected to have a major influence on the response of the connection. Motivated by this, the current study presents results from three large-scale experiments on breakout connections representative of construction practice in the United States. In addition to interrogating the effect of axial force on lateral or flexural cyclic response, the experiments also feature larger (than previously tested) column sizes and base plates, and also a larger slab on grade outside the breakout, providing realistic boundary conditions with respect to uplift of the breakout.

The next section of the chapter summarizes observations from previous studies conducted in the United States as well as a previous study from Japan. This is followed by a discussion of the experiments conducted as part of this study. Results from the experiments (both current and previous) are then used to propose a model for strength characterization that provides good accuracy across all test programs, and to evaluate models for estimation of rotational stiffness. The

study concludes by providing recommendations for design and representation of these connections, and outlining limitations.

4.2 BACKGROUND AND PREVIOUS WORK

Experiments from two prior test programs are considered in this study to supplement test data from this study, and to inform model development and validation. Both these test programs feature details that may be considered similar to construction practice in the United States. These programs were conducted at Brigham Young University (termed BYU tests) and Kyoto University, termed the KU tests. The BYU series (Richards et al., 2018; Hanks and Richards, 2019) consists of 10 experiments (applying load along the strong axis) on specimens with shallowly embedded details, intended to represent a slab-on-grade overtopping an exposed base plate type connection. A strength model was developed to quantify the flexural strength of breakout connections. Figure 4.3 illustrates the key concept of the strength model (details and associated equations are available in Richards et al. 2018). As per this approach, the effect of the breakout and surrounding slab may be represented by assuming that the breakout effectively spreads the compression out over a distance $d_{breakout}$ from the face of the column. The failures in the specimens from BYU study all showed separation of the entire slab from the footing below, rather than separation of the breakout from the slab or breakout of concrete above the base plate.

In the KU test series, Cui et al. (2009) tested 7 specimens of column base connections embedded in concrete, referred to hereafter as the KU study (Kyoto University). Of these, two specimens are physically similar to breakout connections used in the United States (i.e., the overtopping slab only reinforced by top mesh bars, with no reinforcement around the base plate), and are consequently

considered in this study. The specimens featured square-tube columns with a welded base plate featuring twelve anchor rods (distributed on multiple rows), with different embedments (100 and 200 mm). The specimens showed a notable increase in strength (10 to 95%) as well as elastic stiffness (10 to 47%) as compared to a similar base connection without the embedment. The study identified the failure mode of most specimens (including the ones of interest shown in Table 4.1) as an upward punching shear failure of the overtopping slab with a 45-degree cone formation. An analytical model was proposed to evaluate the moment capacity of the connection by adding the strength of multiple components (base plate and column bearing, concrete slab, and anchor rods), assuming plastic response of the connection.

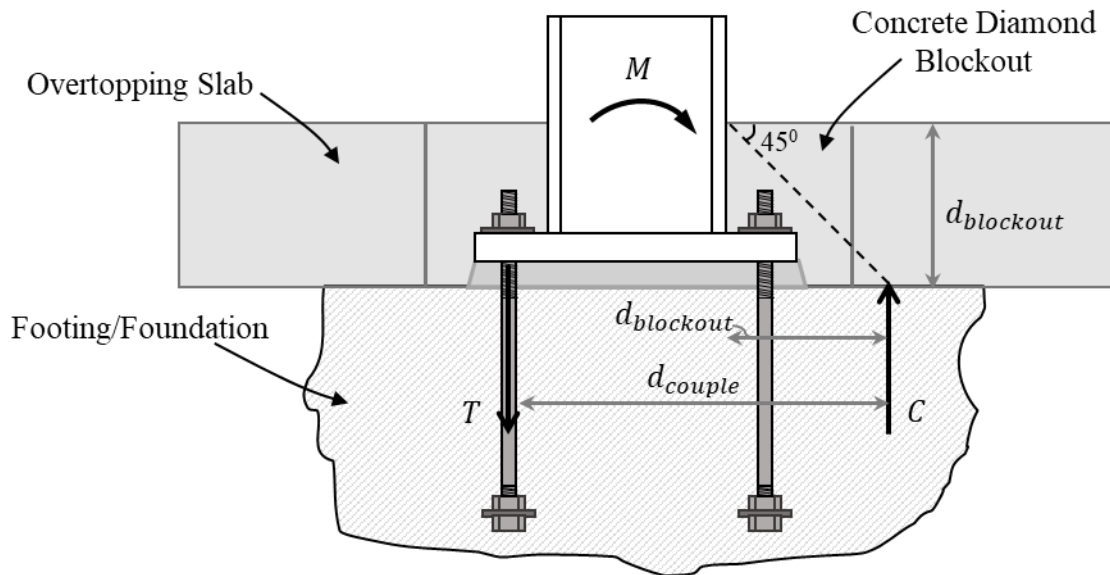


Figure 4.3 – Schematic illustration of the blockout column base connection strength model developed by Richards et al. (2018)

These two test programs provide an understanding of the load transfer and failure modes of blockout connections, indicating that the embedment generated by the blockout supplements by the resistance by restraining the motion of the column in the horizontal direction, and the embedded

base plate in the vertical direction. These mechanisms are qualitatively similar to those observed for embedded column base connections, by Grilli and Kanvinde (2017). The next section describes the experiments conducted as part of the current study.

4.3 EXPERIMENTAL PROGRAM

This section outlines the experimental test setup, matrix, applied loading protocol, and instrumentation for the recent experiments conducted in this study. Figures 4.4 and 4.5 illustrate aspects of the test setup and specimen detailing, respectively; whereas Table 4.1 summarizes the test matrix, along with key results that are discussed later.

Test Setup and Instrumentation

Figure 4.4 shows the test setup, including the specimen, reaction frame for lateral loads, and the loading cross-beam to introduce compressive axial loads. Specific aspects of the test setup are now summarized:

- All specimens were cantilever columns attached to a footing through a blockout in the slab. Lateral deformations were applied to the columns with a servo-hydraulic actuator attached at the top. This location (3.4 m above the base plate) was assumed to represent the inflection point in a first story column. All columns were of ASTM A992 steel with Grade 50 ($F_y = 345 \text{ MPa}$) and were designed to remain elastic to induce failure in the base connection.
- The footing dimensions (common for all tests) are indicated on Figure 4.5. All footings used concrete with nominal compressive strength $f'_c = 27.6 \text{ MPa}$, and were provided with minimal longitudinal and transverse reinforcement. The reinforcement featured an identical top and bottom mesh of #5 hooked bars (#16 metric size) placed longitudinally at 305 mm (12 in.) on center and transversely at 178 mm (7 in.) on center, with a 76 mm (3 in.) bottom cover.

The footings were fastened to the strong floor using pretensioned rods/tie downs as shown in Figure 4.5.

- An overtopping slab of length of 2.43 m (96 in.), a width of 1.82 m (72 in.) and depth 305 mm (12 in.) with a nominal compressive strength $f'_c = 27.6 \text{ MPa}$ was cast on top of each footing, consistent with standard practice. The slab reinforcement represented typical temperature and shrinkage reinforcement (top mesh only). A diamond-shaped breakout formwork was placed to allow for column placement. After column placement, the space created by the breakout was filled with plain concrete ($f'_c = 27.6 \text{ MPa}$), resulting in cold joints with the underlying footing, as well as the surrounding slab.
- The loading-beam shown in Figure 4.4 introduced a constant compressive axial load through an assembly of tension rods and hydraulic jacks in Tests #2, and #3. The lower end of the tension rods was connected to a freely rotating clevis, such that the axial forces were follower forces and did not introduce ($P - \Delta$) moment into the connection as the column rotated.
- The columns were welded to the base plates with Partial Joint Penetration (PJP) welds and reinforcing fillet welds. The plate and welds were sized to remain elastic, forcing yielding into the anchors.

All specimens featured 4 anchor rods with the same diameter (1 in./25.4 mm) and material grade (ASTM F1554, Gr. 55 – 380 MPa). At the bottom end of the rods, a square plate washer and nut assembly provided anchorage, while at the top, a nut and plate washer were used along with oversized base plate holes as specified by *AISC Design Guide One* (2006). A shear lug with a thickness of 25.4 mm was fillet welded to the bottom of the base plate protruding 82.5 mm (3.25 in.) from the bottom surface of the base plate. A 50 mm (2 in.) layer of non-shrink grout with nominal compressive strength $f_{grout} = 55 \text{ MPa}$ was provided between the base plate and the top

surface of the concrete footing after the setting and leveling of the base plate on shim stacks. The fabrication and erection procedure for the detail is similar to that used in current field practice. Major instrumentation included measurements of: (1) lateral force and displacement at the top of the column (i.e., at the actuator location); (2) axial force in the column; (3) vertical displacements of the diamond breakout concrete; (4) strain gage measurements from the anchor rods and the base plate surface to monitor local strains. Additional transducers were installed to detect unanticipated response modes such as out of plane and torsional response of the column.

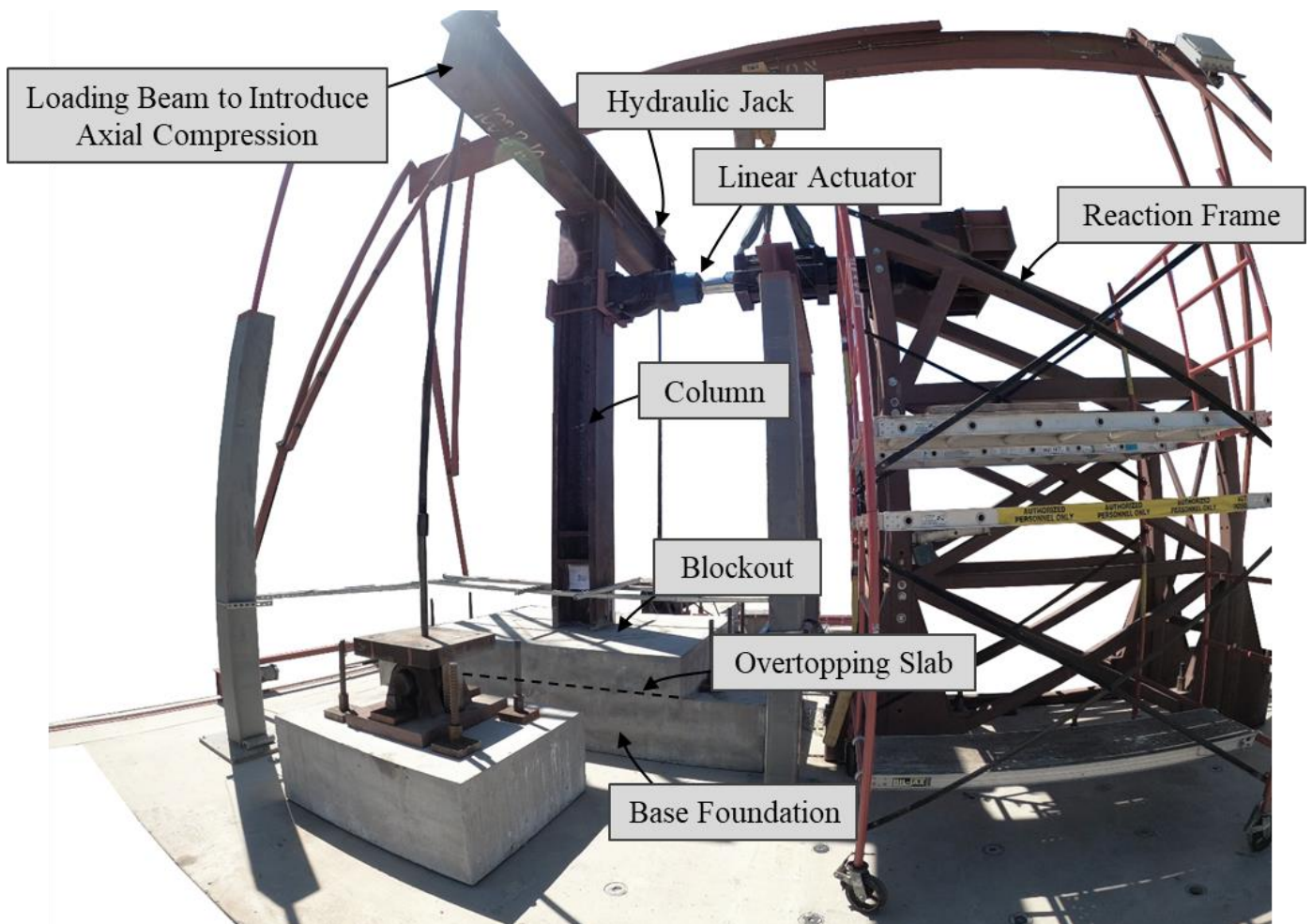


Figure 4.4 – Wide angle view of test setup

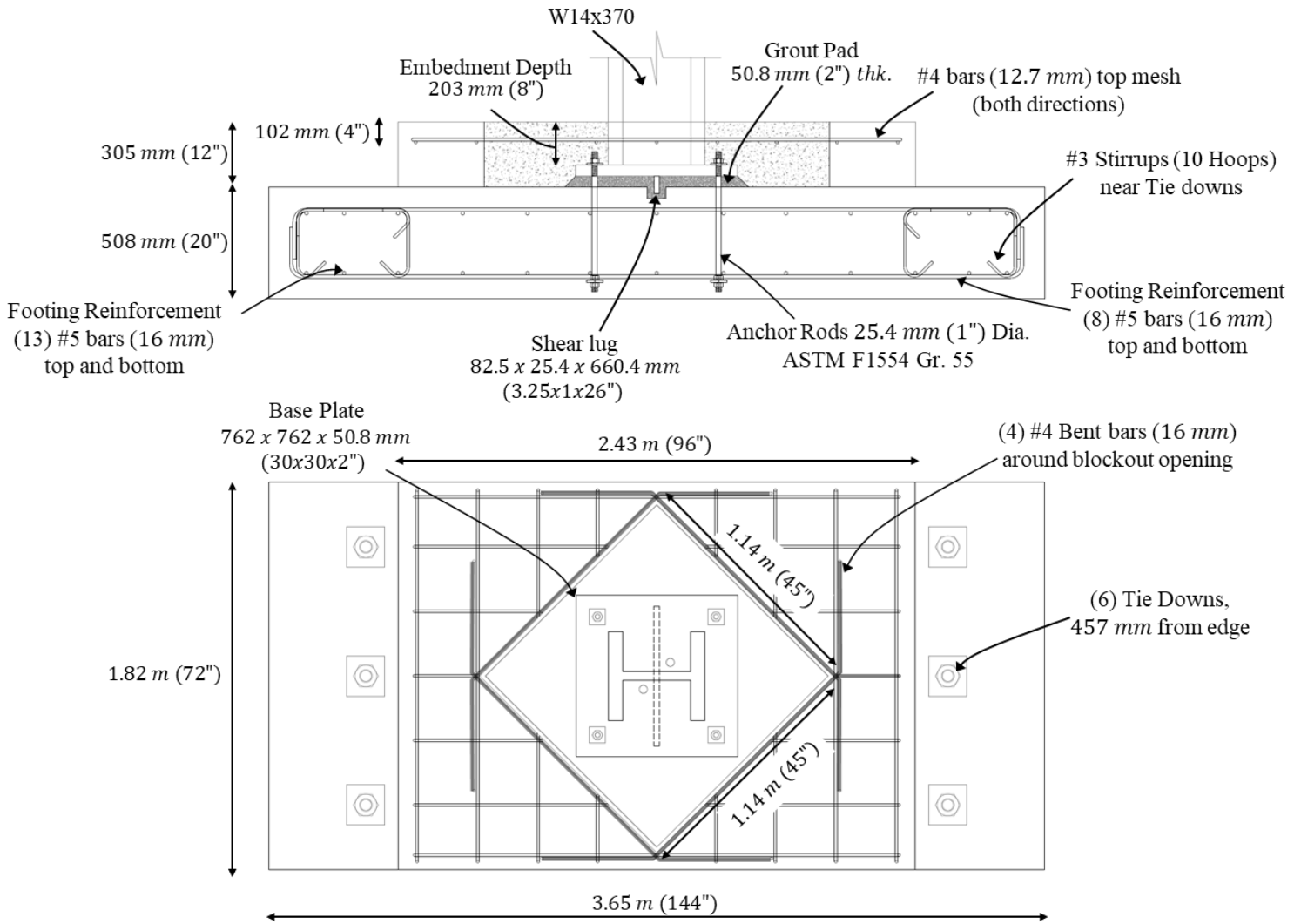


Figure 4.5 – Schematic illustration of experimental specimens detailing

Ancillary Testing and Material Properties

Ancillary tests were conducted to characterize the mechanical properties of the materials used in the tested specimens; these tests included: (1) tension tests of the anchor rods, (2) compression tests on standard concrete cylinders, and (3) compression tests of grout cylinders. Concrete samples were taken during the casting of the footing, overtopping slab, as well as the blockout and grout specimens were cast during the installation of the column. Table 4.2 summarizes measured material properties corresponding to each large-scale test.

Table 4.1 – Tests Matrix and Results from UCD Tests

Test ^{a,b}	Axial Load P [kN]	Embedment Depth d_{embed} [mm]	Anchor Rod Diameter ^{c,d} d^{rod} [mm]	ASTM ^e F1554 Anchor Grade	M_{DG1} ^f [kN.m]	M_{max}^{test} ^g [kN.m]	M_y^{test} [kN.m]	$\frac{M_{max}^{test}}{M_{DG1}}$	$\frac{M_y^{test}}{M_{DG1}}$	$\frac{M_y^{test}}{M_{max}^{test}}$	$Drift_{max}$ [%]
1	0	203 (8")	25.4 (1")	55 (380 MPa)	275	571 (+)	463 (+)	2.07	1.68	0.81	5 (+)
						553 (-)	443 (-)	2.01	1.61	0.80	5 (-)
2	445 (100 kip)	203 (8")	25.4 (1")	55 (380 MPa)	436	857 (+)	624 (+)	1.96	1.43	0.73	5.7 (+)
						861 (-)	586 (-)	1.97	1.34	0.68	5.1 (-)
3	667 (150 kip)	203 (8")	25.4 (1")	55 (380 MPa)	515	898 (+)	786 (+)	1.74	1.52	0.88	6.1 (+)
						780 (-)	547 (-)	1.51	1.06	0.70	5.5 (-)
							Mean	1.88	1.45	0.77	5.4
							CoV	0.11	0.15	0.09	0.08

^aTests featured $W14 \times 370$ (customary units) cantilever columns - ASTM A992 Grade 345 MPa.

^bBase plate dimensions: $N \times B \times t_p = 762 \times 762 \times 51$ mm; Edge distance between rod centerline and edge of plate = 101.5 mm. with 2 rods on each side; Oversized hole diameter in plate = 47.5 mm.

^cUnthreaded diameter (rod shank) with a 4" threaded portion on top and bottom.

^dSquare plate washers at top and bottom dimensions: $76 \times 76 \times 9.5$ mm and $76 \times 76 \times 12$ mm, respectively.

^eValues of anchor rod yield strength F_y^{rod} are nominal. Refer to Table 4.2 for measured material properties.

^fMoment calculated in accordance with current procedures outlined in AISC's Design Guide One - Fisher and Kloiber (2006), using measured material properties.

^gMaximum moment at the level of base plate level measured for specimens in each direction of loading (positive and negative), where the positive sign denotes the first deformation cycle direction

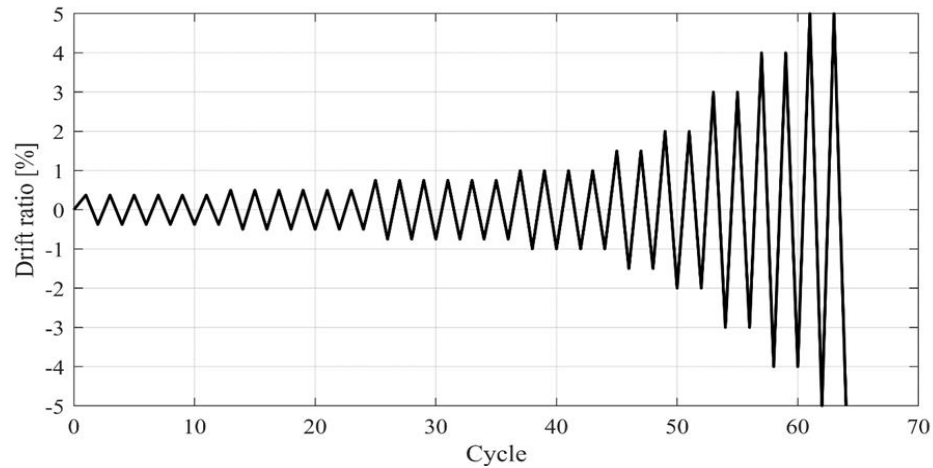


Figure 4.6 – Loading protocol

Large Scale Test Matrix

Referring to Table 4.1, the selected specimen characteristics were selected to be representative of current design practice with axial load as the primary variable. Specifically:

- The compressive axial loads were varied to examine the effect on the moment capacity. The level of applied axial load was chosen such that yielding of the base plate on the compression side of the connection was avoided.
- The anchor sizes were chosen to ensure yielding in the anchors, while other components of exposed base connection remained elastic. The embedment length of anchor rods was sufficient to achieve full tensile capacity prior to pullout/breakout concrete failure following *AISC Design Guide 1* and ACI 318-19 standards (ACI 2019).

Axial load was introduced first and held constant while the lateral displacement-controlled loading protocol was applied. Figure 4.6 illustrates the lateral loading protocol, expressed in terms of the column drift ratio measured with respect to the top of the base plate – which is usually considered to be the datum for structural analysis and design (i.e., the breakout is not considered). The ATC-SAC (Krawinkler et al. 2000) history was selected to represent deformation histories consistent with seismic demands in moment frame buildings.

4.4 EXPERIMENTAL RESULTS

Response plots for column base moment versus rotation (determined from the total deformation after subtracting the elastic column deformations) are presented in Figures 4.7a-d for the three tested specimens, whereas Figures 4.8a-d show photographs of damage progression and failure for one of the tests (Test #2); the damage progression is qualitatively similar for all other experiments. The photographs illustrate response and failure modes of the tested specimens and correspond to the loading instants identified by the numbers 1 to 3 in Figures 4.7a-c. The typical damage progression included the following:

1. On the compression side of the connection, small cracks began to form on the concrete surface in front of the column flange indicative of concrete crushing – Figure 4.8a, corresponding to Point “1” on Figures 4.7a-c.
2. On the tension side of the connection, diagonal cracks are seen emanating from the corner of the column flange extending into the blockout and beyond into the overtopping slab around it – Figure 4.8b, corresponding to Point “2” on Figures 4.7a-c. This (as determined subsequently) is indicative of the breakout cone of the concrete forming underneath the surface as the plate pushes the concrete upwards. The capacity of the connection is reached around this time.
3. Cracks perpendicular to the direction of loading (which appeared earlier) start to grow at the corners of the blockout, Figure 4.8c. These cracks indicate splitting of the outside slab (at its weakest net section) due to wedging of the blockout as it tries to rotate further. After this point, the blockout concrete begins to rotate somewhat freely within the diamond-shaped hole, shimmying up as the deformations increase – also shown on Figure 4.8c. This continues until the strains in the anchors accumulate, eventually causing fracture of one of the anchors, which occurs at around 5-6% drift, corresponding to Point “3” on Figures 4.7a-c.

4. Figure 4.8d shows a post-test photograph of the concrete and blockout after removal of the column; the location of the column, and the diamond blockout are indicated. This shows the blowout cone, which extends through into the surrounding overtopping slab.

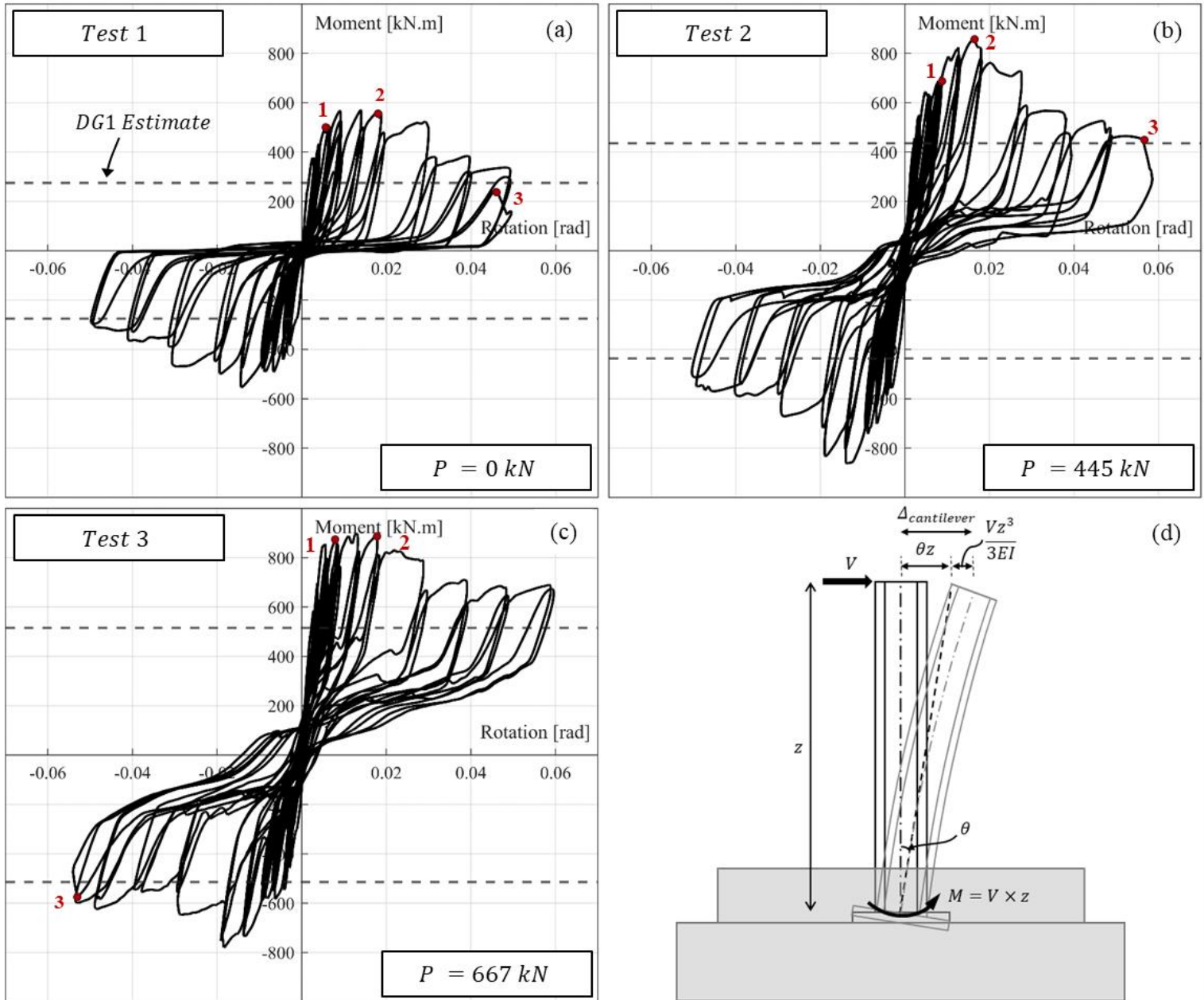


Figure 4.7 – Moment rotation plots for all experiments and schematic illustration of plotted quantities

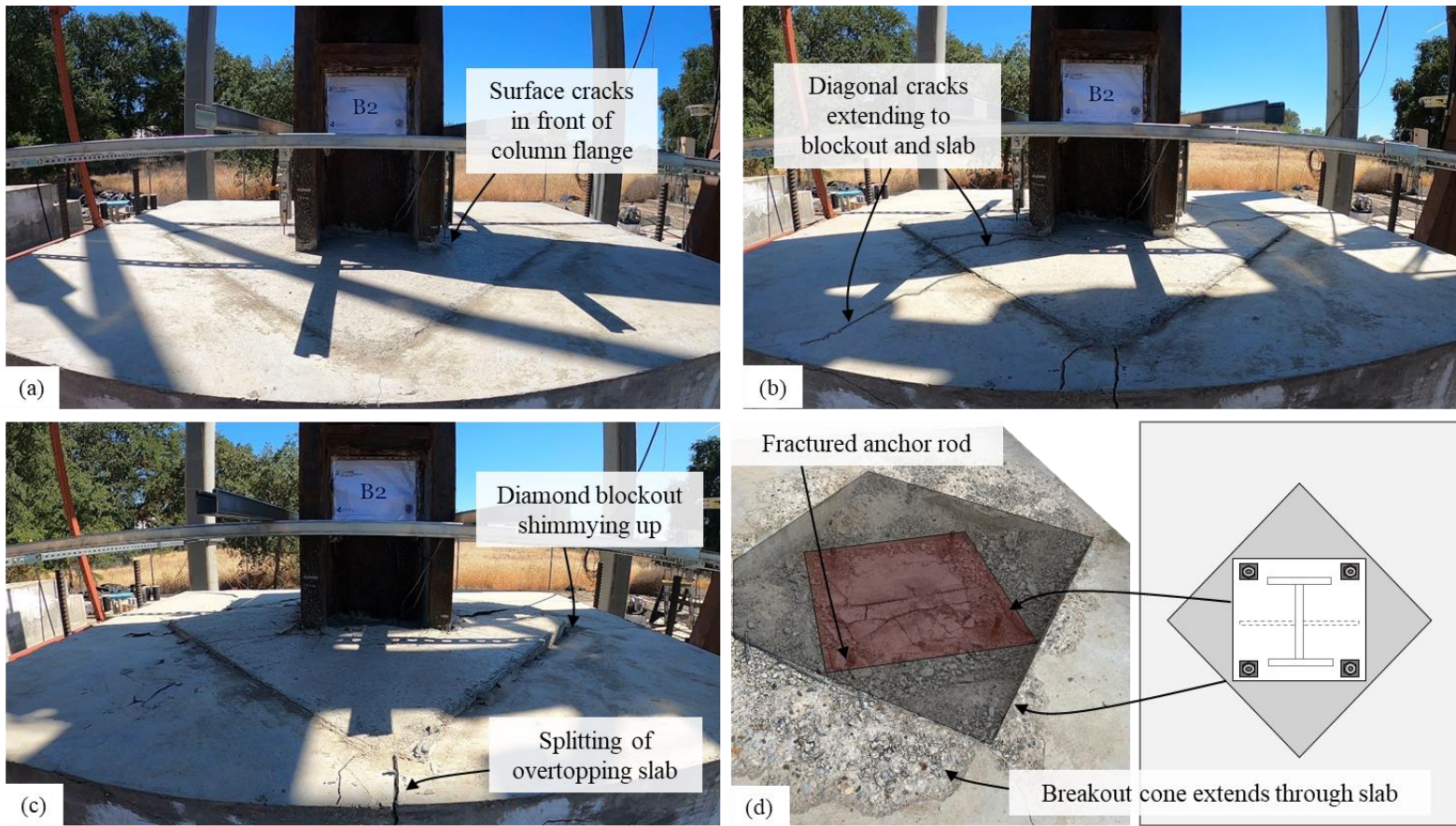


Figure 4.8 – Typical damage progression for one of the tested specimens (Test #2)

Table 4.2 – Summary of measured material strengths from ancillary tests

Test #	Anchor Rod Yield Strength ^a F_y^{rod} [MPa]	Anchor Rod Ultimate Strength F_u^{rod} [MPa]	(Base Foundation) Concrete Compressive Strength ^b f'_c [MPa]	(Overtopping Slab) Concrete Compressive Strength f'_c [MPa]	(Blockout) Concrete Compressive Strength f'_c [MPa]	Grout Compressive Strength f_{grout} [MPa]
1	400	552	30.5	28.1	28.0	58.5
2			31.0	28.6	28.3	60.1
3			30.7	28.3	28.1	58.5

^a ASTM F1554 Rod Grade 55 (ASTM 2020).

^b Compressive strength for concrete and grout cylinders is measured on the day of full-scale test.

Table 4.1 summarizes important quantitative data. This includes the maximum base moment observed during testing M_{max}^{test} with two values provided, one for each loading direction (M_{max+}^{test} , and M_{max-}^{test}), where the positive sign denotes the direction of the first deformation cycle. These moments represent the column moments calculated at the elevation of the top surface of base plate, which is usually considered as the datum in structural analysis and design. In addition to the ultimate moments M_{max+}^{test} , and M_{max-}^{test} , the yield moment strengths, M_{y+}^{test} , and M_{y-}^{test} are of interest as well. However, unlike the ultimate moments, these cannot be determined objectively given the nonlinearity of the load deformation curve even at relatively low moments (see Figures 4.7a-c). As a result, a procedure outlined by Grilli et al. (2017) is used to estimate these in a consistent way – this involves conducting a least squares fit of a bilinear moment-rotation relationship to the backbone of the experimental moment-rotation curve. The ratio of the yield moment to the ultimate moment $M_y^{test}/M_{max}^{test}$ is also tabulated in Table 4.1 for each of the experiments. The average value of $M_y^{test}/M_{max}^{test}$ for all experiments is 0.77 with a Coefficient of Variation (CoV) 0.09, which suggests consistency and may be considered as a fraction of ultimate strength for design purposes. The table also includes the ratio between the maximum base moment, M_{max}^{test} and yield base moment, M_y^{test} observed during testing with respect to the design moment M_{DG1} . Referring to Table 4.1 and Figures 4.7a-c, the following observations may be made:

- A majority (2 out of 3) of the experiments are stronger in the positive direction, such that the average of $M_{max+}^{test}/M_{max-}^{test}$ is 1.05 with a Coefficient of Variation (CoV) 0.07. This suggests that damage caused by loading in one direction affects the strength in the reverse direction.
- A comparison among Tests #1, 2 and 3 provides a direct assessment of the effect of axial load, indicating that the moment capacity of the connection steadily increases with respect to axial

load. This is not unexpected, because the axial compression introduces a pre-stress into the connection, delaying the uplift of the base plate.

- All specimens exhibited excellent deformation capacity until 5-6% drift without considerable strength degradation.

4.5 MODELS FOR STRENGTH CHARACTERIZATION

Richards et al. (2018) and Hanks and Richards (2019) proposed a method to characterize the strength of breakout connections. The details of the method (illustrated previously in Figure 4.3) may be found in Hanks and Richards (2019); only the main concepts are summarized here. The method incorporates the effect of the breakout by assuming that it effectively extends the plate on the compression side of the connection, and the moment at the base of the column is resisted by a force couple consisting of a resultant tensile force T in the anchor rods and a compression resultant C at the base of the breakout, located at the distance d_{couple} as indicated in Figure 4.3. For each of experiments considered in this study (i.e., from the Richards et al. 2018, Hanks and Richards 2019, and Cui et al. 2009 test programs as well as the tests described in this study – see Table 4.3), this approach (termed Method 1) is used to estimate the moment strength. The strength comparisons made in this section utilize the ultimate strength from the experiments (i.e., M_{max}^{test}) because it can be estimated objectively. Corresponding model-based estimates (i.e., $M_{max}^{Method\ 1}$) utilize the measured (rather than specified) ultimate strength of the anchor rod (F_u^{rod}), rather than the yield strength (F_y^{rod}) for a consistent comparison with the experiment. Note that the anchor rod is the only element in the connection that yields, such that the strength of the base plate or column material is not relevant. Figures 4.9a-f plot results for all the experiments (BYU, KU, and UCD series) from various strength characterization methods against two test variables, i.e., the

column embedment (normalized by the depth of the column, i.e., d_{embed}/d_{col}), and the axial force (normalized by the crushing strength of the footing under the base plate, i.e., P/P_{crush}). Specifically, Figures 4.9a-b plot the test-predicted ratios M_{max}^{test}/M_{DG1} for the DG1 approach, which entirely disregards the effect of the overtopping slab or blockout. Figures 4.9c-d are similar, except that the test-predicted ratios $M_{max}^{test}/M_{max}^{Method\ 1}$ are plotted for Method 1 outlined above. Finally Figures 4.9e-f plot results for a new strength characterization approach proposed herein (and presented later) – this is termed Method 2. Referring to Figures 4.9a-d, and the corresponding entries in Table 4.3, it is noted that:

- The average test-predicted ratio for the DG1 method, i.e., M_{max}^{test}/M_{DG-1} is 1.67 with a CoV 0.32. This is not unexpected, because the DG1 entirely disregards the contribution of the overtopping slab. Moreover, this suggests that using the DG1 approach to assess the strength of blockout connections is highly conservative. This is further confirmed through an examination of Figure 4.9a, which shows a positive trend with respect to the embedment ratio d_{embed}/d_{col} (implying greater conservatism as the embedment increases). No such trend is observed with respect to the axial load ratio P/P_{crush} .
- The average test-predicted ratio for Method 1, i.e., $M_{max}^{test}/M_{max}^{Method\ 1}$ is 1.38 with a CoV 0.50. This suggests, that on average, the conservatism is reduced by accounting for the effect of embedment. Nonetheless, the method is still conservative and has a significant variability (CoV), suggesting that it does not accurately represent the underlying physics when examined across all the tests. More specifically, Figure 4.9c shows that while the approach works well for $P/P_{crush} = 0$ (with an average $M_{max}^{test}/M_{max}^{Method\ 1} = 0.93$), the accuracy of the method decreases for applied axial compression. This is not surprising either, because Method 1 is

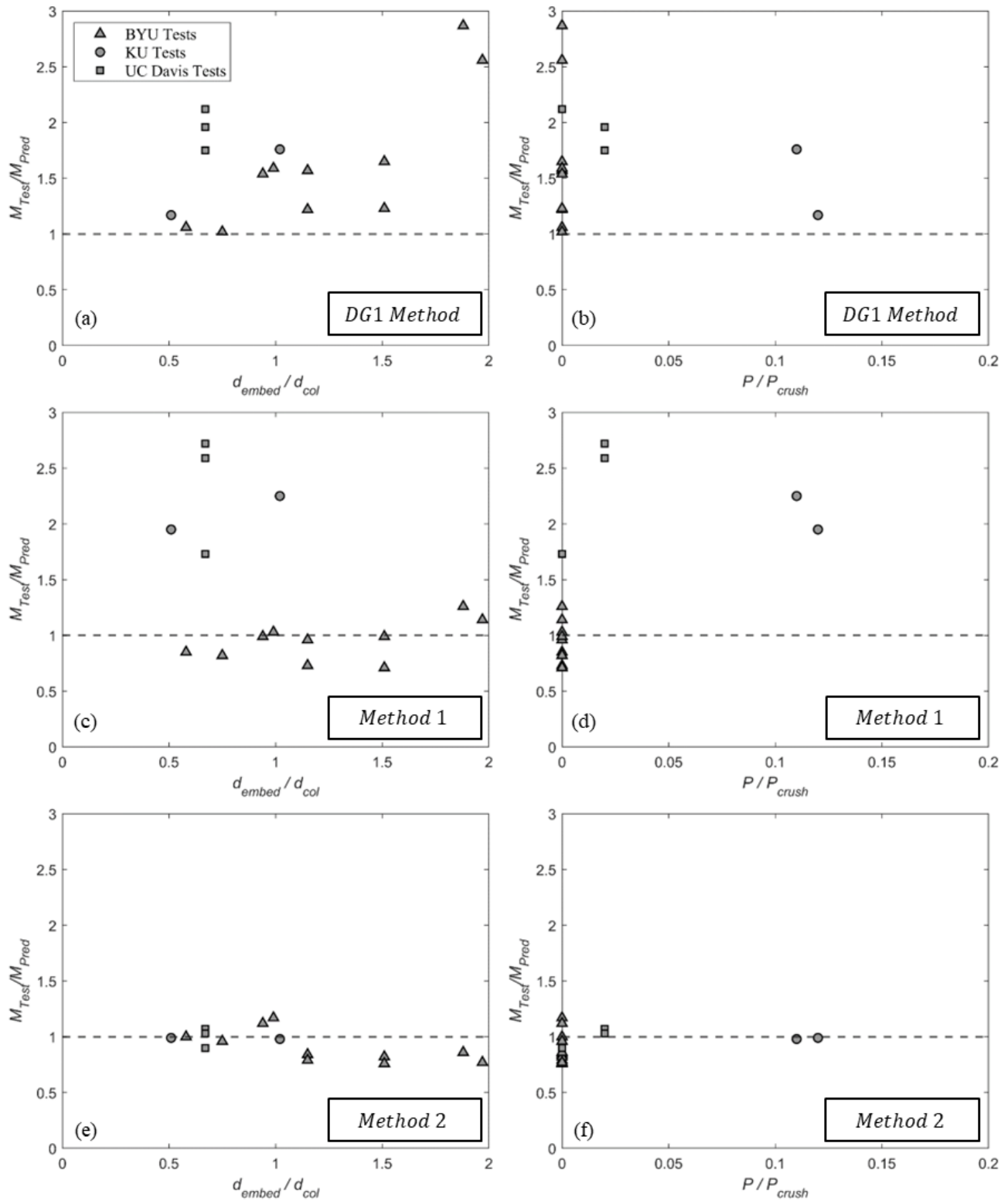


Figure 4.9 – Test-predicted ratios for all experiments from various strength characterization methods plotted against d_{embed}/d_{col} and P/P_{crush}

based on experiments (Richards et al. 2018; Hanks and Richards 2019) that do not include an axial force.

Table 4.3 – Test Matrix from UCD, BYU and KU Studies and Results

Test Prog	Test # ^a	Column Size	$d_{embed\ c,d}$ [mm]	P [kN]	Base Plate Size $t_p \times N \times B$ [mm]	d_{rod} [mm]	$F_{rod\ y}$ [MPa]	$F_{rod\ u}$ [MPa]	$M_{max\ e}^{test}$ [kN.m]	$\frac{M_{max}^{test}}{M_{DG1}}$	$\frac{M_{max}^{test}}{M_{max}^{Method\ 1}}$	$\frac{M_{max}^{test}}{M_{max}^{Method\ 2}}$	$\frac{\beta^{test}}{\beta_{UC-Ex}^{Method}}$	$\frac{\beta^{test}}{\beta_{BYU}^{Method}}$
UCD	1	W14x370	203	0	2 x 30 x 30" (51 x 762 x 762)	25.4	400 MPa (58.1 ksi)	552 MPa (80 ksi)	588	2.12	1.73	0.90	2.05	1.67
UCD	2			445		25.4			882	1.96	2.59	1.07	1.50	1.97
UCD	3			667		25.4			925	1.75	2.72	1.03	1.32	1.98
								Mean	1.94	2.35	1.00	1.62	1.87	
								COV	0.09	0.23	0.09	0.23	0.09	
BYU	D2 ^b	W14x53	121	0	2.25 x 22 x 16" (57 x 559 x 406)	25.4	355 MPa (51.5 ksi)	621 MPa (90 ksi)	487	1.06	0.85	1.00	0.75	0.98
BYU	D3 ^b		324		25.4	559			1.22	0.73	0.84	0.76	1.24	
BYU	D4 ^b		343		25.4	369			1.57	0.96	0.79	1.34	0.96	
BYU	F2 ^b	W10x77	102	0	3 x 20 x 16" (76 x 508 x 406)	28.6	341 MPa (49.5 ksi)	527 MPa (76.5 ksi)	447	1.02	0.82	0.96	0.84	1.10
BYU	F3 ^b		305		28.6	539			1.23	0.71	0.82	0.88	1.21	
BYU	F4 ^b		330		28.6	372			1.65	0.99	0.76	1.85	1.07	
BYU	A1 ^b	W8x35		0	1 x 13 x 13" (25 x 330 x 330)	19	314 MPa (45.5 ksi)	560 MPa (81 ksi)	109	1.59	1.03	1.17	0.74	0.78
BYU	A2 ^b	W8x48			19	105			1.54	0.99	1.12	0.84	0.82	
BYU	B1	W8x35			19	175			2.56	1.14	0.77	1.42	0.80	
BYU	B2	W8x48			19	196			2.87	1.26	0.86	1.81	0.96	
											Mean	1.63	0.95	0.91
								COV	0.38	0.19	0.16	0.39	0.16	
KU	SL-100	HSS 8x8x3/8	76	511	1 x 11.8 x 11.8" (25 x 300 x 300)	12.7	303 MPa (44 ksi)	552 MPa (63.7 ksi)	135	1.17	1.95	0.99	-	-
KU	SL-200		178		12.7	206			1.76	2.25	0.98	-	-	

									Mean	1.46	2.10	0.98	-	-
									COV	0.28	0.10	0.00	-	-
									Mean (All)	1.67	1.38	0.94	1.24	1.19
									COV (All)	0.32	0.50	0.14	0.38	0.35

^a Test names refer to the reported labeling system in each respective publication (Richards et al. 2018; Hanks and Richards 2019; Cui et al. 2009).

^b Tests from BYU program for which separation of slab occurred (refer to Figure 4.10f).

^c Embedded depth d_{embed} is calculated based on the schematic in Figure 4.10b.

^d Reported values for breakout concrete compressive strength f_c' were used as follows: 28 MPa (4 ksi) for UCD and KU, 31 MPa (4.5 ksi) for BYU (D and F tests), and 17.2 MPa (2.5 ksi) for BYU (A and B tests).

^e M_{max}^{test} is the maximum moment value of both directions of loading (positive and negative) calculated at the top of foundation level

In summary, neither the DG1 approach, nor Method 1 provide satisfactory characterization of connection strength, motivating an approach that is able to characterize the strength of breakout connections with more generality, across a large range of configurations, and considering the effect of axial force as well. This is the topic of the next subsection.

Proposed Approach for Strength Characterization

As discussed in the preceding sections, introduction of the breakout concrete provides significant additional resistance with respect to the DG1 method (see Table 4.3). This additional resistance may be attributed to two mechanisms as determined by Grilli and Kanvinde (2017) in the context of Embedded Base Connections. These mechanisms are illustrated in Figures 4.10a-b: (1) the development of horizontal bearing stresses against the column flanges, and (2) the development of downward vertical stresses that resist uplift of the base plate. The breakout connections are similar in terms of the overall mechanics as compared to the connections studied by Grilli and Kanvinde (2017), with three differences:

1. The breakout connections include a fully designed exposed base plate connection under the breakout with anchor rods; this has two implications. First, the distribution of moments between the horizontal and vertical bearing mechanisms is affected by the fixity of the exposed base plate under the breakout. Second, the failure modes also include those associated with the exposed base plate connection, e.g., anchor rod yielding and failure.
2. The embedment of the breakout connections is usually lower (in the range of 200-400mm) as compared to the embedded connections.
3. The breakout connections include a cold joint (see Figures 4.2a-b) between the breakout concrete and the surrounding slab.

Based on these observations, the key assumption of the method is that the total applied base moment is resisted through a combination of horizontal and vertical bearing such that their contributions to the overall strength are additive, as follows:

$$M_{base} = M_{HB} + M_{VB} \quad (4.1)$$

This assumption is based on the visually observed failure modes in the various experiments, and implies the development of a plastic mechanism in which the following response modes are mobilized and considered to be acting “in parallel” such that their contributions at the limit state can be incorporated as shown in Figures 4.10c-d: (1) yielding of the anchor rods on the tension side accompanied by uplift of the base connection, (2) development of an upward stress block on the compression side of the base plate, similar to that assumed in DG1, (3) development of a downward stress block on the uplifting side of the plate, in the vertical direction; and (4) development of bearing stress blocks on both sides of the embedded column (top and bottom) in the horizontal direction. Figure 4.10c-d schematically illustrates the idealized internal forces and stresses associated with the transfer of moment and shear for both the vertical and horizontal resistance mechanisms.

Moment Resistance due to Vertical Bearing Stresses

Referring to Figure 4.10c, the bearing stress underneath the base plate (on the compression side of the connection) may be represented as a rectangular block with a value of f_{lower} denoting the lower side of the plate and the corresponding width Y_{lower} . This follows the approach of DG1 for exposed base plate connections. The bearing stress magnitude f_{lower} may be determined as $f_{lower} = \min(f_{grout}, f_{concrete})$, wherein f_{grout} is the crushing strength of the grout, whereas $f_{concrete}$ is determined to account for the confining effect of the footing size as follows:

$$f_{concrete} = 0.85 \times f'_c \times \sqrt{A_2/A_1} \leq 1.7 \times f'_c \quad (4.2)$$

Where f'_c is the compressive strength of concrete, A_1 is the plate bearing area, and A_2 is the effective concrete area (typically the plan area of the footing). In the case of breakout base connections, since both the concrete and the grout are confined, f_{lower} is usually governed by the value of $f_{concrete}$. The width of the bearing stress block Y_{lower} is an unknown; its calculation is discussed later. The tension side of the base plate has two downward forces acting on it (see Figure 4.10c). One is the anchor rod force (summation over all anchors) denoted T , whereas the other is the downward bearing stress on the upper surface of the base plate, termed f_{upper} . Of these, $T = 0.75 \times n_{rod} \times F_u^{rod} \times A_{rod}$ (assuming yielding is mobilized in the rods), where n_{rod} is the number of anchor rods in a line, F_u^{rod} is the ultimate strength of the anchor rod material and A_{rod} is the unthreaded area of the anchor rod. The downward bearing stress block on the upper surface of the base plate f_{upper} may be represented as a resultant downward force F_{upper} , which acts over an effective plate width Y_{upper} as shown in Figure 4.11c. The magnitude of F_{upper} depends on the strength required to fail (or break loose) the concrete above the plate on the tension side of the connection. As discussed previously, this can occur through two mechanisms. The first of these is breakout of the concrete in the breakout and surrounding region. This force may be calculated using the Concrete Capacity Design (CCD) method proposed by Fuch et al. (1995) as shown below:

$$F_{upper} = F_{breakout} = \frac{40}{9} \times \frac{1}{\sqrt{d_{cover}}} \times \sqrt{f'_c} \times A_{35} \quad (4.3)$$

In the above equation, d_{cover} is thickness of the material which must be ruptured for breakout, which is equal to d_{embed} for tension breakout (see Figure 4.10c for reference). The term A_{35} is the projected area of a 35-degree failure cone emanating from the edges of the effective plate width (i.e., the width Y_{upper} of the downward bearing stress block f_{upper}). The effective plate width is

taken as $0.3N$, following the work of Grilli and Kanvinde (2017); where N is the length of the base plate. The projected area A_{35} is shown in Figure 4.10e and is calculated using the equation below:

$$A_{35} = (B + 3 d_{embed}) \times (0.3 N + 1.5 d_{embed}) - (B \times 0.3 N) \quad (4.4)$$

Once these two quantities are determined, two equations may be written corresponding to the vertical force and moment equilibrium as shown below:

$$f_{lower} \times B \times Y_{lower} - P - T = F_{upper} \quad (4.5)$$

$$M_{VB} = F_{upper} \times \left(N - \frac{0.3N}{2} \right) + T \times (N - g) + P \times \frac{N}{2} - f_{lower} \times B \times \frac{Y_{lower}^2}{2} \quad (4.6)$$

Given the applied axial force P , the two equations may be used to solve for the two unknowns Y_{lower} , and M_{VB} . It is important to note that the above Equations (4.5) and (4.6) directly converge to DG1 method for exposed base connections in the case of the breakout/overtopping slab is absent (i.e., $F_{upper} = 0$). The moment M_{VB} calculated in this manner reflects the moment at the bottom end of the embedded column, i.e., at the elevation of the top of the base plate. The moment M_{VB} is calculated in this way for the 3 experiments at UC Davis, the 2 experiments at KU and 2 out of 10 experiments (i.e., Tests B1 and B2) at BYU that failed through the breakout mode.

The second mechanism, through which the concrete overlying the base plate may fail, involves separation of the slab at the cold joint (see Figure 4.10f). Referring to Table 4.3 and prior discussion, this was observed for 8 out of the 10 BYU tests. To estimate the vertical moment strength corresponding to this, DG1 approach is followed by ignoring the effect of bearing stress acting downwards on the upper surface of the base plate (i.e., $F_{upper} = 0$). The equilibrium equations (4.5) and (4.6) above are solved again, with $F_{upper} = 0$.

Moment Resistance due to Horizontal Bearing Stresses

Referring to Figure 4.10d, another portion of the applied moment and shear is resisted through the development of bearing stress blocks on both sides of the embedded column. The model adopted

herein is developed by Mattock and Gaafar (1982) for strength characterization of steel coupling beam embedded in concrete shear walls, and adapted by the AISC Seismic Provisions (AISC 341-16 2016) and the AISC Seismic Design Manual (AISC 2018) for estimation the strength of Embedded Column Base Connections. The model is based on the force couple developed from the top and bottom stress blocks where a parabolic distribution of bearing stresses is assumed for C_{bottom} , and C_{top} is estimated by a uniform stress equal to:

$$f_b^{top} = 4.04 \sqrt{f'_c} \left(\frac{b_w}{b_f} \right)^n \quad (4.7)$$

In the above equation for f_b^{top} (in MPa), the term b_w/b_f accounts for the effect of confinement, wherein b_w (in mm) is the width of the foundation, and b_f (jn mm) is width of the flange. The exponent n is calibrated based on experimental data to a value of $n = 0.24$. As per Mattock and Gaafar (1982), the bearing stress distribution at the bottom of the embedded section may be expressed as parabolic function with maximum stress of f'_c at a strain of $\varepsilon_b = 0.002$, such that $f_b^{bottom} = 1000 f'_c [\varepsilon_b - 250 \varepsilon_b^2]$. Referring to Figure 4.10d, the term k_2 defines the location of the resultant compressive force C_{bottom} such that:

$$k_2 = \frac{1 - 0.375 \left[\frac{d_{embed} - c}{c} \right]}{3 - 1.5 \left[\frac{d_{embed} - c}{c} \right]} \quad (4.8)$$

and,

$$C_{bottom} = 0.5 \frac{b_f}{c} \left(\frac{b_w}{b_f} \right)^n f'_c (d_{embed} - c)^2 \left[3 - 1.5 \left[\frac{d_{embed} - c}{c} \right] \right] \quad (4.9)$$

$$C_{top} = f_b^{top} \beta_1 c b_f \quad (4.10)$$

In the above, c (in mm) is the neutral axis depth and β_1 is the factor relating the depth of equivalent rectangular stress block to neutral axis depth, as shown in Figure 4.10d. The moment resistance due to horizontal stresses, M_{HB} may be obtained by simultaneously solving the force and moment

equilibrium equations based on the assumed stress distributions described above and shown in Figure 4.10d:

$$V - C_{top} + C_{bottom} = 0 \quad (4.11)$$

$$V \times z = C_{top} \times \left(d_{embed} - \frac{\beta_1 c}{2} + t_p + t_g \right) - C_{bottom} \times [k_2(d_{embed} - c) + t_p + t_g] \quad (4.12)$$

Such that, t_p (in mm) is the thickness of base plate and t_g (in mm) is the grout layer thickness (if any). Once V and c are calculated from equations (4.11) and (4.12),

$$M_{HB} = V \times z \quad (4.13)$$

The connection strength as per the proposed approach is then calculated such that:

$$M_{max}^{Method\ 2} = M_{VB} + M_{HB} \quad (4.14)$$

It should be mentioned that the above equation implicitly employs a moment-to-shear ratio as a given parameter for defining the problem (i.e., z the height of column inflection point), such that for a given base moment $M_{max}^{Method\ 2}$, the corresponding column/connection shear V is constrained to it. Thus, the reported values of moment capacity depend on this moment-to-shear ratio. The results from the moment capacity calculations for all the tests using the proposed model (denoted $M_{max}^{Method\ 2}$) are summarized in Table 4.3 and illustrated in Figures 4.9e-f; these are similar to Figures 4.9a-d, i.e., they plot the test-predicted ratios against the normalized embedment and axial load. Referring to this figure and Table 4.3, it is observed that:

- The model represents the moment capacity of the blockout connection when compared to tested specimens with good accuracy. When compared to the previously discussed approaches (DG1 and Method 1), the proposed model shows significantly reduced variability and bias with an average $M_{max}^{test}/M_{max}^{Method\ 2}$ of 0.94 and CoV of 0.14, across all the tests, suggesting that the model is able to capture the underlying physics of connection response. For the UCD and KU test series, where slab separation did not occur, average $M_{max}^{test}/M_{max}^{Method\ 2}$ values are 1.0 (CoV

= 0.09), and 0.98 (CoV = 0) respectively, indicating that for realistic situations, the method shows excellent performance.

- For the tests where the slab separation mode of failure occurred (i.e., tests from the BYU program as indicated in Table 4.3), the proposed approach (with adjusted vertical bearing capacity – as explained above) is able to capture the physics and fundamental behavior of the breakout connection with a fair accuracy, as indicated by the average test-predicted ratio of 0.91, with a CoV of 0.16, which is acceptable, although marginally slightly worse than for the other tests. Even if such failure is unlikely in realistic conditions (where a larger slab is present), the agreement between experiments and model further confirm the efficacy of the model in terms of representing the overall physics of connection response.
- Referring to Figure 4.9e, for cases where d_{embed}/d_{col} is greater than 1.5, the method yields slightly unconservative results (with an average $M_{max}^{test}/M_{max}^{Method 2}$ of 0.85). These details approach “deeply embedded” connections, similar to those tested by Grilli and Kanvinde (2017). As noted in that study, for these deeper embedments, a full mechanism is often not developed before breakout failure, such that the component strengths may not be considered additive.

4.6 MODELS FOR STIFFNESS CHARACTERIZATION

While the major focus of this study is to develop a strength model, the rotational stiffness characterization of such connections is also important, especially from the standpoint of structural performance assessment where rotational stiffness of column base connections plays a critical role (Zareian and Kanvinde 2013, Falborski et al. 2020). Although this study does not develop a new model for rotational stiffness characterization, it evaluates two existing models against all the available test data summarized in Table 4.3. The first is an approach presented by Kanvinde et al. (2012) for exposed base plates referred to as UC-Exposed Method, which does not consider the effect of the blockout or overtopping slab, whereas the second approach is by Richards et al. (2018), referred to as BYU Method, which considers the effect of the blockout and overtopping slab. Both these methods are now briefly summarized and applied to the test data outlined previously in Table 4.3.

The UC-Exposed method leverages internal force distributions from AISC *Design Guide 1* to determine the rotational stiffness of exposed base connection. The method considers deformations from the base plate, anchors and concrete foundation (as shown in Figure 4.11a) to calculate the overall connection rotation under a given moment. Although the method is specifically developed for exposed column base connections (without the blockout), it is discussed in this study to examine its suitability for use in predicting the stiffness of blockout connections. The BYU method for calculating the rotational stiffness of blockout connection estimates the rotational stiffness of the embedded base plate, and then represents it as an equivalent spring at the end of a beam in an elastic foundation, which represents the embedded portion of the column. Table 4.3 summarizes the ratio between the rotational stiffness calculated for each of the tested specimens β^{test} from the considered programs and the predicted rotational stiffness using the two methods outlined above

(i.e., $\beta_{UC-Exposed}^{Method}$ and β_{BYU}^{Method}). A graphical representation of the test-predicted ratio for the rotational stiffness against the column embedment is also shown in Figures 4.11c-d.

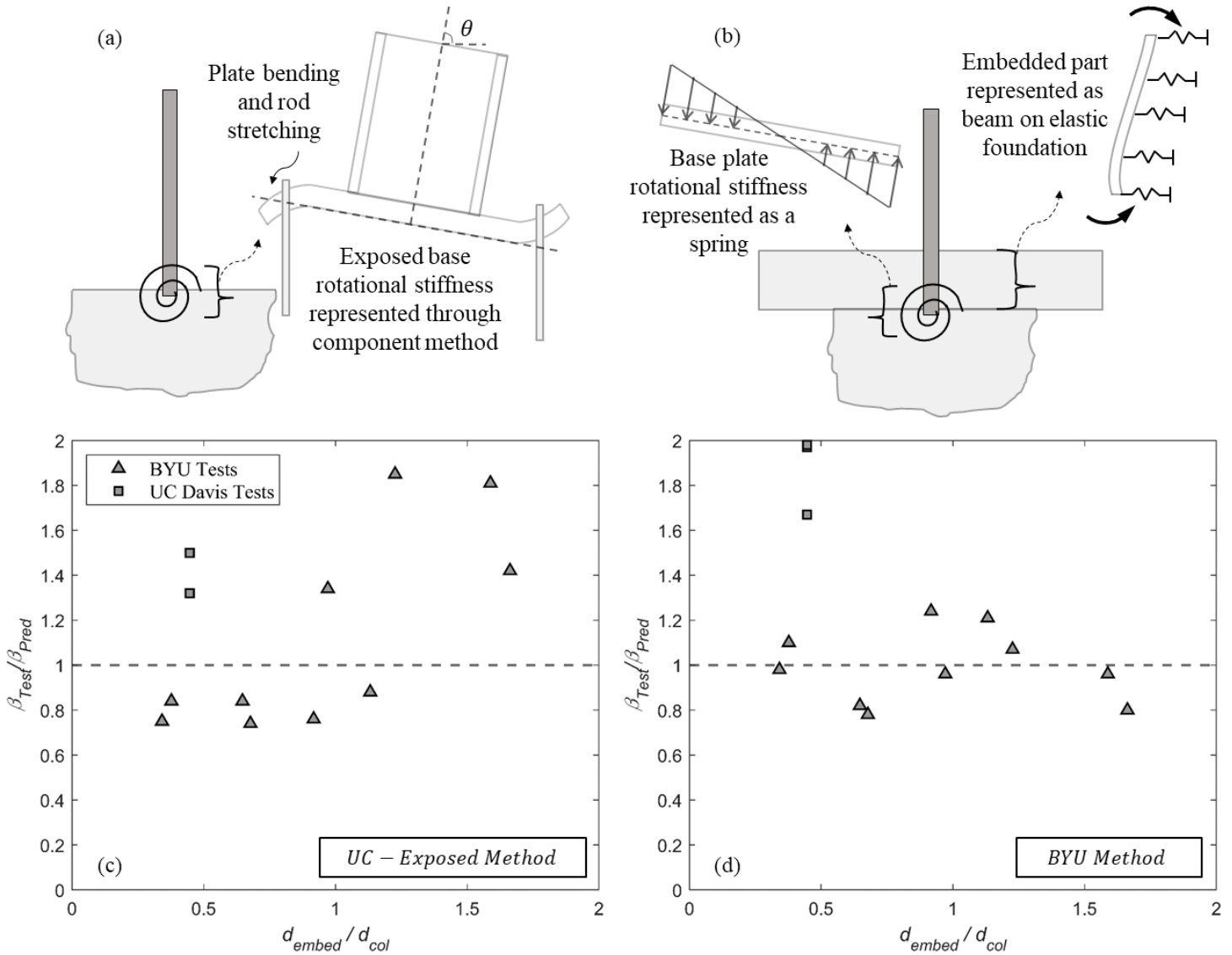


Figure 4.11 – Key elements of stiffness method proposed by (a) UC Method - Kanvinde et al. (2012) and (b) BYU Method - Richards et al. (2018); (c-d) Test-predicted ratios for rotational stiffness from both methods.

Referring to Table 4.3, the average test-predicted ratio $\beta^{test}/\beta_{UC-Exposed}^{Method}$ is 1.24 with a CoV 0.38.

Whereas average test-predicted ratio $\beta^{test}/\beta_{BYU}^{Method}$ is 1.19 with a CoV 0.35. Referring to these values and Figures 4.11c-d, the following observations may be made:

- Both models provide reasonable estimates of the rotational stiffness, with some degree of uncertainty. While these errors (in the range of 19 to 25%) are not ideal, they may be acceptable in the context of structural performance assessment where the current practice is to simulate these connections as either fixed or pinned (i.e., a stiffness of zero or infinity). In fact, research by Zareian and Kanvinde (2013), and more recently by Falborski and Kanvinde (2022) suggests that some variation in base flexibility, in the neighborhood of the true flexibility does not significantly affect structural response.
- The efficacy of the methods does not appear to depend on the embedment (as shown in Figures 4.11c-d), or on axial load.

Based on the above two observations, the existing methods (particularly the BYU approach) are appropriate for estimating base stiffness in the current performance assessment content.

4.7 SUMMARY AND CONCLUSIONS

This study presents findings from three tests of breakout column base connections representative of construction practice in the United States. These findings synthesized with findings from similar experiments from two other test programs to evaluate current strength and stiffness estimation approaches for these connections, and to propose a new strength characterization method. The experiments reveal that the current strength characterization methods (including the AISC DG1 approach and another approach proposed by BYU) are somewhat inaccurate; the former because it does not consider the effect of the breakout concrete, and the latter because it is based on test

data that does not include axial load. To address this, a new method is proposed for strength estimation. This method assumes the formation of a mechanism within the connection, such that the total moment and shear is resisted by a combination of horizontal stresses in the footing that resist rotation of the column (similar to a deeply embedded connection or a coupling beam) and vertical stresses and anchor rod forces that resist rotation of the base plate (similar to an exposed base plate connection). The method predicts the strength of specimens from 15 specimens (from three test programs) with good accuracy, and shows minimal dependence on test parameters, suggesting that it represents the physics of response with fidelity. The strength model may be used in two contexts:

1. To reduce conservatism in the design of exposed base plate connections, which is usually conducted using AISC DG1 type approaches, anticipating an increase in strength due to the installation of the blockout. In this context, it is important to note that the strength model predicts the maximum strength of the connection as a whole, whereas the aim of conventional design approaches is to preclude yield in any of the members. However, the test data from this test program as well as others (e.g. Richards et al. 2018; Hanks and Richards 2019) indicate that the connection yield moment (which typically corresponds to the yielding of the first component, e.g., the anchors) is roughly 80% of the ultimate strength, with modest variability. This factor may be used in conjunction with the proposed method to design the connection.
2. For seismic performance assessment. As discussed previously, exposed base plate connections are used in both lateral load resisting frames as well as gravity frames. Cumulatively, their resistance can significantly affect structural performance, particularly collapse resistance. Thus, simulating the nonlinear response of these connections in pushover analysis or Nonlinear Response History Analysis in the context of FEMA P695 (Applied Technology Council 2009)

is important. Typically, these connections are represented as rotational springs with calibrated hysteretic properties (e.g., Torres-Rodas et al. 2018). Strength estimates for breakout connections calculated from the proposed method may be used within such models.

The study also evaluates rotational stiffness models, and concludes that the model developed at BYU (Richards et al., 2018) provide good estimates of base flexibility, and will possibly offer vast improvements in assessment of structural performance (including internal force distributions and seismic performance) as compared to assumptions of pinned or fixed bases. In closing, it is important to note some limitations of the study and the strength model proposed herein. First, the test configurations sampled only a limited set of parameters. While these parameters are fairly realistic, extrapolation of test results to highly dissimilar configurations may be prone to error. For example, the strength model begins to lose accuracy for embedments that are significantly deeper than common floor slabs. Similarly, the plastic mechanism used in the model implicitly presumes some ductility in various load resisting mechanisms (e.g., anchors and concrete crushing); this too may be compromised for different details or material grades. Addressing these issues will require additional study.

CHAPTER 5

SEISMIC PERFORMANCE OF EMBEDDED COLUMN BASE CONNECTIONS WITH ATTACHED REINFORCEMENT: TESTS AND STRENGTH MODELS

5.1 INTRODUCTION

Embedded Column Base (ECB) connections in seismically designed Steel Moment Frames are commonly used to connect the steel columns to concrete foundations for mid- to high-rise buildings. Unlike low-rise buildings for which Exposed-Type Base Plate Connections (where a base plate is welded to the column with attached anchor rods to the foundation – See Figure 5.1a) are suitable, in mid- to high-rise frames, the embedment is required to resist large base moments and provide fixity through bearing of column flanges against concrete, as shown in Figure 5.1b. The column is usually welded to a base plate resting in a thin concrete layer for leveling purposes. Face bearing plates are often employed on the top of concrete surface to transfer axial compression and facilitate the formation of a shear panel as prescribed for similar connections (e.g., Composite Beam-Column Connections or Steel Coupling Beams in Concrete Shear Walls).

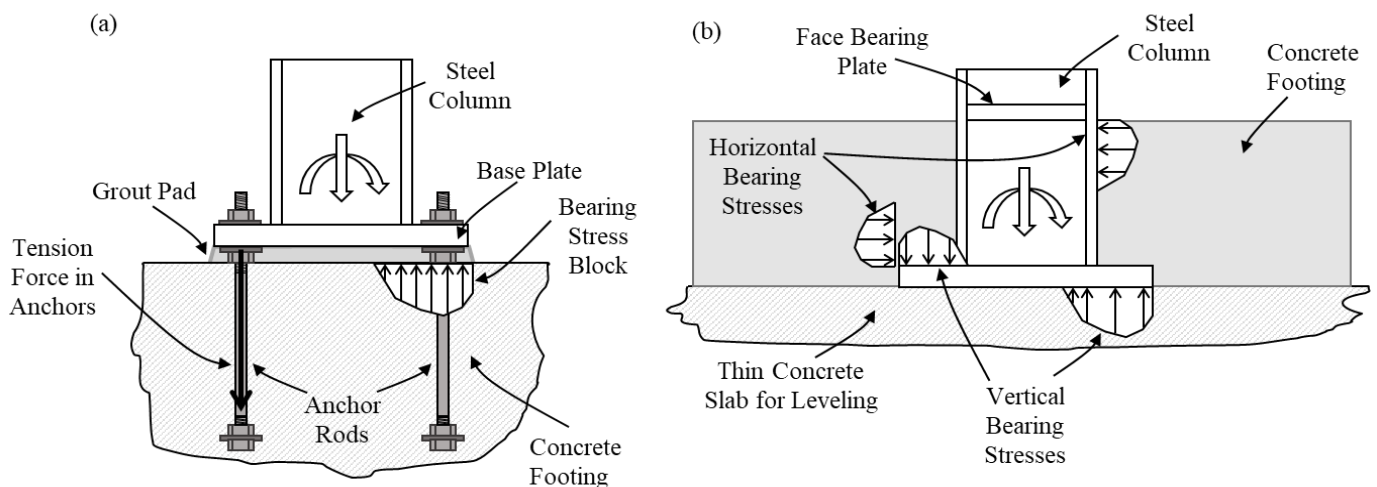


Figure 5.1 – Column base connections and force transfer mechanisms: (a) exposed type; (b) embedded type (ECB Connection)

Significant research has been conducted on the Exposed-type Base Connection in the last two decades, including large-scale experimental testing (Astaneh et al. 1992; Fahmy et al. 1999; Gomez et al. 2010; Kanvinde et al. 2015; Trautner et al. 2017; and Hassan et al. 2022), analytical (Wald et al. 2000), and computational simulations for both component (Inamasu et al. 2020; Hassan et al. 2022), and frame (Falborski et al. 2020), leading to the development of design considerations (AISC Design Guide One – Fisher and Kloiber 2006; AISC 341-16; SEAOC 2015 Seismic Design Manual SSDM). In contrast, research on ECB connections is sparse, with no experimentally-validated guidelines or methods for design, and only limited finite-element parametric studies (Pertold et al. 2000a, b). Current design practice in the United States, rely on adaptations of methods developed for other similar components such as Composite Beam-Column Connections (ASCE 1994) and Steel Coupling Beams Embedded in Concrete Shear Walls (Marcakis and Mitchell 1980; Mattock and Gaafar 1982; Harris et al. 1993; Shahrooz et al. 1993). The AISC Seismic Provisions (AISC 341-16) and the AISC Seismic Design Manual (AISC 2012) suggest the use of the method developed by Mattock and Gaafar (1982) for strength characterization and design of ECB connections. These ad hoc adaptations (in the absence of experimental data) are susceptible to inaccuracies owing to the disregard of behavioral aspects specific to the ECB connections including: (1) concrete confinement effect which is limited around a thin shear wall or a composite beam-column connection; (2) the presence of a base plate welded to the column section; (3) the presence of axial load which is higher in case of columns; as well as (4) other differences in reinforcing bar patterns. Other studies related to ECB connections (Cui et al. 2009; Richards et al. 2018; Hanks and Richards 2019) examined the effect of an overtopping slab-on-grade on top of an Exposed-type column base connection. This type of connection (known as blackout column base connection) is distinct from ECB connection in fundamental behavioral

characteristics wherein the concrete embedment is incidental (for construction purposes) and the primary mode of moment resistance is that of the base uplift (through anchor rod tension and vertical bearing on the overlying slab). As a consequence, they are not readily applicable to ECB connections.

Previous experimental studies (Grilli et al. 2017), on a similar project on ECB connections representative of the United States construction practice (similar to that shown in Figure 5.1b) serve as the only test data available on the seismic performance of such connections. These five specimens featured wide flange steel cantilever columns embedded within a concrete footing and subjected to cyclic lateral deformation history under a constant axial force (compression and tension). The main variables were the column size, embedment depth, and axial load. The specimens were designed with minimal longitudinal and transverse reinforcement such that observed failure modes and strengths were associated (to the possible extent), with the concrete only.

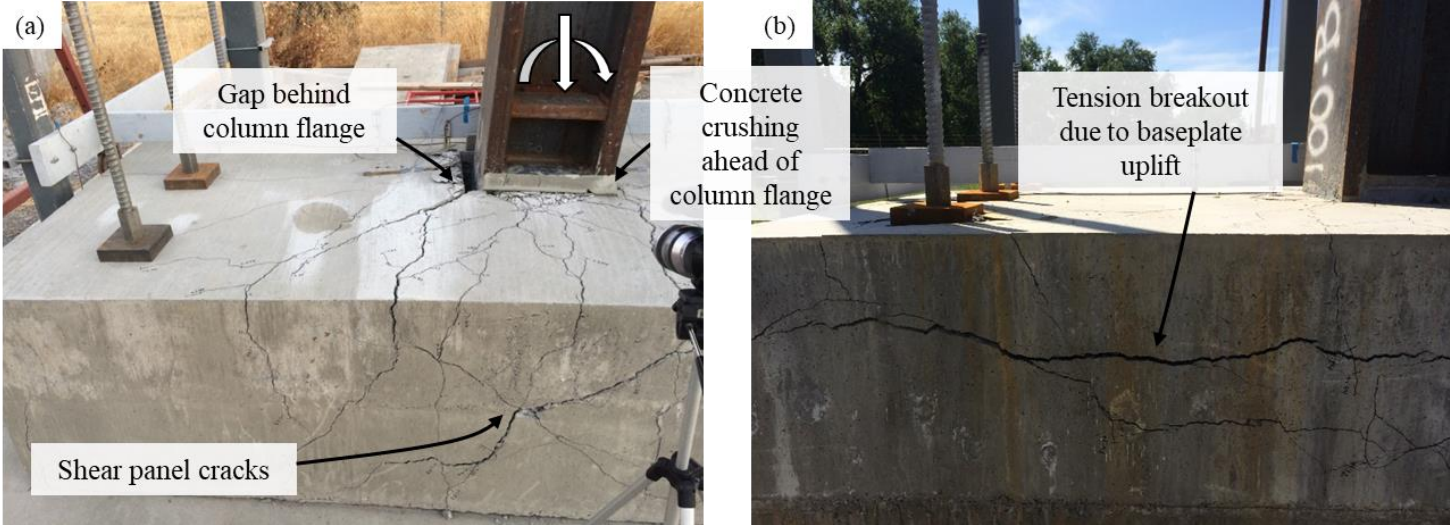


Figure 5.2 – Experimental program (Grilli et al. 2017): damage patterns suggesting modes of failure/deformations governed by (a) horizontal bearing, and (b) vertical bearing

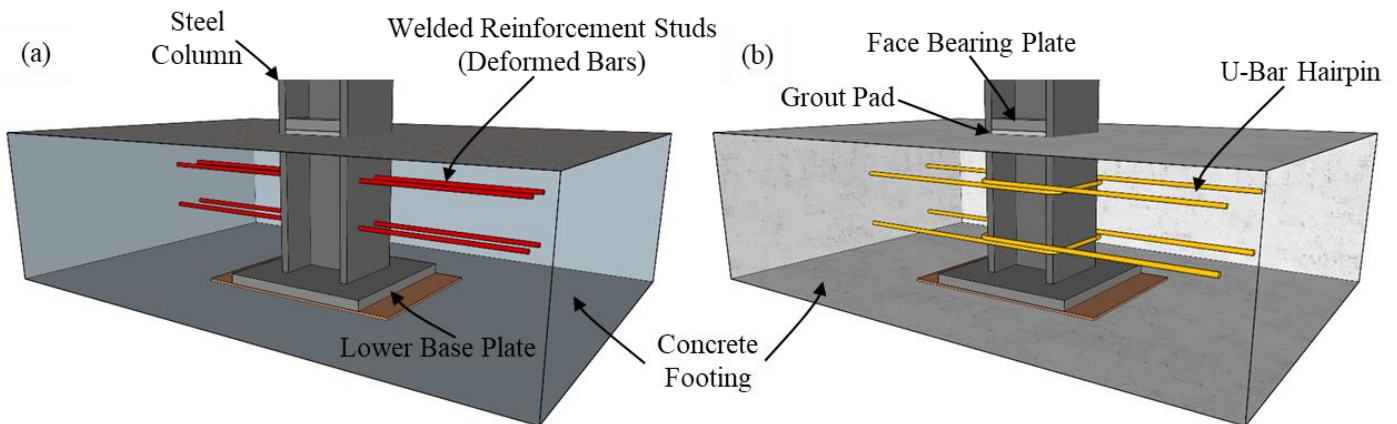
The results from this experimental program (Grilli et al. 2017 and Grilli and Kanvinde 2017), provided insights into the fundamental physics of the ECB connections, including failure modes which informed the development of strength models suitable for the design of ECB connections. The study postulated internal stress distributions and mechanisms for resisting applied moments and axial loads in ECB connections. Figure 5.1b shows two primary mechanisms of moment resistance, as outlined by Grilli and Kanvinde (2017): (1) horizontal bearing stresses against the column flanges along with a complementary shear panel zone (similar to that observed in composite steel beam column connections: ASCE 1994; Sheikh et al. 1989; Cordova and Deierlein 2005); and (2) vertical bearing stresses resisting uplift of the base plate. While all the tested specimens suggested that the strength of such connections is determined by the ultimate horizontal bearing stress of the concrete ahead of the column flange (which is consistent with the current design standards i.e., AISC 341-16 and the AISC Seismic Design Manual), other failure modes might as well be active as indicated by Grilli and Kanvinde (2017). This includes: (1) Tension breakout of concrete due to the uplift of the base plate on the tension side of connection, and (2) Shear cracking or failure in the web panel in the concrete footing. Figures 5.2a-b show posttest photographs illustrating the failure modes observed from two specimens in the experimental program (Grilli et al. 2017) with different embedment depths; similar response was observed for other tests.

Notwithstanding the valuable contribution from the experiments to provide direct assessment to the response of ECB connections and support a strength characterization method, the study is limited by a relatively small data set and the examination of a single detail. The specimens featured only one generic detail (Figure 5.1b) with the absence of major reinforcement. Other detail

(commonly used in practice) may feature additional reinforcement (welded/attached to the column) which have the potential to affect the failure modes of horizontal bearing and vertical bearing (specifically the tension-breakout), as well as improve the energy dissipation characteristics of the connection.

Motivated by these issues, this study presents a series of five full-scale experiments of ECB connections with attached reinforcement bars along with a proposed method for strength characterization of ECB connections. The testing program demonstrates ECB connection details that are commonly used by the construction practice in the United States. Figure 5.3 schematically illustrates the main features for the tested details developed in consultation with an oversight committee of practitioners and fabricators (see “Acknowledgments”). These specimens feature a similar detail to the one examined by Grilli et al. (2017), with the exception of reinforcement fixtures attached to the embedded column flanges with varying configurations, size, confinement effect. Two main techniques for reinforcement attachment are examined, namely, Welded reinforcement bars to the column flange (deformed weldable bars – commonly used in practice); and U-bar hairpin reinforcement bars (recommended by AISC Seismic Provisions 341-16 for steel coupling beams) anchored by the embedded portion of the column and alternating to engage both column flanges (See Figure 5.3b). The main objectives of this study are to: (1) Query the effect of additional reinforcement on the seismic performance of ECB connections, and (2) critically examine the assumptions commonly used to design ECB connections along with the available strength models/approaches while providing recommendations for improved design of ECB connections.

The next section begins by briefly providing relevant background on prevalent approaches/models for estimating the strength of ECB connections, followed by a description of the experimental program and evaluation of the strength characterization approaches (along with the new strength estimation method) against test data.



**Main footing reinforcement is not shown for clarity*

Figure 5.3 – Details under investigation for the experimental program: (a) Welded Reinforcement Stud, and (b) U-bar Hairpin

5.2 CURRENT PRACTICE AND AVAILABLE STRENGTH MODELS

As previously discussed, the current practice (in the United States) and design provisions (AISC Seismic Design Manual) adapt the flexural and shear resistance of a steel coupling beam embedded in a concrete shear wall for the seismic design of ECB connections. Figure 5.4a illustrates the assumptions adopted by this approach (referred to here after as AISC SDM Method). Referring to this figure, the applied moment and shear are resisted through the development of bearing stress blocks on both sides of the embedded column flanges. Equation (5.1) below provides a closed form solution for the moment capacity, obtained by solving for the force and moment equilibrium based on the assumed stress blocks. This equation is based on the work done by Mattock and

Gaafar for steel coupling beams embedded in concrete shear walls and subjected to reversed cyclic loading (1982).

$$M_{base}^{AISC\ SDM} = 1.54 \sqrt{f'_c} \left(\frac{b_w}{b_f}\right)^{0.66} \beta_1 \times b_f \times L_e \times \frac{g}{2} \times \left(\frac{0.58 - 0.22 \times \beta_1}{0.88 + \frac{g}{2 \times L_e}}\right) \quad (5.1)$$

Where f'_c is the specified compressive strength of concrete (in ksi); b_w (in inches) is the width concrete foundation perpendicular to the loading direction (b_w is the thickness of wall pier in the original equation); b_f (in inches) is the width of the embedded section (column) flange; L_e (in inches) is the embedment depth of the steel column measured from the face of the foundation (as shown in Figure 5.4a); $g/2$ (in inches) is the distance from the top surface of the foundation to the inflection point of the column; and β_1 is the factor relating the depth of equivalent rectangular stress block to the neutral axis depth c as defined in ACI 318-19 (ACI 2019). The term $\left(\frac{b_w}{b_f}\right)^{0.66}$ accounts for the effect of concrete confinement and spread of compressive stress ahead of the column flange such that the value 0.66 is calibrated to match experimental results by Mattock and Gaafar (1982). Referring to Figure 5.2a, the values c/L_e and k_2 are assumed to be 0.66 and 0.36, respectively as reported by Mattock and Gaafar (1982) for design purposes. From the perspective of ECB connections, the following aspects of this method are problematic: (1) it assumes that the entire moment is carried solely by the bearing against the flanges (i.e., it does not consider the effect of the embedded base plate and its contribution to moment resistance), (2) the term reflecting the effect of concrete confinement is unbounded which has the potential of overestimating the bearing stresses in concrete foundations (which are significantly wider than the embedded steel section as compared to shear walls), and (3) several factors relating to the mechanics of the method (for example, the ratio of the neutral axis location to the depth of embedment c/L_e and consequently the value k_2 – see Figure 5.4a) have been particularized for

simplification based on geometrical aspects/constraints which are not necessarily analogous for the case of ECB connections.

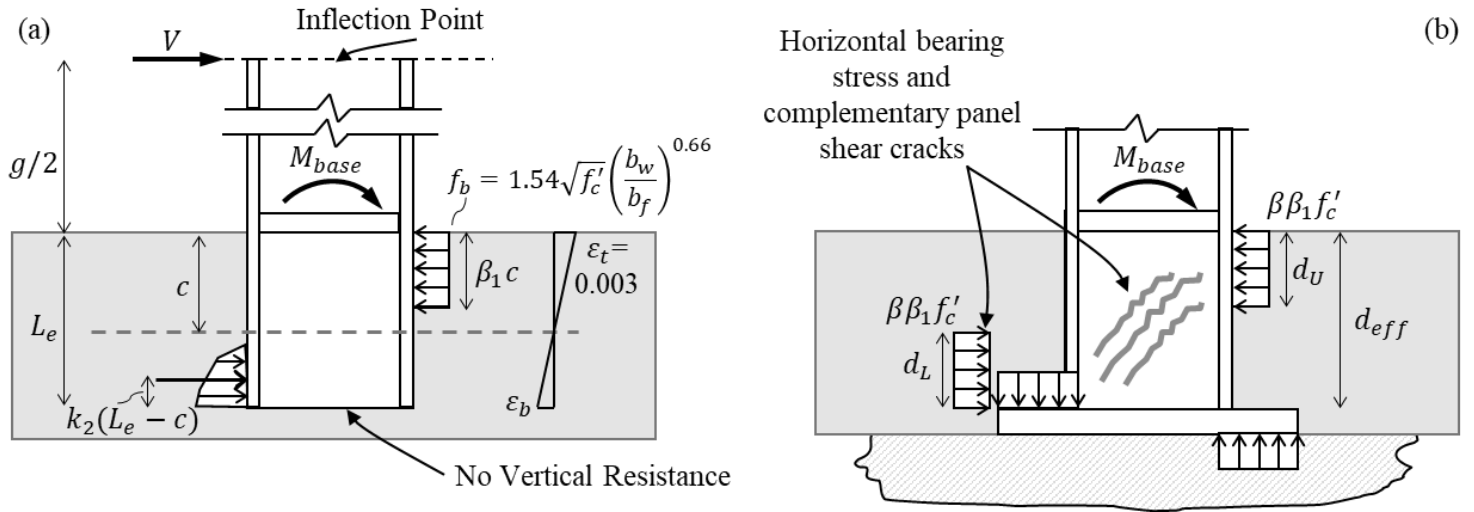


Figure 5.4 – Strength model assumptions from (a) the AISC Seismic Design Manual approach (AISC 2018), and (b) Grilli and Kanvinde (2017) model

Grilli and Kanvinde (2017) developed a strength model based on physical observations of connection damage and failure from test data and simulations. The model provides a fundamental understanding of the internal force transfer in embedded base connections (schematically illustrated in Figure 5.4b). Referring to Figure 5.4b, the key assumption of the method is that the total applied base moment (denoted M_{base}) is resisted by two mechanisms: (1) horizontal bearing stresses against the column flange, accompanied by the formation of a shear panel action – this portion of the moment is denoted M_{HB} , and (2) vertical bearing stresses against the base plate that resist its rotation – this moment is denoted M_{VB} . Thus,

$$M_{base} = M_{HB} + M_{VB} \quad (5.2)$$

wherein M_{HB} denotes the moment carried by horizontal bearing stresses, and M_{VB} denotes the moment carried by vertical bearing stresses. The distribution of moments between these two

mechanisms is determined through a semi-empirical equation that is inspired by a beams-on-elastic foundations solution (Hetenyi 1946). In practical terms, the moments carried by each of these mechanisms is determined from the following equations:

$$M_{VB} = \alpha \times M_{base} \quad (5.3)$$

and,

$$M_{HB} = (1 - \alpha) \times M_{base} \quad (5.4)$$

The term α , which determines the split is calculated as:

$$\alpha = 1 - (d_{embed}/d_{ref}) \geq 0 \quad (5.5)$$

in which,

$$d_{ref} = \frac{C}{\rho}, \text{ where } \rho = \left(\frac{E_{concrete}}{4 \times E_{steel} \times I_{column}} \right)^{\frac{1}{4}} \quad (5.6)$$

The term α represents the fraction of the moment resisted by vertical bearing on the embedded section such that, α approaches 0 (i.e., all the moment carried by horizontal stresses) as d_{embed} approaches ∞ . The terms corresponding to the elastic modulus of steel E_{steel} , the second moment of inertia of the steel column I_{column} and the elastic modulus of concrete $E_{concrete}$ (which is assumed to indirectly represent the effective stiffness of the concrete per unit length of the column – analogous to a subgrade modulus) set the scale over which the horizontal stresses attenuate, based on an interpretation of the Hetenyi solution for beams on elastic foundations (1946). The basis of the proposed equations and the underlying physics is detailed in Grilli and Kanvinde (2017). The term C is a calibration constant (equal to 1.77), and in the original work by Grilli and Kanvinde (2017), is particularized to the case of a column base plate embedded in concrete, without any attachments (i.e., welded reinforcement, anchor rods, etc.). This constant implicitly

accounts for the rotational fixity of the base plate embedded within the concrete. The flexural resistance of the connection is then be calculated as follows:

$$M_{base}^{Grilli} = \frac{1}{1-\alpha} \times \left(\beta \beta_1 f'_c b_j \times \left\{ d_L d_{eff} - \frac{d_L^2 + d_U^2}{2} \right\} \right) \quad (5.7)$$

Where β is assumed to be constant and equal to 2 to account for the confinement effect (while keeping it bounded – compared to the term proposed by the SDM Method). b_j (in inches) is equal to $(b_f + B)/2$ and accounts for the concrete compression field forming outside of the panel zone. The effective embedment depth d_{eff} is defined as the minimum of d_{embed} and d_{ref} . Referring to Figure 5.4b, the depths of the horizontal concrete stress blocks (lower and upper, namely, d_L and d_U , respectively) are determined by solving equilibrium equations (for moment and shear), where the maximum resistance proposed by Grilli and Kanvinde (2017) occurs when $d_L + d_U$ reaches 60% of the effective embedment depth. This assumption is consistent with the approach adopted for composite connections design by the ASCE guidelines for composite connections (ASCE 1994). The above equation assumes that no limit states are engaged either in the embedded base plate or the vertical stresses restraining it until the peak moment is reached (i.e., the horizontal bearing failure limits state occurs before vertical bearing failure).

Both models do not account for the reinforcement attached to the column flanges (commonly used in practice), either through ignoring its contribution (as per the AISC SDM Model – where the reinforcement is only prescribed for force transfer) or by not accounting for its presence in the mechanical model through the equilibrium equations (as per Grilli and Kanvinde 2017). This is problematic as the presence of additional reinforcement (attached to the column flange) greatly influences the strength and stiffness of the connection, which could possibly affect the failure modes/limit states observed. In the next section, a description of the experimental program

featuring ECB connections with reinforcement attachments is presented. The results from the tested specimens are then used to provide direct comparisons with the available strength models while providing recommendations for an improved model for strength characterization and design of ECB connections.

5.3 EXPERIMENTAL PROGRAM

This section outlines the experimental test setup, test matrix and loading protocol. Figures 5.5 and 5.6 illustrate important features of the test setup and specimens detailing, respectively, whereas Table 5.1 summarizes the test matrix along with key experimental results.

Test Setup

Figure 5.5 shows the test setup, including the specimen. Specific aspects of the test setup and specimens are outlined below:

- 1- All specimens featured wide flange cantilever columns. The height (9.5 ft above the surface of concrete) of load application was assumed to be the inflection point in a first story column. The load was applied through a servo-controlled hydraulic actuator attached at the top. The columns were all ASTM A992 Grade 50 (345 MPa) and were designed to remain elastic throughout the test.
- 2- For axial compression application, two hollow hydraulic jacks were positioned at the ends of a crossbeam (shown in Figure 5.5) and connected to tension rods which were attached to a freely rotating clevis, such that the axial forces did not introduce ($P - \Delta$) moments and acted as follower forces.
- 3- The columns were placed on a plywood sheet (with 1 in. thickness and same plan dimensions of the lower base plate) to provide a more realistic supporting condition such

that columns are usually set/supported on a thin unreinforced slab for erection purposes (rather than directly on bare soil).

- 4- Plates were provided at the top (stiffener-like face bearing plates) and the bottom (base plates) of the embedment region (See Figure 5.6), consistent with the design practice. The bottom plate is similar to the ones used in exposed column base connections to allow the column to be supported stably during concrete casting, while also providing resistance to uplift. The top plates were added to provide resistance to compression by distributing the axial force from the column to the foundation in direct bearing.
- 5- The pedestals were fastened to the laboratory floor with 6 pre-tensioned threaded anchors (3 on each side) designed to have minimal effect on the stress distribution in the vicinity of the column.

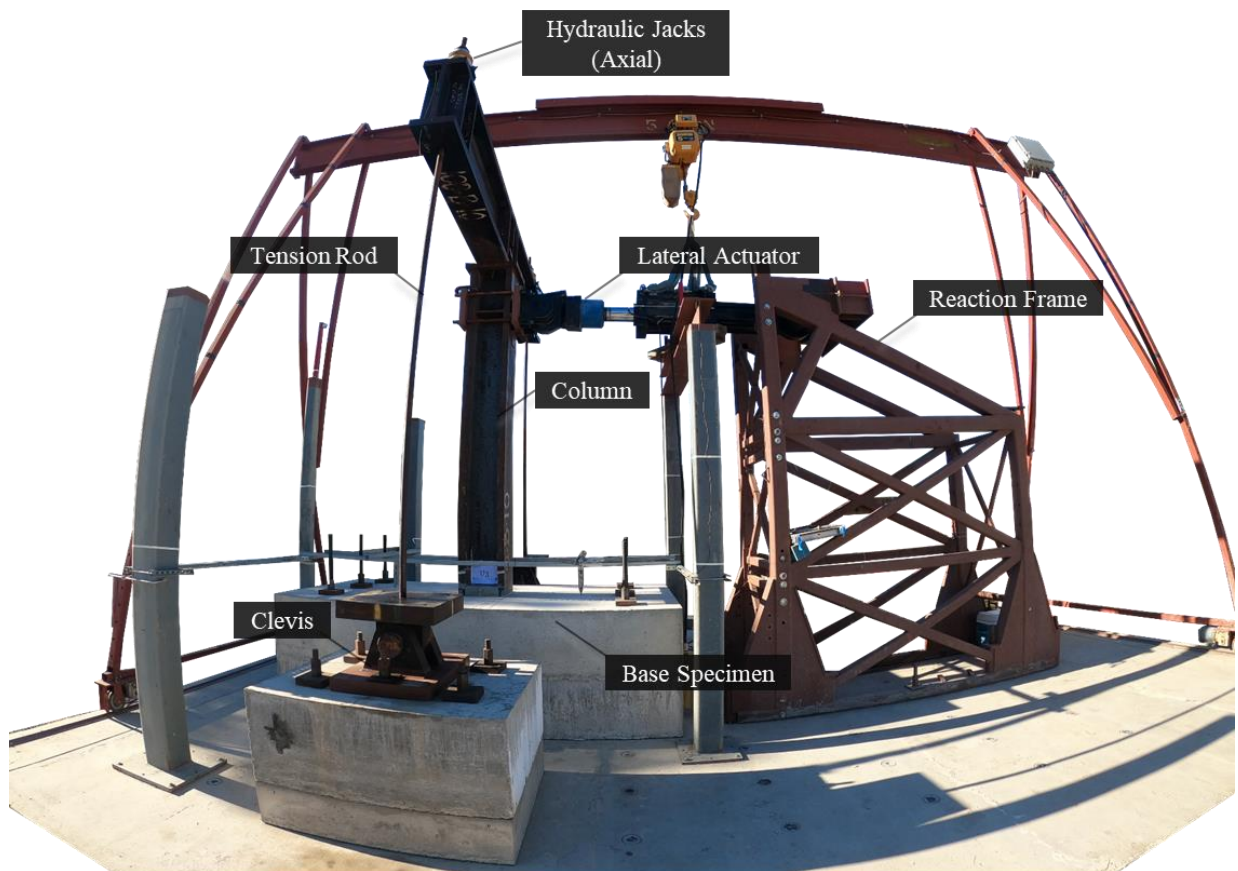


Figure 5.5 – Wide angle view of test setup

Table 5.1 – Tests Matrix and Key Results

Test ^a	Axial Load P [kip]	Column Size b_f [in.]	Embed. Depth d_{embed} [in.]	z^b [in.]	Attached Reinforcement Grade	Rft. Configuration	M_{max+}^{test} [k.ft]	M_{max-}^{test} [k.ft]	$\frac{M_{max}^{test\ c}}{M_{max}^{AISC\ SDM}}$	$\frac{M_{max}^{test}}{M_{max}^{Grilli}}$	$\frac{M_{max}^{test}}{M_{max}^{Grilli-HB}}$	$\frac{M_{max}^{test}}{M_{max}^{Model}}$		
1	100	W14 x 370 (16.5)	20	113	Weldable Rebar Studs ASTM A706 Grade 60	(4) #4 (0.5" diameter)	994	1002	0.77	0.54	0.95	0.86		
2	100			113			U-bar Hairpin ASTM A615 Grade 60	(8) #6 (0.75" diameter)	1055	904	0.81	0.57	1.02	0.92
3	100			113					1334	1109	1.03	0.70	1.23	1.15
4	100			113	(4) #4 (0.5" diameter) + Vertical Reinforcement (STR)	1196			908	0.92	0.65	1.16	0.99	
5	100	W18 x 311 (12)		113		1220			820	1.05	0.72	1.37	1.09	
									Mean	0.92	0.63	1.15	1.00	
									CoV	0.14	0.13	0.15	0.12	
1G	100	W14 x 370 (16.5)			112			1902	1927	1.45	1.07	1.81	1.33	
2G	100	W18 x 311 (12)			112			1714	1599	1.44	1.05	1.87	1.23	
3G	-	W14 x 370 (16.5)		30	122			2759	2540	0.97	1.01	1.19	1.00	
4G	100		122			3042	2664	1.07	1.11	1.31	1.09			
5G	150 (T)		122			2803	2555	0.99	1.03	1.21	1.05			
									Mean	1.19	1.05	1.48	1.14	
									CoV	0.20	0.04	0.23	0.12	
								Mean (All)	1.07	0.84	1.33	1.09		
								CoV (All)	0.20	0.27	0.21	0.11		

^aNew tests are labeled from 1-5, whereas tests from Grilli et al. (2017) are labeled from 1G-5G.

^bMoment-to-shear ratio (i.e., distance from point of load application to top of concrete) – See Figure 5.10c

^c M_{max}^{test} is the maximum moment value of both directions of loading (positive and negative).

Test Matrix

Referring to Table 5.1, the following test parameters were varied: (1) the method of reinforcement attachment (welded versus anchored), (2) the reinforcement area (the total area added – with varying rebar sizes), (3) the column size, and (4) the addition of supplemental vertical reinforcement (stirrups) along the length of the concrete pedestal. Parametric values of the test matrix were selected considering similarity to construction practice and limitations of the test setup; specifically:

- 1- The selected columns were sized to ensure failure in the connection (i.e., remain elastic). For a real concrete pedestal or grade beam, the embedded column (hypothetical column) is smaller as compared to the ones used in this study. In turn, the embedded depths are comparable to those commonly used for moment frames.
- 2- Compressive axial loads were selected to be almost 10-20% of the axial yield capacity of such hypothetical column that would have an embedment depth similar to the one employed in the study.
- 3- The footing design was similar to the specimens tested by Grilli et al. (2017) in terms of concrete dimensions and nominal reinforcement. The footings were provided with minimal longitudinal and transverse reinforcement such that the observed failure modes and strengths were associated (to the extent possible), with concrete only. The column embedment depth d_{embed} , footing dimensions and reinforcement are illustrated in Figure 5.6.
- 4- Referring to Figure 5.6, For each test (out of 5 total specimens), different additional reinforcement attachments details were installed. All tests featured two rows of attached reinforcement bars (close to the face of the concrete footing, and near the end of the

embedment length). The attached reinforcement was fully developed in tension by providing an adequate tension development length as per ACI 318-19 (ACI 2019). The location of the attached reinforcement were selected in accordance with the AISC 341-16 and AISC SDM provisions (AISC 2016; AISC 2018) such that: (a) The first region (top row) of the attached reinforcement coincided with the longitudinal footing reinforcing bars closest to the face of the foundation; and (b) the second region (bottom row) is placed a distance no less than $d_{col}/2$ from the termination of the embedded length.

- 5- Test #1 presented the method of attachment through arc welding of 1/2 in. diameter weldable stud rebars (ASTM A706 Grade 60) – see Figure 5.3a, whereas Test #2 featured #4 (1/2 in. diameter) U-bar hairpin reinforcement (ASTM A615 Grade 60) anchored through the column embedment (alternating in each row to engage the flanges in both loading directions). Test #3 featured the case of bundled U-bar hairpin reinforcement with different diameter as a total of 4 #6 U-bar hairpins per row (3/4 in. diameter). For Tests #4 and 5 a series of supplemental vertical reinforcement/stirrups (detailed in Figures 5.6) were installed to query its effect on avoiding some failure modes (tension breakout) and increasing the connection capacity.
- 6- The test matrix may be considered fractional factorial, such that, subsets of tests examine the effects of isolated test variables. For example, Tests #1 and 2 provide a direct examination of the effect of different attachment techniques (i.e., arc welding versus anchoring/fixing), whereas Tests #2 and 3 provide an interrogation of the effect of reinforcement area/size. In addition, Tests #2 and 4 allow the investigation of the vertical reinforcement (stirrups) effect, whereas Tests #4 and 5 directly examine the effect of column width/size. It is worth mentioning that specimens from this program also allow

direct comparison with tests from the experimental program by Grilli et al. (2017), wherein the test variables as the general effect of horizontal reinforcement as well as column width could be examined, as discussed in the subsequent section.

Standard cylinder tests were performed for concrete pours as well as casted grout for all specimens. Sample tests from the attached reinforcement (both welded studs and U-bar hairpins) used in the experiments are also tested. Table 5.2 summarizes the results of ancillary tests for measured material properties which are used for results analysis and analytical models interpretation.

Table 5.2 – Summary of measured material strengths from ancillary tests

Test	Number of samples ^a	Yield Strength F_y^{rod} ^b [ksi]	Ultimate Strength F_u^{rod} [ksi]	Concrete Compressive Strength f'_c ^c [ksi]	Grout Compressive Strength f_{grout} ^c [ksi]
ASTM A706 - Grade 60 Reinforcement	2	71.2	94.2	-	-
ASTM A615 - Grade 60 Reinforcement	2	65.0	102.5	-	-
Concrete Cylinders	5	-	-	4.0	-
Grout Cylinders	4	-	-	-	8.50

^a Average values for tested samples are presented.

^b Measured yield stress for ASTM A706 rods is based on the 0.2% offset method.

^c Compressive strength for concrete and grout cylinders is measured on the day of full-scale test.

Loading Protocol

For all test specimens, the axial compression was first introduced and held constant while the lateral deformation history (expressed in terms of column drift ration) was applied. Figure 5.8 illustrates the employed protocol consisting of ATC-SAC loading history (Krawinkler et al. 2000) applied in an increasing manner until 6% drift amplitude (one specimen reached 7%). The ATC-SAC loading history was selected to demonstrate performance of the connection under seismic demand.

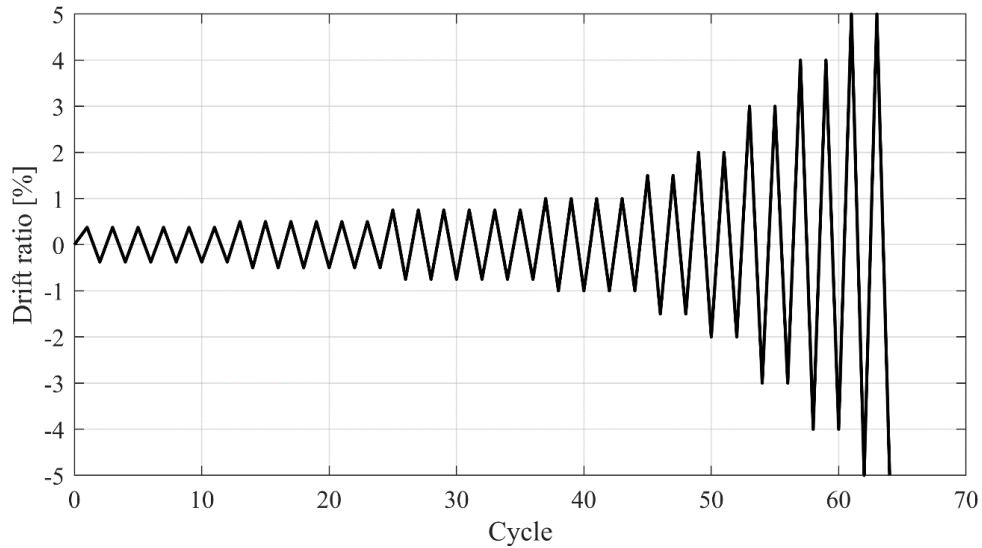


Figure 5.7 – Loading protocol with ATC-SAC (Krawinkler et al. 2000) loading history

5.4 EXPERIMENTAL RESULTS

Figures 5.8a-e show the load-deformation (specifically the moment-rotation curves) of all the five specimens after subtracting the elastic column rotations from the overall drift. Figures 5.9a-c show photographs of damage progression and failure modes for the tested specimens, whereas Table 5.1 shows key results, specifically with respect to model predictions. A qualitative assessment of experimental response for the tested specimens is now presented, to facilitate the interpretation of quantitative data, which is presented subsequently.

Qualitative discussion of failure modes

Figures 5.9a-c show photographic illustrations of damage and failure throughout the applied loading history. All specimens followed a qualitatively similar damage progression, with some exceptions/variations pertaining to the connection (reinforcement) detailing. During the initial stages of loading (with drift applied less than 1%), minor cracks initiated at the corners of the

column (flanges) as shown in Figure 5.9a. Followed by this, diagonal shear cracks formed on the sides of the block accompanied by a vertical crack in the concrete behind the column flanges (where the tension in the reinforcement bars is the highest), which grew in width as loading progressed with spalling of the concrete ahead of the column flanges. These vertical cracks effectively compromise the vertical/uplift capacity of the base plate (as explained later). As the applied drift increased, the diagonal shear cracks on the sides of the concrete block grew in width as an indication of development of concrete panel (however, not controlling the failure). The final failure mode varied from one specimen to another based on the additional vertical reinforcement (stirrups) installed. One of two scenarios occurred (shown photographically in Figures 5.9b-c), these are:

- 1- In Tests #1, 2 and 3, the final failure was accompanied by a breakout on the tension side of the connection. This failure mechanism is similar to the well-known anchor pryout failure modes in concrete (Andreson and Meinheit 2007) which was observed in similar details by Grilli et al. (2017) – see Figure 5.2b. As the base moment is shared by the vertical and horizontal bearing mechanism (as previously discussed), the pryout failure occurs as the moment resisting the uplift of the base plate reaches a critical value.
- 2- For Tests #4 and 5 (featuring additional stirrups/vertical reinforcement-detailed in Figure 5.6), the presence of supplemental reinforcement mitigated the final tension breakout failure (cone failure described above), instead the failure occurred at the interface of the vertical crack forming behind the column flanges (as shown in Figure 5.9c) at a location between installed stirrups. No spreading of failure (i.e., cone formation) was observed for such tests.

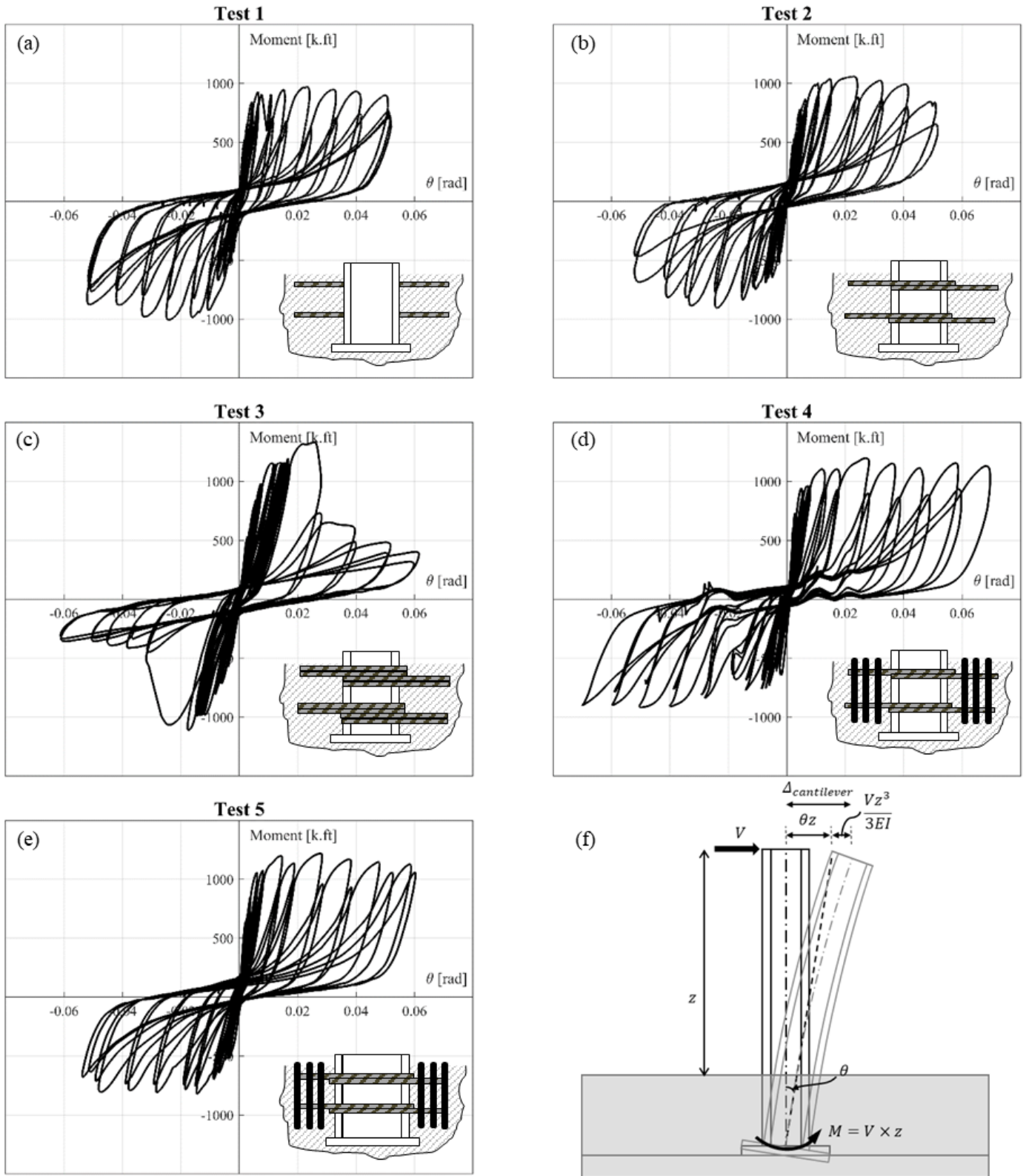
In all tests, the peak moment was achieved between 1.5% to 2% drift. After this, the strength at following cycles started to deteriorate as the concrete block started to separate, reducing the moment resisted by bearing ahead of the flanges (as well as through plate uplift). A similar pinched hysteresis with excellent deformation capacity and minimal strength degradation (i.e., less than 20% drop in peak base moments at 4% drift) was observed, except for Test #3 (with bundled U-bar hairpins) which had a drop in load after achieving capacity at around 2-2.5% drift).

Quantitative discussion of test data

Table 5.1 summarizes key quantities measured in the experiments. Two moment values are recovered for each test corresponding to maximum moment observed in each loading direction. These are denoted as M_{max+}^{test} and M_{max-}^{test} , such that the positive sign denotes the direction of application of the first deformation cycle. Referring to the table and Figures 5.8 and 5.9, the following observations could be made:

- 1- The main observation (referring to quantitative data from Grilli et al. 2017 – see Table 5.1), is that the application of horizontal reinforcement (i.e., attached reinforcement to column flanges) significantly reduced the strength (and stiffness) previously observed in similar details with no reinforcement and otherwise identical – see Figure 5.9d. This is because, the horizontal reinforcement introduced a tension field in the concrete area over the uplifting region of the base plate, which in turn, reduced the vertical resistance (from base plate upward bearing against concrete) resulting in a net reduction in strength relative to unreinforced specimens. Implications of this are discussed in the next section.
- 2- For comparing the effect of reinforcement attachment method in Tests #1 and 2 (Welded Rebar Stud versus U-bar Hairpin), the peak moment achieved from both tests is very close

while the load-deformation shows modest difference in terms of cycle-to-cycle degradation.



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Figure 5.8 – Moment-rotation plots for all tests, and a schematic illustration of plotted quantities

- 3- A comparison between Tests #2 and 4 provides a direct assessment of the effect of additional vertical reinforcement/stirrups. Apparently, the installation of stirrups increased the strength/capacity of the connection by about 20%. This may be attributed to the fact that the vertical reinforcement mitigated/delayed the formation of the tension breakout cone which in turn allowed for higher moment resistance.
- 4- Comparing Tests #4 and 5 (which are similar in terms of embedment depth, attached reinforcement, and stirrups but differ in terms of column section and base plate geometry – see Table 5.1), the achieved capacities are almost identical. This is different from the observations from (Grilli et al. 2017) for a similar comparison (except with no reinforcement or stirrups attached), such that, a 12% increase in capacity was observed for specimen with wider flange (W14x370). This may be due to the fact that the moment distribution between the horizontal and vertical mechanisms (which is initially dependent on the stiffness of the embedded column – such that a highly flexible column will transfer less moment to the base) has been disturbed due to the formation of the crack behind the column flange, which caused a non-unique distinguishment between both scenarios (different column sizes).
- 5- The effect of additional horizontal reinforcement (reinforcement attachment) is assessed through Tests #2 and 3 (which differ only in terms of the amount of attached horizontal reinforcement). A 20% increase in moment capacity was observed in Test #3, with an increase in the number and diameters of the attached reinforcement.
- 6- All experiments achieved a tremendous deformation capacity in excess of 6% drift (as compared to about 3% for cases without attached reinforcement – see Figure 5.9d). This implies an excellent performance considering the deformation and hysteretic

characteristics of the connection when compared to deformation demands in a design-level shaking (2-3% drift).

The next section describes the development of a strength model for ECB connections considering all observed failure modes (and their interactions), while also applying/adopting fundamental principles from existing methods. This is followed by an assessment of the model while investigating the efficacy of the available strength characterization models for ECB connections against test data.

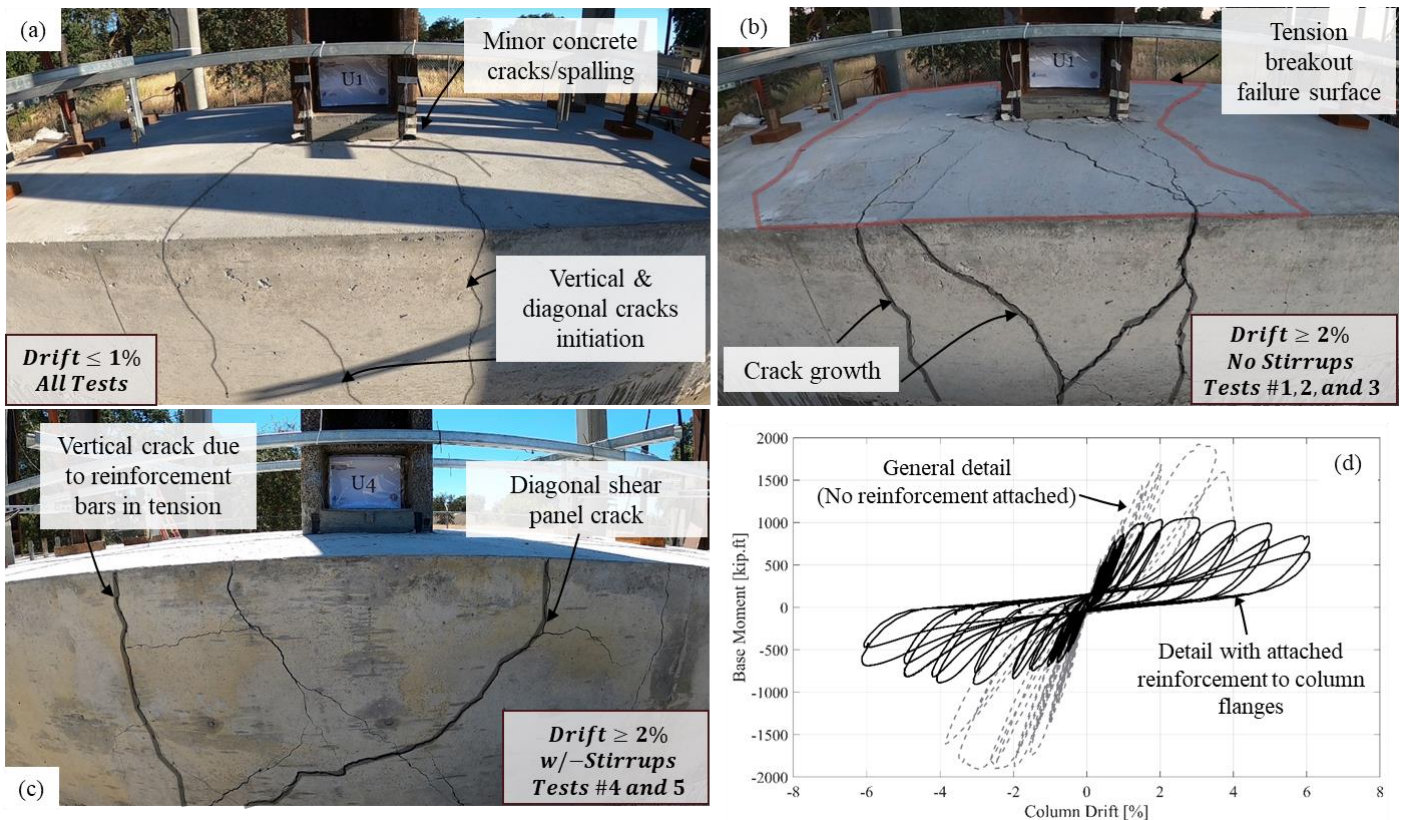


Figure 5.9 – Typical damage progression and behavioral insights: (a) below 1% drift for all tests; (b) failure mode for specimens with no stirrups (Tests #1, 2, and 3); (c) failure mode for specimens with stirrups (Tests #4 and 5); (d) moment-drift curve showing the effect of additional horizontal reinforcement as compared to a generic detail from Grilli et al. (2017)

5.5 PROPOSED MODEL FOR STRENGTH CHARACTERIZATION

Based on the observations from the experimental program, this section describes the development of strength model to facilitate the design and strength characterization of ECB connections. The model is based on three considerations (1) to reflect critical aspects of physics and internal force transfer as observed in previous experimental studies (Grilli and Kanvinde 2017), (2) to capture all relevant effects/failure modes associated with the addition/attachment of horizontal reinforcement, and (3) to quantify the vertical restraint provided to the base plate under varying levels of vertical/stirrup reinforcement.

Figure 5.10a schematically illustrates the two primary mechanisms of moment resistance, as discussed previously: (1) horizontal bearing stresses against the column flanges along with complementary shear panel zone, and (2) vertical bearing stresses resisting uplift of the base plate. The key assumption of the method is that the total applied base moment (denoted M_{base}) is resisted through a combination of horizontal and vertical bearing such that their moment contributions are additive (as shown in equation 5.2). This is consistent with the notation presented by Grilli and Kanvinde (2017) and discussed in a previous section. As proposed by Grilli and Kanvinde (2017), it is assumed that the net moment M_{base} is distributed in a constant proportion between the two mechanisms before any limit state/capacity is reached in either of the mechanisms (vertical or horizontal) through the introduction of the ratio α . This distribution is based on the assumption that no limit states are engaged simultaneously until the peak moment is reached. This is not the case for the ECB specimens tested in this program, wherein the peak moment is attained after obvious deformations in both vertical and horizontal directions.

Following this, the proposed model/approach adopts the concept of plastic mechanism development in which various response modes are mobilized and considered to be acting “in

parallel” such that their maximum contributions (limit states) are additive as shown in Figure 5.10b. The resistance due to each of those mechanisms is now discussed.

Moment resistance due to horizontal bearing stresses

Considering the free body diagram in Figure 5.10c, a portion of the applied moment (i.e., M_{HB}) and accompanied shear V is resisted through the development of bearing stresses on both sides of the embedded column flanges. A modified version of the previously discussed approach developed by Mattock and Gaafar (1981) is adopted in order to provide an estimation of the moment resistance provided by horizontal bearing mechanism while adding the horizontal reinforcement effect. The model idealizes the internal force transfer proposed by the original method while including the contribution of the attached reinforcement to the overall moment resistance. The developed bearing stresses are idealized such that a uniform and parabolic stress distributions are assumed for the top stress f_b^{top} , and the bottom stress f_b^{bottom} , respectively, such that:

$$f_b^{top} = 1.54 \sqrt{f'_c} \left(\frac{b_w}{b_f} \right)^n \quad (5.8)$$

And

$$f_b^{bottom} = 1000 f'_c [\varepsilon_b - 250 \varepsilon_b^2] \quad (5.9)$$

In the above equation for f_b^{top} (in ksi), the term b_w/b_f accounts for the effect of confinement, wherein b_w (in inches) is the width of the foundation, and b_f (in inches) is width of the flange. The exponent n is calibrated based on experimental data to a value of $n = 0.66$ (based on study by Mattock and Gaafar 1981- briefly described above). The concrete strain is assumed to vary linearly, with the maximum concrete strain taken as 0.003 at the top of the foundation, and defined as ε_b at the bottom (end of embedment). As per equation (5.9), the bearing stress distribution at the bottom of the embedded section may be expressed as parabolic function with maximum stress

of f'_c at a strain of $\varepsilon_b = 0.002$. Referring to Figure 5.10c, the term k_2 defines the location of the resultant compressive force C_{bottom} such that:

$$k_2 = \frac{1-0.375\left[\frac{d_{embed}-c}{c}\right]}{3-1.5\left[\frac{d_{embed}-c}{c}\right]} \quad (5.10)$$

and,

$$C_{bottom} = 0.5 \frac{b_f}{c} \left(\frac{b_w}{b_f}\right)^n f'_c (d_{embed} - c)^2 \left[3 - 1.5 \left[\frac{d_{embed}-c}{c}\right]\right] \quad (5.11)$$

and,

$$C_{top} = f_b^{top} \beta_1 c b_f \quad (5.12)$$

In the above, c (in inches) is the neutral axis depth and β_1 is the factor relating the depth of equivalent rectangular stress block to neutral axis depth. The attached reinforcement is assumed can act in tension and compression (in the case of welded rebars) and only in tension (in the case of the U-bar Hairpin) – see Figure 5.10c. The reinforcement bar is assumed to be elastic-perfectly-plastic and fully developed in tension (as per ACI 318-19). Forces in the rebars ($F_{rebar} = A_{rebar} \times F_y$) are assumed to be in the same direction of the applied shear for bars above the neutral axis, while being in the opposite direction for bars below. The resultant from each rebar row (upper and lower) are directly added to the resultants from the stress distributions, such that moment resistance due to horizontal stresses, M_{HB} may be obtained by simultaneously solving the force and moment equilibrium equations based on the assumed force distributions, where:

$$V - C_{top} + C_{bottom} - F_{rebar}^{top} + F_{rebar}^{bottom} = 0 \quad (5.12)$$

$$V \times z = -C_{top} \frac{\beta_1 c}{2} + C_{bottom} \times [d_{embed} - k_2(d_{embed} - c)] - F_{rebar}^{top} d_r^{top} + F_{rebar}^{bottom} d_r^{bottom} \quad (5.13)$$

In the above equations, F_{rebar}^{top} , and F_{rebar}^{bottom} are the resultant forces from the engaged reinforcement rods, and d_r^{top} , and d_r^{bottom} are the distances from the rebars location to the top of the foundation surface, for the top and bottom rebars, respectively. Once V and c are calculated from equations (5.12) and (5.13), the moment resisted through horizontal bearing is then calculated as follows:

$$M_{HB} = V \times z \quad (5.14)$$

In the above derivation, the problem is defined while implicitly employing a moment-to-shear ratio (i.e., z the height of the column inflection point) as a given parameter. This implies that for a calculated value of M_{HB} , the corresponding connection shear V is constrained to it.

The next subsection provides and detailed discussion on the estimation of the moment resistance due to vertical bearing stress.

Moment resistance due to vertical bearing stresses

Referring to Figure 5.10d, the base plate at the bottom is subjected to bearing stresses on the lower as well as the upper surfaces, resisting the moment transferred to the base through the column flanges, as well as the net axial force transferred to the base plate. The base plate is assumed to resist the total axial force (through upward bearing in case of compressive load or downward bearing in case of tensile load) in addition to the moment resisted through the vertical bearing mechanism M_{VB} . The bearing stress distributions are idealized such that the moment is resisted through equal bearing blocks at the two ends of the plate (denoted f_{VB}^M) with equal length Y , such that $Y = 0.3N$, where N is the length of the base plate. This is based on agreement with test data (from this program as well as Grilli et al. 2017), and following similar approaches adopted for

composite connection design by the ASCE guidelines for composite connections (ASCE 1994). Following this, the vertical bearing stress in the blocks can be expressed as:

$$f_{VB}^M = \frac{M_{VB}}{(N-Y) \times Y \times B} \quad (5.15)$$

The stress due to the axial force (denoted f_{VB}^P) is considered to be uniform over the footprint of the base plate such that $f_{VB}^P = P/(B \times N)$, where P is the axial load and B is the width of the base plate (perpendicular to the direction of loading). This axial stress may be added or subtracted from the stress blocks f_{VB}^M , resulting in a stepped stress distribution where the end blocks carry stress equal to $f_{VB} = f_{VB}^M \pm f_{VB}^P$, depending on the axial load sign as shown in Figure 5.10d.

As previously discussed in the experimental study, two main failure modes were observed pertaining to the vertical resistance mechanism and involving the failure of the concrete block above the plate on the tension side of the connection. Since this failure type is generally controlled by the total force in the bearing block, rather than the bearing stress, the resultant of the stepped bearing stress distribution on the tension side of the connection is utilized for the model calculations, such that:

$$F_t = (f_{VB}^M - f_{VB}^P) \times (Y \times B) \quad (5.16)$$

This force F_t is calculated based on each failure mechanism/mode depending on the connection detailing. Referring to the prior discussion on the experimental results, the first failure mode observed is the breakout of the concrete through a cone failure on the tension side of the connection. The total breakout force may be calculated as shown below:

$$F_t = F_t^{breakout} = \frac{40}{9} \times \frac{1}{\sqrt{d_{cover}}} \times \sqrt{f_c'} \times A_{35} \quad (5.17)$$

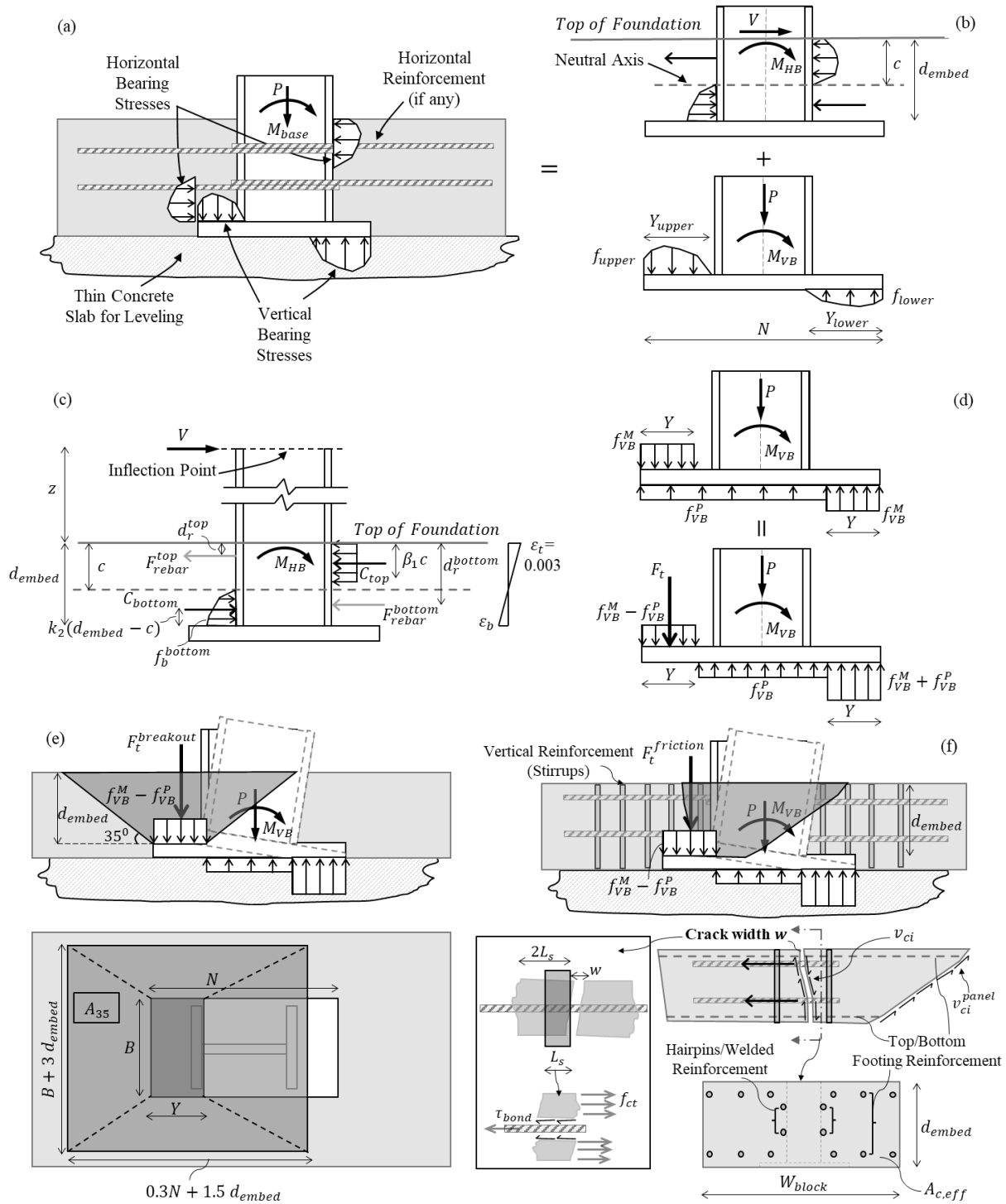


Figure 5.10 – Proposed model for strength characterization: (a) overall mechanism; (b) moment resisted due to horizontal forces and due to vertical forces; (c) horizontal resistance mechanism model (modified Mattock and Gaafar 1981) with the effect of reinforcement; (d) idealized vertical moment resistance – stepped bearing distribution due to moment and axial load; (e) tension concrete breakout failure mode (vertical bearing) with projected area A_{35} illustration; (f) shear/friction failure mode between stirrups (vertical bearing) with crack model illustrations

The above equation is based on the Concrete Capacity Design (CCD) method proposed by Fuchs et al. (1995), such that d_{cover} is thickness of the material which must be ruptured for breakout, which is equal to d_{embed} for tension breakout. The term A_{35} is the projected area of a 35-degree failure cone emanating from the edges of the stress block on the tension. The projected area A_{35} is shown in Figure 5.10e and is calculated using the equation below:

$$A_{35} = (B + 3 d_{embed}) \times (0.3 N + 1.5 d_{embed}) - (B \times 0.3 N) \quad (5.18)$$

Once established this way, the moment resisted through vertical bearing can be determined by solving both equations (5.15) and (5.16):

$$M_{VB} = \left(F_t - \frac{P \times Y}{N} \right) \times (N - Y) \quad (5.19)$$

It should be mentioned that this failure mode is applicable to details where no horizontal reinforcement is attached (tests by Grilli et al. 2017). As previously discussed, once reinforcement is attached to column flanges, a tension field is created above the uplifting end of the base plate reducing the resistance to vertical motion (to almost zero). In turn, the vertical bearing resistance could be conservatively assumed as zero (i.e., $M_{VB} = 0$). for cases where no additional vertical reinforcement (stirrups) is installed (for example, Tests #1, 2 and 3 from the experimental program).

The second failure mode observed is associated with the presence of vertical reinforcement/stirrups supplementary to the attached horizontal reinforcement. The purpose from having such reinforcement is to increase the vertical bearing resistance by mitigating the breakout failure mode. Referring to the test results and Figures 5.8d-e, the stirrups added a fair amount of vertical resistance while shifting the failure mode from a cone breakout into a direct shear failure at the weak point in the foundation (i.e., the cracked section between the stirrups location – see

Figure 5.9c). For this, the total resultant force F_t is calculated based on the amount of resistance provided by the upward bearing of the base plate against the cracked concrete section above. This requires the determination of the shear stress on the crack interface (i.e., the shear friction).

Based on the derivations by (Vecchio and Collins 1986), cracks occurring along the interface between the cement paste and the aggregate particles result in a rough surface which can transfer shear through aggregate interlocking (see Figure 5.10f). Vecchio and Collins (1985) developed a relationship between the shear stress transferred across the crack v_{ci} , the crack width w , and the required compressive stress f_{ci} (in psi) on the crack, such that:

$$v_{ci} = 0.18 v_{ci,max} + 1.64 f_{ci} - 0.82 \frac{f_{ci}}{v_{ci,max}} \quad (5.20)$$

Where $v_{ci,max}$ (in psi) is the maximum shear stress that can be transferred across a crack when its width is held at w (in inches), and given by:

$$v_{ci,max} = \frac{2.16 \sqrt{f'_c}}{0.3 + \left(\frac{24w}{a+0.63}\right)} \quad (5.21)$$

Such that, a (in inches) is the diameter of the coarse aggregate in the cracked concrete, taken as 0.75 inches. Given that the crack (as shown in Figure 5.10f) is subjected to tension, therefore f_{ci} in equation (5.20) could be considered as zero, and the equation is reduced to

$$v_{ci} = 0.18 v_{ci,max} \quad (5.22)$$

It should be mentioned that the diagonal crack (formed due to panel shear) has zero shear strength (v_{ci}^{panel} - see Figure 5.10f) due to the fact that the shear panel crack has already opened up completely by the time the capacity connection capacity is attained. In order to calculate the crack width w , a classical mechanical approach based on the bond-slip relationship at reinforced concrete interface (i.e., bond law - CEB-FIP Model Code 1990) is employed. This method predicts the maximum crack width assuming the maximum possible slipping length, such that:

$$w = 2 L_s (\varepsilon_{sm} - \varepsilon_{cm}) \quad (5.23)$$

Where $2L_s$ is the maximum slip length and ε_s and ε_{cm} are the average value of steel and concrete strains, respectively. The transfer length L_s is defined as:

$$L_s = \frac{f_{ct} A_{c,eff}}{\tau_{bond} \Sigma \pi d_i} \quad (5.24)$$

Where f_{ct} (in ksi) is the tensile strength of concrete (taken as $7.5 \sqrt{f'_c}$ following the ACI 318-19 provisions), $A_{c,eff}$ (in square inches) is the effective area of concrete taken as $W_{block} \times d_{embed}$ (see Figure 5.10f) such that W_{block} is the width of the concrete foundation block, τ_{bond} (in ksi) is the average bond strength along the transfer length, taken as $0.95 \sqrt{f'_c}$ (ksi) based on canonical literature (CEB-fib Model Code 1990), and d_i is the diameters of bars crossing the considered crack (including the foundation main reinforcement bars as well as the horizontally attached reinforcement – as shown in Figure 5.10f). Once determined in this manner, the value of the upward force due to shear friction/aggregate interlocking across cracked section can be calculated as:

$$F_t^{friction} = v_{ci} \times A_{c,eff} \quad (5.25)$$

The above equation is then applied to equation (5.19) to calculate the vertical moment capacity for the connection where vertical/stirrups reinforcement is provided.

Finally, the connection strength as per the proposed unified model may be estimated as:

$$M_{max}^{Model} = M_{HB} + M_{VB} \quad (5.26)$$

Results and comparison to experimental data

Table 5.1 summarizes the test-to-predicted ratios for the strength estimates $M_{max}^{test}/M_{max}^{Model}$ for all test data points (i.e., from current experimental study and previous experimental program by Grilli

et al. 2017) using the methodology prescribed in the previous section. Also included in the table are the test-to-predicted ratios for the connection strength calculated as per the AISC SDM model $M_{max}^{test}/M_{max}^{AISC\ SDM}$, and the model developed by Grilli and Kanvinde (2017), $M_{max}^{test}/M_{max}^{Grilli}$, discussed previously (except with the inclusion of the effect of horizontal reinforcement for the model by Grilli and Kanvinde 2017 - following the approach explained above). Adding to the models' comparison, the test-to-predicted ratios using the model by Grilli and Kanvinde (2017), without considering the resistance to vertical uplift (for tests featuring horizontal reinforcement), denoted $M_{max}^{test}/M_{max}^{Grilli-HB}$, is also presented. Figures 5.11a-d plot the test-to-predicted ratios from all models against the column embedment depth (normalized by the depth of the column, i.e., d_{embed}/d_{col}). Referring to Table 5.1 and the figure, it is observed that:

- For the AISC SDM Method, results are little bit unconservative for cases with reinforcement while the method shows high variability across all test points (Overall Coefficient of Variation - CoV = 0.20). This is expected as the approach does not consider reinforcement effect (only considered for force transfer), and due to the fact that other aspects of the method (mentioned previously), where implicit assumptions in the method were particularized based on geometrical aspects/constraints which are not necessarily applicable to ECB connections (different ECB details other than the ones tested might yield different results).
- For the original model developed by Grilli and Kanvinde (2017), the method overestimates the strength of the connections (with reinforcement) with an average test-predicted ratio of 0.63 and CoV = 0.13. Referring to the preceding discussion and the qualitative progression of test response, this is not surprising as it suggests that the specimens do not derive significant strength from the vertical bearing mechanism. This

is because the horizontal reinforcement introduces tension in the bearing zone above the uplifting plate, greatly reducing the vertical resistance. In fact, a closer look at the test data suggests that the introduction of stirrups in this region result in a slight increase in the test-predicted ratio (i.e., on average 0.69 for Tests #4 and 5, compared to 0.55 for Tests #1 and #2). However, this increase, which presumably occurs due to the enhancement of vertical breakout strength of the concrete above the base plate, is not sufficient to overcome the loss of strength due to the tension field produced by the horizontal reinforcement.

- Considering the same model, while disregarding the vertical bearing resistance, the model results in significantly improved predictions of test data (compared to the original model including vertical resistance), with an average test-predicted ratio of 1.15, which is somewhat conservative. Interestingly, this model predicts the response of the tests without stirrups (i.e., Tests #1 and 2) with great accuracy (test-predicted ratio 1.00), whereas for the tests with stirrups (Test #4 and 5), the results are significantly conservative (i.e., test-predicted ratio of 1.27). This indicates that the vertical bearing capacity is enhanced to a significant degree by the stirrups, but not to the level of the previous Grilli et al. (2017) tests in which no horizontal reinforcement was present.
- Finally for the proposed unified model, overall, the model predicts the experimentally observed moment capacities with reasonable accuracy; on average the test-to-predicted ratio = 1.00 with a CoV = 0.12. As shown in Table 5.2, the agreement with both testing programs (with different details) is excellent (on average 1.09, with a tight CoV = 0.11). Referring to Figure 5.11d, the proposed method shows great accuracy across all

different details with different embeddings this indicates that the model reflects the fundamental mechanics and behavioral aspects consistent with the phenomena controlling the strength of the ECB connection details.

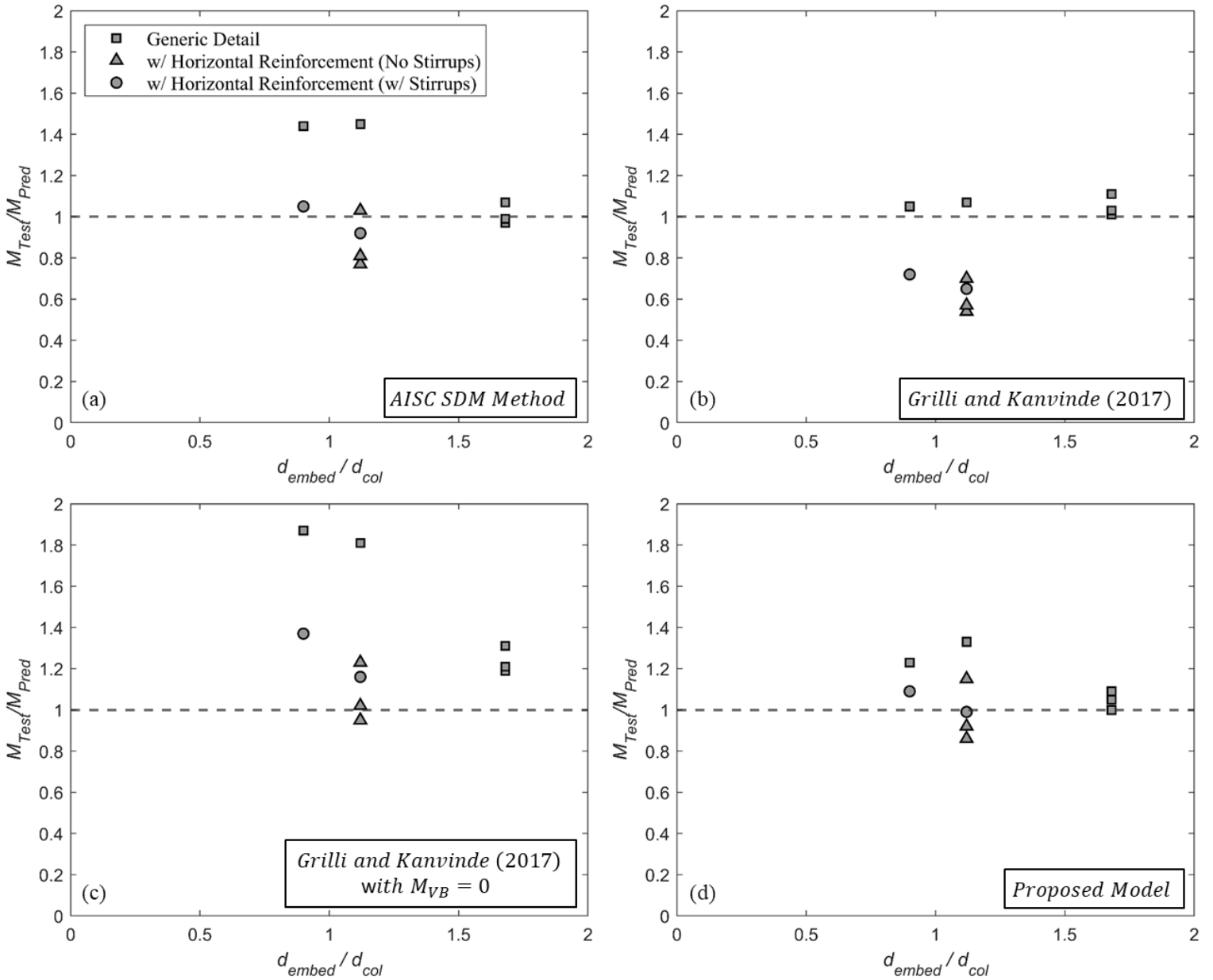


Figure 5.11 – Test-predicted ratios for all experiments from various strength characterization methods plotted against d_{embed}/d_{col}

5.6 SUMMARY AND CONCLUSIONS

Embedded Column Base (ECB) connections are widely used in mid- to high-rise steel moment frames to resist base moments. Despite their prevalence, methods available to design, and estimate their strength rely on experimental data on components (steel coupling beams embedded in concrete shear walls, and/or composite beam column connections) similar in aspects, however with major differences. This study presents findings from five tests representing of ECB connections with attached horizontal reinforcement (to increase connection strength) representative of the current construction practice. All specimens were cantilever columns loaded with cyclic lateral deformations under a constant axial load. The test variables were the method of reinforcement attachment (Welded reinforcement to column flange or U-bar hairpins anchored through the embedded portion of the column), area of the attached horizontal reinforcement, column cross section, and presence of additional vertical/stirrups reinforcement.

The tests revealed incredible a huge deformation capacity for such connections. The main observation is that the addition of attached horizontal reinforcement (specifically to column flanges – as common construction practice), reduces the strength and stiffness (albeit, significantly increases the ductility) of such connections as compared to details with no reinforcement attached. This is due to the fact that, the horizontal reinforcement introduces a tension field in the concrete area above the uplifting region of the embedded plate, resulting in a reduced vertical resistance and an overall net reduction in strength. Two main types of failure were observed: one was characterized by a breakout of concrete cone on the tension side of the connection, whereas the other was associated with a higher strength owing to the presence of additional vertical/stirrups reinforcement which mitigated the breakout failure, and instead failed in shear friction mode at the cracked interface between the cement paste and the aggregates between the stirrups location.

Based on these observations, a series of load resisting mechanisms are postulated (each is associated with local failure modes). A strength characterization model, based on these findings, is presented. The proposed approach is based on an idealized internal force distribution and fundamental mechanics, while providing adherence to key modes of physical response observed across all the test programs. To this end, the method idealizes some aspects of behavior, and leverages apposite elements/assumptions from previously developed strength models (Grilli and Kanvinde 2017 and AISC Seismic Design Manual 2018) and canonical theories on material behavior. The proposed approach is used to characterize the strength of all experiments, The results are encouraging, such that the new approach results in an average test-to-predicted ratio of 1.09, with a CoV of 0.11. This is significantly more accurate than the test-to-predicted ratios from the current AISC SDM approach or the Grilli and Kanvinde 2017 model, which shows higher variability and greater conservatism, respectively.

Despite the accuracy of the proposed approach and the improvement (with knowledge advancement) over the current approaches for strength characterization and design of ECB connections, the model has numerous limitations. The model is only validated against 10 test – since these are the only available data on ECB connections. The proposed method considered different failure modes pertaining to the uplift/vertical resistance, however other limit states associated with vertical bearing are also possible depending on the connection configuration; these include: (1) concrete breakout under the compression toe of the lower base plate (due to placement of the column on a thin layer of concrete), or (2) yielding of the base plate (if not sufficiently thick).

In conclusion, it is emphasized that the response of these connections is controlled by highly nonlinear and complex interactions between the various components (steel column/base, concrete,

and reinforcement). As a result, the development of a design or strength characterization method that explicitly satisfies equilibrium, compatibility, and nonlinear constitutive response of the various components is intractable. Consequently, the method presented in this study is based on some simplifying assumptions. This implies that caution should be applied in extrapolating the results of this study to details that are highly dissimilar from those examined in this study.

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