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### Publication Date

1969-09-01

SESM 69-28

STRUCTURES AND MATERIALS RESEARCH  
DEPARTMENT OF CIVIL ENGINEERING

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**REFINED FINITE ELEMENT  
ANALYSIS OF ELASTIC-  
PLASTIC THIN SHELLS  
OF REVOLUTION**

P. SHARIFI  
E. P. POPOV

Report to  
Army Research Office, Durham  
Contract No. DAHCO 4 69 C 0037

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DECEMBER 1969

STRUCTURAL ENGINEERING LABORATORY  
UNIVERSITY OF CALIFORNIA  
BERKELEY CALIFORNIA

REFINED FINITE ELEMENT ANALYSIS OF  
ELASTIC-PLASTIC THIN SHELLS OF REVOLUTION

by

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ABSTRACT

A refined axisymmetric curved finite element for the analysis of thin elastic plastic shells of revolution is described in the report. The improved element is obtained by employing cubic polynomials for the assumed in-plane and out-of-plane displacements in terms of local Cartesian coordinates. This introduces into the solution two internal degrees of freedom in the cord direction of each element. These internal degrees of freedom are removed by static condensation before assembling the individual element stiffness matrices, and are subsequently recovered after the nodal displacements are obtained. On comparison with the previous formulation, this procedure greatly improves the accuracy of the solution especially with regards to in-plane stress-resultants at discontinuities in the meridional curvature and interelement equilibrium of forces. The latter fact makes it possible to analyze shells with discontinuous meridional slope. In using this element, improvement in the convergence of the elastic-plastic solutions has been also observed.

An earlier computer program using curved elements has been modified to incorporate the refined element. Complete listing of the modified program written in Fortran IV language is given. Two examples illustrate applications of the new program.

The reported analysis is limited to situations of axisymmetric loading and boundary conditions.

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NOTATION

$dA$	- surface element of the reference surface of shell
$dS$	- surface element
$dv$	- volume element
$E$	- Young's modulus
$h$	- shell thickness
$l$	- cord length of an element
$M_s, M_\theta$	- meridional and circumferential bending moments per unit length, respectively
$N$	- total degrees of freedom of the discretized structure
$N_s, N_\theta$	- meridional and circumferential in-plane forces per unit length, respectively
$p^E$	- elastic limit load
$p^{EP}$	- elastic-plastic load
$r_1$	- meridional radius of curvature
$S_\tau$	- part of boundary surface where stresses are specified
$u_1, u_2$	- displacements as shown in Fig. 1
$U$	- meridional displacement
$W$	- transverse (radial) displacement
$u_i$	- displacement components
$\alpha_i$	- generalized coordinates
$\beta$	- an angle as shown in Fig. 1
$\epsilon_s^0, \epsilon_\theta^0$	- meridional and circumferential strains of the reference surface of shell, respectively
$\eta$	- local coordinate for an element, see Fig. 1
$\kappa_s, \kappa_\theta$	- meridional and circumferential change of curvatures of shell, respectively

- $\nu$  - Poisson ratio
- $\xi$  - local coordinate for an element, see Fig. 1
- $\sigma_y$  - yield stress in tension
- $\tau^{ij}, \tau_{ij}$  - stress tensor
- $\varphi$  - latitude angle, see Fig. 1
- $\chi$  - meridional rotation
- $\psi$  - as shown in Fig. 1
- $\{ \}$  - vector; column matrix
- $[ ]$  - matrix
- $[A]$  - displacement transformation matrix, see (12)
- $[B]$  - as defined in (6)
- $[C]$  - matrix of elastic-plastic moduli
- $[K]$  - stiffness matrix of the entire system
- $[\underline{k}]$  - condensed element stiffness matrix in physical coordinate, see (14)
- $[k]$  - element stiffness matrix
- $[k_\alpha]$  - element stiffness matrix in generalized coordinates, see (8)
- $\{p\}$  - as defined in (10)
- $\{Q\}$  - equivalent nodal point force in physical coordinates, see (14)
- $\{Q_\alpha\}$  - equivalent nodal point force in generalized coordinates
- $\{q\}$  - nodal point displacement
- $\{R\}$  - external nodal point load of the system in global coordinates
- $[\underline{R}]$  - condensed element load vector
- $\{r\}$  - nodal point displacement of the system in global coordinates

- $\{r_1\}$  - element nodal displacement corresponding to external degrees of freedom
- $\{r_2\}$  - element nodal displacement corresponding to internal degrees of freedom
- $[T]$  - as defined in (16) and (17)
- $\{\alpha\}$  - generalized coordinates
- $\{\epsilon\}$  - strain tensor expressed in column matrix
- $\{\epsilon\}$  - as defined in (6)
- $\{\tau\}$  - stress tensor expressed in column matrix
- $[\varphi]$  - as defined in (9)
- $[\varphi_p]$  - interpolating function for surface loads, see (10)



## INTRODUCTION

During the preparation of a paper on the elastic-plastic analysis of pressure vessel heads [1]\*, considerable inaccuracies in the in-plane stress-resultants were observed at junctures between the cylinders and toroidal knuckles as well as between knuckles and spherical closures. An expedient of using very small elements in such locations somewhat resolved this difficulty, however this was achieved at an increase in the computer time. Moreover, although not uncommon in the finite element work, the interelement equilibrium of forces was not altogether satisfactory. To obtain these solutions the previously developed formulation [2,3] for shells of revolution for axisymmetrical loadings utilizing curved elements has been employed. In terms of local Cartesian coordinates, in the earlier formulation a cubic expansion was used for the transverse displacements, and a linear one for in-plane deformation. Subsequent study showed that this formulation inadequately relates the interaction of flexural and in-plane forces.

A more consistent approach is to use the same order of polynomial expansions for both the in-plane and out-of-plane displacements. In this regard, whereas a cubic expansion for transverse displacements is necessary to comply with the requirements of continuity, rigid body nodes, and constant curvature, this is not the case for in-plane displacements. By adopting a cubic polynomial expansion for the in-plane displacements, two internal degrees of freedom are added to the six

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\* The bracketed numbers refer to the corresponding items in the list of References.

nodal degrees of freedom existing in the previous formulation. This necessitates a process of static condensation in order to remove these two additional degrees of freedom before assembling the individual element stiffness matrices, and recovering them after the nodal displacements are found.

After deriving the appropriate expressions for a refined element having eight degrees of freedom instead of six and programming the modified solution, several advantages of the new formulation became apparent. By using the refined elements, faster rate of convergence of elastic-plastic solutions is obtained, and the results are more accurate. This is achieved at the expense of but slightly lengthier process of solution than that used in the previous approach.

The basic method of solution of axisymmetrically loaded elastic-plastic thin shells of revolution has been presented previously [2,3,4] and will not be repeated. Here discussion will be confined principally with regards to the development of the refined element. A new elastic-plastic analysis of shells with a discontinuity in the meridional slope, made possible by the greater accuracy of the improved formulation, is also given. The developed solution is illustrated by two examples. In the one, its superiority to the earlier results is brought up; in the other, an elastic-plastic shell with a discontinuity in the meridional slope is solved.

GEOMETRY OF A CURVED ELEMENT

The geometry of an axisymmetric curved shell element is illustrated in Fig. 1. As has been shown in [2] and [4], its meridional curve in dimensionless coordinates  $\xi$  and  $\eta$  may be expressed as

$$\eta = \xi(1 - \xi) (a_1 + a_2 \xi + a_3 \xi^2 + a_4 \xi^3) \quad (1)$$

where

$$a_1 = \tan \beta_i$$

$$a_2 = \tan \beta_i + \frac{1}{2} \eta_i''$$

$$a_3 = - (5 \tan \beta_i + 4 \tan \beta_j) + \frac{1}{2} \eta_j'' - \eta_i''$$

$$a_4 = 3(\tan \beta_i + \tan \beta_j) + \frac{1}{2} (\eta_j'' - \eta_i'')$$

$$\eta'' = \frac{d^2 \eta}{d\xi^2} = - \frac{l}{r_1 \cos^3 \beta}$$

$$l = \text{cord length}$$

Note that the curve given by (1) satisfies the requirements of continuity of slopes and curvatures at the nodal circles.

DISPLACEMENTS PATTERN

In this development the following displacement model, expressed in terms of local Cartesian coordinates, Fig. 1, is assumed over each discrete element:

$$\begin{aligned} u_1 &= \alpha_1 + \alpha_2 \xi + \alpha_3 \xi^2 + \alpha_4 \xi^3 \\ u_2 &= \alpha_5 + \alpha_6 \xi + \alpha_7 \xi^2 + \alpha_8 \xi^3 \end{aligned} \quad (2)$$

where  $\alpha$ 's are the generalized coordinates. The number of these generalized coordinates is equal to the total number of internal and external degrees of freedom of the element. The six degrees of freedom at the nodes  $i$  and  $j$ , Fig. 2, are the external D.O.F., and the two at the nodes  $m$  and  $n$  are the internal D.O.F. On assembling the elements into a representation of the overall shell, compatibility must be maintained for all the displacements degrees of freedom occurring at the interelement nodes, i.e., at  $i$  and  $j$  in Fig. 2. The two displacement degrees of freedom at the internal nodes  $m$  and  $n$  are not required in the assemblage. Thus they must be removed by a process of static condensation prior to assemblage of the total structural stiffness matrix.

The displacement model (2) must be specialized for the case of the central cap, Fig. 3. Here, if  $W$  and  $U$  are the radial and tangential components of displacements, because of symmetry, at the apex, the tangential component of displacement,  $U_i$ , and rotation,  $X_i$ , vanish. Hence,

$$U_i = u_1^i \sin \psi + u_2^i \cos \psi = 0 \quad (3)$$

$$\chi_i = \frac{dW}{ds} \Big|_i - \frac{U_i}{r_1} = \frac{1}{\ell} \left( - \frac{du_1}{d\xi} \Big|_i \tan \beta + \frac{du_2}{d\xi} \Big|_i \right) = 0$$

Further, the following relation holds between (U, W) and ( $u_1, u_2$ ):

$$\begin{pmatrix} U \\ W \end{pmatrix} = \begin{pmatrix} \cos \beta & \sin \beta \\ -\sin \beta & \cos \beta \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} \quad (4)$$

where

$$\tan \beta = \frac{d\eta}{d\xi} \equiv \eta'$$

On substituting (2) into (3), one obtains:

$$\frac{\alpha_1}{\alpha_5} = - \frac{\cos \psi}{\sin \psi} \quad (a)$$

$$\alpha_6 = \alpha_2 \tan \beta_i \quad (b)$$

Defining  $\alpha_1 \equiv -\alpha_3' \cos \psi$ , (a) gives  $\alpha_5 = \alpha_3' \sin \psi$ .

Defining  $\alpha_2 \equiv \alpha_4'$ , (b) gives  $\alpha_6 = \alpha_4' \tan \beta_i$ .

Fulfillment of the symmetry conditions (3) reduces the number of generalized coordinates from eight to six for the cap element. The resulting displacement pattern in ( $\xi - \eta$ ) coordinates is:

$$u_1 = -\alpha_3' \cos \psi + \alpha_4' \xi + \alpha_5' \xi^2 + \alpha_6' \xi^3$$

$$u_2 = \alpha_3' \sin \psi + \alpha_4' \tan \beta_i \xi + \alpha_7' \xi^2 + \alpha_8' \xi^3 \quad (5)$$

ELEMENT STIFFNESS MATRIX

The details of generating the element stiffness matrix for an axisymmetric curved element have been discussed elsewhere [2, 4]. Only the general outline of the procedure is indicated here, with the emphasis placed on the new features of the formulation that arise due to the modification of the old element.

By simple differentiation of (2) or (5) the strain-displacement relation may be expressed as follows:

$$\begin{matrix} \{\epsilon(\xi)\} & = & [B(\xi)] & \{\alpha\} \\ 4 \times 1 & & 4 \times 8 & 8 \times 1 \end{matrix} \quad (6)$$

where the transpose of the strain vector  $\{\epsilon\}$ , as defined in [2], is given by

$$\{\epsilon\}^T = \langle \epsilon_s^0 \quad \epsilon_\theta^0 \quad \kappa_s \quad \kappa_\theta \rangle$$

Here  $\epsilon_s^0$  and  $\epsilon_\theta^0$  are the meridional and circumferential strains of the reference surface of the shell, respectively, and  $\kappa_s$  and  $\kappa_\theta$  are the corresponding quantities of the changes in shell curvatures.

The B matrices for the cap and frustum elements are given in Appendix I.

As shown in [2] the relationship between stress,  $\tau$ , and strain,  $\epsilon$ , for an elastic-plastic material can be expressed as

$$\begin{matrix} \{\tau(\xi)\} & = & [C(\xi)] & \{\epsilon(\xi)\} \\ 4 \times 1 & & 4 \times 4 & 4 \times 1 \end{matrix} \quad (7)$$

where C is a matrix of elastic-plastic moduli.

On applying the principle of virtual displacement, the element stiffness matrix in terms of generalized coordinates can be stated as

$$[k_{\alpha}] = \int_{\Delta V} [B]^T [C] [B] dV \quad (8)$$

8x3

where  $\Delta V$  signifies the volume of the element.

The generalized load vector also can be obtained by utilizing the principle of virtual displacement in the following manner.

Let the relations (2) and/or (5) together with the expression for meridional rotation be represented in matrix form as:

$$\{u(\xi)\} = [\varphi(\xi)] \{\alpha\} \quad (9)$$

3x1          3x8    8x1

where

$$\{u\}^T = \langle u_1 \ u_2 \ \chi \rangle$$

and the matrix  $[\varphi]$  is given in Appendix II.

Next, the surface loads  $p(\xi)$  can be expressed in terms of interpolating functions  $\varphi_p$  as

$$\{p(\xi)\} = [\varphi_p(\xi)] \{p_i\} \quad (10)$$

3x1          3x6    6x1

where  $p_i$  is the intensity of the distributed loads at the external nodes.

Then, by applying the principle of virtual displacement, it can be shown that the equivalent generalized loads  $Q_{\alpha}$  at the external and internal nodes are

$$\{Q_{\alpha}\} = \int_{\Delta S} [\varphi]^T \{p(\xi)\} dS \quad (11)$$

8x1

where  $\Delta S$  is the surface area of the element.

To transform the above element stiffness matrix and the load vector to physical coordinates, one proceeds as follows.

By substituting the coordinates of the element nodal points into (9), one gets the nodal displacements  $\{q\}$  in terms of generalized coordinates:

$$\begin{matrix} \{q\} \\ 8 \times 1 \end{matrix} \equiv \begin{matrix} \left\{ \begin{matrix} u_i \\ u_j \\ u_k \end{matrix} \right\} \\ 3 \times 1 \\ 3 \times 1 \\ 2 \times 1 \end{matrix} = \begin{matrix} [A] \\ 8 \times 8 \end{matrix} \begin{matrix} \{\alpha\} \\ 8 \times 1 \end{matrix} \quad (12)$$

and

$$\{\alpha\} = [A]^{-1} \{q\} \quad (13)$$

where

$$\{q\}^T = \langle u_1^i \ u_2^i \ \chi^i \ \vdots \ u_1^j \ u_2^j \ \chi^j \ \vdots \ u_1^m \ u_1^n \rangle$$

The matrices  $A$  and  $A^{-1}$  are given in Appendix III, both for the cap and frustum elements.

The stiffness matrix and the load vector in physical coordinates are obtained by the following transformation:

$$\begin{matrix} [k] \\ 8 \times 8 \end{matrix} = \begin{matrix} [A^{-1}]^T \\ 8 \times 8 \end{matrix} \begin{matrix} [k_\alpha] \\ 8 \times 8 \end{matrix} \begin{matrix} [A^{-1}] \\ 8 \times 8 \end{matrix} \quad (14)$$

$$\begin{matrix} \{Q\} \\ 8 \times 1 \end{matrix} \equiv \begin{matrix} \left\{ \begin{matrix} Q_1 \\ Q_2 \end{matrix} \right\} \\ 6 \times 1 \\ 2 \times 1 \end{matrix} = \begin{matrix} [A^{-1}]^T \\ 8 \times 8 \end{matrix} \begin{matrix} \left\{ \begin{matrix} Q_1 \alpha \\ Q_2 \alpha \end{matrix} \right\} \\ 6 \times 1 \\ 2 \times 1 \end{matrix}$$



where

$\{Q_1\}$  are the equivalent generalized loads acting on the external nodes  
6x1

and

$\{Q_2\}$  are the loads acting on the two internal nodes.

In (14) the matrices  $[k]$  and  $\{Q\}$  are defined in local Cartesian coordinates  $(\xi, \eta)$ . In order to assemble the elements, these matrices must be expressed in global coordinates.

Two different sets of global coordinates are considered in this formulation:

(a) For the analysis of axisymmetric shells with discontinuous meridional slope, the  $(r, z)$  coordinates are taken as the global coordinates, Fig. 4(a). The required transformation can be stated as:

$$\begin{matrix} \begin{Bmatrix} u_i \\ u_j \\ u_k \end{Bmatrix} \\ 8 \times 1 \end{matrix} = \begin{matrix} \begin{bmatrix} T_i & 0 & 0 \\ 0 & T_j & 0 \\ 0 & 0 & I \end{bmatrix} \\ 8 \times 8 \end{matrix} \begin{matrix} \begin{Bmatrix} r_i \\ r_j \\ r_k \end{Bmatrix} \\ \begin{matrix} 3 \times 1 \\ 3 \times 1 \\ 2 \times 1 \end{matrix} \end{matrix} \quad (15)$$

where

$$\{r\}^T = \langle u_r^i \ u_z^i \ \chi^i : u_r^j \ u_z^j \ \chi^j : u_1^m \ u_1^n \rangle ,$$

$I$  is an identity matrix, and  $T$  has the following form:

$$T_i = T_j = \begin{bmatrix} \sin \psi & -\cos \psi & 0 \\ \cos \psi & \sin \psi & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad (16)$$

The angle  $\psi$  is defined in Fig. 4(a).

(b) For the analysis of shells with continuous meridional slope, the (U, W) coordinates are taken as the global coordinates, Fig. 4(b). The transformation is similar to (15) except that:

$$\{r\}^T = \langle U^i \ W^i \ \chi^i \ : \ U^j \ W^j \ \chi^j \ : \ u_1^m \ u_1^n \rangle ,$$

$$T_i = \begin{bmatrix} \cos \beta_i & -\sin \beta_i & 0 \\ \sin \beta_i & \cos \beta_i & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad (17)$$

and an expression similar to (17) applies for  $T_j$ , where the slope,  $\tan \beta$ , of the meridional curve is expressed in local  $(\xi, \eta)$  coordinates.

For the cap element, the top left corner sub-matrix,  $T_i$ , in (15) is replaced by an identity matrix in both cases (a) and (b).

Either in case (a) or (b), the element stiffness matrix and the load vector, Equations (14), are transformed into global coordinates using the following relations:

$$\begin{aligned} [k]_G &= [M]^T [k]_L [M] \\ 8 \times 8 & \quad 8 \times 8 \quad 8 \times 8 \quad 8 \times 8 \end{aligned} \quad (18)$$

$$\{R\} \equiv \{Q\}_G = [M]^T \{Q\}_L$$

where letters L and G signify the local and global coordinate, respectively, and M is the transformation matrix defined in (15).

Before proceeding with the actual assembly of the stiffness

matrices, the terms in (18) corresponding to the internal degrees of freedom must be condensed out from  $[K]_G$  and  $\{R\}$ . This operation is discussed in the following section.

STATIC CONDENSATION

The equilibrium equations for an element in global coordinates can be written as

$$\begin{matrix} [k] & \{r\} & = & \{R\} \\ 8 \times 8 & 8 \times 1 & & 8 \times 1 \end{matrix} \quad (19)$$

where for simplicity in subsequent discussion subscripts G have been deleted from all quantities.

Equation (19) can be partitioned to distinguish between the terms corresponding to the external and the internal degree of freedom.

Thus, one has

$$\begin{matrix} \begin{bmatrix} k_{11} & \vdots & k_{12} \\ \vdots & \ddots & \vdots \\ k_{21} & \vdots & k_{22} \end{bmatrix} & \begin{Bmatrix} r_1 \\ r_2 \end{Bmatrix} & = & \begin{Bmatrix} R_1 \\ R_2 \end{Bmatrix} \\ 6 \times 6 & 6 \times 2 & 6 \times 1 & 6 \times 1 \\ 2 \times 6 & 2 \times 2 & 2 \times 1 & 2 \times 1 \end{matrix} \quad (19a)$$

where the subscript 2 designates the terms related to the two internal degrees of freedom. These terms can be removed as follows:

$$\{R_1\} = [k_{11}] \{r_1\} + [k_{12}] \{r_2\} \quad (20a)$$

$$\{R_2\} = [k_{21}] \{r_1\} + [k_{22}] \{r_2\} \quad (20b)$$

On solving (20b) for  $\{r_2\}$ , one has

$$\{r_2\} = [k_{22}]^{-1} \{R_2\} - [k_{22}]^{-1} [k_{21}] \{r_1\} \quad (20c)$$

whence on substituting into (20a) the expression for  $\{r_2\}$  from (20c)

$$[k_{11} - k_{12} k_{22}^{-1} k_{21}] \{r_1\} = \{R_1 - k_{12} k_{22}^{-1} R_2\} \quad (21)$$

which can be rewritten as

$$\begin{array}{ccc} [\underline{k}] & \{r_1\} & = \{R\} \\ 6 \times 6 & 6 \times 1 & 6 \times 1 \end{array} \quad (21a)$$

where  $[\underline{k}]$  and  $\{R\}$  are the condensed stiffness matrix and load vector, respectively, and are defined in (21). The matrix multiplications and inversion involved in the process of condensation can be done directly since the only matrix to be inverted is only a  $2 \times 2$ .

The condensed  $\underline{k}$  and  $\underline{R}$  must be found for all elements and assembled according to the well established procedures of the direct stiffness method. The resulting equilibrium equations for the assemblage of the elements are:

$$\begin{array}{ccc} [K] & \{r\} & = \{R\} \\ N \times N & N \times 1 & N \times 1 \end{array} \quad (22)$$

where  $N = 3 \times$  (total number of nodes), and the stiffness matrix  $K$  is a banded symmetric matrix having a width of 6.

Equations (22), after being modified for the geometric boundary conditions, can be solved by a process of Gauss elimination and back substitution to obtain the displacement vector  $\{r\}$ . This vector  $\{r\}$  contains the displacements occurring at the external degrees of freedom. The displacements at the internal degrees of freedom are needed to complete the solution. For each element, they are recovered, using (20c).

Using in sequence Eqs. (15), (13), (6), and (7), the stress field may be determined, and thus the solution of the problem becomes complete.

ANALYSIS OF ELASTIC-PLASTIC SHELLS OF REVOLUTION

The details of elastic-plastic analysis of shells of revolution, utilizing axisymmetric curved finite elements, has been fully described before [2, 4], and will not be elaborated upon here. Essentially, the theory discussed in this report is used to modify an existing computer program [3] into which the use of a refined element is incorporated. In addition, a second version of the program is so coded that the shells with discontinuous meridional slope can be analyzed. These programs are written in FORTRAN IV language, and their listings and user's guide are provided in Appendix IV, and V.

For the purpose of analysis, the shell must be subdivided into a number of elements. It is recommended to use smaller elements in the regions where high gradients of displacements are anticipated. Drastic changes in the size of neighboring elements should be avoided. For a closed shell, numbering of the nodal circles should be started from the point on the axis of symmetry.

The shell is assumed to be initially stress free. After the first increment of loading is applied, the magnitude of the load is so scaled that plastic deformation just sets-in in some region of the shell. This constitutes an elastic analysis of the system. In the remainder of the elastic-plastic analysis, the loading is continued in small increments.

## EXAMPLES

### 1. Shells with Continuous Meridional Slope

#### A Pressure Vessel with a Torispherical Head

Consider a typical torispherical pressure vessel head attached to a long cylinder, as shown in the insert of Fig. 5. Let the diameter  $D$  of the head skirt be 100 in., the radius of the spherical crown  $L = D$ , the radius of the toroidal part  $r = 0.06 D$ , and the shell thickness  $h = 0.008$ . These proportions of the head conform to the 1965 ASME Code for Unfired Pressure Vessels. The material of the shell is assumed to be elastic-perfectly plastic, with  $E = 30 \times 10^6$  psi,  $\nu = 0.3$ , and yield stress,  $\sigma_y = 30,000$  psi.

This vessel under a uniform internal pressure has been previously analyzed [1] using the old finite element. The elastic-plastic analysis is repeated here using the new refined finite-element. The same element layout and load increment sizes were used in both solutions. The results of the two analyses are shown in Figs. 5 through 8.

Figures 5 and 6 show the meridional in-plane force and moment, respectively. The curves are plotted for the elastic-limit pressure of 104 psi, and an elastic-plastic load of 204 psi.

Comparison of the two solutions in Figs. 5 and 6 clearly shows the improvements obtained by using the refined element. The dips in the curves of  $N_s$ , Fig. 5, at the junctures of torus with the sphere and cylinder are smoothed out. The refined element also gives smoother variation of  $M_s$  in the vicinity of the juncture of the torus and the cylinder, Fig. 6.

A comparison of the two load-deflection curves in Fig. 7 shows a

better convergence with the refined elements.\* The gradual spread of elastic-plastic zones with increasing internal pressure, as obtained in the two solutions, is shown in Fig. 8. Although the pattern of plastic propagation remains essentially alike in the two solutions, the new solution shows a somewhat faster rate of plastification. Stated alternatively, at the same load level, more material appears to be plastified according to the new solution. The first hinge circle forms at an internal pressure of  $1.69 p^E$  and  $1.79 p^E$  according to new and old solutions, respectively.

## 2. Shells with Discontinuous Meridional Slope

### A Pressure Vessel with a Shallow Spherical Head

Consider a cylindrical pressure vessel with a shallow spherical cap of radius  $L = D/(2 \sin \varphi_0) = 100$  in. as shown in the insert of Fig. 9. Let  $\varphi_0 = 45^\circ$  and the shell thickness  $h = 0.02 D$ , where  $D$  is the diameter of the cylindrical vessel. The material of the shell is assumed to be elastic-perfectly plastic, with  $E = 30 \times 10^6$  psi,  $\nu = 0.3$ , and yield stress,  $\sigma_y = 30,000$  psi.

For the purposes of analysis, the vessel was divided into 22 uneven elements - 12 in the spherical cap, and 10 in the cylindrical body. A total of 16 load increments were used, starting from the elastic limit load of 53.5 psi.

Some results of the elastic-plastic analysis are shown in Figs. 9 through 12. The meridional moment and the in-plane force distributions are plotted in Figs. 9 and 10, respectively. The curves

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\* The results of a convergence study [2,4] indicate that the new load-deflection curve, Fig. 7, could have been obtained if the old elements were used with much smaller load increments.



correspond to an elastic limit load of 53.5 psi, and an elastic-plastic load of 114 psi. At the latter pressure, according to present analysis, the first hinge circle is formed. The sharp peak in  $M_s$ , Fig. 19, and the high compressive circumferential forces  $N_\theta$ , Fig. 10(b), at and near the juncture of the head with the cylinder show the undesirable features of this type of an attachment.

Due to the discontinuity in the slope of the meridian at the juncture between the head and the cylinder, there is a slight discontinuity in  $N_s$  at the same point, Fig. 10(a). Here equilibrium is satisfied by the presence of transverse shear forces.

The inelastic moment and in-plane force distribution retain in general their elastic trends. However, due to plastic flow, there is some stress redistribution. The drastic change in the magnitude of  $N_\theta$  at the juncture of the head and the cylinder, Fig. 10(b), is due to the formation of a narrow plastic band in this zone. As the width of this plastic region increases, the negative peaks of  $N_\theta$  are shifted further apart into the cylinder and the spherical head. This phenomenon can be explained by noting the fact that the state of stress of the points outside the plastic region falls inside the yield surface, and these stresses can increase at an elastic rate, whereas the stress paths of the points in the plastic region are constrained to follow the boundary of the yield surface, resulting in a slower rate of increase and decrease in the magnitude of the forces in the meridional and circumferential directions, respectively.

Figure 11 shows the load deflection characteristics of the analyzed pressure vessel. The progressive yielding within the wall

thickness of the vessel is illustrated in Figure 12. The yielding starts at the inner face of the juncture, and with increasing internal pressure propagates across the thickness and along the shell. The first hinge circle is formed at an internal pressure of 114 psi or  $2.13 p^E$ .

CONCLUSIONS

A modified version of the Khojasteh-Bakht axisymmetric shell element is developed for elastic-plastic analysis of shells of revolution. With a limited amount of extra work involved, the modified element proves to be superior to the old element in the following respects.

(a) The internal forces are computed more accurately. This is especially true in the case of in-plane forces. The inter-element force equilibrium is greatly improved so that the analysis of shells with discontinuous meridional slope is possible without the danger of getting inaccurate results at the discontinuities.

(b) The rate of convergence is also improved, making it possible to choose a smaller number of elements and/or fewer load increments to obtain comparable results with those one might get using the old element.

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- [1] Popov, E. P., Khojasteh-Bakht, M., Sharifi, P., "Elastic-Plastic Analysis of Some Pressure Vessel Heads," ASME paper No. 69-WA/PVP-7, presented at the Winter Annual Meeting in Los Angeles, Nov. 1969.
- [2] Khojasteh-Bakht, M., "Analysis of Elastic-Plastic Shells of Revolution Under Axisymmetric Loading by the Finite Element Method," Report SESM 67-8, Structural Eng. Lab., Univ. of Calif., Berkeley, April 1967. Also available as NASA Report CR-85735.
- [3] Khojasteh-Bakht, M., "Computer Program for Elastic-Plastic Analysis of Axisymmetrically Loaded Shells of Revolution," Report SESM 68-3, Struct. Eng. Lab., Univ. of Calif., Berkeley, April 1968.
- [4] Khojasteh-Bakht, M., Popov, E. P., "Analysis of Elastic-Plastic Shells of Revolution," ASCE J. of Eng. Mech. Div. (in press; scheduled for publication April 1970).

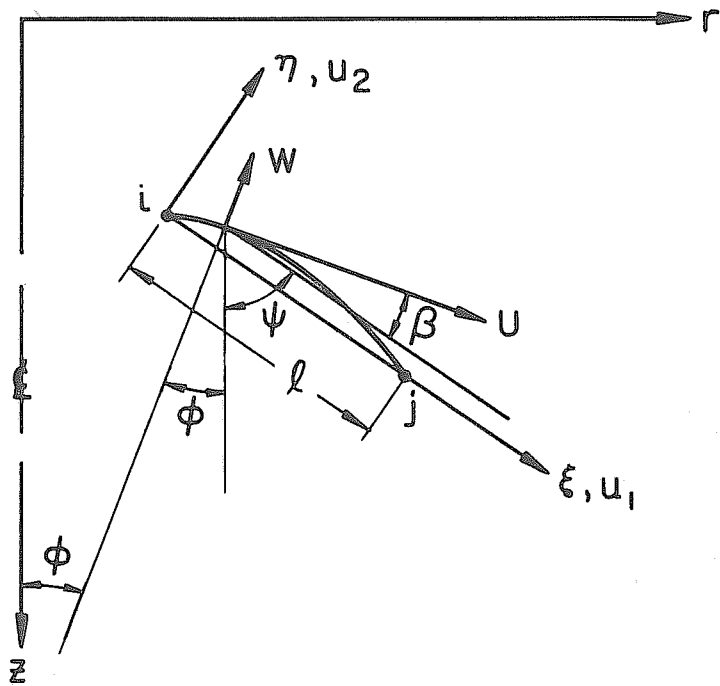


FIG. 1 GEOMETRY OF DISPLACEMENTS OF A CURVED ELEMENT

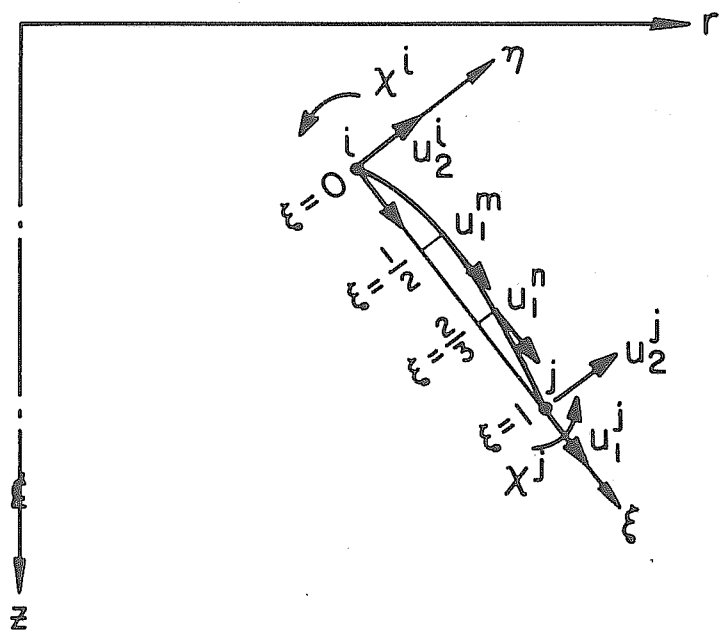


FIG. 2 INTERNAL AND EXTERNAL DEGREES OF FREEDOM

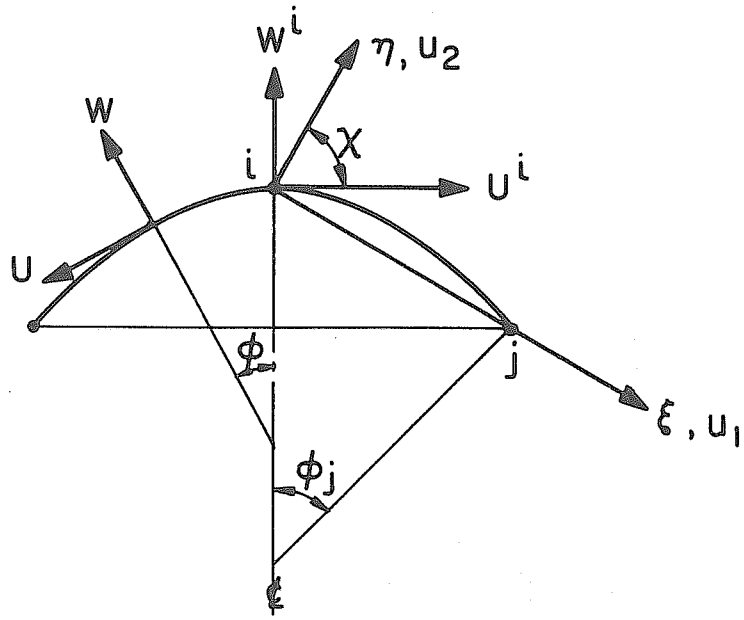
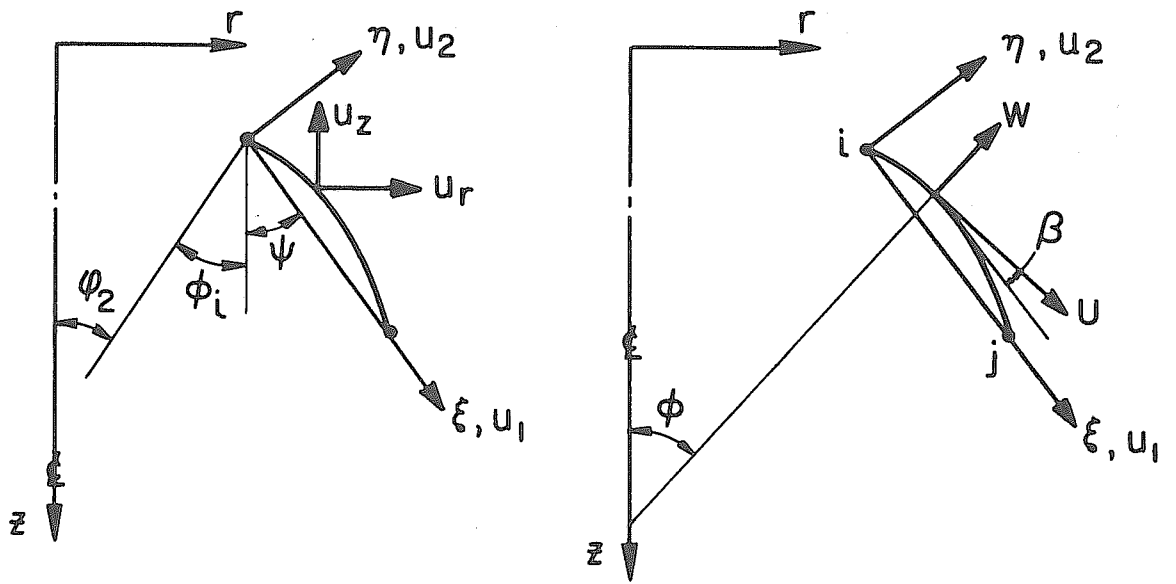


FIG. 3 CENTRAL CAP ELEMENT



(a)  $(r, z)$  Global Coordinates

(b)  $(U, W)$  Global Coordinates

FIG. 4 GLOBAL AND LOCAL COORDINATES

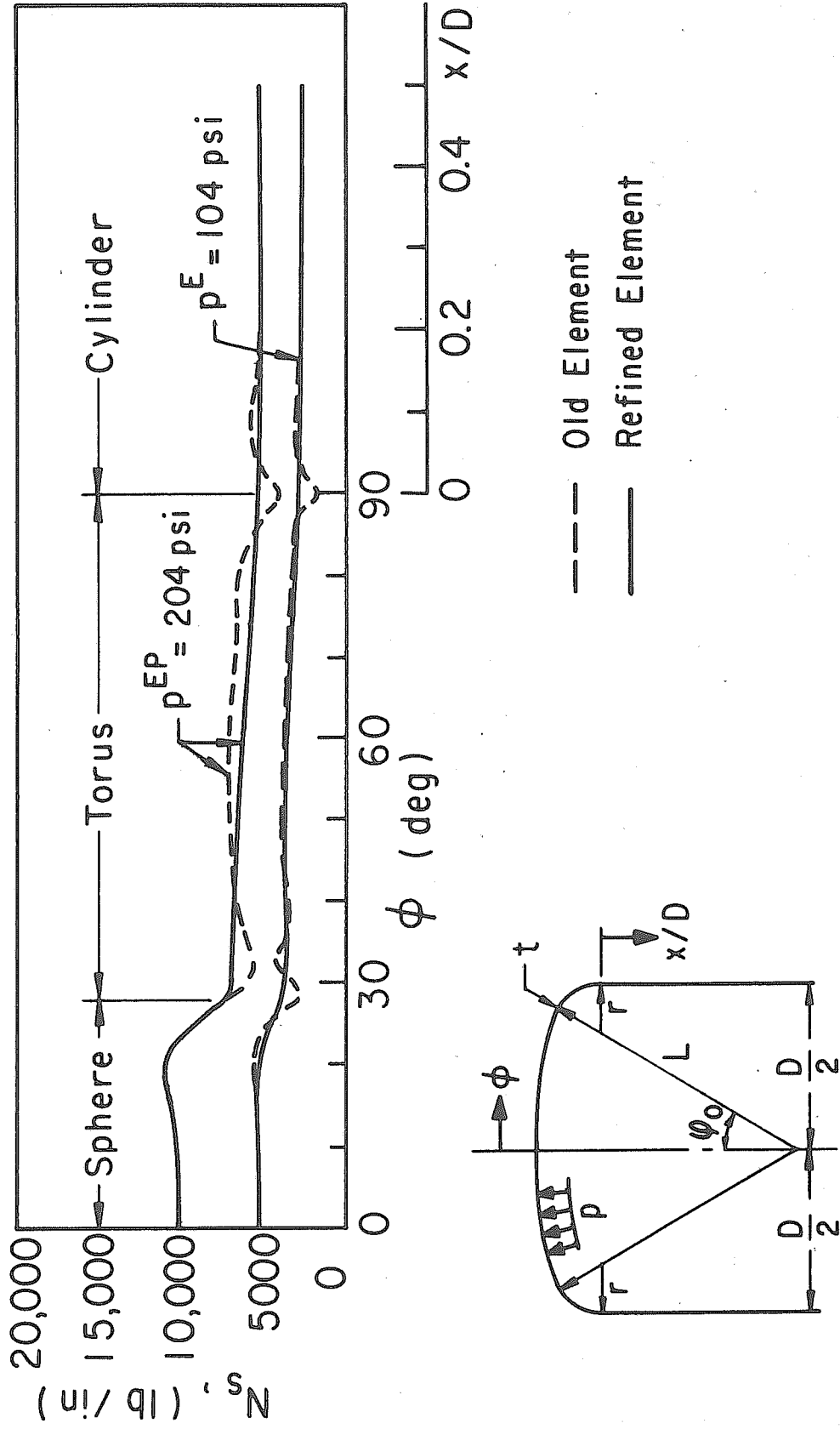


FIG. 5 MERIDIONAL IN-PLANE FORCE IN A TORISPHERICAL HEAD

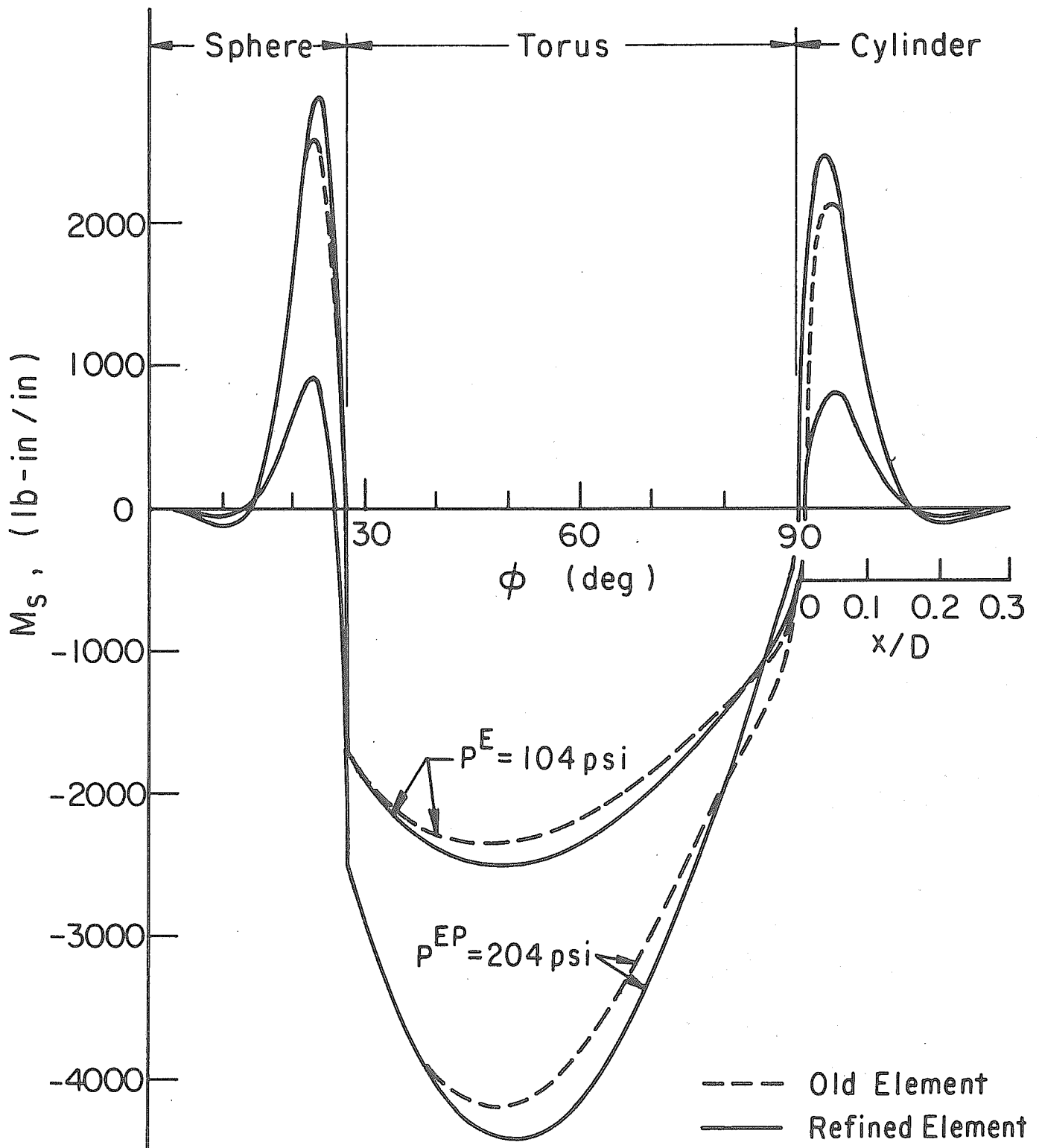


FIG. 6 MERIDIONAL MOMENT IN A TORI SPHERICAL HEAD WITH  $D=L=100$  in.,  $r/L=0.06$ , AND  $t/L=0.008$



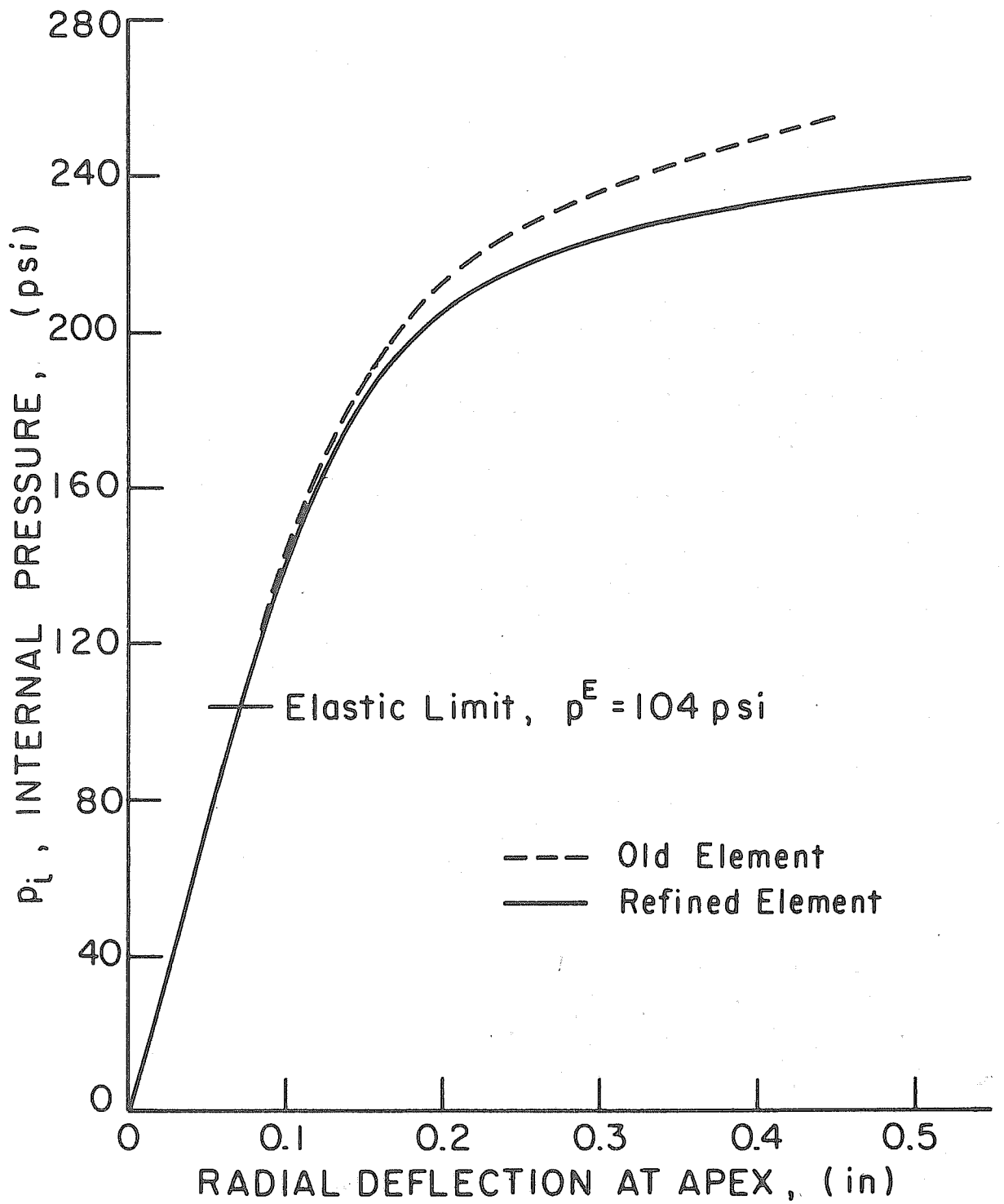


FIG. 7 LOAD DEFLECTION CHARACTERISTICS TORISPHERICAL HEAD

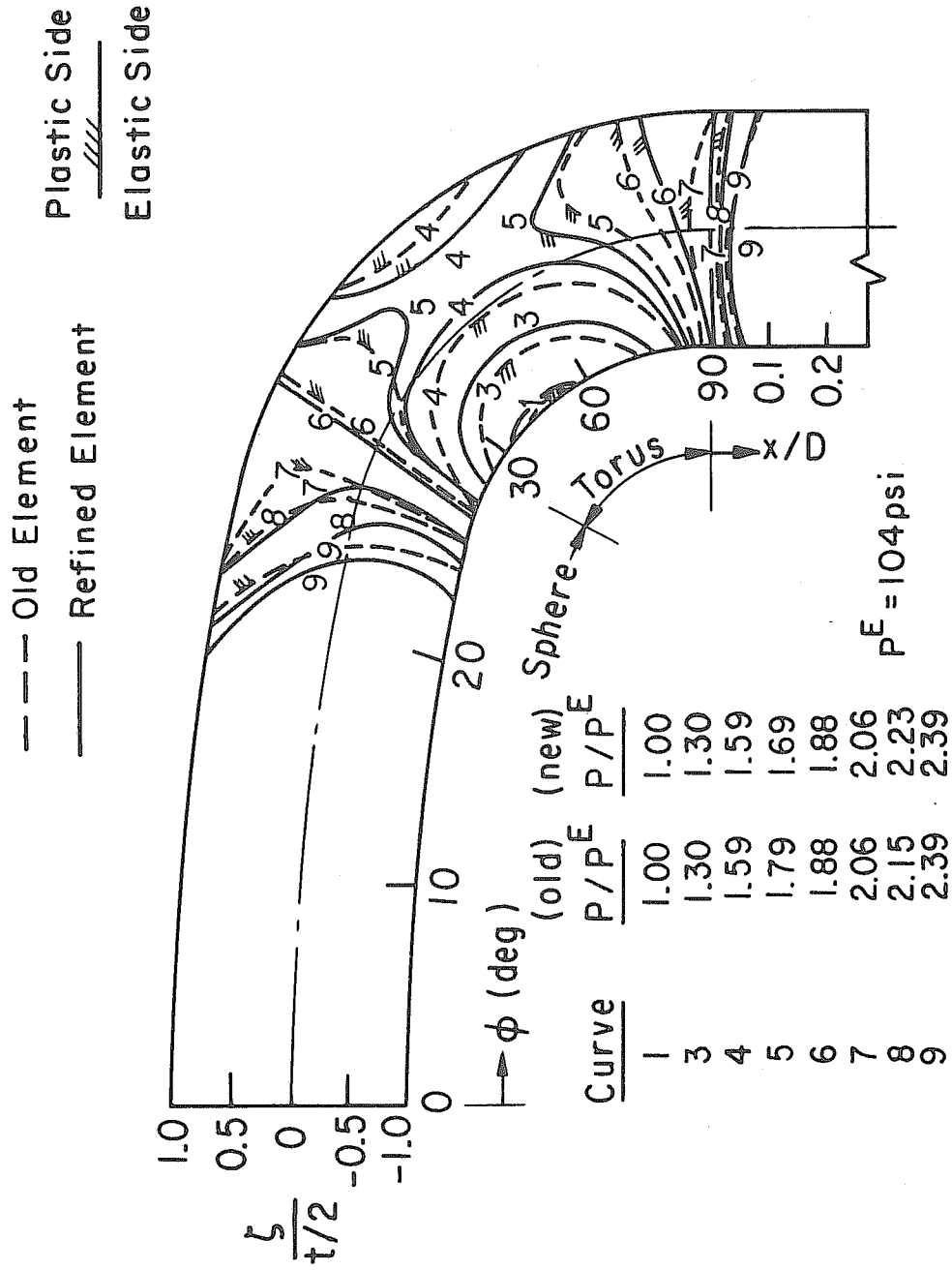


FIG. 8 ELASTIC PLASTIC BOUNDARIES

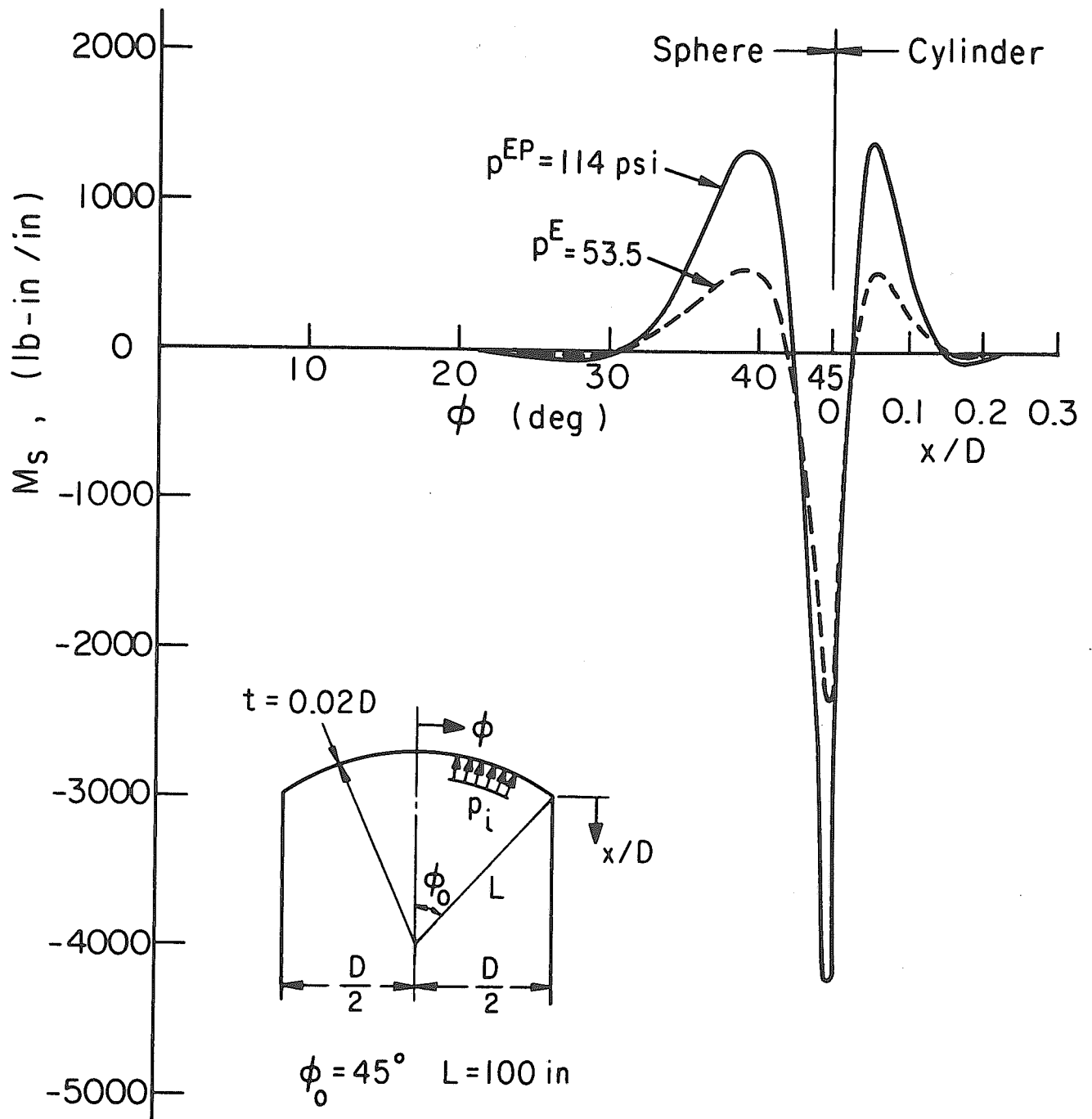


FIG. 9 MERIDIONAL MOMENTS

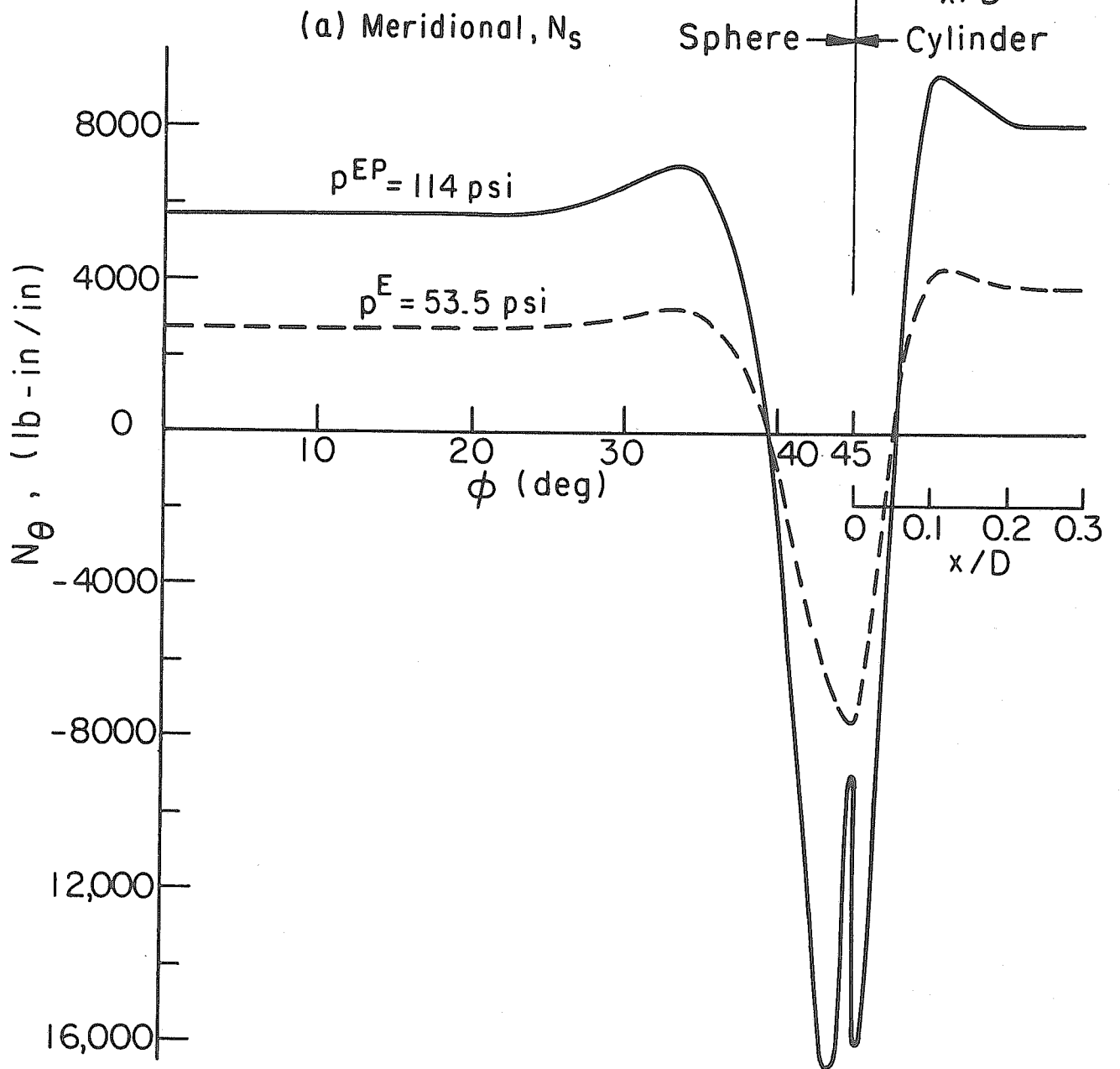
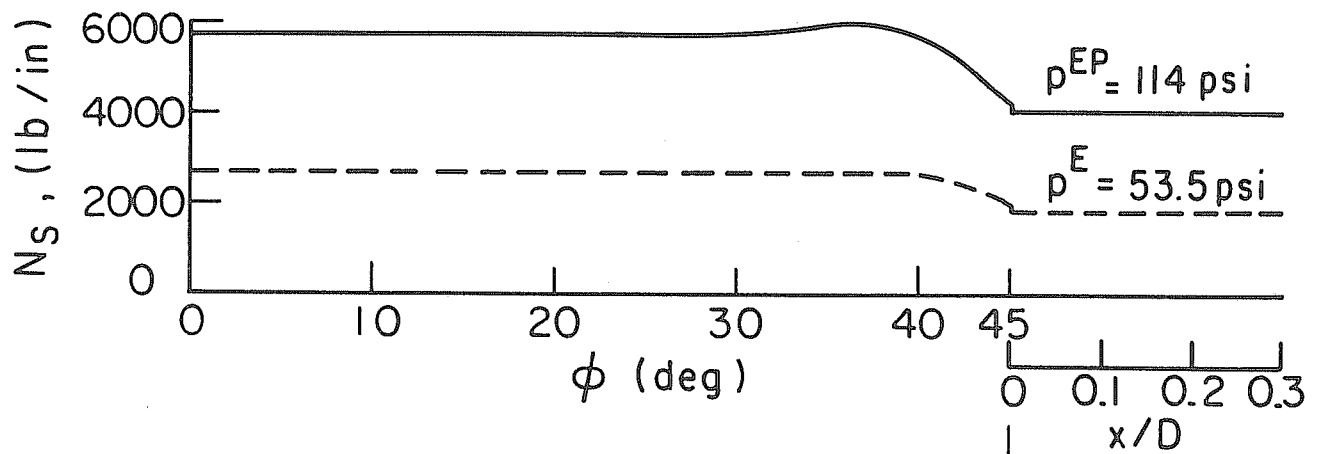


FIG. 10 IN-PLANE FORCES

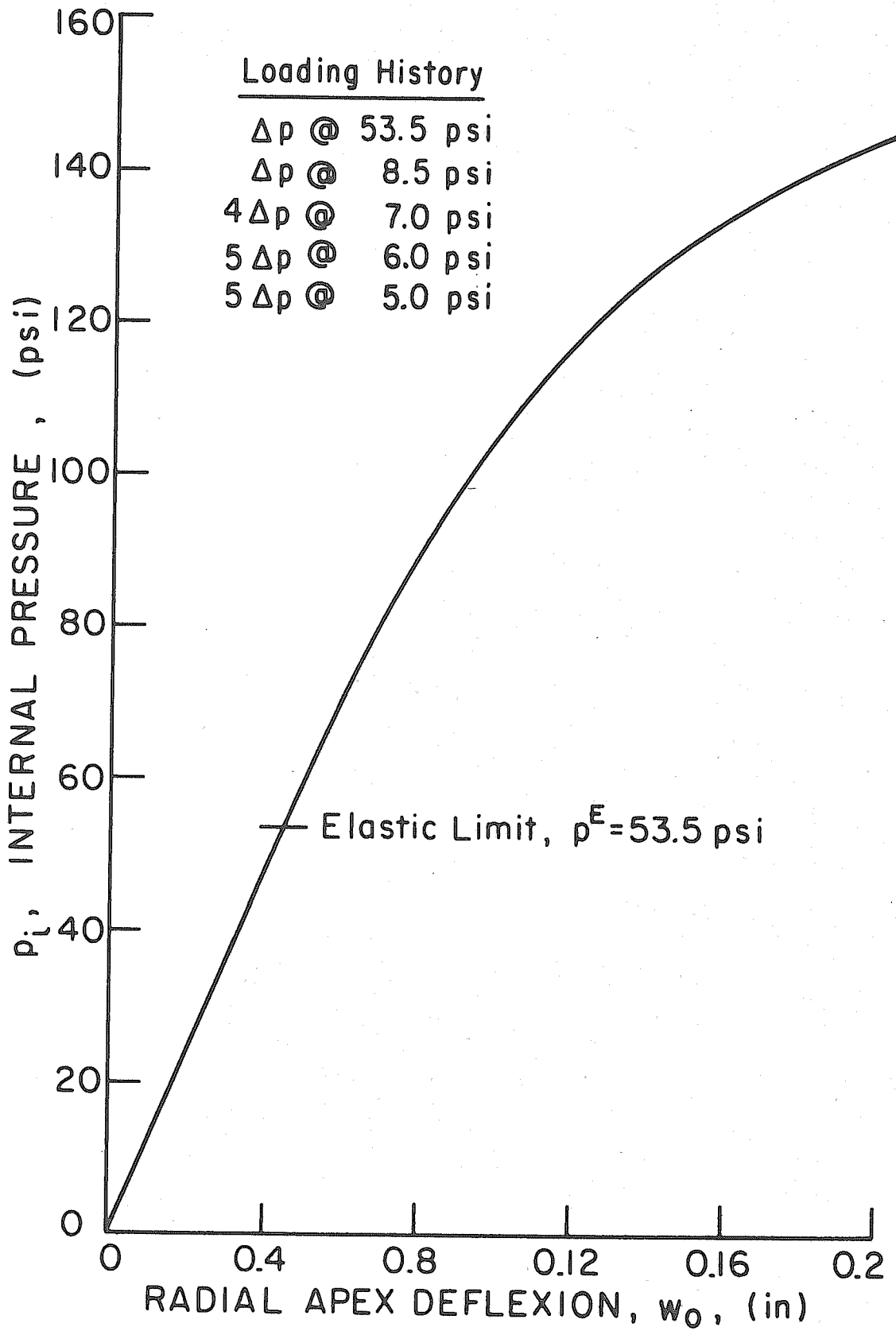


FIG. II LOAD DEFLECTION CHARACTERISTICS

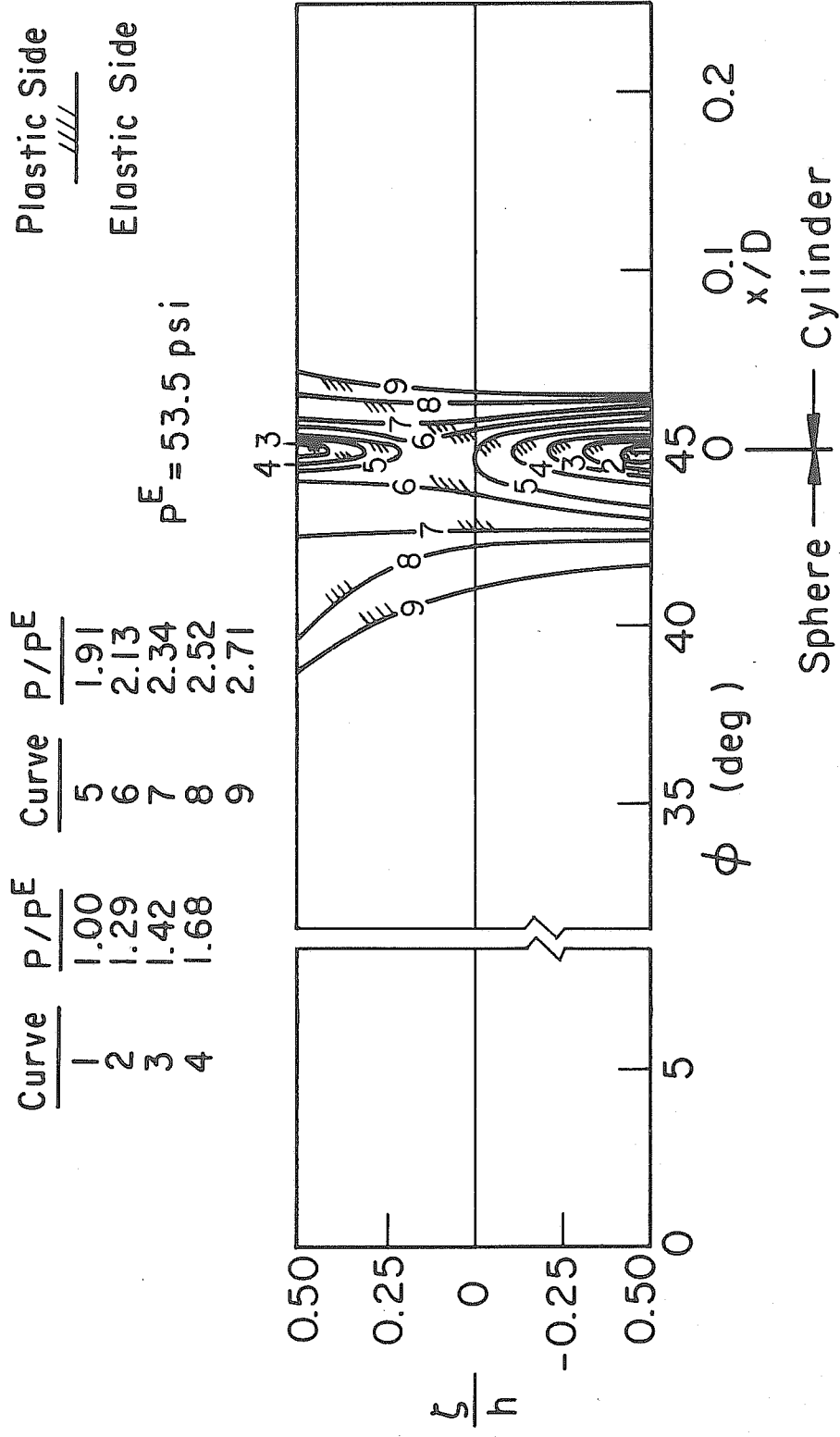


FIG. 12 ELASTIC PLASTIC BOUNDARIES

APPENDIX I

MATRIX [B], Eq. (6)

1 - CAP ELEMENT

$$\begin{bmatrix}
 0 & 0 & 0 & \rho(1+\eta'\tan\beta_1) & 2\xi\rho & 3\xi^2\rho & 2\xi\eta'\rho & 3\xi^2\eta'\rho \\
 0 & 0 & 0 & \frac{\cos\varphi_1}{\bar{r}\cos\beta_1} & \frac{\xi\sin\psi}{\bar{r}} & \frac{\xi^2\sin\psi}{\bar{r}} & \frac{\xi\cos\psi}{\bar{r}} & \frac{\xi^2\cos\psi}{\bar{r}} \\
 0 & 0 & 0 & \Phi(1+2\eta'\tan\beta_1-\eta'^2) & \Omega+2(1-\eta'^2)\xi\Phi & 3\xi[\Omega+\xi(1-\eta'^2)\Phi] & 4\xi\eta'\Phi-\mu & 3\xi(2\xi\eta'\Phi-\mu) \\
 0 & 0 & 0 & \frac{\eta'-\tan\beta_1}{\xi}\psi & 2\eta'\psi & 3\xi\eta'\psi & -2\psi & -3\xi\psi
 \end{bmatrix}$$

where  $\bar{r} = \frac{r}{\xi}$ , Note  $r(0) = 0$

$$\rho = \frac{1}{\ell(1+\eta')^2} ; \quad \mu = \frac{2}{\ell^2(1+\eta')^2}$$

$$\Phi = \frac{\eta''}{\ell^2(1+\eta')^2} ; \quad \psi = \frac{\sin\psi+\eta'\cos\psi}{\ell\bar{r}(1+\eta')^2} ; \quad \Omega = \frac{2\eta'}{\ell^2(1+\eta')^2}$$

Continued/

2 - FRUSTUM ELEMENT, [B]

$$\begin{bmatrix} 0 & \rho & 25\rho & 3\xi^2\rho & 0 & \eta'\rho & 25\eta'\rho & 3\xi^2\eta'\rho \\ \frac{\sin\psi}{r} & \frac{\sin\psi}{r}\xi & \frac{\sin\psi}{r}\xi^2 & \frac{\sin\psi}{r}\xi^3 & \frac{\cos\psi}{r} & \frac{\cos\psi}{r}\xi & \frac{\cos\psi}{r}\xi^2 & \frac{\cos\psi}{r}\xi^3 \\ 0 & (1-\eta'^2)\Phi & 25(1-\eta'^2)\Phi+\Omega & 3\xi[\xi(1-\eta'^2)\Phi+\Omega] & 0 & 2\eta'\Phi & 45\eta'\Phi-\mu & 3\xi(25\eta'\Phi-\mu) \\ 0 & \eta'\psi & 25\eta'\psi & 3\xi^2\eta'\psi & 0 & -\psi & -25\psi & -3\xi^2\psi \end{bmatrix}$$

where

$$\psi = \frac{\sin\psi+\eta'\cos\psi}{2} \frac{3/2}{\ln(1+\eta')}; \quad \text{The rest are defined in previous page.}$$



APPENDIX IIMATRIX  $[\varphi]$ , Eq. (9)

1 - CAP ELEMENT

$$\begin{pmatrix} 0 & 0 & -\cos \psi & \xi & \xi^2 & \xi^3 & 0 & 0 \\ 0 & 0 & \sin \psi & \xi \tan \beta_i & 0 & 0 & \xi^2 & \xi^3 \\ 0 & 0 & 0 & \rho(\tan \beta_i - \eta') & -2\xi\eta'\rho & -3\xi^2\eta'\rho & 2\xi\rho & 3\xi^2\rho \end{pmatrix}$$

2 - FRUSTUM ELEMENT

$$\begin{pmatrix} 1 & \xi & \xi^2 & \xi^3 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & \xi & \xi^2 & \xi^3 \\ 0 & -\eta'\rho & -2\xi\eta'\rho & -3\xi^2\eta'\rho & 0 & \rho & 2\xi\rho & 3\xi^2\rho \end{pmatrix}$$

where

$$\rho = \frac{1}{l(1 + \eta'^2)}$$

APPENDIX III

MATRIX [A], Eq. (12)

I - CAP ELEMENT

0	0	0	0	0	0	0	0	0	0
0	0	1	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	$-\cos \psi$	1	1	1	1	1	1	1
0	0	$\sin \psi$	$\tan \beta_i$	0	0	0	0	1	1
0	0	0	$(\frac{\tan \beta_i - \tan \beta_j}{l}) \cos^2 \beta_j$	$\frac{-2 \sin \beta_j \cos \beta_j}{l}$	$\frac{-3 \sin \beta_j \cos \beta_j}{l}$	$\frac{2 \cos^2 \beta_j}{l}$	$\frac{3 \cos^2 \beta_j}{l}$		
0	0	$-\cos \psi$	1/3	1/9	1/27	0	0		
0	0	$-\cos \psi$	2/3	4/9	8/27	0	0		

NOTE that for cap element  $\{u_i\}^T = \langle u^i w^i X^i \rangle$  in (U,W) coordinates.

Continued/

2 - FRUSTUM ELEMENT, [A]

1	0	0	0	0	0	0	0	0	0
0	0	0	0	1	0	0	0	0	0
0	$\frac{-\sin \beta_i \cos \beta_i}{l}$	0	0	0	$\frac{\cos^2 \beta_i}{l}$	0	0	0	0
1	1	1	1	0	0	0	0	0	0
0	0	0	0	1	1	1	1	1	1
0	$\frac{-\sin \beta_j \cos \beta_j}{l}$	$\frac{-2 \sin \beta_j \cos \beta_j}{l}$	$\frac{-3 \sin \beta_j \cos \beta_j}{l}$	0	$\frac{\cos^2 \beta_j}{l}$	$\frac{2 \cos^2 \beta_j}{l}$	$\frac{3 \cos^2 \beta_j}{l}$	0	0
1	1/3	1/9	1/27	0	0	0	0	0	0
1	2/3	4/9	8/27	0	0	0	0	0	0

Continued/

MATRIX  $[A]^{-1}$ , Eq. (13)

1 - CAP ELEMENT

0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	1	0	0	0	0	0	0	0	0
0	$5.5 \cos \psi$	0	1	0	0	0	9	-4.5	
0	$-9.0 \cos \psi$	0	-4.5	0	0	0	-22.5	18.	
0	$4.5 \cos \psi$	0	4.5	0	0	0	13.5	-13.5	
0	$-\cos \psi(11 \tan \beta_i + \tan \beta_j)$	0	$-2 \tan \beta_i$	3	$-\mathcal{L}(1 + \tan^2 \beta_j)$		$-18 \tan \beta_i$	$9(\tan \beta_i + \tan \beta_j)$	
0	$-3 \sin \psi$		$-5.5 \tan \beta_j$				$-4.5 \tan \beta_j$		
0	$\cos \psi(5.5 \tan \beta_i + \tan \beta_j)$	0	$\tan \beta_i$	-2	$\mathcal{L}(1 + \tan^2 \beta_j)$		$9 \tan \beta_i$	$-4.5 \tan \beta_i$	
	$+ 2 \sin \psi$		$+5.5 \tan \beta_j$				$+4.5 \tan \beta_j$	$-9 \tan \beta_j$	

Continued/

2 - FRUSTUM ELEMENT,  $[A^{-1}]$

1	0	0	0	0	0	0	0	0	0
-5.5	0	0	1	0	0	0	9	-4.5	
9	0	0	-4.5	0	0	0	-22.5	18	
-4.5	0	0	4.5	0	0	0	13.5	-13.5	
0	1	0	0	0	0	0	0	0	
$-5.5 \tan \beta_i$	0	$\ell(1 + \tan^2 \beta_i)$	$\tan \beta_i$	0	0	0	$9 \tan \beta_i$	$-4.5 \tan \beta_i$	
$11 \tan \beta_i$ + $\tan \beta_j$	-3	$-2\ell(1 + \tan^2 \beta_i)$	$-2 \tan \beta_i$ $-5.5 \tan \beta_j$	3	$-\ell(1 + \tan^2 \beta_j)$	0	$-18 \tan \beta_i$ $-4.5 \tan \beta_j$	$9(\tan \beta_i + \tan \beta_j)$	
$-5.5 \tan \beta_i$ $-\tan \beta_j$	2	$\ell(1 + \tan^2 \beta_i)$	$\tan \beta_i$ $+5.5 \tan \beta_j$	-2	$\ell(1 + \tan^2 \beta_j)$	0	$9 \tan \beta_i$ $+4.5 \tan \beta_j$	$-4.5 \tan \beta_i$ $-9 \tan \beta_j$	

APPENDIX IV  
USER'S GUIDE

A. Elastic-Plastic Analysis of Axisymmetric Shells with Continuous Meridional Slope

Input Data Instructions

1. Number of Input Control Card (I5)

Col. 1 to 5 - number of structural systems to be analyzed at the same time in one run

Note: Only one card is necessary for any number of input structural systems

2. Title Card (I2A6)

Col. 1 to 72 - alphameric information to be printed in the output

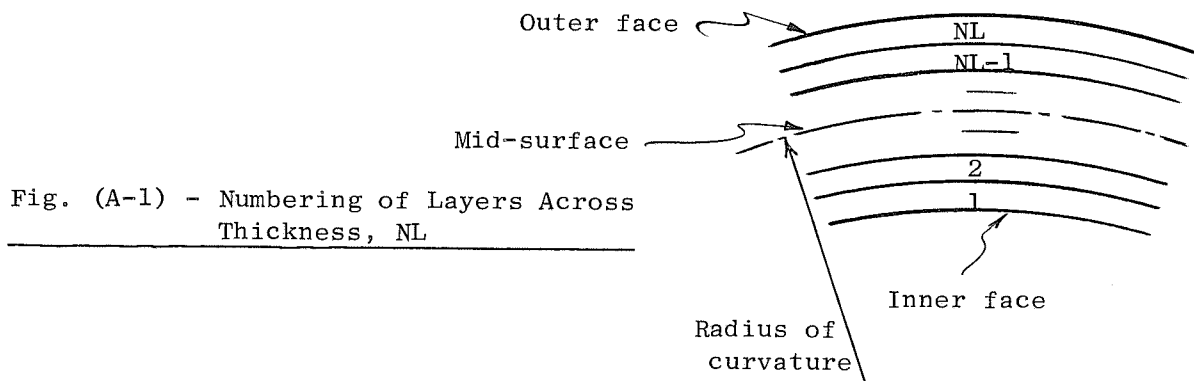
3. Control Card (4I5)

Col. 1 to 5 - NN, number of nodal circles (max. 50)

Col. 6 to 10 - NL, number of layers in shell thickness h (max. 20)

Col. 11 to 15 - NLI, number of load increments

Col. 16 to 20 - NUMBC, number of constrained nodes (max. 5)



4. Nodal Coordinate Cards (4F15.0)

One card for each nodal point (total of NN)

## 4. (Cont'd)

Col. 1 to 15 -  $r_i$ , radical coordinate of the node

Col. 16 to 30 -  $z_i$ , vertical coordinate of the node

Col. 31 to 45 -  $\text{PHI}_i$ , latitude angle  $\varphi_i$  of node

Col. 46 to 60 -  $H_i$ , shell thickness at node  $i$

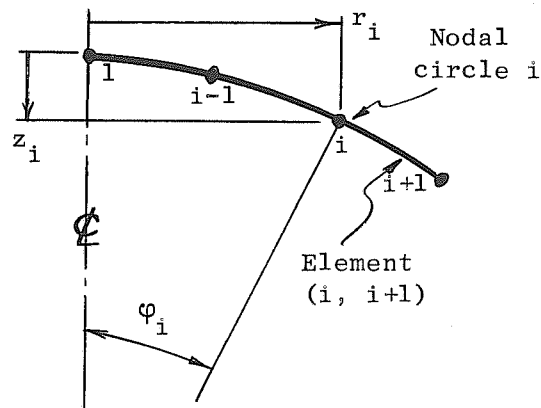


Fig. (A-2) - Nodal Coordinate Sign Convention

5. Element Curvature Cards (2F15.0)

One for each element (total of NN-1)

Col. 1 to 15 -  $\text{CRV}(m,i)$ , Meridional Curvature at  $i$  of element  $(i, i+1)$

Col. 16 to 30 -  $\text{CRV}(m, i+1)$ , Meridional Curvature at  $i+1$  of element  $(i, i+1)$

6. Material Index Card (I5)

Col. 1 to 5 - NP, number of points which describe the  $\sigma - \epsilon$  relation ( $\text{NP} \geq 2$ )

7. Material Property Card (3E15.0)

(Total of NP cards) describing  $\epsilon_i, \sigma_i, E_i$  at each station starting from  $\epsilon_1 = 0, \sigma_1, E_1^t$ , (elastic limit)

Col. 1 to 15 -  $\epsilon_i$ , strain at  $i$

Col. 16 to 30 -  $\sigma_i$ , stress at  $i$

Col. 31 to 45 -  $E_i^t$ , tangent modulus at  $i$

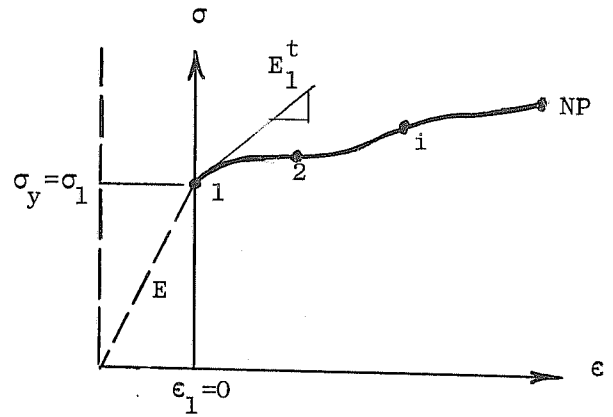


Fig. (A-3) - Stress-strain Diagram

8. Elastic Constants Card (E10.3, F5.0)

Col. 1 to 10 - E, Elastic Young's Modulus

Col. 11 to 15 -  $\nu$ , Poisson ratio

9. Boundary Conditions Cards (I4, 1X, 3I1)

(Total of NUMBC cards.) For closed top shells, the boundary condition at node 1 is not required.

Col. 1 to 4 -  $NBC_{(i)}$ , boundary node number

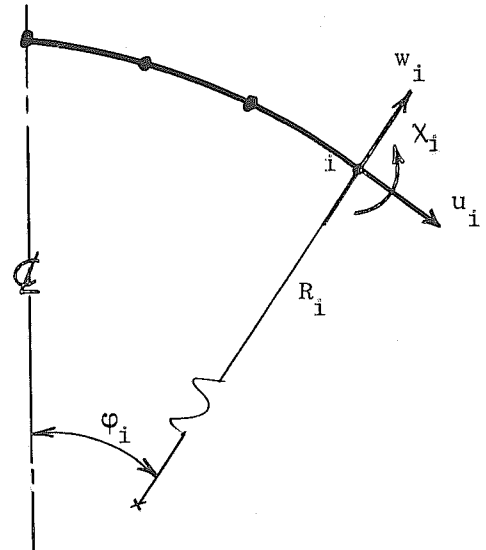
Col. 6 - NTAG(1), displacement  $u_i$  at boundary node  $i$

Col. 7 - NTAG(2), displacement  $w_i$  at boundary node  $i$

Col. 8 - NTAG(3), rotation  $\chi_i$  at boundary node  $i$

NTAG(i)  $\left\{ \begin{array}{l} = 1 \text{ constrained displacement or rotation} \\ = 0 \text{ free displacement or rotation} \end{array} \right.$

Fig. (A-4) - Sign Convention for Displacement and Rotation





10. Load Index Card (I5)

Col. 1 to 5 - INDEX, two cases may occur:

- A. INDEX = 0, (or blank) when non uniform and/or concentrated load is acting on shell. In this case, one must specify the magnitude of loads on all the nodes of shell - see 11.
- B. INDEX = number of uniformly loaded nodal points. This can occur when:
- 1) the entire shell is subjected to a uniformly distributed loading; or
  - 2) the top part of shell (say node 1 to n) is under a uniformly distributed load and no load is acting on the remainder of the shell. (Here INDEX = n.)

When Option B is used only one load card is the input and program will generate the same loading for all the INDEX nodes.

Note: When a concentrated load is acting anywhere, Option B cannot be used.

11. Nodal Load Card(s) (6E12.0)

If INDEX = 0 (or blank), one node-load card per node. If INDEX  $\neq$  0, only one load card is required.

Col. 1 to 12 - (meridional concentrated force,  $P_t$ )  $\times r_i$ ; where  $r_i$  is the radial coordinate of nodal circle (see Fig. 2)

Col. 13 to 24 - (radial concentrated force,  $P_r$ )  $\times r_i$

Col. 25 to 36 - (concentrated moment, M)  $\times r_i$

Col. 37 to 48 - meridional distributed force,  $p_t$  (force/area)

Col. 49 to 60 - radial distributed force,  $p_r$  (force/area)

Col. 61 to 72 - distributed moment, m (force-length/area)

- Note:
- a. In step 11, the intensity of load at the nodal points are the input; the program will compute the equivalent nodal loads.
  - b. Steps 10 and 11 must be repeated NLI times (see 3).
  - c. A concentrated force cannot be applied at the apex.
  - d. The concentrated loads must be multiplied by their respective radial distances from shell axis.

If more input is wanted, i.e., different structural systems are to be analyzed, card in step 1 is set equal to the number of input cases and steps 2-11 are repeated that many times.

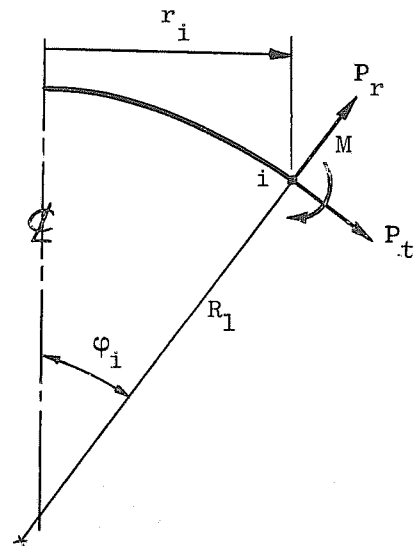


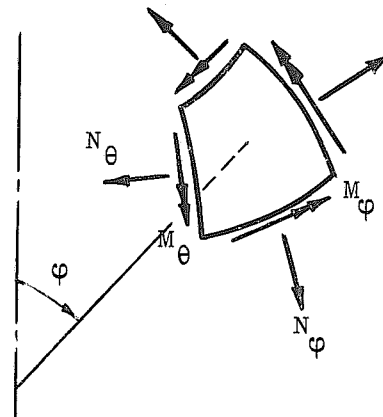
Fig. (A-5) - Nodal Load Sign Convention

Output Description

The following information is printed out on the basis of the above program:

1. Complete echo check of the input data
2. Computed nodal forces on system
3. Incremental and total magnitudes of:
  - a. Nodal displacements in u-w-X coordinates (see Fig. 4 for sign convention)
  - b. Nodal forces,  $N_\theta$ ,  $N_\varphi$ ,  $M_\theta$ ,  $M_\varphi$

Fig. (A-6) - Sign Convention for Output Forces



4. For each nodal point and at each layer across the thickness, the following quantities are output:
  - a. Increments of  $\epsilon_\theta$  and  $\epsilon_\varphi$
  - b. Total  $\sigma_\theta$ ,  $\sigma_\varphi$ ,  $\sigma_e$  (equivalent stress) and the modification factor.

$$M_F \begin{cases} = 1 & \text{if state of stress is inside the yield surface} \\ \neq 1 & \text{if state of stress is on the yield surface} \end{cases}$$

$$\sigma_e = (\sigma_\theta^2 + \sigma_\varphi^2 - \sigma_\theta \sigma_\varphi)^{\frac{1}{2}}$$

$\sigma_{\theta}$  - hoop stress

$\sigma_{\varphi}$  - meridional stress

$\epsilon_{\theta}, \epsilon_{\varphi}$  - hoop and meridional strains

Strain and stress are positive when tension.

B. Elastic-Plastic Analysis of Axisymmetric Shells with Discontinuous Meridional Slope

Input Data Instructions

1. (as before)\*

2. (as before)

3A. Control Card (5I5)

Col. 1 - 5 - NN, number of nodal circles (max 50)

Col. 6 - 10 - NL, number of layers in shell thickness (max 20), see Fig. (A-1)

Col. 11 - 15 - NLI, number of load increments

Col. 16 - 20 - NUMBC, number of constrained nodes (max 5)

Col. 21 - 25 - NDISC, number of nodes where meridional slope is discontinuous (max 5)

Note: More than one element should be laid out between any two consecutive discontinuities.

3B. Node Number Card (5I5)

The node numbers where slope is discontinuous (NDISC number).

4. One card for each element end (total of  $2(NN-1)$  cards).

Col. 1 - 15 -  $r_i$  (or  $r_j$ ), radial coordinate of node  $i$ , (or  $j$ )

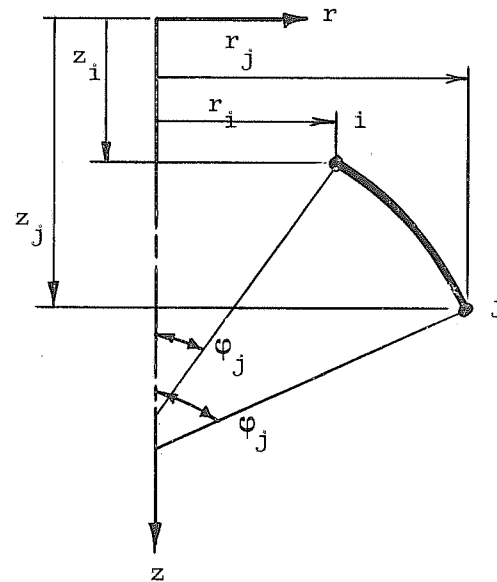
Col. 16 - 30 -  $z_i$  (or  $z_j$ ), vertical coordinate of node  $i$ , (or  $j$ )

Col. 31 - 45 -  $\phi_i$  (or  $\phi_j$ ), latitude angle (deg.) of node  $i$ , (or  $j$ )

Col. 46 - 60 -  $H_i$  (or  $H_j$ ), shell thickness at node  $i$ , (or  $j$ )

\* Refer to the instructions given under the same item number in part A of Appendix IV.

Fig. (B-1) - Nodal Coordinate Sign Convention



5, 6, 7, and 8. (as before)

9. Boundary Conditions Cards (I4, lX, 3Il)

Total of NUMBC cards. For closed top shells, the boundary condition at node 1 is not required.

Col. 1 - 4 - NBC(i), constrained node number

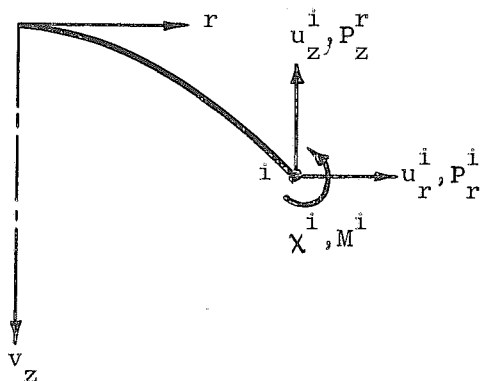
Col. 6 - NTAG(1), displacement  $u_r^i$

Col. 7 - NTAG(2), displacement  $u_z^i$

Col. 8 - NTAG(3), rotation  $\chi^i$

$$NTAG(i) = \begin{cases} = 1 & \text{constrained displacement or rotation} \\ = 0 & \text{free displacement or rotation} \end{cases}$$

Fig. (B-2) - Sign Convention for Nodal Displacements and Concentrated Loads



10. (as before)

11. As before except that the sign convention for concentrated loads is changed to the one shown in Fig. (B-2). The sign convention for distributed loads remains the same as in Fig. (A-5).

Output Description

The computer output is similar to the one described in part A of this appendix except for the following items:

- (a) The incremental and total nodal displacements are output in the  $(r, z; \chi)$  coordinates (see Fig. B-2 for sign convention).
- (b) The interelement forces and strains in the meridional direction are not averaged up at the nodes where meridional slope is discontinuous. Thus, the force and strain quantities at a discontinuity are output separately for the two elements meeting there.



APPENDIX V

```
C   ELASTIC PLASTIC ANALYSIS OF AXISYMMETRIC SHELLS WITH CONTINUOUS
C   MERIDIONAL SLOPE
C
C   PROGRAM MAIN (INPUT,OUTPUT,TAPE1,TAPE2,TAPE3,TAPE4,TAPE5=INPUT,
1  TAPE6 = OUTPUT ,TAPE 8, TAPE9 )
C
C   COMMON/ DIV / NE , NL , NLI
C
C   READ (5,22)NIPT
C   DO 100 I=1, NIPT
1  CALL INPUTD
C
C   CALL GEOMTY
C
C   DO 100 NLL = 1,NLI
C
C   WRITE (6,1000) NLL
C
C   CALL STIFNS (NLL)
C
C   CALL NODL0D
C
C   CALL DISPL
C
C   CALL STRESS(NLL)
C
C   CALL MATPP
C
C   100 CONTINUE
C
C   STOP
C
C   22 FORMAT (I5)
C   1000 FORMAT(31H1NUMBER OF LOADING INCREMENT = ,I5)
C
C   END
1
```

## SUBROUTINE INPUTD

```

C
COMMON/ DIV / NE , NL , NLI
COMMON/GEOM1 /R(50 ),Z(50 ),PHI(50 ),H(50 ) , CRV(2,50 )
COMMON/ MAT1 / E,U,NP,SIGMA(15),ETAN(15),EP(15),EE(2,2)
COMMON/ MAT2 / STI(20),EPL(20),AP(2,2,20),DST(2,20,50 ),ZT,STN
COMMON/STSS1 / T(2,20) , F(4,50 )
COMMON/BNDRCN/ NEQBC,NEBC(15)
COMMON/INPTDT/ NTAG(5,3) , NBC(5)
COMMON/BANARG/ NUMEQ,NBNWD,A(150,6),B(150)
COMMON/ DSPL1/ BT(150)
COMMON/ NTAP / NTAP1 , NTAP2

C
WRITE(6,2000)
READ (5,1000)
WRITE(6,1000)

C
C NUMBER OF NODES , LAYERS , LOAD INCREMENTS , AND BOUNDRY CONDITIONS
C
READ (5,1001)NN,NL, NLI, NUMBC
WRITE(6,2001)NN,NL, NLI, NUMBC

C
READ (5,1002) ( R(I),Z(I),PHI(I),H(I), I= 1,NN)
WRITE(6,2002) ( I,R(I),Z(I),PHI(I),H(I), I= 1,NN)

C
NE = NN - 1
READ (5,1003) ( (CRV(M,I) , M=1,2),I=1,NE)
WRITE(6,2003) ( I,(CRV(M,I) , M=1,2),I=1,NE)

C
READ (5,1004) NP,(EP(I),SIGMA(I),ETAN(I),I=1,NP)
WRITE(6,2004) ( I,EP(I),SIGMA(I),ETAN(I),I=1,NP)

C
READ (5,1005) E,U
WRITE(6,2005) E,U

C
READ (5,1006) (NBC(N) , (NTAG(N,I) , I=1,3) , N=1,NUMBC)
WRITE(6,2006) (NBC(N) , (NTAG(N,I) , I=1,3) , N=1,NUMBC)

C
C BAND WIDTH , NUMBER OF SIMULTANEOUS EQUATIONS, NUMBER OF ELEMENTS
C
NBNWD = 6
NUMEQ = 3 * NN
NE = NN - 1

C
C ANGLE PHI IN TERMS OF RADIAN
C
DO 10 I = 1,NN
10 PHI(I) = PHI(I)/57.2957795130822

C
C NORMALIZED TANGENT MODULII
C
DO 150 I = 1,NP
150 ETAN(I) = ETAN(I) / E

C
C SET UP TOTAL DISPLACEMENTS

```

```

C
DO 160 I=1,NUMEQ
160 BT(I) = 0.0
C
C ELASTIC MODULI IN CASE OF PLANE STRESS (ISOTROPIC)
C
EE(1,1) = E / (1.-U) / (1.+U)
EE(1,2) = U * EE(1,1)
EE(2,1) = EE(1,2)
EE(2,2) = EE(1,1)
C
C SET UP STRESS RESULTANTS
C
DO 220 I=1,NN
DO 220 M=1,4
220 F(M,I) = 0.0
C
C SET UP EQUIVALENT STRESS , EQUIVALENT PLASTIC STRAIN , STRESS
C VECTOR , AND (AP) MATRIX
C
NTAP1 = 8
NTAP2 = 9
REWIND NTAP1
DO 240 I=1,NN
DO 230 K=1,NL
STI(K) = SIGMA(1)
EPL(K) = 0.0
DO 230 N=1,2
T(N,K) = 0.0
DO 230 M=1,2
230 AP(M,N,K) = 0.0
WRITE(NTAP1) STI ,EPL , AP, T
240 CONTINUE
END FILE NTAP1
C
C BOUNDARY CONDITIONS
C
L = 0
DO 250 N=1,NUMBC
DO 250 I=1,3
M = NTAG(N,I)
IF(M .LE. 0) GO TO 250
L = L + 1
NEBC(L) = 3 * (NBC(N) - 1) + I
250 CONTINUE
NEQBC = L
C
RETURN
C
1000 FORMAT(72H
1
1001 FORMAT(4I5)
1002 FORMAT ( 4F15. )
1003 FORMAT(2F15.0)

```

1004 FORMAT(I5 / (3E15.0))  
 1005 FORMAT(E10.3,F5.0)  
 1006 FORMAT(I4,1X,3I1)

C

2000 FORMAT(1H1)  
 2001 FORMAT( //  
   1 30H NUMBER OF NODAL CIRCLES . . . I10 /  
   2 30H NUMBER OF LAYERS . . . . . I10 /  
   3 30H NUMBER OF LOAD INCREMENTS . . I10 /  
   4 30H NUMBER OF BOUNDRY CONDITIONS I10 ///)  
 2002 FORMAT(2X,4HNODE,6X,11HABSCISSA-R-,8X,12H ORDINATE-Z-,7X,  
   1 14HLATITUDE ANGLE , 9X,9HTHICKNESS / 15X,5H(IN.),15X,5H(IN.),  
   2 13X,8H(DEGREE),14X,5H(IN.)//((I4,4E20.7))  
 2003 FORMAT(30H-CURVATURES AT NODAL CIRCLES /  
   1 8H ELEMENT , 7X , 6HEND(1) , 14X , 6HEND(2) //(I5,2E20.7))  
 2004 FORMAT(1H-,14X ,26HEQUIVALENT PLASTIC STRAIN ,8X,18HEQUIVALENT ST  
   RESS ,13X,16HTANGENT MODULUS //(I5,3E30.7))  
 2005 FORMAT( 30H-MODULUS OF ELASTICITY (PSI) ,E20.7/  
   1 30H POISSON RATIO . . . . . ,E20.7///)  
 2006 FORMAT(43H BOUNDRY CONDITIONS (1=RESTRAINED,0=FREE) //  
   1 6H POINT , 3X , 3H U , 2X , 3H W , 2X , 3HROT //(I6,3I5))

C

END

1

## SUBROUTINE GEOMTY

C  
C  
C COMPUTE GEOMETRIC PARAMETERS FOR COMPLETELY COMPATIBLE ELEMENT (3)

COMMON/ DIV / NE , NL , NLI  
COMMON/GEOM1 /R(50 ),Z(50 ),PHI(50 ),H(50 ) , CRV(2,50 )  
COMMON/GEOM2 / COF(10) , B1(4,8,10) , B2(4,8,2) , C(8,8)  
COMMON/GEOM3 /CORD,SNT,CNT,SNB1,CNB1,TNB1,SNB2,CNB2,TNB2,SNP,CNP  
COMMON/GEOM4 /YBAR,YP,YPP,RW,XT,ARC,RV,CNP1,CNP2,B(4,8)  
COMMON /GEOM5/ A1,A2,A3,A4  
COMMON/BANARG/NUMEQ,NBNWD,BK(150,6),P(150)  
COMMON/INTEG1/ NUMIPD  
COMMON/INTEG2/YP1(10),FAC(10)

C  
C DIMENSION X(12) , W(10) , SINF(50 ) , CSNF(50 )

C  
C EQUIVALENCE (SINF(1),BK(1)) , (CSNF(1),BK(151))

C  
C DATA X / 0.0,0.013046735741414 , 0.067468316655507,  
1 0.160295215850488, 0.283302302935376 , 0.425562830509184,  
2 0.574437169490816, 0.716697697064624, 0.839704784149512,  
3 0.932531683344493, 0.986953264258586, 1.0 /

C  
C DATA W / 0.066671344308688, 0.149451349150581,  
1 0.219086362515982, 0.269266719309996, 0.295524224714753,  
2 0.295524224714753, 0.269266719309996, 0.219086362515982,  
3 0.149451349150581, 0.066671344308688 /

C  
C REWIND 1  
REWIND 2  
REWIND 3  
REWIND 4

C  
C NUMIPD = 10  
WRITE(6,1006)

C  
C NN = NE + 1  
DO 10 I = 1,NN  
SINF(I) = SIN(PHI(I))  
10 CSNF(I) = COS(PHI(I))

C  
C COMPUTE GEOMETRICAL PARAMETERS

C  
C DO 100 I = 1,NE  
DR = R(I+1) - R(I)  
DZ = Z(I+1) - Z(I)  
CORD = SQRT(DR\*\*2 + DZ\*\*2)  
SNT = DR / CORD  
CNT = DZ / CORD

C  
C SNB1 = CSNF(I) \* CNT - SINF(I) \* SNT  
CNB1 = SINF(I) \* CNT + CSNF(I) \* SNT  
TNB1 = SNB1 / CNB1  
SNB2 = CSNF(I+1) \* CNT - SINF(I+1) \* SNT  
CNB2 = SINF(I+1) \* CNT + CSNF(I+1) \* SNT

```

C      TNB2 = SNB2 / CNB2
C
C      CNP1 = CSNF(I) / CNB1
C      CNP2 = CSNF(I+1) / CNB2
C
C      YPP1 = -CORD * CRV(1,I) / CNB1**3
C      YPP2 = -CORD * CRV(2,I) / CNB2**3
C
C      A1 = TNB1
C      A2 = TNB1 + 0.50 * YPP1
C      A3 = -(5.*TNB1 + 4.*TNB2) + (0.5*YPP2 - YPP1)
C      A4 = 3. * (TNB1 + TNB2) + 0.50 * (YPP1 - YPP2)
C
C      SNP = SIN(PHI(I+1) - PHI(I))
C      CNP = COS(PHI(I+1) - PHI(I))
C
C      ESTABLISH STRAIN-DISPLACEMENT MATRICES
C
C      NIPD2 = NUMIPD + 2
C      DO 70 K = 1,NIPD2
C      XT = X(K)
C      YBAR = (1.-XT) * (A1 + XT * (A2 + XT * (A3 + XT * A4)))
C      YP = A1*(1.-2.*XT) + XT*(A2*(2.-3.*XT) + XT*(A3*(3.-4.*XT) +
1 A4 * XT * (4.-5.*XT)))
C      YPP = 2.*(-A1 + A2 * (1.-3.*XT)) + XT * (A3 * (6.-12.*XT) +
1 A4 * XT * (12.-20.*XT))
C      RV = CORD * (SNT + YBAR * CNT)
C      RW = R(I) + XT * RV
C      ARC = SQRT(1. + YP**2)
C
C      IF(R(I) .NE. 0.0) GO TO 20
C
C      STRAIN - DISPLACEMENT MATRIX FOR CENTRAL CAP
C
C      CALL B1MATX
C      GO TO 30
C
C      STRAIN - DISPLACEMENT MATRIX FOR A FRUSTRUM
C
C      20 CALL B2MATX
C
C      30 IF(K.EQ. 1 .OR. K .EQ. NIPD2) GO TO 50
C      KK = K - 1
C      YP1(KK) = YP
C      FAC(KK) = 0.50 * CORD * RW * W(KK)
C      COF(KK) = ARC * FAC(KK)
C
C      DO 40 N = 1,8
C      DO 40 M = 1,4
C      40 B1(M,N,KK) = B(M,N)
C      GO TO 70
C
C      TO BE USED IN STRESS SUBROUTINE
C
C      50 KK = (NUMIPD + K) / (NUMIPD + 1)

```

```
DO 60 N = 1,8
DO 60 M = 1,4
60 B2(M,N,KK) = B(M,N)
70 CONTINUE
C
C   DISPLACEMENT TRANSFORMATION MATRIX
C
C   IF(R(I) .NE. 0.0) GO TO 80
C
C   DISPLACEMENT TRANSFORMATION MATRIX FOR CENTRAL CAP
C
C   CALL C1MATX
C   GO TO 90
C
C   DISPLACEMENT TRANSFORMATION MATRIX FOR A FRUSTRUM
C
C   80 CALL CMATX
C
C   90 WRITE (1) B1, COF
C   WRITE (2) B2
C   WRITE (3) C
C   WRITE (4) YP1, FAC, TNB1, SNT, CNT
C   WRITE(6,1007) I,CORD,SNT,CNT,TNB1,TNB2
C
C   100 CONTINUE
C
C   END FILE 1
C   END FILE 2
C   END FILE 3
C   END FILE 4
C
C   RETURN
C
C   1006 FORMAT(8H-ELEMENT,5X,4HCORD,14X,4HSINT,14X,4HCSNT,14X,4HTNB1,
C   1 14X,4HTNB2 //)
C   1007 FORMAT(I4,5E18.7)
C
C   END
1
```

## SUBROUTINE STIFNS(NLL)

V-8

C  
C  
C

SUBROUTINE TO SET UP SYSTEM STIFFNESS MATRIX

```

COMMON/ DIV / NE , NL , NLI
COMMON/GEOM1 /R(50 ),Z(50 ),PHI(50 ),H(50 ), CRV(2,50 )
COMMON/GEOM2 / COF(10) , B1(4,8,10) , B2(4,8,2) , C(8,8)
COMMON/ GEOM4/YBAR,YP, YPP , RW , XT , ARC , RV , CNP1,CNP2,B(4,8)
COMMON/ MAT3 / SUMA(2,50 ,3), SUMB(2,50 ,3), TB(20), RAT(20)
COMMON/STF1/ D(4,4) , SKI(8,8) , SK(8,8)
COMMON/BANARG/NUMEQ,NBNWD,BK(150,6),P(150)
COMMON/INTEG1/ NUMIPD
COMMON DD(2,8,50), DB(6,2,50), RB(2,50)

```

C

```

DIMENSION SKG(8,8) , TEMP(8,8)
EQUIVALENCE (SKG(1),SK(1)) , (TEMP(1),SKI(1))

```

C

```

REWIND 1
REWIND 3

```

C

```

DO 1 N=1,6
DO 1 M=1,NUMEQ
1 BK(M,N) = 0.0

```

C

```

DO 100 I=1,NE
II = I

```

C

```

READ (1) B1, COF
READ (3) C

```

C

C

ELEMENT STIFFNESS MATRIX IN GENERALIZED COORDINATES

C

```

DO 5 N=1,8
DO 5 M=1,8
5 SKG(M,N) = 0.0

```

C

```

DO 50 L=1,NUMIPD
LL = L + 1
IF (NLL .NE. 1) GO TO 7
CALL DIMATX(LL,II)
GO TO 8

```

C

```

7 CALL DMATX(LL,II)

```

C

```

8 DO 10 N=1,8
DO 10 M=1,4
10 B(M,N) = 0.0

```

C

```

DO 20 N=1,8
DO 20 M=1,4
DO 20 K=1,4
20 B(M,N) = B(M,N) + D(M,K) * B1(K,N,L)

```

C

```

DO 30 N=1,8
DO 30 M=1,8

```



```

30 SKI(M,N) = 0.0
C
  DO 40 N=1,8
  DO 40 M=1,8
  DO 40 K=1,4
40 SKI(M,N) = SKI(M,N) + B1(K,M,L) * B(K,N)
C
  DO 50 N=1,8
  DO 50 M=1,8
50 SKG(M,N) = SKG(M,N) + COF(L) * SKI(M,N)
C
  ELEMENT STIFFNESS MATRIX IN SYSTEM CO-ORDINATES
C
  DO 60 N=1,8
  DO 60 M=1,8
60 TEMP(M,N) = 0.0
C
  DO 70 N=1,8
  DO 70 M=1,8
  DO 70 K=1,8
70 TEMP(M,N) = TEMP(M,N) + SKG(M,K) * C(K,N)
C
  DO 80 N = 1, 8
  DO 80 M = 1, 8
80 SK(M,N) = 0.
C
  DO 90 N=1,8
  DO 90 M=1,8
  DO 90 K=1,8
90 SK(M,N) = SK(M,N) + C(K,M) * TEMP(K,N)
  IF(R(I) .NE. 0.0) GO TO 95
  SK(1,1) = 1.0
  SK(3,3) = 1.0
C
95 CONTINUE
C
  CONDENSATION
C
  DET = SK(7,7) * SK(8,8) - SK(7,8) * SK(8,7)
  DD(1,1,I) = SK(8,8) / DET
  DD(2,2,I) = SK(7,7) / DET
  DD(1,2,I) = -SK(7,8) / DET
  DD(2,1,I) = -SK(8,7) / DET
C
  DO 105 N = 1, 6
  K = N + 2
  DO 105 M = 1,2
  DD(M,K,I) = 0.
105 DB(N,M,I) = 0.
C
  DO 115 N = 1, 6
  DO 110 M = 1,2
  DO 110 K = 1, 2
  J = N + 2
  DB(N,M,I) = DB(N,M,I) + SK(N,K+6) * DD(K,M,I)

```

```
110 DD(M,J,I) = DD(M,J,I) + DD(M,K,I) * SK(K+6,N)
DO 115 JJ = 1, 6
DO 115 KK = 1, 2
115 SK(JJ,N) = SK(JJ,N) - SK(JJ,KK+6) * DD(KK,N+2,I)
```

C

```
DO 100 M=1,6
DO 100 N=M,6
II = 3*(I-1) + M
JJ = N-M+1
100 BK(II,JJ) = BK(II,JJ) + SK(M,N)
END FILE 9
```

C

```
RETURN
END
```

1

SUBROUTINE NODL0D

SUBROUTINE TO GENERATE CONSISTENT NODAL LOADS

COMMON/ DIV /NE,NL,NLI  
 COMMON/BANARG/ NUMEQ,NBNWD,A(150,6),B(150)  
 COMMON/GEOM1 /R(50 ),Z(50 ),PHI(50 ),H(50 ), CRV(2,50 )  
 COMMON/GEOM2 / COF(10) , B0(4,8,10) , B2(4,8,2) , C(8,8)  
 COMMON/INTEG1/NUMIPD  
 COMMON/INTEG2/YP1(10),FAC(10)  
 COMMON DD(2,8,50), DB(6,2,50), RB(2,50)

DIMENSION B1(150),DP(8),PSTAR(8),TEMP(8),X(10)

DATA X / 0.013046735741414 , 0.067468316655507,  
 1 0.160295215850488, 0.283302302935376 , 0.425562830509184,  
 2 0.574437169490816, 0.716697697064624, 0.839704784149512,  
 3 0.932531683344493, 0.986953264258586 /

REWIND 3  
 REWIND 4

READ (5,900) INDX  
 IF (INDX .EQ. 0) GO TO 5  
 READ (5,1000) B(1), B(2), B(3), B1(1), B1(2), B1(3)  
 NE3 = 3\* INDX  
 DO 3 I= 4,NE3, 3  
 B (I) = B (1)  
 B (I+1) = B (2)  
 B (I+2) = B (3)  
 B1(I) = B1(1)  
 B1(I+1) = B1(2)  
 3 B1(I+2) = B1(3)  
 NN = NE +1  
 IF (INDX .EQ. NN ) GO TO 7  
 NEX = NE3 + 1  
 NE3 = 3 \* NN  
 DO 4 I = NEX, NE3  
 B (I) = 0.0  
 4 B1(I) = 0.0  
 GO TO 7  
 5 NE3 = 3 \* (NE + 1)  
 READ (5,1000) (2(I),B(I+1),B(I+2),B1(I),B1(I+1),B1(I+2),I=1,NE3,3)  
 7 WRITE(6,2000) (B(I),B(I+1),B(I+2),B1(I),B1(I+1),B1(I+2),I=1,NE3,3)  
 DO 100 I=1,NE  
 L = 3 \* (I-1)  
 READ (3) C  
 READ (4) YP1, FAC, TNB1, SNT, CNT  
 DO 10 J=1,8  
 10 PSTAR(J) = 0.0

```

DO 20 K=1,NUMIPD
PU = B1(L+1) + X(K) * (B1(L+4) - B1(L+1))
PW = B1(L+2) + X(K) * (B1(L+5) - B1(L+2))
C
IF(R(I) .NE. 0.0) GO TO 15
SUM1 = (PU - PW * YP1(K)) * FAC(K)
SUM2 = (PU * YP1(K) + PW) * FAC(K)
DP(1) = 0.0
DP(2) = 0.0
DP(3) = -SUM1 * CNT + SUM2 * SNT
DP(4) = (SUM1 + SUM2 * TNB1) * X(K)
DP(5) = SUM1 * X(K) * X(K)
DP(6) = X(K) * DP(5)
DP(7) = SUM2 * X(K) * X(K)
DP(8) = DP(7) * X(K)
GO TO 16
C
15 DP(1) = (PU - PW * YP1(K)) * FAC(K)
DP(2) = X(K) * DP(1)
DP(3) = X(K) * DP(2)
DP(4) = X(K) * DP(3)
DP(5) = (PU * YP1(K) + PW) * FAC(K)
DP(6) = X(K) * DP(5)
DP(7) = X(K) * DP(6)
DP(8) = X(K) * DP(7)
C
16 DO 20 J=1,8
20 PSTAR(J) = PSTAR(J) + DP(J)
C
DO 30 J=1,8
30 TEMP(J) = 0.0
C
DO 40 N=1,8
DO 40 M=1,8
40 TEMP(N) = TEMP(N) + C(M,N) * PSTAR(M)
C
CONDENSATION
C
RB(1,I) = TEMP(7)
RB(2,I) = TEMP(8)
DO 45 N=1, 6
DO 45 K=1, 2
45 TEMP(N) = TEMP(N) - DB(N,K,I) * RB(K,I)
C
DO 50 N=1,6
LL = L + N
50 B(LL) = B(LL) + TEMP(N)
C
100 CONTINUE
C
WRITE(6,2003) (B(I) , I=1,NUMEQ)
C
RETURN
C
900 FORMAT (I5)

```

```
1000 FORMAT (6E12.0)
2000 FORMAT(1H1,20X,18HCONCENTRATED LOADS ,42X,17HDISTIBUTED LOADS //
  1 8X,10HMERIDIONAL ,12X,6HRADIAL ,14X,6HMOMENT ,12X,10HMERIDIONAL ,
  2 12X, 6HRADIAL ,14X,6HMOMENT /(6E20.7))
2003 FORMAT(44H1CONSISTENT EXTERNAL LOADS AT NODAL CIRCLES //
  1 8X,10HMERIDIONAL ,12X,6HRADIAL ,14X,6HMOMENT /(3E20.7))
```

C

END

1

```

SUBROUTINE DISPL
C
COMMON /BANARG/  NN, MM,A(150, 6),B(150)
COMMON/BNDRCN/  NEQBC,NEBC(15)
COMMON/ DSPL1/  BT(150)
C
DO 100  N=1,NEQBC
I = NEBC(N)
A(I,1) = 1.0
B(I) = 0.0
DO 100  J=2,MM
A(I,J) = 0.0
L = I-J+1
IF(L .LE. 0)  GO TO 100
A(L,J) = 0.0
100 CONTINUE
C
CALL BANSOL
C
DO 200  I=1,NN
200 BT(I) = BT(I) + B(I)
C
WRITE(6,2001) (B(I) , I=1,NN)
WRITE(6,2002) (BT(I), I=1,NN)
C
RETURN
C
2001 FORMAT(50H1DISPLACEMENT INCREMENTS AT NODAL CIRCLES //
1 8X,10HMERIDIONAL ,12X,6HRADIAL ,13X,8HROTATION /(3E20.7))
2002 FORMAT(50H1TOTAL DISPLACEMENTS AT NODAL CIRCLES //
1 8X,10HMERIDIONAL ,12X,6HRADIAL ,13X,8HROTATION /(3E20.7))
C
END
1
```

## SUBROUTINE STRESS(NLL)

V-15

C

```

COMMON/ DIV / NE , NL , NLI
COMMON/GEOM1 /R(50 ),Z(50 ),PHI(50 ),H(50 ) , CRV(2,50 )
COMMON/GEOM2 / COF(10) , B1(4,8,10) , B2(4,8,2) , C(8,8)
COMMON/STSS1 / T(2,20) , F(4,50 )
COMMON/STSS2 / ALPHA(8),DSTR(2) ,BE(2,8),DFRC(4)
COMMON/ MAT2 / STI(20),EPL(20),AP(2,2,20),DST(2,20,50 ),ZT,STN
COMMON/BANARG/ NUMEQ,NBNWD,A(150,6),B(150)
COMMON/INTEG1/ NUMIPD
COMMON/STF1/ D(4,4) , SKI(8,8) , SK(8,8)
COMMON DD(2,8,50), DB(6,2,50), RB(2,50)

```

C

```

DIMENSION TEMP(4,8) , DF(4,50), Q(8)
EQUIVALENCE (TEMP(1),SKI(1)) , (DF(1),A(1))

```

C

```

REWIND 2
REWIND 3

```

C

```

NN = NE + 1
ANL = NL
DO 10 I=1,NN
DO 5 K=1,NL
DO 5 M=1,2
5 DST(M,K,I) = 0.0
DO 10 N=1,4
10 DF(N,I) = 0.0

```

C

```

WRITE (6,1000)

```

C

```

DO 140 I=1,NE
READ (2) B2
READ (3) C

```

C

```

DO 20 M=1,8
20 ALPHA(M) = 0.0

```

C

C

C

```

RECOVERING CONDENSED DEG OF FREEDOM

```

C

```

Q(7) = 0.
Q(8) = 0.
IX = 3 * (I-1)

```

C

```

DO 15 M = 1, 2
DO 12 K = 1, 2
L = M + 6
12 Q(L) = Q(L) + DD(M,K,I) * RB(K,I)
DO 15 J = 1, 6
JJ = J + IX
15 Q(L) = Q(L) - DD(M,J+2, I) * B(JJ)

```

C

```

DO 17 JJ = 1,6
J = IX + JJ
17 Q(JJ) = B(J)

```

C

```

      DO 30 M=1,8
      DO 30 N=1,8
30 ALPHA(M) = ALPHA(M) + C(M,N) * Q(N)
C
      DO 140 L=1,2
      II = I+L-1
C
C      DETERMINATION OF STRAIN ALONG THE THICKNESS
C
      DO 70 K=1,NL
      AK = K
      ZBAR = ((AK - 0.50)/ANL - 0.50) * H(II)
      DO 40 N=1,8
      DO 40 M=1,2
40 BE(M,N) = B2(M,N,L) + ZBAR * B2(M+2,N,L)
C
      DO 50 M=1,2
50 DSTR(M) = 0.0
C
      DO 60 M=1,2
      DO 60 N=1,8
60 DSTR(M) = DSTR(M) + BE(M,N) * ALPHA(N)
C
      DO 70 M=1,2
70 DST(M,K,II) = DST(M,K,II) + 0.50 * DSTR(M)
C
C      DETERMINATION OF STRESS RESULTANTS
C
      III = I
      LL = 1 + (NUMIPD+1) * (L-1)
      IF (NLL .NE. 1) GO TO 80
      CALL DIMATX(LL,III)
      GO TO 90
C
80 CALL DMATX(LL,III)
C
90 DO 100 N=1,8
      DO 100 M=1,4
100 TEMP(M,N) = 0.0
C
      DO 110 N=1,8
      DO 110 M=1,4
      DO 110 K=1,4
110 TEMP(M,N) = TEMP(M,N) + D(M,K) * B2(K,N,L)
C
      DO 120 M=1,4
120 DFRC(M) = 0.0
C
      DO 130 M=1,4
      DO 130 K=1,8
130 DFRC(M) = DFRC(M) + TEMP(M,K) * ALPHA(K)
C
      WRITE (6,1001) I,L,(DFRC(M) , M=1,4)
C
      DO 140 M=1,4

```



```

140 DF(M,II) = DF(M,II) + 0.50 * DFRC(M)
C
DO 150 M=1,2
DO 150 K=1,NL
DST(M,K,1) = 2.0 * DST(M,K,1)
150 DST(M,K,NN) = 2.0 * DST(M,K,NN)
C
DO 160 M=1,4
DF(M,1) = 2.0 * DF(M,1)
160 DF(M,NN) = 2.0 * DF(M,NN)
C
C
C
TOTAL STRESS RESULTANTS
C
DO 170 I=1,NN
DO 170 M=1,4
170 F(M,I) = F(M,I) + DF(M,I)
C
WRITE (6,1002) (I,(DF(M,I),M=1,4),I=1,NN)
WRITE (6,1003) (I,(F(M,I),M=1,4),I=1,NN)
DO 180 I=1,NN,2
I1 = I + 1
180 WRITE (6,1004) (I,K,(DST(M,K,I),M=1,2),I1,K,(DST(M,K,I1),
1 M=1,2),K=1,NL)
C
RETURN
1000 FORMAT(55H1 INCREMENTS OF STRESS RESULTANTS AT THE END OF ELEMENTS/
1 8H ELEMENT,2X,7HEND NO.,7X,16HMERIDIONAL FORCE ,9X,16HCIRCUMFER.
2 FORCE ,8X,18HMERIDIONAL MOMENT ,7X,18HCIRCUMFER. MOMENT //)
1001 FORMAT(I5,4X,I5,4E25.7)
1002 FORMAT(50H1 INCREMENTS OF STRESS RESULTANTS AT NODAL CIRCLES /
1 6H NODE,10X,16HMERIDIONAL FORCE ,9X,16HCIRCUMFER. FORCE ,8X,
2 18HMERIDIONAL MOMENT ,7X,18HCIRCUMFER. MOMENT //(I5,4E25.7))
1003 FORMAT(50H1 TOTAL STRESS RESULTANTS AT NODAL CIRCLES /
1 6H NODE,10X,16HMERIDIONAL FORCE ,9X,16HCIRCUMFER. FORCE ,8X,
2 18HMERIDIONAL MOMENT ,7X,18HCIRCUMFER. MOMENT //(I5,4E25.7))
1004 FORMAT(30H2 INCREMENTS OF STRAINS /
15H NODE,2X,5HLAYER,7X,10HMERIDIONAL,10X,10HCIRCUMFER.,21X,
25H NODE,2X,5HLAYER,7X,10HMERIDIONAL,10X,10HCIRCUMFER. //
3(I4,2X,I4,2E20.5,20X,I4,2X,I4,2E20.5))
C
END
1

```

## SUBROUTINE MATPP

## SUBROUTINE TO ESTABLISH MATERIAL PROPERTIES

```

COMMON/ DIV / NE , NL , NLI
COMMON/ MAT1 / E,U,NP,SIGMA(15),ETAN(15),EP(15),EE(2,2)
COMMON/ MAT2 / STI(20),EPL(20),AP(2,2,20),DST(2,20,50 ),ZT,STN
COMMON/ MAT3 / SUMA(2,50 ,3), SUMB(2,50 ,3), TB(20), RAT(20)
COMMON/ MAT4 / DSTP(2) , DSTE(2) , DT(2) , TT(2)
COMMON/STSS1 / T(2,20) , F(4,50 )
COMMON/ NTAP / NTAP1 , NTAP2

```

```

REWIND NTAP1
REWIND NTAP2

```

```

NN = NE + 1
DO 5 J=1,3
DO 5 I=1,NN
DO 5 N=1,2
SUMA( N,I,J) = 0.0
5 SUMB( N,I,J) = 0.0

```

```

DO 200 I=1,NN

```

```

READ (NTAP1) STI, EPL, AP, T

```

```

DO 150 K=1,NL
DO 10 M=1,2
10 DSTP(M) = 0.0

```

```

DO 20 M=1,2
DO 20 N=1,2
20 DSTP(M) = DSTP(M) + AP(M,N,K) * DST(N,K,I)

```

```

DO 30 M=1,2
30 DSTE(M) = DST(M,K,I) - DSTP(M)

```

```

DO 40 M=1,2
40 DT(M) = 0.0

```

```

DO 50 M=1,2
DO 50 N=1,2
50 DT(M) = DT(M) + EE(M,N) * DSTE(N)

```

```

DO 60 M=1,2
60 TT(M) = T(M,K) + DT(M)

```

```

S1 = TT(1) - 0.50 * TT(2)
S2 = TT(2) - 0.50 * TT(1)
TBAR = SQRT(TT(1)*S1 + TT(2)*S2)
IF (DSTP(1) .EQ. 0.0 .AND. DSTP(2) .EQ. 0.0) GO TO 70

```

```

S1 = T(1,K) - 0.50 * T(2,K)
S2 = T(2,K) - 0.50 * T(1,K)
FLAG = S1 * DT(1) + S2 * DT(2)

```

```

      IF (FLAG .LT. 0.0) GO TO 70
C
      EP1 = DSTP(1) + 0.50 * DSTP(2)
      EP2 = DSTP(2) + 0.50 * DSTP(1)
      DEP = SQRT(4./3. * (DSTP(1)*EP1 + DSTP(2)*EP2))
      EPL(K) = EPL(K) + DEP
      GO TO 80
C
      70 STM = 0.999 * STI(K)
      IF (TBAR .LT. STM) GO TO 90
C
      80 KK = K
      II = I
      CALL INTERP(KK,II)
      RAT(K) = STN / TBAR
      GO TO 100
C
      90 ZT = 1.0
      STN = STI(K)
      RAT(K) = 1.0
C
      100 DO 110 M=1,2
      110 T(M,K) = RAT(K) * TT(M)
C
      S1 = T(1,K) - 0.50 * T(2,K)
      S2 = T(2,K) - 0.50 * T(1,K)
      TB(K) = SQRT(S1 * T(1,K) + S2 * T(2,K))
      IF (TB(K) .EQ. 0.0) GO TO 120
      S1 = S1 / TB(K)
      S2 = S2 / TB(K)
      SS1 = (S1 + U*S2) * (1. - ZT)
      SS2 = (S2 + U*S1) * (1. - ZT)
      DNOM = (1.-U)*(1.+U)*ZT + S1*SS1 + S2*SS2
      S1 = S1 / DNOM
      S2 = S2 / DNOM
      AP(1,1,K) = S1 * SS1
      AP(1,2,K) = S1 * SS2
      AP(2,1,K) = S2 * SS1
      AP(2,2,K) = S2 * SS2
      GO TO 135
C
      120 DO 130 M=1,2
      DO 130 N=1,2
      130 AP(M,N,K) = 0.0
C
      135 AK = K
      DO 140 N=1,2
      SUMA( N,I,1) = SUMA( N,I,1) + AP(1,N,K)
      SUMB( N,I,1) = SUMB( N,I,1) + AP(2,N,K)
      SUMA( N,I,2) = SUMA( N,I,2) + AP(1,N,K) * (AK-0.50)
      SUMB( N,I,2) = SUMB( N,I,2) + AP(2,N,K) * (AK-0.50)
      SUMA( N,I,3) = SUMA( N,I,3) + AP(1,N,K) * (AK*(AK-1.) + .33333333)
      140 SUMB( N,I,3) = SUMB( N,I,3) + AP(2,N,K) * (AK*(AK-1.) + .33333333)
C
      150 STI(K) = STN

```

```
C      WRITE(NTAP2) STI, EPL, AP, T
      WRITE (6,1000) (I,(K,(T(M,K )),M=1,2),TB(K),RAT(K)), K=1, NL)
C
200 CONTINUE
      END FILE NTAP2
C
      NTAPT = NTAP1
      NTAP1 = NTAP2
      NTAP2 = NTAPT
C
      RETURN
C
1000 FORMAT(30H2STRESS DISTRIBUTION /
1 8H NODE , 2X , 5HLAYER , 11X , 10HMERIDIONAL , 15X , 10HCIRCUM
2FER. , 11X , 18HEQUIVALENT STRESS , 4X , 20HMODIFICATION FACTOR
3 // (I5 , 3X , I5 , 3E25.7 , F20.5))
C
      END
1
```

SUBROUTINE INTERP(K,I)

V-21

C  
C  
C

SUBROUTINE FOR LINEAR INTERPOLATION OF MATERIAL PROPERTIES

COMMON/ MAT1 / E,U,NP,SIGMA(15),ETAN(15),EP(15),EE(2,2)  
COMMON/ MAT2 / STI(20),EPL(20),AP(2,2,20),DST(2,20,50 ),ZT,STN

C  
C

IF (EPL(K) .GT. EP(NP)) GO TO 100

DO 10 IP=2,NP

IF (EPL(K) .LE. EP(IP)) GO TO 50

10  
C

CONTINUE

50 RHO = (EPL(K) - EP(IP-1)) / (EP(IP) - EP(IP-1))  
STN = SIGMA(IP-1) + RHO \* (SIGMA(IP) - SIGMA(IP-1))  
ZT = ETAN(IP-1) + RHO \* (ETAN(IP) - ETAN(IP-1))  
RETURN

C

100 WRITE (6,1000) K,I,EPL(K)  
STOP

C

1000 FORMAT(I5,I5,E20.5 / 40H-MATERIAL PROP. DATA IS EXCEEDED )  
END

1

## SUBROUTINE BIMATX

```

COMMON/GEOM3 /CORD,SNT,CNT,SNB1,CNB1,TNB1,SNB2,CNB2,TNB2,SNP,CNP
COMMON/GEOM4 /YBAR,YP,YPP,RW,XT,ARC,RV,CNP1,CNP2,B(4,8)
COMMON /GEOM5/ A1,A2,A3,A4

```

```

DO 10 N=1,3
DO 10 M=1,4
10 B(M,N) = 0.0

```

```

RHO = 1. / (CORD * ARC**2)
AMU = 1. / RV
ALPHA = RHO / ARC
PHI = ALPHA * RHO * YPP
PSI = (SNT + YP * CNT) * ALPHA * AMU
GAMA = 2.0*(A2-A1) + XT*(3.0*(A3-A2) + XT*(4.0*(A4-A3) -
1 XT*5.0*A4))
OMG = 2. * YP * ALPHA / CORD
TET = (1. - YP * YP ) * PHI

```

```

B(1,4) = RHO * (1. + YP * TNB1)
B(2,4) = AMU * CNP1
B(3,4) = (1. + YP * (2. * TNB1 - YP)) * PHI
B(4,4) = GAMA * PSI

```

```

B(1,5) = 2. * RHO * XT
B(2,5) = AMU * XT * SNT
B(3,5) = 2. * XT * TET + OMG
B(4,5) = 2. * YP * PSI

```

```

R(1,6) = 1.5 * XT * B(1,5)
R(2,6) = XT * B(2,5)
R(3,6) = 3. * XT * (XT * TET + OMG )
R(4,6) = 1.5 * XT * B(4,5)

```

```

B(1,7) = YP * B(1,5)
B(2,7) = AMU * XT * CNT
B(3,7) = 2. * (2.*PHI * XT * YP - ALPHA/CORD)
B(4,7) = -2. * PSI

```

```

B(1,8) = 1.50 * B(1,7) * XT
B(2,8) = B(2,7) * XT
B(3,8) = 6. * (PHI * XT * YP - ALPHA/CORD) * XT
B(4,8) = -3. * PSI * XT

```

```

RETURN
END

```

## SUBROUTINE BMATX

V-23

C  
COMMON/GEOM3 /CORD,SNT,CNT,SNB1,CNB1, TNB1,SNB2,CNB2, TNB2,SNP,CNP  
COMMON/GEOM4 /YBAR,YP,YPP,RW,XT,ARC,RV,CNP1,CNP2,B(4,8)

C  
RHO = 1./((CORD \* ARC\*\*2)  
AU = 2./((CORD\*\*2 \* ARC\*\*3)  
PSI = (SNT + YP \* CNT)/(CORD \* RW \* ARC\*\*3)  
PHI = YPP / (CORD\*\*2 \* ARC\*\*5)  
OMG = YP \* AU

C  
R(1,1) = 0.0  
B(2,1) = SNT / RW  
R(3,1) = 0.0  
B(4,1) = 0.0

C  
R(1,2) = RHO  
B(2,2) = B(2,1) \* XT  
R(3,2) = (1.-YP\*\*2) \* PHI  
R(4,2) = YP \* PSI

C  
B(1,3) = 2. \* XT \* RHO  
B(2,3) = B(2,2) \* XT  
B(3,3) = B(3,2) \* 2. \* XT + OMG  
B(4,3) = B(4,2) \* 2. \* XT

C  
B(1,4) = B(1,3) \* 1.5 \* XT  
B(2,4) = B(2,3) \* XT  
B(3,4) = 3. \* XT \* ( XT \* B(3,2) + OMG )  
B(4,4) = B(4,3) \* 1.5 \* XT

C  
B(1,5) = 0.0  
B(2,5) = CNT / RW  
B(3,5) = 0.0  
B(4,5) = 0.0

C  
B(1,6) = YP \* RHO  
B(2,6) = B(2,5) \* XT  
B(3,6) = 2. \* YP \* PHI  
B(4,6) = -PSI

C  
B(1,7) = 2. \* B(1,6) \* XT  
B(2,7) = B(2,6) \* XT  
B(3,7) = 2. \* B(3,6) \* XT - AU  
B(4,7) = -2. \* PSI \* XT

C  
B(1,8) = 1.5 \* B(1,7) \* XT  
B(2,8) = B(2,7) \* XT  
R(3,8) = 3. \* (B(3,6) \* XT - AU) \* XT  
B(4,8) = 1.5 \* B(4,7) \* XT

C  
RETURN  
END

1

## SUBROUTINE C1MATX

C

```
COMMON/GEOM2 / COF(10) , B1(4,8,10) , B2(4,8,2) , C(8,8)
COMMON/GEOM3 /CORD,SNT,CNT,SNB1,CNB1,TNB1,SNB2,CNB2,TNB2,SNP,CNP
COMMON/ GEOM4/YBAR,YP, YPP , RW , XT , ARC , RV , CNP1,CNP2,B(4,8)
```

C

```
DO 10 N=1,8
DO 10 M=1,8
10 C(M,N) = 0.0
TICJ = TNB1 * CNB2
```

C

```
C(3,2) = 1.0
C(4,2) = CNT * 5.5
C(5,2) = -9. * CNT
C(6,2) = 4.5 * CNT
C(7,2) = -CNT * (11. * TNB1 + TNB2) - 3. * SNT
C(8,2) = CNT * (5.5 * TNB1 + TNB2) + 2. * SNT
```

C

```
C(4,4) = CNB2
C(5,4) = -4.5 * CNB2
C(6,4) = -C(5,4)
C(7,4) = -2. * TICJ - 2.5 * SNB2
C(8,4) = TICJ + 3.5 * SNB2
```

C

```
C(4,5) = -SNB2
C(5,5) = 4.5 * SNB2
C(6,5) = -C(5,5)
C(7,5) = SNB2 * (2. * TNB1 + 5.5 * TNB2) + 3. * CNB2
C(8,5) = -SNB2 * (TNB1 + 5.5 * TNB2) - 2. * CNB2
```

C

```
C(7,6) = -CORD / CNB2 **2
C(8,6) = -C(7,6)
```

C

```
C(4,7) = 9.
C(5,7) = -22.5
C(6,7) = 13.5
C(7,7) = -18. * TNB1 - 4.5 * TNB2
C(8,7) = 9. * TNB1 + 4.5 * TNB2
```

C

```
C(4,8) = -4.5
C(5,8) = 18.
C(6,8) = -13.5
C(7,8) = 9. * (TNB1 + TNB2)
C(8,8) = -4.5 * TNB1 - 9.0 * TNB2
```

C

```
RETURN
END
```

I



## SUBROUTINE CMATX

V-25

C  
C  
C  
SUBROUTINE TO CONSTRUCT DISPL. TRANS. MATRIX IN U-W CO-ORDINATES

COMMON/GEOM2 / COF(10) , B1(4,8,10) , B2(4,8,2) , C(8,8)  
COMMON/GEOM3 /CORD,SNT,CNT,SNB1,CNB1,TNB1,SNB2,CNB2,TNB2,SNP,CNP

C  
C  
TJCI = TNB2 \* CNB1  
TICJ = TNB1 \* CNB2

C  
C  
C(1,1) = CNB1  
C(2,1) = -5.5 \* CNB1  
C(3,1) = 9. \* CNB1  
C(4,1) = -4.5 \* CNB1  
C(5,1) = SNB1  
C(6,1) = -5.5 \* SNB1  
C(7,1) = 8. \* SNB1 + TJCI  
C(8,1) = -3.5 \* SNB1 - TJCI

C  
C  
C(1,2) = -SNB1  
C(2,2) = 5.5 \* SNB1  
C(3,2) = -9. \* SNB1  
C(4,2) = 4.5 \* SNB1  
C(5,2) = CNB1  
C(6,2) = 5.5 \* TNB1 \* SNB1  
C(7,2) = -SNB1 \* (11. \* TNB1 + TNB2) - 3. \* CNB1  
C(8,2) = SNB1 \* (5.5 \* TNB1 + TNB2) + 2. \* CNB1

C  
C  
C(1,3) = 0.0  
C(2,3) = 0.0  
C(3,3) = 0.0  
C(4,3) = 0.  
C(5,3) = 0.  
C(6,3) = CORD / CNB1\*\*2  
C(7,3) = -2.\*C(6,3)  
C(8,3) = C(6,3)

C  
C  
C(1,4) = 0.0  
C(2,4) = CNB2  
C(3,4) = -4.5 \* CNB2  
C(4,4) = -C(3,4)  
C(5,4) = 0.0  
C(6,4) = TICJ  
C(7,4) = -2. \* TICJ - 2.5 \* SNB2  
C(8,4) = TICJ + 3.5 \* SNB2

C  
C  
C(1,5) = 0.0  
C(2,5) = -SNB2  
C(3,5) = 4.5 \* SNB2  
C(4,5) = -C(3,5)  
C(5,5) = 0.0  
C(6,5) = -TNB1 \* SNB2  
C(7,5) = SNB2 \* (2. \* TNB1 + 5.5 \* TNB2) + 3. \* CNB2  
C(8,5) = -SNB2 \* ( TNB1 + 5.5 \* TNB2) - 2. \* CNB2

```
C(1,6) = 0.0
C(2,6) = 0.0
C(3,6) = 0.0
C(4,6) = 0.0
C(5,6) = 0.0
C(6,6) = 0.0
C(7,6) = -CORD / CNB2**2
C(8,6) = -C(7,6)
```

C

```
C(1,7) = 0.
C(2,7) = 9.
C(3,7) = -22.5
C(4,7) = 13.5
C(5,7) = 0.
C(6,7) = 9. * TNB1
C(7,7) = -18. * TNB1 - 4.5 * TNB2
C(8,7) = 9.0 * TNB1 + 4.5 * TNB2
```

C

```
C(1,8) = 0.
C(2,8) = -4.5
C(3,8) = 18.
C(4,8) = -13.5
C(5,8) = 0.
C(6,8) = -4.5 * TNB1
C(7,8) = 9. * (TNB1 + TNB2)
C(8,8) = -4.5 * TNB1 - 9.0 * TNB2
```

C

```
RETURN
END
```

1

SUBROUTINE DIMATX(L,I)

COMMON/GEOM1 /R(50 ),Z(50 ),PHI(50 ),H(50 ) , CRV(2,50 )  
COMMON/STF1/ D(4,4) , SKI(8,8) , SK(8,8)  
COMMON/ MAT1 / E,U,NP,SIGMA(15),ETAN(15),EP(15),EE(2,2)

DIMENSION X(12)

DATA X / 0.0,0.013046735741414 , 0.067468316655507,  
1 0.160295215850488, 0.283302302935376 , 0.425562830509184,  
2 0.574437169490816, 0.716697697064624, 0.839704784149512,  
3 0.932531683344493, 0.986953264258586, 1.0 /

HI = H(I) + X(L) \* (H(I+1) - H(I))

DO 10 N=1,2

DO 10 M=1,2

10 D(M,N) = EE(M,N) \* HI

DO 20 N=3,4

DO 20 M=1,2

20 D(M,N) = 0.0

DO 30 N=1,2

DO 30 M=3,4

30 D(M,N) = 0.0

DO 40 N=3,4

DO 40 M=3,4

40 D(M,N) = D(M-2,N-2) \* HI\*\*2 / 12.

RETURN

END

1

SUBROUTINE DMATX(L,I)

```

COMMON/ DIV / NE , NL , NLI
COMMON/GEOM1 /R(50 ),Z(50 ),PHI(50 ),H(50 ) , CRV(2,50 )
COMMON/ MAT1 / E,U,NP,SIGMA(15),ETAN(15),EP(15),EE(2,2)
COMMON/ MAT3 / SUMA(2,50 ,3), SUMB(2,50 ,3), TB(20), RAT(20)
COMMON/STF1/ D(4,4) , SKI(8,8) , SK(8,8)

DIMENSION X(12) , TEMP(2,2,3) , TMP(2,2)

DATA X / 0.0,0.013046735741414 , 0.067468316655507,
1 0.160295215850488, 0.283302302935376 , 0.425562830509184,
2 0.574437169490816, 0.716697697064624, 0.839704784149512,
3 0.932531683344493, 0.986953264258586, 1.0 /

DO 10 N=1,4
DO 10 M=1,4
10 D(M,N) = 0.0

ANL = NL
HI = H(I) + X(L) * (H(I+1) - H(I))
FAC = HI / ANL
DO 20 J=1,3
DO 20 N=1,2
TEMP(1,N,J) = (SUMA( N,I,J) + X(L)*(SUMA( N,I+1,J)-SUMA( N,I,J)))
1 * FAC**J
20 TEMP(2,N,J) = (SUMB( N,I,J) + X(L)*(SUMB( N,I+1,J)-SUMB( N,I,J)))
1 * FAC**J

TMP(1,1) = -TEMP(1,1,1) + HI
TMP(1,2) = -TEMP(1,2,1)
TMP(2,1) = -TEMP(2,1,1)
TMP(2,2) = -TEMP(2,2,1) + HI

DO 30 N=1,2
DO 30 M=1,2
DO 30 K=1,2
30 D(M,N) = D(M,N) + EE(M,K) * TMP(K,N)

DO 40 N=1,2
DO 40 M=1,2
40 TMP(M,N) = 0.50 * HI * TEMP(M,N,1) - TEMP(M,N,2)

DO 50 N=3,4
DO 50 M=1,2
DO 50 K=1,2
50 D(M,N) = D(M,N) + EE(M,K) * TMP(K,N-2)

DO 60 N=1,2
DO 60 M=3,4
60 D(M,N) = D(N,M)

DO 70 N=1,2
DO 70 M=1,2
70 TMP(M,N) = (-0.25 * HI*TEMP(M,N,1) + TEMP(M,N,2))*HI - TEMP(M,N,3)

```

C

```
TMP(1,1) = TMP(1,1) + HI**3 / 12.  
TMP(2,2) = TMP(2,2) + HI**3 / 12.
```

C

```
DO 80 N=3,4  
DO 80 M=3,4  
DO 80 K=1,2  
80 D(M,N) = D(M,N) + EE(M-2,K) * TMP(K,N-2)
```

C

```
RETURN  
END
```

1

## SUBROUTINE BANSOL

\*\*\*\*\*  
 IN-CORE LINEAR EQUATION SOLVER FOR SYMMETRIC BAND MATRICES  
 \*\*\*\*\*

COMMON /BANARG/ NN, MM, A(150, 6), B(150)

DIMENSION S(1)

EQUIVALENCE (S, A)

NCOL = 150

NR = NN

NRS = NR - 1

MMR = MM - 1

DECOMPOSE MATRIX A

DO 120 N = 1, NRS

M = N - 1

MR = MINO (MM, NR-M)

PIVOT = S(N)

J = N

DO 120 L = 2, MR

J = J + NCOL

C = S(J)/PIVOT

I1 = M + L

I2 = I1 + (MR-L)\*NCOL

II = J

DO 110 I = I1, I2, NCOL

S(I) = S(I) - C\*S(II)

110 II = II + NCOL

120 S(J) = C

REDUCE AND BACKSUBSTITUTE VECTOR B

DO 220 N = 1, NRS

MR = MINO (MMR, NR-N)

C = B(N)

B(N) = C/S(N)

K = N

L1 = N + 1

L2 = N + MR

DO 220 L = L1, L2

K = K + NCOL

220 B(L) = B(L) - S(K)\*C

B(NR) = B(NR)/S(NR)

300 DO 320 I = 1, NRS

N = NR - I

MR = MINO (MMR, I)

J = N

L1 = N + 1

L2 = N + MR

DO 320 L = L1, L2

J = J + NCOL

320 B(N) = B(N) - S(J)\*B(L)

RETURN

END

```
C   ELASTIC PLASTIC ANALYSIS OF AXISYMMETRIC SHELLS WITH DISCONTINUOUS
C   MERIDIONAL SLOPE
C
C   PROGRAM MAIN (INPUT,OUTPUT,TAPE1,TAPE2,TAPE3,TAPE4,TAPE5=INPUT,
1  TAPE6 = OUTPUT ,TAPE 8, TAPE9 )
C
C   COMMON/ DIV / NE , NL , NLI
C
C   READ (5,22)NIPT
C   DO 100 I=1, NIPT
1  CALL INPUTD
C
C   CALL GEOMTY
C
C   DO 100 NLL = 1,NLI
C
C   WRITE (6,1000) NLL
C
C   CALL STIFNS (NLL)
C
C   CALL NODLOD
C
C   CALL DISPL
C
C   CALL STRESS(NLL)
C
C   CALL MATPP
C
100 CONTINUE
C
C   STOP
C
C   22 FORMAT (I5)
1000 FORMAT(31HINUMBER OF LOADING INCREMENT = ,I5)
C
C   END
1
```

## SUBROUTINE INPUTD

MODIFIED SUBROUTINE TO HANDLE THE SLOPE DISCONTIN.

```

COMMON/ DIV / NE , NL , NLI
COMMON/GEOM1 /R(2, 50),Z(2, 50),PHI(2, 50),H(2, 50),CRV(2,50)
COMMON/STSSD2/FA(4, 5), FB(4,5)
COMMON/STSSD3/NDIS( 5), NDISC
COMMON/ MAT1 / E,U,NP,SIGMA(15),ETAN(15),EP(15),EE(2,2)
COMMON/ MAT2 / STI(20),EPL(20),AP(2,2,20),DST(2,20,50 ),ZT,STN
COMMON/MATD2/ STIX(2,20, 5), EPLX(2,20, 5), ZTX, STNX
COMMON/STSS1 / T(2,20) , F(4,50 )
COMMON/BNDRCN/ NEQBC,NEBC(15)
COMMON/INPTDT/ NTAG(5,3) , NBC(5)
COMMON/BANARG/ NUMEQ,NBNWD,A(150,6),B(150)
COMMON/ DSPL1/ BT(150)
COMMON/ NTAP / NTAP1 , NTAP2
COMMON APA1(2,20, 5), APB1(2,20, 5), APA2(2,20, 5), APB2(2,20, 5),
A TAX(2,20, 5), TBX(2,20, 5)

```

```

WRITE(6,2000)
READ (5,1000)
WRITE(6,1000)

```

NUMBER OF NODES , LAYERS , LOAD INCREMENTS , AND BOUNDRY CONDITIONS

```

READ (5,1001)NN,NL, NLI, NUMBC, NDISC
WRITE(6,2001)NN,NL, NLI, NUMBC, NDISC

```

```

READ (5,1102) (NDIS(I), I= 1,NDISC)
WRITE(6,2102) (NDIS(I), I= 1,NDISC)

```

```

NE = NN - 1
READ (5,1002) (( R(M,I),Z(M,I),PHI(M,I),H(M,I), M=1,2), I=1,NE)
WRITE(6,2002)(I,(M,R(M,I),Z(M,I),PHI(M,I),H(M,I), M=1,2), I=1,NE)

```

```

READ (5,1003) ( (CRV(M,I) , M=1,2),I=1,NE)
WRITE(6,2003) (I,(CRV(M,I) , M=1,2),I=1,NE)

```

```

READ (5,1004) NP,(EP(I),SIGMA(I),ETAN(I),I=1,NP)
WRITE(6,2004) (I,EP(I),SIGMA(I),ETAN(I),I=1,NP)

```

```

READ (5,1005) E,U
WRITE(6,2005) E,U

```

```

READ (5,1006) (NBC(N) , (NTAG(N,I) , I=1,3) , N=1,NUMBC)
WRITE(6,2006) (NBC(N) , (NTAG(N,I) , I=1,3) , N=1,NUMBC)

```

BAND WIDTH , NUMBER OF SIMULTANEOUS EQUATIONS, NUMBER OF ELEMENTS

```

NBNWD = 6
NUMEQ = 3 * NN

```

ANGLE PHI IN TERMS OF RADIAN



```

DO 10 I = 1,NE
DO 10 M= 1,2
10 PHI(M,I) = PHI(M,I) / 57.2957795130823

```

```

C
C   NORMALIZED TANGENT MODULI
C

```

```

DO 150 I = 1,NP
150 ETAN(I) = ETAN(I) / E

```

```

C
C   SET UP TOTAL DISPLACEMENTS
C

```

```

DO 160 I=1,NUMEQ
160 BT(I) = 0.0

```

```

C
C   ELASTIC MODULI IN CASE OF PLANE STRESS (ISOTROPIC)
C

```

```

FE(1,1) = E / (1.-U) / (1.+U)
EE(1,2) = U * EE(1,1)
EE(2,1) = EE(1,2)
FE(2,2) = EE(1,1)

```

```

C
C   SET UP STRESS RESULTANTS
C

```

```

DO 220 I=1,NN
DO 220 M=1,4
220 F(M,I) = 0.0

```

```

C
C   ADDITIONAL INITIALIZATION IN THE CASE OF SLOPE DISCONTINUITY.
C

```

```

DO 225 I= 1,NDISC
DO 222 M = 1,4
,FA(M,I) = .0
222 FB(M,I) = .0
DO 225 K =1, NL
DO 223 JX = 1, 2
STIX(JX,K,I) = SIGMA(1)
FPLX(JX,K,I) = 0.
TAX(JX,K,I) = .0
223 TBX(JX,K,I) = .0
DO 225 N=1,2
APA1(N,K,I) = .0
APA2(N,K,I) = .0
APB2(N,K,I) = .0
225 APB1(N,K,I) = .0

```

```

C
C   SET UP EQUIVALENT STRESS , EQUIVALENT PLASTIC STRAIN , STRESS
C   VECTOR , AND (AP) MATRIX
C

```

```

NTAP1 = 8
NTAP2 = 9
REWIND NTAP1
DO 240 I=1,NN
DO 230 K=1,NL
STI(K) = SIGMA(1)
EPL(K) = 0.0

```

```

DO 230 N=1,2
  T(N,K) = 0.0
DO 230 M=1,2
230 AP(M,N,K) = 0.0
  WRITE(NTAP1) STI ,EPL , AP, T
240 CONTINUE
  END FILE NTAP1

```

C  
C  
C

BOUNDRY CONDITIONS

```

L = 0
DO 250 N=1,NUMBC
DO 250 I=1,3
  M = NTAG(N,I)
  IF(M .LE. 0) GO TO 250
  L = L + 1
  NEBC(L) = 3 * (NBC(N) - 1) + I
250 CONTINUE
  NEQBC = L

```

C

RETURN

C

1000 FORMAT(72H

1

```

1001 FORMAT(5I5)
1002 FORMAT ( 4F15. )
1003 FORMAT(2F15.0)
1004 FORMAT(I5 / (3E15.0))
1005 FORMAT(E10.3,F5.0)
1006 FORMAT(I4,1X,3I1)

```

C

2000 FORMAT(1H1)

2001 FORMAT( //

```

1 30H NUMBER OF NODAL CIRCLES . . . I10 /
2 30H NUMBER OF LAYERS . . . . . I10 /
3 30H NUMBER OF LOAD INCREMENTS . . I10 /
4 30H NUMBER OF BOUNDRY CONDITIONS I10 /
5* NUMBER OF NODES WITH DISCONT. SLOPE* I4 /// )

```

1102 FORMAT (10I5)

2102 FORMAT ( \* NODES WHERE SLOPE IS DISCONTINUOUS...\*10I10///)

2002 FORMAT (//

```

A2X,*ELEMENT* 2X,4H END 7X,11HABSCISSA-R-,8X,12H ORDINATE-Z-,7X,
1 14HLATITUDE ANGLE , 9X,9HTHICKNESS / 25X,5H(IN.),15X,5H(IN.),
2 13X,8H(DEGREE),14X,5H(IN.)///( 2I7,4E20.9/7X, 17, 4E20.9))

```

2003 FORMAT(30H-CURVATURES AT NODAL CIRCLES /

```

1 8H ELEMENT , 7X , 6HEND(1) , 14X , 6HEND(2) //(I5,2E20.7))

```

2004 FORMAT(1H-,14X ,26HEQUIVALENT PLASTIC STRAIN ,8X,18HEQUIVALENT ST  
1RESS ,13X,16HTANGENT MODULUS //(I5,3E30.7))

2005 FORMAT( 30H-MODULUS OF ELASTICITY (PSI) ,E20.7/

```

1 30H POISSON RATIO . . . . . ,E20.7///)

```

2006 FORMAT(43H BOUNDRY CONDITIONS (1=RESTRAINED,0=FREE) //

```

1 6H POINT , 3X , 3H R , 2X , 3H Z , 2X , 3HROT //(I6,3I5))

```

C

END

1

## SUBROUTINE GEOMTY

C  
C COMPUTE GEOMETRIC PARAMETERS FOR COPELETELY COMPATIBLE ELEMENT (3)  
C MODIFIED SUBROUTINE TO HANDLE THE SLOPE DISCONTIN.  
C

COMMON/ DIV / NE , NL , NLI  
COMMON/GEOM1 /R(2, 50),Z(2, 50),PHI(2, 50),H(2, 50),CRV(2,50)  
COMMON/GEOM2 / COF(10) , B1(4,8,10) , B2(4,8,2) , C(8,8)  
COMMON/GEOM3 /CORD,SNT,CNT,SNB1,CNB1,TNB1,SNB2,CNB2,TNB2,SNP,CNP  
COMMON/GEOM4 /YBAR,YP,YPP,RW,XT,ARC,RV,CNP1,CNP2,B(4,8)  
COMMON /GEOM5/ A1,A2,A3,A4  
COMMON/BANARG/NUMEQ,NBNWD,BK(150,6),P(150)  
COMMON/INTEG1/ NUMIPD  
COMMON/INTEG2/YP1(10),FAC(10)

C  
C DIMENSION X(12) , W(10) , SINF(2,50), CSNF(2,50)  
C

C EQUIVALENCE (SINF(1),BK(1)) , (CSNF(1),BK(151))  
C

DATA X / 0.0,0.013046735741414 , 0.067468316655507,  
1 0.160295215850488, 0.283302302935376 , 0.425562830509184,  
2 0.574437169490816, 0.716697697064624, 0.839704784149512,  
3 0.932531683344493, 0.986953264258586, 1.0 /

C  
C DATA W / 0.066671344308688, 0.149451349150581,  
1 0.219086362515982, 0.269266719309996, 0.295524224714753,  
2 0.295524224714753, 0.269266719309996, 0.219086362515982,  
3 0.149451349150581, 0.066671344308688 /  
C

C  
C REWIND 1  
C REWIND 2  
C REWIND 3  
C REWIND 4

C  
C NUMIPD = 10  
C WRITE(6,1006)

C  
C NN = NE + 1  
C DO 10 I = 1,NE  
C DO 10 M = 1,2  
C SINF (M,I) = SIN(PHI(M,I))  
10 CSNF (M,I) = COS(PHI(M,I))  
C

C COMPUTE GEOMETRICAL PARAMETERS  
C

C  
C DO 100 I = 1,NE  
C DR = R(2,I) - R(1,I)  
C DZ = Z(2,I) - Z(1,I)  
C CORD = SQRT(DR\*\*2 + DZ\*\*2)  
C SNT = DR / CORD  
C CNT = DZ / CORD  
C

C  
C SNB1 = CSNF(1,I) \* CNT - SINF(1,I) \* SNT  
C CNB1 = SINF(1,I) \* CNT + CSNF(1,I) \* SNT  
C TNB1 = SNB1 / CNB1

```

SNB2 = CSNF(2,I) * CNT - SIN(2,I) * SNT
CNB2 = SIN(2,I) * CNT + CSNF(2,I) * SNT
TNB2 = SNB2 / CNB2

```

```

C
CNP1 = CSNF(1,I) / CNB1
CNP2 = CSNF(2,I) / CNB2

```

```

C
YPP1 = -CORD * CRV(1,I) / CNB1**3
YPP2 = -CORD * CRV(2,I) / CNB2**3

```

```

C
A1 = TNB1
A2 = TNB1 + 0.50 * YPP1
A3 = -(5.*TNB1 + 4.*TNB2) + (0.5*YPP2 - YPP1)
A4 = 3. * (TNB1 + TNB2) + 0.50 * (YPP1 - YPP2)

```

```

C
DPHI = PHI(2,I) - PHI(1,I)
SNP = SIN(DPHI)
CNP = COS(DPHI)

```

```

C
C
ESTABLISH STRAIN-DISPLACEMENT MATRICES

```

```

C
NIPD2 = NUMIPD + 2
DO 70 K = 1,NIPD2
XT = X(K)
YBAR = (1.-XT) * (A1 + XT * (A2 + XT * (A3 + XT * A4)))
YP = A1*(1.-2.*XT) + XT*(A2*(2.-3.*XT) + XT*(A3*(3.-4.*XT) +
1 A4 * XT * (4.-5.*XT)))
YPP = 2.*(-A1 + A2 * (1.-3.*XT)) + XT * (A3 * (6.-12.*XT) +
1 A4 * XT * (12.-20.*XT))
RV = CORD * (SNT + YBAR * CNT)
RW = R(1,I) + XT * RV
ARC = SQRT(1. + YP**2)

```

```

C
IF(R(1,I) .NE. .0) GO TO 20

```

```

C
C
STRAIN - DISPLACEMENT MATRIX FOR CENTRAL CAP

```

```

C
CALL B1MATX
GO TO 30

```

```

C
C
STRAIN - DISPLACEMENT MATRIX FOR A FRUSTRUM

```

```

C
20 CALL B1MATX

```

```

C
30 IF(K.EQ. 1 .OR. K .EQ. NIPD2) GO TO 50
KK = K - 1
YPI(KK) = YP
FAC(KK) = 0.50 * CORD * RW * W(KK)
COF(KK) = ARC * FAC(KK)

```

```

C
DO 40 N = 1,8
DO 40 M = 1,4
40 B1(M,N,KK) = B(M,N)
GO TO 70

```

```

C

```

```
C      TO BE USED IN STRESS SUBROUTINE
C
50 KK = (NUMIPD + K) / (NUMIPD + 1)
   DO 60 N = 1,8
   DO 60 M = 1,4
60 B2(M,N,KK) = B(M,N)
70 CONTINUE

C      DISPLACEMENT TRANSFORMATION MATRIX
C
C      IF(R(1,I) .NE. .0) GO TO 80
C
C      DISPLACEMENT TRANSFORMATION MATRIX FOR CENTRAL CAP
C
C      CALL CIMATX
C      GO TO 90

C      DISPLACEMENT TRANSFORMATION MATRIX FOR A FRUSTRUM
C
80 CALL CMATX

C
90 WRITE (1) B1, COF
   WRITE (2) B2
   WRITE (3) C
   WRITE (4) YP1, FAC, TNB1, SNT, CNT
   WRITE(6,1007) I,CORD,SNT,CNT,TNB1,TNB2

C
100 CONTINUE

C
   END FILE 1
   END FILE 2
   END FILE 3
   END FILE 4

C
   RETURN

C
1006 FORMAT(8H-ELEMENT,5X,4HCORD,14X,4HSINT,14X,4HCSNT,14X,4HTNB1,
1 14X,4HTNB2 //)
1007 FORMAT(I4,5E18.7)

C
   END

1
```

SUBROUTINE STIFNS(NLL)

SUBROUTINE TO SET UP SYSTEM STIFFNESS MATRIX  
 MODIFIED SUBROUTINE TO HANDLE THE SLOPE DISCONTIN.

COMMON/ DIV / NE , NL , NLI  
 COMMON/GEOM1 /R(2, 50),Z(2, 50),PHI(2, 50),H(2, 50),CRV(2,50)  
 COMMON/MATD1 /SUMA1(2,5 ,3), SUMA2(2,5 ,3), SUMB1(2,5 ,3)  
 A ,SUMB2(2,5 ,3)  
 COMMON/STSSD3/NDIS( 5), NDISC  
 COMMON/GEOM2 / COF(10) , B1(4,8,10) , B2(4,8,2) , C(8,8)  
 COMMON/ GEOM4/YBAR,YP, YPP , RW , XT , ARC , RV , CNP1,CNP2,B(4,8)  
 COMMON/ MAT3 / SUMA(2,50 ,3), SUMB(2,50 ,3), TB(20), RAT(20)  
 COMMON/STF1/ D(4,4) , SKI(8,8) , SK(8,8)  
 COMMON/BANARG/NUMEQ,NBNWD,BK(150,6),P(150)  
 COMMON/INTEG1/ NUMIPD  
 COMMON/CONDNS/ DD(2,8,50), DB(6,2,50), RB(2,50)

DIMENSION SKG(8,8) , TEMP(8,8)  
 EQUIVALENCE (SKG(1),SK(1)) , (TEMP(1),SKI(1))

REWIND 1  
 REWIND 3

NX = 1  
 MA = 0  
 MB = 0  
 DO 1 N=1,6  
 DO 1 M=1,NUMEQ  
 1 BK(M,N) = 0.0

DO 100 I=1,NE  
 IF (NX .GT. NDISC) GO TO 2  
 IF ( I+1 .EQ. NDIS(NX)) MB =1  
 IF ( I .EQ. NDIS(NX)) MA =1  
 2 II = I

READ (1) B1, COF  
 READ (3) C

ELEMENT STIFFNESS MATRIX IN GENERALIZED COORDINATES

DO 5 N=1,8  
 DO 5 M=1,8  
 5 SKG(M,N) = 0.0

DO 50 L=1,NUMIPD  
 LL = L + 1  
 IF (NLL .NE. 1) GO TO 7  
 CALL DIMATX(LL,II)  
 GO TO 8

7 CALL DMATX(LL,II,MA,MB,NX)

8 DO 10 N=1,8

```

      DO 10 M=1,4
10 R(M,N) = 0.0
C
      DO 20 N=1,8
      DO 20 M=1,4
      DO 20 K=1,4
20 B(M,N) = B(M,N) + D(M,K) * B1(K,N,L)
C
      DO 30 N=1,8
      DO 30 M=1,8
30 SKI(M,N) = 0.0
C
      DO 40 N=1,8
      DO 40 M=1,8
      DO 40 K=1,4
40 SKI(M,N) = SKI(M,N) + B1(K,M,L) * B(K,N)
C
      DO 50 N=1,8
      DO 50 M=1,8
50 SKG(M,N) = SKG(M,N) + COF(L) * SKI(M,N)
C
      IF (MA .EQ. 1) NX = NX + 1
      MA = 0
      MB = 0
C
      ELEMENT STIFFNESS MATRIX IN SYSTEM CO-ORDINATES
C
      DO 60 N=1,8
      DO 60 M=1,8
60 TEMP(M,N) = 0.0
C
      DO 70 N=1,8
      DO 70 M=1,8
      DO 70 K=1,8
70 TEMP(M,N) = TEMP(M,N) + SKG(M,K) * C(K,N)
C
      DO 80 N = 1, 8
      DO 80 M = 1, 8
80 SK(M,N) = 0.
C
      DO 90 N=1,8
      DO 90 M=1,8
      DO 90 K=1,8
90 SK(M,N) = SK(M,N) + C(K,M) * TEMP(K,N)
      IF(R(1,I) .NE. .0) GO TO 95
      SK(1,1) = 1.0
      SK(3,3) = 1.0
C
95 CONTINUE
C
      CONDENSATION
C
      DET = SK(7,7) * SK(8,8) - SK(7,8) * SK(8,7)
      DD(1,1,I) = SK(8,8) / DET
      DD(2,2,I) = SK(7,7) / DET

```

```
DD(1,2,I) = -SK(7,8) / DET  
DD(2,1,I) = -SK(8,7) / DET
```

C

```
DO 105 N = 1, 6  
K = N + 2  
DO 105 M = 1, 2  
DD(M,K,I) = 0.  
105 DB(N,M,I) = 0.
```

C

```
DO 115 N = 1, 6  
DO 110 M = 1, 2  
DO 110 K = 1, 2  
J = N + 2  
DB(N,M,I) = DB(N,M,I) + SK(N,K+6) * DD(K,M,I)  
110 DD(M,J,I) = DD(M,J,I) + DD(M,K,I) * SK(K+6,N)  
DO 115 JJ = 1, 6  
DO 115 KK = 1, 2  
115 SK(JJ,N) = SK(JJ,N) - SK(JJ,KK+6) * DD(KK,N+2,I)
```

C

```
DO 100 M=1,6  
DO 100 N=M,6  
II = 3*(I-1) + M  
JJ = N-M+1  
100 BK(II,JJ) = BK(II,JJ) + SK(M,N)  
END FILE 9
```

C

```
RETURN  
END
```

1



## SUBROUTINE NODLOD

C SUBROUTINE TO GENERATE CONSISTENT NODAL LOADS  
 C MODIFIED SUBROUTINE TO HANDLE THE SLOPE DISCONTIN.  
 C

COMMON/ DIV /NE,NL,NLI  
 COMMON/BANARG/ NUMEQ,NBNWD,A(150,6),B(150)  
 COMMON/GEOM1 /R(2, 50),Z(2, 50),PHI(2, 50),H(2, 50),CRV(2,50)  
 COMMON/GEOM2 / COF(10) , B0(4,8,10) , B2(4,8,2) , C(8,8)  
 COMMON/INTEG1/NUMIPD  
 COMMON/INTEG2/YP1(10),FAC(10)  
 COMMON/CONDNS/ DD(2,8,50), DB(6,2,50), RB(2,50)

C DIMENSION B1(150),DP(8),PSTAR(8),TEMP(8),X(10)

C DATA X / 0.013046735741414 , 0.067468316655507,  
 1 0.160295215850488, 0.283302302935376 , 0.425562830509184,  
 2 0.574437169490816, 0.716697697064624, 0.839704784149512,  
 3 0.932531683344493, 0.986953264258586 /

C REWIND 3  
 C REWIND 4

C READ (5,900) INDX  
 IF (INDX .EQ. 0) GO TO 5  
 READ (5,1000) B(1), B(2), B(3), B1(1), B1(2), B1(3)  
 NE3 = 3\* INDX  
 DO 3 I= 4,NE3, 3  
 B (I) = B (1)  
 B (I+1) = B (2)  
 B (I+2) = B (3)  
 B1(I) = B1(1)  
 B1(I+1) = B1(2)  
 3 B1(I+2) = B1(3)  
 NN = NE +1  
 IF (INDX .EQ. NN ) GO TO 7  
 NEX = NE3 + 1  
 NE3 = 3 \* NN  
 DO 4 I = NEX, NE3  
 B (I) = 0.0  
 4 B1(I) = 0.0  
 GO TO 7  
 C  
 5 NE3 = 3 \* (NE + 1)  
 READ (5,1000) (B(I),B(I+1),B(I+2),B1(I),B1(I+1),B1(I+2),I=1,NE3,3)  
 7 WRITE(6,2000) (2(I),B(I+1),B(I+2),B1(I),B1(I+1),B1(I+2),I=1,NE3,3)  
 C  
 DO 100 I=1,NE  
 L = 3 \* (I-1)  
 C  
 READ (3) C  
 READ (4) YP1, FAC, TNB1, SNT, CNT  
 C  
 DO 10 J=1,8  
 10 PSTAR(J) = 0.0

```

C
DO 20 K=1,NUMIPD
PU = B1(L+1) + X(K) * (B1(L+4) - B1(L+1))
PW = B1(L+2) + X(K) * (B1(L+5) - B1(L+2))

```

```

C
IF (R(1,I) .NE. 0) GO TO 15
SUM1 = (PU - PW * YP1(K)) * FAC(K)
SUM2 = (PU * YP1(K) + PW) * FAC(K)
DP(1) = 0.0
DP(2) = 0.0
DP(3) = -SUM1 * CNT + SUM2 * SNT
DP(4) = (SUM1 + SUM2 * TNB1) * X(K)
DP(5) = SUM1 * X(K) * X(K)
DP(6) = X(K) * DP(5)
DP(7) = SUM2 * X(K) * X(K)
DP(8) = DP(7) * X(K)
GO TO 16

```

```

C
15 DP(1) = (PU - PW * YP1(K)) * FAC(K)
DP(2) = X(K) * DP(1)
DP(3) = X(K) * DP(2)
DP(4) = X(K) * DP(3)
DP(5) = (PU * YP1(K) + PW) * FAC(K)
DP(6) = X(K) * DP(5)
DP(7) = X(K) * DP(6)
DP(8) = X(K) * DP(7)

```

```

C
16 DO 20 J=1,8
20 PSTAR(J) = PSTAR(J) + DP(J)

```

```

C
DO 30 J=1,8
30 TEMP(J) = 0.0

```

```

C
DO 40 N=1,8
DO 40 M=1,8
40 TEMP(N) = TEMP(N) + C(M,N) * PSTAR(M)

```

```

C
CONDENSATION

```

```

C
RB(1,I) = TEMP(7)
RB(2,I) = TEMP(8)
DO 45 N=1,6
DO 45 K=1,2
45 TEMP(N) = TEMP(N) - DB(N,K,I) * RB(K,I)

```

```

C
DO 50 N=1,6
LL = L + N
50 B(LL) = B(LL) + TEMP(N)

```

```

C
100 CONTINUE

```

```

C
WRITE(6,2003) (B(I), I=1,NUMEQ)

```

```

C
RETURN
C

```

900 FORMAT (I5)

1000 FORMAT (6E12.0)

2000 FORMAT(/// 20X,18HCONCENTRATED LOADS ,42X,17HDISTRIBUTED LOADS //  
1 8X,10H R-FORCE ,11X,7HZ-FORCE ,14X,6HMOMENT ,12X,10HMERIDIONAL,  
2 12X, 6HRADIAL ,14X,6HMOMENT /(6E20.7))

2003 FORMAT(44HCONSISTENT EXTERNAL LOADS AT NODAL CIRCLES //  
1 8X,10H R-FORCE ,10X,8H Z-FORCE,14X,6HMOMENT /(3E20.7))

C

FND

1

## SUBROUTINE DISPL

```
C
COMMON /BANARG/  NN, MM, A(150, 6), B(150)
COMMON /BNDRCN/  NEQBC, NEBC(15)
COMMON / DSPL1/  BT(150)

C
DO 100  N=1, NEQBC
  I = NEBC(N)
  A(I,1) = 1.0
  B(I) = 0.0
  DO 100  J=2, MM
    A(I,J) = 0.0
    L = I-J+1
    IF(L .LE. 0)  GO TO 100
    A(L,J) = 0.0
100 CONTINUE

C
CALL BANSOL

C
DO 200  I=1, NN
200 BT(I) = BT(I) + B(I)

C
WRITE(6,2001) (B(I) , I=1, NN)
WRITE(6,2002) (BT(I), I=1, NN)

C
RETURN

C
2001 FORMAT(50H1DISPLACEMENT INCREMENTS AT NODAL CIRCLES //
1 7X,11H HORIZONTAL,10X,8HVERTICAL,13X,8HROTATION /(3E20.7))
2002 FORMAT(50H1TOTAL DISPLACEMENTS AT NODAL CIRCLES //
1 7X,11H HORIZONTAL,10X,8HVERTICAL,13X,8HROTATION /(3E20.7))

C
END

1
```

SUBROUTINE STRESS(NLL)

MODIFIED SUBROUTINE TO HANDLE THE SLOPE DISCONTIN.

COMMON/ DIV / NE , NL , NLI  
 COMMON/GEOM1 /R(2, 50),Z(2, 50),PHI(2, 50),H(2, 50),CRV(2,50)  
 COMMON/GEOM2 / COF(10) , B1(4,8,10) , B2(4,8,2) , C(8,8)  
 COMMON/STSS1 / T(2,20) , F(4,50 )  
 COMMON/STSS2 / ALPHA(8),DSTR(2) ,BE(2,8),DFRC(4)  
 COMMON/STSSD1/DSTA(2,20, 5), DSTB(2,20,5)  
 COMMON/STSSD2/FA(4, 5), FB(4,5)  
 COMMON/STSSD3/NDIS( 5), NDISC  
 COMMON/ MAT2 / STI(20),EPL(20),AP(2,2,20),DST(2,20,50 ),ZT,STN  
 COMMON/BANARG/ NUMEQ,NBNWD,A(150,6),B(150)  
 COMMON/INTEG1/ NUMIPD  
 COMMON/STF1/ D(4,4) , SKI(8,8) , SK(8,8)  
 COMMON/CONDNS/ DD(2,8,50), DB(6,2,50), RB(2,50)

DIMENSION DFA(4,5 ) , DFB(4,5)  
 DIMENSION TEMP(4,8) , DF(4,50), Q(8)  
 EQUIVALENCE (TEMP(1),SKI(1)) , (DF(1),A(1))

REWIND 2  
 REWIND 3

NN = NE + 1  
 ANL = NL  
 DO 10 I=1,NN  
 DO 5 K=1,NL  
 DO 5 M=1,2  
 5 DST(M,K,I) = 0.0  
 DO 10 N=1,4  
 10 DF(N,I) = 0.0

DO 15 I= 1,NDISC  
 DO 12 K = 1,NL  
 DO 12 M = 1,2  
 12 DSTA(M,K,I) = 0.0  
 12 DSTB(M,K,I) = 0.0  
 DO 15 N=1,4  
 DFA(N,I) = .0  
 15 DFB(N,I) = .0  
 WRITE (6,1000)

NX = 1  
 MA = 0  
 MB = 0  
 DO 148 I=1,NE

READ (2) B2  
 READ (3) C

DO 20 M=1,8  
 20 ALPHA(M) = 0.0

C RECOVERING CONDENSED DEG OF FREEDOM

C  
 Q(7) = 0.  
 Q(8) = 0.  
 IX = 3 \* (I-1)

C  
 DO 25 M = 1, 2  
 DO 22 K = 1, 2  
 L = M + 6  
 22 Q(L) = Q(L) + DD(M,K,I) \* RB(K,I)  
 DO 25 J = 1, 6  
 JJ = J + IX  
 25 Q(L) = Q(L) - DD(M,J+2, I) \* B(JJ)

C  
 DO 27 JJ = 1,6  
 J = IX + JJ  
 27 Q(JJ) = B(J)

C  
 DO 30 M=1,8  
 DO 30 N=1,8  
 30 ALPHA(M) = ALPHA(M) + C(M,N) \* Q(N)

C  
 DO 148 L=1,2  
 II = I+L-1  
 IF (NDIS(NX) .EQ. II .AND. NDIS(NX) .EQ. I+1) MB=1  
 IF (NDIS(NX) .EQ. II .AND. NDIS(NX) .EQ. I) MA=1

C DETERMINATION OF STRAIN ALONG THE THICKNESS

C  
 DO 78 K=1,NL  
 AK = K  
 ZBAR = ((AK - 0.50)/ANL - 0.50) \* H(L,I)  
 DO 40 N=1,8  
 DO 40 M=1,2  
 40 BE(M,N) = B2(M,N,L) + ZBAR \* B2(M+2,N,L)

C  
 DO 50 M=1,2  
 50 DSTR(M) = 0.0

C  
 DO 60 M=1,2  
 DO 60 N=1,8  
 60 DSTR(M) = DSTR(M) + BE(M,N) \* ALPHA(N)  
 IF (MA .EQ. 1) GO TO 72  
 IF (MB .EQ. 1) GO TO 75

C  
 DO 70 M=1,2  
 70 DST(M,K,II) = DST(M,K,II) + 0.50 \* DSTR(M)  
 GO TO 78  
 72 DO 73 M= 1,2  
 73 DSTA(M,K,NX) = DSTR(M)  
 GO TO 78  
 75 DO 76 M= 1,2  
 76 DSTB(M,K,NX) = DSTR(M)  
 78 CONTINUE

C DETERMINATION OF STRESS RESULTANTS

C  
 III = I  
 LL = 1 + (NUMIPD+1) \* (L-1)  
 IF (NLL .NE. 1) GO TO 80  
 CALL DIMATX(LL,III)  
 GO TO 90

C  
 80 MX = MA  
 MY = MB  
 MZ = NX  
 CALL DMATX(LL,III,MX,MY,MZ)

C  
 90 DO 100 N=1,8  
 DO 100 M=1,4  
 100 TEMP(M,N) = 0.0

C  
 DO 110 N=1,8  
 DO 110 M=1,4  
 DO 110 K=1,4  
 110 TEMP(M,N) = TEMP(M,N) + D(M,K) \* B2(K,N,L)

C  
 DO 120 M=1,4  
 120 DFRC(M) = 0.0

C  
 DO 130 M=1,4  
 DO 130 K=1,8  
 130 DFRC(M) = DFRC(M) + TEMP(M,K) \* ALPHA(K)

C  
 WRITE (6,1001) I,L,(DFRC(M) , M=1,4)

C  
 139 IF (MA .EQ. 1) GO TO 142  
 IF (MB .EQ. 1) GO TO 145

C  
 DO 140 M=1,4  
 140 DF(M,II) = DF(M,II) + 0.50 \* DFRC(M)  
 GO TO 148  
 142 DO 143 M=1,4  
 143 DFA(M,NX) = DFRC(M)  
 MA = 0  
 IF (NDISC .GT. NX) NX = NX + 1  
 GO TO 148  
 145 DO 146 M=1,4  
 146 DFB(M,NX) = DFRC(M)  
 MB = 0  
 148 CONTINUE

C  
 DO 150 M=1,2  
 DO 150 K=1,NL  
 DST(M,K,1) = 2.0 \* DST(M,K,1)  
 150 DST(M,K,NN) = 2.0 \* DST(M,K,NN)

C  
 DO 160 M=1,4  
 DF(M,1) = 2.0 \* DF(M,1)  
 160 DF(M,NN) = 2.0 \* DF(M,NN)

```

C
DO 220 I = 1, NDISC
DO 215 N = 2,4
DFA(N,I) = 0.5 * (DFA(N,I) + DFB(N,I))
215 DFB(N,I) = DFA(N,I)
C
DO 220 K = 1, NL
DSTA(2,K,I) = 0.5 * (DSTA(2,K,I) + DSTB(2,K,I))
220 DSTB(2,K,I) = DSTA(2,K,I)
C
WRITE (6,1002)
IX = 1
IF (NDISC .EQ. 0) GO TO 200
NX = 1
190 JX = NDIS(NX) -1
WRITE(6,1100)(I, (DF(M,I), M=1,4), I= IX, JX)
JN = JX +1
WRITE (6,1110) JN,JX, (DFB(M,NX), M=1,4)
WRITE (6,1110) JN,JN, (DFA(M,NX), M=1,4)
IX = JX+2
IF (NX .EQ. NDISC) GO TO 200
NX = NX + 1
GO TO 190
200 WRITE(6,1100)(I, (DF(M,I), M=1,4), I= IX, NN)
C
C
C
TOTAL STRESS RESULTANTS
C
WRITE (6,2000)
NX = 1
DO 170 I=1,NN
IF ( I .EQ. NDIS(NX)) GO TO 164
DO 162 M= 1,4
162 F(M,I) = F(M,I) + DF(M,I)
WRITE (6,2001) I, (F(M,I), M=1,4)
GO TO 170
164 DO 165 M=1,4
FA(M,NX) = FA(M,NX) + DFA(M,NX)
165 FB(M,NX) = FB(M,NX) + DFB(M,NX)
NEL = I-1
WRITE (6,2002) I, NEL, (FB(M,NX), M=1,4)
WRITE (6,2002) I, I, (FA(M,NX), M=1,4)
IF (NDISC .GT. NX) NX = NX +1
170 CONTINUE
C
IX = 1
IF (NDISC .EQ. 0) GO TO 179
NX = 1
172 JX = NDIS(NX) -1
DO 174 I = IX, JX, 2
II = I+1
IF ( II .GT. JX) GO TO 173
WRITE (6,1004) (I,K, (DST(M,K,I),M=1,2),II ,K,(DST(M,K,II ) ,
I M=1,2),K=1,NL)
GO TO 174
173 WRITE (6,1005) (I,K, (DST(M,K,I) , M=1,2), K=1, NL)

```



174 CONTINUE

JN = JX + 1

WRITE(6,1006) JX,JN, (JN,K,(DSTB(M,K,NX), M=1,2),  
1JN, K, (DSTA(M,K,NX), M=1,2), K=1,NL)

IX = JX+2

IF (NX .EQ. NDISC) GO TO 179

NX = NX + 1

GO TO 172

179 DO 180 I= IX, NN, 2

II = I + 1

180 WRITE (6,1004) (I,K, (DST(M,K,I),M=1,2),II ,K,(DST(M,K,II ) ,  
I M=1,2),K=1,NL)

C

RETURN

1000 FORMAT(55H1INCREMENTS OF STRESS RESULTANTS AT THE END OF ELEMENTS/  
1 8H ELEMENT,2X,7HEND NO.,4X, 16HMERIDIONAL FORCE ,5X,16HCIRCUMFER.  
2 FORCE ,5X,18HMERIDIONAL MOMENT ,4X,18HCIRCUMFER. MOMENT //)

1001 FORMAT(I5,4X,I5,4E21.7)

1002 FORMAT(50H1INCREMENTS OF STRESS RESULTANTS AT NODAL CIRCLES /  
1 6H NODE,18X,16HMERIDIONAL FORCE ,6X,16HCIRCUMFER. FORCE ,6X,  
2 18HMERIDIONAL MOMENT ,4X,18HCIRCUMFER. MOMENT // )2000 FORMAT(50H1TOTAL STRESS RESULTANTS AT NODAL CIRCLES /  
1 6H NODE,18X,16HMERIDIONAL FORCE ,6X,16HCIRCUMFER. FORCE ,6X,  
2 18HMERIDIONAL MOMENT ,4X,18HCIRCUMFER. MOMENT // )1004 FORMAT(30H2INCREMENTS OF STRAINS /  
15H NODE,2X,5HLAYER,7X,10HMERIDIONAL,10X,10HCIRCUMFER.,21X,  
25H NODE,2X,5HLAYER,7X,10HMERIDIONAL,10X,10HCIRCUMFER. //  
3(I4,2X,I4,2E20.6,20X,I4,2X,I4,2E20.6))1005 FORMAT(30H2INCREMENTS OF STRAINS /  
15H NODE,2X,5HLAYER,7X,10HMERIDIONAL,10X,10HCIRCUMFER. //  
2(I4, 2X, I4, 2E20.6 ))1006 FORMAT  
A(1H2 \* INCREMENTS OF STRAINS AT THE NODE WHERE SLOPE IS DISCONTI  
INUOUS. \* //17X,\*ELEMENT\* 70X, \*ELEMENT\* / 18X,I3, 74X, I3//  
15H NODE,2X,5HLAYER,7X,10HMERIDIONAL,10X,10HCIRCUMFER.,21X,  
25H NODE,2X,5HLAYER,7X,10HMERIDIONAL,10X,10HCIRCUMFER. //  
3(I4,2X,I4,2E20.6,20X,I4,2X,I4,2E20.6))

2001 FORMAT (I5, 11X, 4E22.7)

2002 FORMAT (I5, \* ELEMENT\* I3, 4E22.7 )

1100 FORMAT (I5, 11X, 4E22.7)

1110 FORMAT (I5, \* ELEMENT\* I3, 4E22.7 )

C

END

1

SUBROUTINE MATPP

SUBROUTINE TO ESTABLISH MATERIAL PROPERTIES  
MODIFIED SUBROUTINE TO HANDLE THE SLOPE DISCONTIN.

COMMON/ DIV / NE , NL , NLI  
COMMON/ MAT1 / E,U,NP,SIGMA(15),ETAN(15),EP(15),EE(2,2)  
COMMON/ MAT2 / STI(20),EPL(20),AP(2,2,20),DST(2,20,50 ),ZT,STN  
COMMON/ MAT3 / SUMA(2,50 ,3), SUMB(2,50 ,3), TB(20), RAT(20)  
COMMON/ MAT4 / DSTP(2) , DSTE(2) , DT(2) , TT(2)  
COMMON/STSS1 / T(2,20) , F(4,50 )  
COMMON/MATD1 /SUMA1(2, 5,3), SUMA2(2, 5,3), SUMB1(2, 5,3)  
A ,SUMB2(2, 5,3)  
COMMON/STSSD3/NDIS( 5), NDISC  
COMMON/ NTAP / NTAP1 , NTAP2

REWIND NTAP1  
REWIND NTAP2

NN = NE + 1  
DO 6 J=1,3  
DO 5 I=1,NN  
DO 5 N=1,2  
SUMA( N,I,J) = 0.0  
5 SUMB( N,I,J) = 0.0  
DO 6 I=1,NDISC  
DO 6 N=1,2  
SUMA1(N,I,J) = 0.0  
SUMA2(N,I,J) = 0.0  
SUMB2(N,I,J) = 0.0  
6 SUMB1(N,I,J) = 0.0  
NX = 1

DO 200 I=1,NN

READ (NTAP1) STI, EPL, AP, T

IF ( I .NE. NDIS(NX)) GO TO 8  
CALL MATPD(I,NX,RAT)

GO TO 160

8 DO 150 K=1,NL  
DO 10 M=1,2  
10 DSTP(M) = 0.0

DO 20 M=1,2  
DO 20 N=1,2  
20 DSTP(M) = DSTP(M) + AP(M,N,K) \* DST(N,K,I)

DO 30 M=1,2  
30 DSTE(M) = DST(M,K,I) - DSTP(M)

DO 40 M=1,2  
40 DT(M) = 0.0

```

DO 50 M=1,2
DO 50 N=1,2
50 DT(M) = DT(M) + EE(M,N) * DSTE(N)
C
DO 60 M=1,2
60 TT(M) = T(M,K) + DT(M)
C
S1 = TT(1) - 0.50 * TT(2)
S2 = TT(2) - 0.50 * TT(1)
TBAR = SQRT(TT(1)*S1 + TT(2)*S2)
IF (DSTP(1) .EQ. 0.0 .AND. DSTP(2) .EQ. 0.0) GO TO 70
C
S1 = T(1,K) - 0.50 * T(2,K)
S2 = T(2,K) - 0.50 * T(1,K)
FLAG = S1 * DT(1) + S2 * DT(2)
IF (FLAG .LT. 0.0) GO TO 70
C
EP1 = DSTP(1) + 0.50 * DSTP(2)
EP2 = DSTP(2) + 0.50 * DSTP(1)
DEP = SQRT(4./3. * (DSTP(1)*EP1 + DSTP(2)*EP2))
EPL(K) = EPL(K) + DEP
GO TO 80
C
70 STM = 0.999 * STI(K)
IF (TBAR .LT. STM) GO TO 90
C
80 KK = K
II = I
CALL INTERP(KK,II)
RAT(K) = STN / TBAR
GO TO 100
C
90 ZT = 1.0
STN = STI(K)
RAT(K) = 1.0
C
100 DO 110 M=1,2
110 T(M,K) = RAT(K) * TT(M)
C
S1 = T(1,K) - 0.50 * T(2,K)
S2 = T(2,K) - 0.50 * T(1,K)
TB(K) = SQRT(S1 * T(1,K) + S2 * T(2,K))
IF (TB(K) .EQ. 0.0) GO TO 120
S1 = S1 / TB(K)
S2 = S2 / TB(K)
SS1 = (S1 + U*S2) * (1. - ZT)
SS2 = (S2 + U*S1) * (1. - ZT)
DNOM = (1.-U)*(1.+U)*ZT + S1*SS1 + S2*SS2
S1 = S1 / DNOM
S2 = S2 / DNOM
AP(1,1,K) = S1 * SS1
AP(1,2,K) = S1 * SS2
AP(2,1,K) = S2 * SS1
AP(2,2,K) = S2 * SS2
GO TO 135

```

```
C
120 DO 130 M=1,2
    DO 130 N=1,2
130 AP(M,N,K) = 0.0
C
135 AK = K
    DO 140 N=1,2
        SUMA( N,I,1) = SUMA( N,I,1) + AP(1,N,K)
        SUMB( N,I,1) = SUMB( N,I,1) + AP(2,N,K)
        SUMA( N,I,2) = SUMA( N,I,2) + AP(1,N,K) * (AK-0.50)
        SUMB( N,I,2) = SUMB( N,I,2) + AP(2,N,K) * (AK-0.50)
        SUMA( N,I,3) = SUMA( N,I,3) + AP(1,N,K) * (AK*(AK-1.) + .33333333)
140 SUMB( N,I,3) = SUMB( N,I,3) + AP(2,N,K) * (AK*(AK-1.) + .33333333)
C
150 STI(K) = STN
C
    WRITE (6,1000) (I,(K,(T(M,K) ),M=1,2),TB(K),RAT(K)), K=1, NL)
160 CONTINUE
    WRITE(NTAP2) STI, EPL, AP, T
C
200 CONTINUE
    END FILE NTAP2
C
    NTAPT = NTAP1
    NTAP1 = NTAP2
    NTAP2 = NTAPT
C
    RETURN
C
1000 FORMAT(30H2STRESS DISTRIBUTION
1 8H NODE , 2X , 5HLAYER , 11X , 10HMERIDIONAL , 15X , 10HCIRCUM
2FER. , 11X , 18HEQUIVALENT STRESS , 4X , 20HMODIFICATION FACTOR
3 // (I5 , 3X , I5 , 3E25.7 , F20.5))
C
    FND
1
```

SUBROUTINE MATPD(I,NX,RAT)

SUPPLEMENT TO MATPP SUB. IN CASE OF SLOPE DISCON.

COMMON/ DIV / NE , NL , NLI

COMMON/ MAT1 / E,U,NP,SIGMA(15),ETAN(15),EP(15),EE(2,2)

COMMON/MATD2/ STIX(2,20, 5), EPLX(2,20, 5), ZTX, STNX

COMMON/STSSD3/NDIS( 5), NDISC

COMMON/STSSD1/DSTA(2,20, 5), DSTB(2,20,5)

COMMON/MATD1 /SUMA1(2, 5,3), SUMA2(2, 5,3), SUMB1(2, 5,3)

A ,SUMB2(2, 5,3)

COMMON APA1(2,20, 5), APB1(2,20, 5), APA2(2,20, 5), APB2(2,20, 5),

A TAX(2,20, 5), TBX(2,20, 5)

DIMENSION DSTEX(2), DSTPX(2), TTX(2), DTX(2), TBB(20), RAT(1)

DO 200 JX = 1,2

DO 150 K=1,NL

DO 10 M=1,2

10 DSTPX(M) = 0.

IF (JX .EQ. 1) GO TO 25

DO 15 N =1,2

DSTPX(1) = DSTPX(1) + APA1(N,K,NX)\*DSTA(N,K,NX)

15 DSTPX(2) = DSTPX(2) + APB1(N,K,NX)\*DSTA(N,K,NX)

DO 20 M =1,2

20 DSTEX(M) = DSTA(M,K,NX) - DSTPX(M)

GO TO 35

25 DO 30 N =1,2

DSTPX(1) = DSTPX(1) + APA2(N,K,NX)\*DSTB(N,K,NX)

30 DSTPX(2) = DSTPX(2) + APB2(N,K,NX)\*DSTB(N,K,NX)

DO 32 M =1,2

32 DSTEX(M) = DSTB(M,K,NX) - DSTPX(M)

35 DO 40 M=1,2

40 DTX(M) = .0

DO 50 M=1,2

DO 50 N=1,2

50 DTX(M) = DTX(M) + EE(M,N) \* DSTEX(N)

TTX(1) = TAX(JX,K,NX) + DTX(1)

TTX(2) = TBX(JX,K,NX) + DTX(2)

S1 = TTX(1) - .50 \* TTX(2)

S2 = TTX(2) - .50 \* TTX(1)

TBAR = SQRT(TTX(1) \* S1 + TTX(2) \* S2 )

IF(DSTPX(1) .EQ. .0 .AND. DSTPX(2) .EQ. .0) GO TO 70

S1 = TAX(JX,K,NX) - .50 \* TBX(JX,K,NX)

S2 = TBX(JX,K,NX) - .50 \* TAX(JX,K,NX)

FLAG = S1 \* DTX(1) + S2 \* DTX(2)

IF (FLAG .LT. 0.0) GO TO 70

```

EP1 = DSTPX(1) + .50 * DSTPX(2)
EP2 = DSTPX(2) + .50 * DSTPX(1)
DEP = SQRT(4./3. * (DSTPX(1) * EP1 + DSTPX(2) * EP2))
FPLX(JX,K,NX) = EPLX(JX,K,NX) + DEP
GO TO 80

```

C

```

70 STM = 0.999 * STIX(JX,K,NX)
   IF (TBAR .LT. STM) GO TO 90

```

C

```

80 KK = K
   II = NX
   CALL INTERD(KK,II,JX)
   RAT(K) = STNX / TBAR
   GO TO 100

```

C

```

90 ZTX = 1.
   STNX = STIX(JX,K,NX)
   RAT(K) = 1.0

```

C

```

100 TAX(JX,K,NX) = RAT(K) * TTX(1)
    TBX(JX,K,NX) = RAT(K) * TTX(2)

```

C

```

S1 = TAX(JX,K,NX) - .50 * TBX(JX,K,NX)
S2 = TBX(JX,K,NX) - .50 * TAX(JX,K,NX)
TBB(K) = SQRT(S1 * TAX(JX,K,NX) + S2 * TBX(JX,K,NX))
IF (TBB(K) .EQ. 0.0) GO TO 120
S1 = S1 / TBB(K)
S2 = S2 / TBB(K)
SS1 = (S1 + U*S2) * (1. - ZTX)
SS2 = (S2 + U*S1) * (1. - ZTX)
DNOM = (1.-U)*(1.+U)*ZTX + S1*SS1 + S2*SS2
S1 = S1 / DNOM
S2 = S2 / DNOM

```

C

```

IF (JX .EQ. 1) GO TO 117
APA1(1,K,NX) = S1 * SS1
APA1(2,K,NX) = S1 * SS2
APB1(1,K,NX) = S2 * SS1
APB1(2,K,NX) = S2 * SS2
GO TO 135

```

C

```

117 APA2(1,K,NX) = S1 * SS1
    APA2(2,K,NX) = S1 * SS2
    APB2(1,K,NX) = S2 * SS1
    APB2(2,K,NX) = S2 * SS2
    GO TO 135
120 CONTINUE
    IF (JX .EQ. 1) GO TO 127
    DO 124 N = 1,2
    APA1(N,K,NX) = .0
124 APB1(N,K,NX) = .0
    GO TO 135
127 DO 128 N = 1,2
    APA2(N,K,NX) = .0
128 APB2(N,K,NX) = .0

```

C

```

135 AK = K
    IF (JX .EQ. 1) GO TO 145
    DO 140 N=1,2
      SUMA1(N,NX,1) = SUMA1(N,NX,1) + APA1(N,K,NX)
      SUMB1(N,NX,1) = SUMB1(N,NX,1) + APB1(N,K,NX)
      SUMA1(N,NX,2) = SUMA1(N,NX,2) + APA1(N,K,NX) * (AK-.50)
      SUMB1(N,NX,2) = SUMB1(N,NX,2) + APB1(N,K,NX) * (AK-.50)
      SUMA1(N,NX,3) = SUMA1(N,NX,3) + APA1(N,K,NX) * (AK*(AK-1.) +
1.33333333)
140 SUMB1(N,NX,3) = SUMB1(N,NX,3) + APB1(N,K,NX) * (AK*(AK-1.) +
1.33333333)
    GO TO 150
145 DO 147 N=1,2
      SUMA2(N,NX,1) = SUMA2(N,NX,1) + APA2(N,K,NX)
      SUMB2(N,NX,1) = SUMB2(N,NX,1) + APB2(N,K,NX)
      SUMA2(N,NX,2) = SUMA2(N,NX,2) + APA2(N,K,NX) * (AK-.50)
      SUMB2(N,NX,2) = SUMB2(N,NX,2) + APB2(N,K,NX) * (AK-.50)
      SUMA2(N,NX,3) = SUMA2(N,NX,3) + APA2(N,K,NX) * (AK*(AK-1.) +
1.33333333)
147 SUMB2(N,NX,3) = SUMB2(N,NX,3) + APB2(N,K,NX) * (AK*(AK-1.) +
1.33333333)

```

C

```

150 STIX(JX,K,NX) = STNX

```

C

```

    IE = I - 2 + JX
    WRITE (6,1200) IE,(I, (K, TAX(JX,K,NX), TBX(JX,K,NX), TBB(K),
1 RAT(K)), K = 1, NL)

```

C

```

200 CONTINUE
    IF (NX .LT. NDISC) NX = NX + 1

```

C

```

    RETURN

```

C

```

1200 FORMAT

```

```

A(1H2, * STRESS DISTRIBUTION AT THE NODE WHERE SLOPE IS DISCONT.
AELEMENT NO.* I5 //
1 8H NODE , 2X , 5HLAYER , 11X , 10HMERIDIONAL , 15X , 10HCIRCUM
2FER. , 11X , 18HEQUIVALENT STRESS , 4X , 20HMODIFICATION FACTOR
3 // (I5 , 3X , I5 , 3E25.7 , F20.5))

```

C

```

    FND

```

1

SUBROUTINE INTERP(K,I)

V-56

```
C
C
C SUBROUTINE FOR LINEAR INTERPOLATION OF MATERIAL PROPERTIES
C
COMMON/ MAT1 / E,U,NP,SIGMA(15),ETAN(15),EP(15),EE(2,2)
COMMON/ MAT2 / STI(20),EPL(20),AP(2,2,20),DST(2,20,50 ),ZT,STN
C
IF (EPL(K) .GT. EP(NP)) GO TO 100
C
DO 10 IP=2,NP
IF (EPL(K) .LE. EP(IP)) GO TO 50
10 CONTINUE
C
50 RHO = (EPL(K) - EP(IP-1)) / (EP(IP) - EP(IP-1))
STN = SIGMA(IP-1) + RHO * (SIGMA(IP) - SIGMA(IP-1))
ZT = ETAN(IP-1) + RHO * ( ETAN(IP) - ETAN(IP-1))
RETURN
C
100 WRITE (6,1000) K,I,EPL(K)
STOP
C
1000 FORMAT(I5,I5,E20.5 / 40H-MATERIAL PROP. DATA IS EXCEEDED )
END
1
```



```
SUBROUTINE INTERD(K,I,J)
```

```
C  
C  
C  
C
```

```
  SUBROUTINE FOR LINEAR INTERPOLATION OF MATERIAL PROPERTIES  
  AT THE NODES WHERE SLOPE IS DISCONT.
```

```
  COMMON/ MAT1 / E,U,NP,SIGMA(15),ETAN(15),EP(15),EE(2,2)  
  COMMON/MATD2/ STIX(2,20, 5), EPLX(2,20, 5), ZTX, STNX
```

```
C  
C
```

```
  IF (EPLX(J,K,I) .GT. EP(NP)) GO TO 100
```

```
  DO 10 IP=2,NP
```

```
  IF (EPLX(J,K,I) .LE. EP(IP)) GO TO 50
```

```
10 CONTINUE
```

```
50 RHO = (EPLX(J,K,I) - EP(IP-1)) / (EP(IP) - EP(IP-1))
```

```
  STNX = SIGMA(IP-1) + RHO * (SIGMA(IP) - SIGMA(IP-1))
```

```
  ZTX = ETAN(IP-1) + RHO * ( ETAN(IP) - ETAN(IP-1))
```

```
  RETURN
```

```
C
```

```
100 WRITE (6,1000) K,I,EPLX(J,K,I)
```

```
  STOP
```

```
C
```

```
1000 FORMAT(I5,I5,E20.5 / *-MATERIAL PROP. DATA IS EXCEEDED AT THE NO  
  ADE WHERE THE SLOPE IS DISCONT.* )
```

```
  END
```

```
1
```

## SUBROUTINE B1MATX

```

COMMON/GEOM3 /CORD,SNT,CNT,SNB1,CNB1,TNB1,SNB2,CNB2,TNB2,SNP,CNP
COMMON/GEOM4 /YBAR,YP,YPP,RW,XT,ARC,RV,CNP1,CNP2,B(4,8)
COMMON /GEOM5/ A1,A2,A3,A4

```

```

DO 10 N=1,3
DO 10 M=1,4
10 B(M,N) = 0.0

```

```

RHO = 1. / (CORD * ARC**2)
AMU = 1. / RV
ALPHA = RHO / ARC
PHI = ALPHA * RHO * YPP
PSI = (SNT + YP * CNT) * ALPHA * AMU
GAMA = 2.0*(A2-A1) + XT*(3.0*(A3-A2) + XT*(4.0*(A4-A3) -
1 XT*5.0*A4))
OMG = 2. * YP * ALPHA / CORD
TET = (1. - YP * YP ) * PHI

```

```

B(1,4) = RHO * (1. + YP * TNB1)
R(2,4) = AMU * CNP1
B(3,4) = (1. + YP * (2. * TNB1 - YP)) * PHI
R(4,4) = GAMA * PSI

```

```

B(1,5) = 2. * RHO * XT
B(2,5) = AMU * XT * SNT
R(3,5) = 2. * XT * TET + OMG
B(4,5) = 2. * YP * PSI

```

```

B(1,6) = 1.5 * XT * B(1,5)
B(2,6) = XT * B(2,5)
B(3,6) = 3. * XT * (XT * TET + OMG )
B(4,6) = 1.5 * XT * B(4,5)

```

```

R(1,7) = YP * B(1,5)
B(2,7) = AMU * XT * CNT
R(3,7) = 2. * (2.*PHI * XT * YP - ALPHA/CORD)
R(4,7) = -2. * PSI

```

```

B(1,8) = 1.50 * B(1,7) * XT
B(2,8) = B(2,7) * XT
B(3,8) = 6. * (PHI * XT * YP - ALPHA/CORD) * XT
B(4,8) = -3. * PSI * XT

```

```

RETURN
FND

```

1

## SUBROUTINE BMATX

V-59

C  
COMMON/GEOM3 /CORD,SNT,CNT,SNB1,CNB1,TNB1,SNB2,CNB2,TNB2,SNP,CNP  
COMMON/GEOM4 /YBAR,YP,YPP,RW,XT,ARC,RV,CNP1,CNP2,B(4,8)

C  
RHO = 1.0/(CORD \* ARC\*\*2)  
AU = 2.0/(CORD\*\*2 \* ARC\*\*3)  
PSI = (SNT + YP \* CNT)/(CORD \* RW \* ARC\*\*3)  
PHI = YPP / (CORD\*\*2 \* ARC\*\*5)  
OMG = YP \* AU

C  
R(1,1) = 0.0  
R(2,1) = SNT / RW  
R(3,1) = 0.0  
R(4,1) = 0.0

C  
R(1,2) = RHO  
R(2,2) = B(2,1) \* XT  
R(3,2) = (1.0 - YP\*\*2) \* PHI  
R(4,2) = YP \* PSI

C  
R(1,3) = 2.0 \* XT \* RHO  
R(2,3) = B(2,2) \* XT  
R(3,3) = B(3,2) \* 2.0 \* XT + OMG  
R(4,3) = B(4,2) \* 2.0 \* XT

C  
B(1,4) = B(1,3) \* 1.5 \* XT  
B(2,4) = B(2,3) \* XT  
B(3,4) = 3.0 \* XT \* ( XT \* B(3,2) + OMG )  
B(4,4) = B(4,3) \* 1.5 \* XT

C  
B(1,5) = 0.0  
R(2,5) = CNT / RW  
B(3,5) = 0.0  
R(4,5) = 0.0

C  
B(1,6) = YP \* RHO  
B(2,6) = B(2,5) \* XT  
B(3,6) = 2.0 \* YP \* PHI  
B(4,6) = -PSI

C  
B(1,7) = 2.0 \* B(1,6) \* XT  
B(2,7) = B(2,6) \* XT  
B(3,7) = 2.0 \* B(3,6) \* XT - AU  
B(4,7) = -2.0 \* PSI \* XT

C  
R(1,8) = 1.5 \* B(1,7) \* XT  
R(2,8) = B(2,7) \* XT  
R(3,8) = 3.0 \* (B(3,6) \* XT - AU) \* XT  
B(4,8) = 1.5 \* B(4,7) \* XT

C  
RETURN  
END

1

## SUBROUTINE C1MATX

V-60

```
C
COMMON/GEOM2 / COF(10) , B1(4,8,10) , B2(4,8,2) , C(8,8)
COMMON/GEOM3 /CORD,SNT,CNT,SNB1,CNB1,TNB1,SNB2,CNB2,TNB2,SNP,CNP
COMMON/ GEOM4/YBAR,YP, YPP , RW , XT , ARC , RV , CNP1,CNP2,B(4,8)
```

```
C
DO 10 N=1,8
DO 10 M=1,8
10 C(M,N) = 0.0
TJ = 5.5 * TNB2
TITJ = 2. * TNB1 + TJ
```

```
C
C(3,2) = 1.0
C(4,2) = CNT * 5.5
C(5,2) = -9. * CNT
C(6,2) = 4.5 * CNT
C(7,2) = -CNT * (11. * TNB1 + TNB2) - 3. * SNT
C(8,2) = CNT * (5.5 * TNB1 + TNB2) + 2. * SNT
```

```
C
C(4,4) = SNT
C(5,4) = -4.5 * SNT
C(6,4) = -C(5,4)
C(7,4) = -SNT * TITJ + 3. * CNT
C(8,4) = SNT * (TNB1 + TJ) - 2. * CNT
```

```
C
C(4,5) = -CNT
C(5,5) = C(6,2)
C(6,5) = -C(5,5)
C(7,5) = CNT * TITJ + 3. * SNT
C(8,5) = -CNT * (TNB1 + TJ) - 2. * SNT
```

```
C
C(7,6) = -CORD / CNB2 **2
C(8,6) = -C(7,6)
```

```
C
C(4,7) = 9.
C(5,7) = -22.5
C(6,7) = 13.5
C(7,7) = -18. * TNB1 - 4.5 * TNB2
C(8,7) = 9. * TNB1 + 4.5 * TNB2
```

```
C
C(4,8) = -4.5
C(5,8) = 18.
C(6,8) = -13.5
C(7,8) = 9. * (TNB1 + TNB2)
C(8,8) = -4.5 * TNB1 - 9.0 * TNB2
```

```
C
RETURN
END
```

1

## SUBROUTINE CMATX

V-61

SUBROUTINE TO CONSTRUCT DISPL. TRANS. MATRIX IN  $U_1$ - $U_2$  CO-ORDINATESCOMMON/GEOM2 / COF(10) , B1(4,8,10) , B2(4,8,2) , C(8,8)  
COMMON/GEOM3 /CORD,SNT,CNT,SNB1,CNB1,TNB1,SNB2,CNB2,TNB2,SNP,CNPTI = 5.5 \* TNB1  
TA = 11. \* TNB1  
TJ = 5.5 \* TNB2  
TITJ = 2. \* TNB1 + TJC(1,1) = SNT  
C(2,1) = - 5.5 \* SNT  
C(3,1) = 9. \* SNT  
C(4,1) = -4.5 \* SNT  
C(5,1) = CNT  
C(6,1) = -TI \* SNT  
C(7,1) = SNT \* (TA + TNB2) - 3. \* CNT  
C(8,1) = -SNT \* (TI + TNB2) + 2. \* CNTC(1,2) = -CNT  
C(2,2) = 5.5 \* CNT  
C(3,2) = -9. \* CNT  
C(4,2) = 4.5 \* CNT  
C(5,2) = SNT  
C(6,2) = CNT \* TI  
C(7,2) = -CNT \* (TA + TNB2) - 3. \* SNT  
C(8,2) = CNT \* (TI + TNB2) + 2. \* SNTC(1,3) = 0.0  
C(2,3) = 0.0  
C(3,3) = 0.0  
C(4,3) = 0.  
C(5,3) = 0.  
C(6,3) = CORD / CNB1\*\*2  
C(7,3) = -2.\*C(6,3)  
C(8,3) = C(6,3)C(1,4) = 0.0  
C(2,4) = SNT  
C(3,4) = C(4,1)  
C(4,4) = -C(3,4)  
C(5,4) = 0.0  
C(6,4) = SNT \* TNB1  
C(7,4) = -SNT \* TITJ + 3. \* CNT  
C(8,4) = SNT \* (TNB1 + TJ) - 2. \* CNTC(1,5) = 0.0  
C(2,5) = -CNT  
C(3,5) = C(4,2)  
C(4,5) = -C(3,5)  
C(5,5) = 0.0  
C(6,5) = -TNB1 \* CNT  
C(7,5) = CNT \* TITJ + 3. \* SNT

C(8,5) = -CNT \* (TNB1 + TJ) - 2. \*SNT

C

C(1,6) = 0.0

C(2,6) = 0.0

C(3,6) = 0.0

C(4,6) = 0.0

C(5,6) = 0.0

C(6,6) = 0.0

C(7,6) = -CORD / CNB2\*\*2

C(8,6) = -C(7,6)

C

C(1,7) = 0.

C(2,7) = 9.

C(3,7) = -22.5

C(4,7) = 13.5

C(5,7) = 0.

C(6,7) = 9. \* TNB1

C(7,7) = -18. \* TNB1 - 4.5 \* TNB2

C(8,7) = 9.0 \* TNB1 + 4.5 \* TNB2

C

C(1,8) = 0.

C(2,8) = -4.5

C(3,8) = 18.

C(4,8) = -13.5

C(5,8) = 0.

C(6,8) = -4.5 \* TNB1

C(7,8) = 9. \* (TNB1 + TNB2)

C(8,8) = -4.5 \* TNB1 - 9.0 \* TNB2

C

RETURN

END

1

SUBROUTINE DIMATX(L,I)

V-63

C

COMMON/GEOM1 /R(2, 50),Z(2, 50),PHI(2, 50),H(2, 50),CRV(2,50)  
COMMON/STF1/ D(4,4) , SKI(8,8) , SK(8,8)  
COMMON/ MAT1 / E,U,NP,SIGMA(15),ETAN(15),EP(15),EE(2,2)

C

DIMENSION X(12)

C

DATA X / 0.0,0.013046735741414 , 0.067468316655507,  
1 0.160295215850488, 0.283302302935376 , 0.425562830509184,  
2 0.574437169490816, 0.716697697064624, 0.839704784149512,  
3 0.932531683344493, 0.986953264258586, 1.0 /

C

HI = H(1,I) + X(L) \* (H(2,I) - H(1,I))  
DO 10 N=1,2  
DO 10 M=1,2  
10 D(M,N) = EE(M,N) \* HI

C

DO 20 N=3,4  
DO 20 M=1,2  
20 D(M,N) = 0.0

C

DO 30 N=1,2  
DO 30 M=3,4  
30 D(M,N) = 0.0

C

DO 40 N=3,4  
DO 40 M=3,4  
40 D(M,N) = D(M-2,N-2) \* HI\*\*2 / 12.

C

RETURN  
END

1

SUBROUTINE DMATX(L,I,MA,MB,NX)

MODIFIED SUBROUTINE TO HANDLE THE SLOPE DISCONTIN.

COMMON/ DIV / NE , NL , NLI  
 COMMON/GEOM1 /R(2, 50),Z(2, 50),PHI(2, 50),H(2, 50),CRV(2,50)  
 COMMON/ MAT1 / E,U,NP,SIGMA(15),ETAN(15),EP(15),EE(2,2)  
 COMMON/ MAT3 / SUMA(2,50,3), SUMB(2,50,3), TB(20), RAT(20)  
 COMMON/STF1/ D(4,4) , SKI(8,8) , SK(8,8)  
 COMMON/MATD1 /SUMA1(2, 5,3), SUMA2(2, 5,3), SUMB1(2, 5,3)  
 A ,SUMB2(2, 5,3)

DIMENSION X(12) , TEMP(2,2,3) , TMP(2,2)

DATA X / 0.0,0.013046735741414 , 0.067468316655507,  
 1 0.160295215850488, 0.283302302935376 , 0.425562830509184,  
 2 0.574437169490816, 0.716697697064624, 0.839704784149512,  
 3 0.932531683344493, 0.986953264258586, 1.0 /

DO 10 N=1,4  
 DO 10 M=1,4  
 10 D(M,N) = 0.0

ANL = NL  
 HI = H(1,I) + X(L) \* (H(2,I) - H(1,I))  
 FAC = HI / ANL  
 IF (MA .EQ. 1) GO TO 13  
 IF (MB .EQ. 1) GO TO 11

DO 20 J=1,3  
 DO 20 N=1,2  
 TEMP(1,N,J) = (SUMA(N,I,J) + X(L)\*(SUMA(N,I+1,J)-SUMA(N,I,J)))  
 1 \* FAC\*\*J  
 20 TEMP(2,N,J) = (SUMB(N,I,J) + X(L)\*(SUMB(N,I+1,J)-SUMB(N,I,J)))  
 1 \* FAC\*\*J  
 GO TO 25

11 DO 12 J=1,3  
 DO 12 N=1,2  
 TEMP(1,N,J) = ( SUMA(N,I,J) + X(L) \* ( SUMA2(N,NX,J) -  
 D SUMA(N,I,J))) \* FAC\*\*J  
 12 TEMP(2,N,J) = ( SUMB(N,I,J) + X(L) \* ( SUMB2(N,NX,J) -  
 D SUMB(N,I,J))) \* FAC\*\*J  
 GO TO 25  
 13 DO 15 J=1,3  
 DO 15 N=1,2  
 TEMP(1,N,J) = (SUMA1(N,NX,J)+ X(L) \* ( SUMA(N,I+1,J) -  
 E SUMA1(N,NX,J))) \* FAC\*\*J  
 15 TEMP(2,N,J) = (SUMB1(N,NX,J)+ X(L) \* ( SUMB(N,I+1,J) -  
 E SUMB1(N,NX,J))) \* FAC\*\*J  
 25 TMP(1,1) = -TEMP(1,1,1) + HI  
 TMP(1,2) = -TEMP(1,2,1)  
 TMP(2,1) = -TEMP(2,1,1)  
 TMP(2,2) = -TEMP(2,2,1) + HI



```
DO 30 N=1,2
DO 30 M=1,2
DO 30 K=1,2
30 D(M,N) = D(M,N) + EE(M,K) * TMP(K,N)
C
DO 40 N=1,2
DO 40 M=1,2
40 TMP(M,N) = 0.50 * HI * TEMP(M,N,1) - TEMP(M,N,2)
C
DO 50 N=3,4
DO 50 M=1,2
DO 50 K=1,2
50 D(M,N) = D(M,N) + EE(M,K) * TMP(K,N-2)
C
DO 60 N=1,2
DO 60 M=3,4
60 D(M,N) = D(N,M)
C
DO 70 N=1,2
DO 70 M=1,2
70 TMP(M,N) = (-0.25 * HI*TEMP(M,N,1) + TEMP(M,N,2))*HI - TEMP(M,N,3)
C
TMP(1,1) = TMP(1,1) + HI**3 / 12.
TMP(2,2) = TMP(2,2) + HI**3 / 12.
C
DO 80 N=3,4
DO 80 M=3,4
DO 80 K=1,2
80 D(M,N) = D(M,N) + EE(M-2,K) * TMP(K,N-2)
C
RETURN
END
1
```

## SUBROUTINE BANSOL

```

C
C *****M*****
C IN-CORE LINEAR EQUATION SOLVER FOR SYMMETRIC BAND MATRICES
C *****
C
COMMON /BANARG/  NN, MM,A(150, 6),B(150)
DIMENSION S(1)
EQUIVALENCE (S,A)
NCOL = 150
NR = NN
NRS = NR - 1
MMR = MM - 1
C DECOMPOSE MATRIX A
DO 120  N = 1,NRS
M = N - 1
MR = MINO (MM,NR-M)
PIVOT = S(N)
J = N
DO 120  L = 2,MR
J = J + NCOL
C = S(J)/PIVOT
I1 = M + L
I2 = I1 + (MR-L)*NCOL
II = J
DO 110  I = I1,I2,NCOL
S(I) = S(I) - C*S(II)
110 II = II + NCOL
120 S(J) = C
C REDUCE AND BACKSUBSTITUTE VECTOR B
DO 220  N = 1,NRS
MR = MINO (MMR,NR-N)
C = B(N)
B(N) = C/S(N)
K = N
L1 = N + 1
L2 = N + MR
DO 220  L = L1,L2
K = K + NCOL
220 B(L) = B(L) - S(K)*C
B(NR) = B(NR)/S(NR)
300 DO 320  I = 1,NRS
N = NR - I
MR = MINO (MMR,I)
J = N
L1 = N + 1
L2 = N + MR
DO 320  L = L1,L2
J = J + NCOL
320 B(N) = B(N) - S(J)*B(L)
RETURN
END

```