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Field-free deterministic switching of a perpendicularly polarized magnet using unconventional spin-orbit torques in WTe₂

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Spin-orbit torque (SOT) driven deterministic control of the magnetization state of a magnet with perpendicular magnetic anisotropy (PMA) is key to next generation spintronic applications including non-volatile, ultrafast, and energy efficient data storage devices¹⁻³. But, field-free deterministic switching of perpendicular magnetization remains a challenge because it requires an out-of-plane anti-damping torque, which is not allowed in conventional spin source materials such as heavy metals (HM)¹⁻³ and topological insulators⁴ due to the system's symmetry. The exploitation of low-crystal symmetries in emergent quantum materials offers a unique approach to achieve SOTs with unconventional forms^{5,6}. Here, we report the first experimental realization of field-free deterministic magnetic switching of a perpendicularly polarized van der Waals (vdW) magnet employing an out-of-plane anti-damping SOT generated in layered WTe₂ which is a low-crystal symmetry quantum material. The numerical simulations confirm that out-of-plane antidamping torque in WTe₂ is responsible for the observed magnetization switching in the perpendicular direction.

SOT has emerged as an efficient means of manipulating the magnetization state of a ferromagnetic (FM) material^{1,2}. The potential technological applications based on SOT driven magnetization manipulation includes energy efficient non-volatile magnetic memories⁷ and spin-torque oscillators^{8,9}. In SOT induced magnetic switching, a charge current density \vec{j}_c (x direction) flowing in HM/FM bilayers results in spin current flowing in the out-of-plane direction (z direction) via spin galvanic effects¹⁻³, which in turn exerts a torque on the magnetization of a nearby magnetic layer. The torque has an antidamping component $\vec{\tau}_{AD} \propto \vec{m} \times \vec{m} \times \vec{p}$ and a field-like component $\vec{\tau}_{FL} \propto \vec{m} \times \vec{p}$ where \vec{m} is the magnetization, and \vec{p} is the spin polarization. But by symmetry, the most efficient type of torque, the anti-damping torque, has the form of $\vec{\tau}_{IP}^{AD} \propto \vec{m} \times \vec{m} \times \hat{y}$ in HM/FM heterostructures and can only deterministically switch the magnetization of a magnet that has an in-plane magnetic anisotropy^{3,10}.

However, for memory applications, magnets with PMA are highly desired because it allows for ultra-compact packing and thermally stable nanometer sized magnetic bits⁷. In conventional HM/FM systems, a small external magnetic field is applied along the direction of the charge current to break the in-plane symmetry of the system allowing for deterministic switching of the magnetization state of a PMA magnet^{1,3}. Previously, a structural asymmetry^{11,12}, tilted anisotropy of the nanomagnet¹³, an in-plane magnetized layer¹⁴⁻¹⁶, and an in-plane effective magnetic field in FM/ferroelectric structures¹⁷, anomalous Hall effect and planar Hall effect in FM/HM/FM trilayers¹⁸, and interplay of SOT and spin-transfer torque¹⁹, have been explored to achieve a field-free deterministic switching of PMA magnets using SOTs. A novel approach for this is to explore the utility of emergent quantum systems as a spin source material wherein SOTs can be controlled by crystal symmetries. Recently, the transition metal dichalcogenides with low-crystal symmetry, such as WTe₂, have been shown to exhibit an out-of-plane antidamping torque, $\vec{\tau}_{OP}^{AD} \propto \vec{m} \times \vec{m} \times \hat{z}$, when current is applied along the low symmetry axis of the WTe₂/FM bilayer system^{5,6}. But, so far, there has been no experimental study establishing that the unconventional out-of-plane antidamping SOT in layered materials with low-crystal symmetry is strong enough to enable the deterministic switching of a PMA magnet.

Here, we experimentally realize field-free deterministic magnetic switching of a perpendicularly polarized magnet using SOTs in a low-symmetry system. For this, we employ a SOT device platform built out of vdW based layered quantum materials and choose WTe₂ as a

spin-source material for generating SOTs^{5,20-23}. In addition to the generation of an out-of-plane antidamping torque, WTe₂ also exhibits properties that are highly relevant for a large charge to spin conversion efficacy: strong spin-orbit coupling, non-trivial band dispersion, topologically protected spin polarized bulk and surface states, pronounced Edelstein effect, and an intrinsic spin Hall effect²⁰⁻²³. WTe₂ is a low-symmetry system, whose *ab*-plane is schematically depicted in Fig. 1a (*c*-axis is perpendicular to the *ab*-plane). The surface of WTe₂ has a mirror symmetry with respect to the *bc*-plane but not about the *ac*-plane. Thus, the system is asymmetric relative to a 180° rotation about the *c*-axis. For the PMA magnet, we utilize Fe_{2.78}GeTe₂ (FGT) which is a layered vdW FM material^{24,25}. The SOT devices are prepared by mechanical dry transfer technique to assemble WTe₂/FGT bilayers and standard device fabrication techniques (Methods and Supplementary Note 1).

In total, we have measured three devices and here we present data from device A. The optical micrograph of the device is shown in Fig. 1b along with a side-view schematic of the device (lower panel). The crystallographic *a*-axis and *b*-axis are labeled in Fig. 1b, and are confirmed by polarized Raman spectroscopy²⁶. Spectra are collected by rotating the polarization of the incident laser for different angles relative to the *a*-axis of WTe₂ and the integrated intensities under each peak are calculated for the contour plot shown in Fig. 1c. A polar plot of the A_g Raman peak at 212 cm⁻¹ (Fig. 1d, corresponding to the dashed line in Fig. 1c) exhibits minimum intensity when the excitation laser polarization is along the straight edge of the WTe₂ flake (Fig. 1b). This is consistent with previous reports^{22,26} and clearly distinguishes the *a*-axis of WTe₂. We also carried out atomic structure characterization of device A using scanning transmission electron microscopy (STEM). Fig. 1e (bottom panel) shows the STEM cross-sectional image confirming that the lateral direction is the *a*-axis WTe₂, consistent with the orientation determined by the Raman spectra. The top-panel of Fig. 1e schematically shows the atomic arrangement of WTe₂ along the *a*-axis as a comparison to the STEM image.

Previously, the presence of a strong out-of-plane antidamping torque in a WTe₂/Permalloy heterostructure was probed by spin torque ferromagnetic resonance⁵. Unlike an out-of-plane field-like torque, the out-of-plane antidamping torque is independent of the reversal of magnetization, reverses with current direction, and can efficiently switch perpendicular magnetizations. The out-of-plane antidamping torque is not allowed in conventional spin source systems, such as platinum and topological insulators, due to in-plane 2-fold symmetry. However, in WTe₂ this symmetry is broken around one crystal axis, allowing for an out-of-plane antidamping torque. Specifically, WTe₂ has a broken mirror symmetry about the *ac*-plane (Fig. 1a), allowing for this torque to exist only when the current is driven along the *a*-axis of WTe₂ (Fig. 2a, upper panel). Along the *b*-axis of WTe₂, the mirror symmetry is preserved and the out-of-plane antidamping torque cannot exist (lower panel of Fig. 2a): when a charge current passes along the *b*-axis and a *bc*-plane mirror operation (\tilde{R}_{bc}) is performed, the current will not switch direction but the torque will still change signs in the out-of-plane direction. A current-induced torque must change sign with current otherwise the torque will have zero magnitude, therefore the out-of-plane antidamping torque vanishes when current is along the *b*-axis.

A typical anomalous Hall effect (AHE) hysteresis loop of the device A is shown in Fig. 2b (ref. ^{24,27}). We determine the effective magnetic anisotropic field $\mu_0 H_k \sim 4.12$ T by measuring the AHE loop with the field applied along the hard axis, indicating a strong PMA (Supplementary Note 4 and Note 6). Next, we demonstrate field-free perpendicular magnetization switching induced by SOTs when a DC current pulse, I_p , is applied (Methods). For the case when current is

applied along the a -axis ($\vec{I} \parallel \hat{a}$), we observe clear deterministic switching (Fig. 2c) which is attributed to the out-of-plane spin polarization (p_z) or an out-of-plane antidamping SOT. The measurements (current sweeps in Fig. 2c) show that the terminal state is determined by the polarity of \vec{I} and the critical current to switch the magnetization is $I_c = 5.63 \pm 0.13$ mA (corresponding to a critical current density $J_c = 6.64 \times 10^{10}$ A/m²). On the other hand, the behavior is completely different when the current is applied along the b -axis; no deterministic switching is observed in the absence of an external in-plane magnetic field (Fig. 2d). In the high current regime, m_z approaches zero with increasing I_p , reflecting multi-domain formation due to Joule heating. This case is similar to SOT switching in conventional HM/FM bilayer systems: the terminal state is close to the demagnetized state $m_z \approx 0$, indicating that the in-plane effective field, generated by either the Oersted effect or spin galvanic effects, drives the magnetic moment of FGT to the device plane. Without the presence of a p_z (or a symmetry breaking in-plane magnetic field), multi-domains are formed after the current is turned off. Each domain is then left randomly oriented which leads to the demagnetization of FGT. Furthermore, using a train of positive and negative current pulses applied along the a -axis of WTe₂ (top panel of Fig. 2e) we deterministically switch the magnetic state of the FGT from up to down and vice-versa (bottom panel of Fig. 2e).

To distinguish the role of the in-plane antidamping torque $\vec{\tau}_{IP}^{AD}$ and the out-of-plane antidamping torque $\vec{\tau}_{OP}^{AD}$, we perform numerical simulations of magnetization switching for a mono-domain FGT. While the actual switching processes are likely to involve domain-wall motions, a monodomain simulation can capture the essential physics of spin torques if we use the coercive field (Supplementary Information Fig. S6) as the effective anisotropy. We first investigate the case of $\vec{I} \parallel \hat{b}$. As shown in Fig. 2f, by varying the current I_e and the ratio of $\vec{\tau}_{IP}^{AD}/I_e$, we find that the initial state ($m_z = -1$) can be switched to an in-plane direction ($m_z = 0$) that are energetically metastable. The threshold decreases with an increasing $\vec{\tau}_{IP}^{AD}/I_e$ which forms the phase boundary. However, if the driving current is turned off, a metastable state will be equally probable to relax to $m_z = -1$ and $m_z = 1$. The mono-domain will easily break up into multiple domains with an average $\langle m_z \rangle = 0$. This is consistent with Fig. 2d, justifying that an in-plane torque $\vec{\tau}_{IP}^{AD}$ alone is unable to switch the magnetization from $m_z = -1$ to $m_z = 1$. By comparing Fig. 2f with Fig. 2d, we can determine the value of $\vec{\tau}_{OP}^{AD}/I_e$. Then, with a fixed ratio of $\vec{\tau}_{OP}^{AD}/I_e$, we simulate the switching process for $\vec{I} \parallel \hat{a}$ by varying I_e and $\vec{\tau}_{OP}^{AD}/I_e$. As shown in Fig. 2g, we find three different phases characterized by the final state of m_z : the unswitched phase ($m_z = -1$), the switched phase ($m_z = 1$), and the in-plane metastable phase ($m_z = 0$). The three phases intersect at a tricritical point around $I_c = 5.9$ mA and $\vec{\tau}_{OP}^{AD}/I_e = 6.2 \times 10^{-5}$ T/mA. Above the tricritical point, the phase boundary separating the unswitched and the switched phases continuously shifts towards smaller I_e , indicating that the out-of-plane antidamping torque $\vec{\tau}_{OP}^{AD}$ is indeed responsible for the magnetization switching in the perpendicular direction. This result not only explains the observation in Fig. 2c but also determines the relative strength of $\vec{\tau}_{OP}^{AD}$ over $\vec{\tau}_{IP}^{AD}$ to be around 10^{-2} for $\vec{I} \parallel \hat{a}$.

To examine the existence of a p_z , we also perform AHE loop shift measurements. In the presence of a p_z , an out-of-plane antidamping SOT can be generated and abruptly shift the AHE hysteresis loop once the current passes a threshold value such that the intrinsic damping is compensated^{1,18}. For $\vec{I} \parallel \hat{a}$ (Fig. 3a) and when I_p is positive (negative), the AHE hysteresis loop shifts to the negative (positive) side. However, for the same conditions but with I_p applied along the b -axis (Fig. 3b), no significant loop shift is observed. The measurements are performed at

different current magnitudes for $\vec{I} \parallel \hat{a}$ and $\vec{I} \parallel \hat{b}$ (Fig. 3c and 3d). Strikingly, we observe two threshold currents and the signature of magnetic excitations due to spin current induced steady precessional states²⁸. Around the first current threshold ($I_{th1} \sim 3.5$ mA), there is a peak in H_c which decreases dramatically with increasing $|I_p|$. The peak of H_c is accompanied by a sudden increase in $|H_{sh}|$ pointing to the onset of magnetic excitation²⁸. The abrupt drop of H_c is the sign of the system entering a current-assisted switching regime, which was seen in a similar measurement setup in a conventional SOT PMA system¹. Joule heating can also contribute to the drop of H_c (Supplementary Note 5). When $|I_p|$ passes the second current threshold ($I_{th2} \sim 5.75$ mA), we observe the onset of a current-induced switching regime, where the decrease in H_c levels off and, particularly for $\vec{I} \parallel \hat{a}$, the deterministic switching is possible because H_c^\pm both shift to one side of the zero field line. Note that I_{th2} is very close to I_c which is determined by current-induced SOT switching at zero field (Fig. 2c). In contrast, for $\vec{I} \parallel \hat{b}$, $|H_{sh}(I_p)|$ shows very weak I_p dependence and is close to zero at all current values which is similar to what has been reported for conventional HM/FM systems¹. These results clearly show the presence of a p_z when $\vec{I} \parallel \hat{a}$, originating from the broken mirror symmetry about the ac -plane. The abrupt shift, instead of a linear shift, in H_{sh} also indicates that no significant out-of-plane field-like torque is present in the system.

To conclude, we have experimentally demonstrated that an out-of-plane antidamping SOT in WTe₂ enables a field free perpendicular magnetization switching of PMA magnet. The presence of an out-of-plane antidamping torque and the potential of a higher charge to spin conversion efficiency in WTe₂ makes TMDs with lower symmetry crystal structure an appealing spin source material for future SOT related magnetic technologies.

Methods

Device Fabrication. WTe₂, FGT, and hexagonal boron nitride (hBN) crystal flakes were prepared by previously published procedures^{25,29,30}. WTe₂, hBN, and FGT were mechanically exfoliated on separate Si/SiO₂(300nm) substrates inside an Argon glovebox environment. The flakes were then optically searched and selected using a fully automated microscope inside the glovebox. On a separate substrate, electrodes were defined using standard electron beam lithography with MMA/PMMA bilayer resist and electron beam deposition was used for Pt electrodes. The heterostructure was made using a custom-built transfer tool inside the glovebox using a polydimethylsiloxane (PDMS) stamp and thin film of polycarbonate (PC). The final device consists, from top to bottom, of hBN/FGT/WTe₂/Pt with Cr(5nm)/Au(110nm) bond pads.

Spin orbit torque measurements. The electrical measurements were performed at variable temperatures in high vacuum (pressure $< 10^{-5}$ mTorr) conditions. An electromagnet was rotated such that the magnetic field can be applied in both in- and out-of-plane directions of the device. Keithley 6221 current source and a Keithley 2182A nanovoltmeter are used for AHE hysteresis loop and current pulse-induced SOT switching experiments. The current pulse used is a square current pulse with varying magnitude and a width of 100 μ s (unless stated otherwise). The transverse resistance, R_{xy} , is measured with a smaller magnitude current (50 μ A) in delta mode (unless stated otherwise) to determine the magnetization state of FGT. We define the normalized perpendicular magnetization $m_z = \frac{M_z}{M_s} = \frac{R_{xy}}{R_{AHE}}$, where M_z is the perpendicular magnetization, and M_s is the saturation magnetization. In the SOT measurements, the initial magnetic state is prepared in $m_z = \pm 1$ (using an external magnetic field) and I_p is swept from 0 mA to ± 10 mA in steps of 250 μ A. We define the critical switching current $I_c = \frac{I_c^+ + I_c^-}{2}$, where I_c^+ (I_c^-) is the current pulse magnitude that drives the magnetization state across $m_z = 0$ at positive (negative) pulse sides. For SOT switching with pulse trains, a series of read current pulses of 500 μ A were applied to read the magnetization state before and after the write current pulse was applied. AHE loop shift measurements are performed by measuring $m_z(H_z)$, where at each perpendicular field H_z a current pulse I_p (500 μ s long) is applied and m_z is measured simultaneously in Pulse Delta mode. We define the coercive field by $H_c = (H_c^+ - H_c^-)/2$ and the shift of the loop by $H_{sh} = [H_c^+ + H_c^-]/2$, where H_c^+ (H_c^-) is the positive (negative) field for which the magnetization reverses.

Numerical simulations. The effective single-domain dynamics is simulated by solving the Landau–Lifshitz–Gilbert equation in the presence of in-plane and out-of-plane antidamping torques as

$$\frac{d\mathbf{m}}{dt} = -\gamma H_A \mathbf{m} \times m_z \hat{\mathbf{z}} + c_{oe} I_e \hat{\mathbf{y}} \times \mathbf{m} + \mathbf{m} \times [(c_{IP}^{AD} I_e \hat{\mathbf{y}} + c_{OP}^{AD} I_e \hat{\mathbf{z}}) \times \mathbf{m}] + c_{OP}^{FL} I_e \hat{\mathbf{z}} \times \mathbf{m} + \alpha \mathbf{m} \times \frac{d\mathbf{m}}{dt}$$

where \mathbf{m} is the unit vector of magnetic moment of FGT, H_A is the easy-axis anisotropy, I_e is the current, c_{oe} , c_{IP}^{AD} , c_{OP}^{AD} and c_{OP}^{FL} are the amplitudes of the Oersted field, the in-plane antidamping torque, the out-of-plane antidamping torque and the out-of-plane field-like torque with respect to I_e , respectively, and α is the Gilbert damping parameter. Based on the materials parameters and the device geometry, we set $H_A = 0.1T$ (using the coercive field as the effective value), $c_{oe} = 2 \times 10^{-4} T/mA$, $\alpha = 0.005$. In the simulation, we use $c_{OP}^{FL} = 0.5 c_{OP}^{AD}$, but we find that c_{OP}^{FL} has

negligible impact on the switching process; the result does not show visible differences if $c_{OP}^{FL} = 0$ or $c_{OP}^{FL} = 4 c_{OP}^{AD}$. The current I_e is applied along \hat{y} direction, so the in-plane spin accumulation and the Oersted field are along \hat{x} direction. The initial state of \mathbf{m} is set to be along $-\hat{z}$ direction, and the final state is obtained when the system reaches equilibrium.

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Author Contributions

S.S. and J.K. designed the experiments and supervised the research. I.K., R.M., and J.G. prepared the devices and performed the experiments. H.Z. and R.C. performed the numerical simulations. M.Z. and J.H. performed the STEM measurements. R.R. carried out polarized Raman measurements. Y.J. and D.G.M. provided the bulk crystals of WTe₂. D.W. and J.E.G. provided the bulk FGT crystals. J.L. and J. H. E. provided the bulk hBN crystals. All authors contributed to write the manuscript.

Competing interests

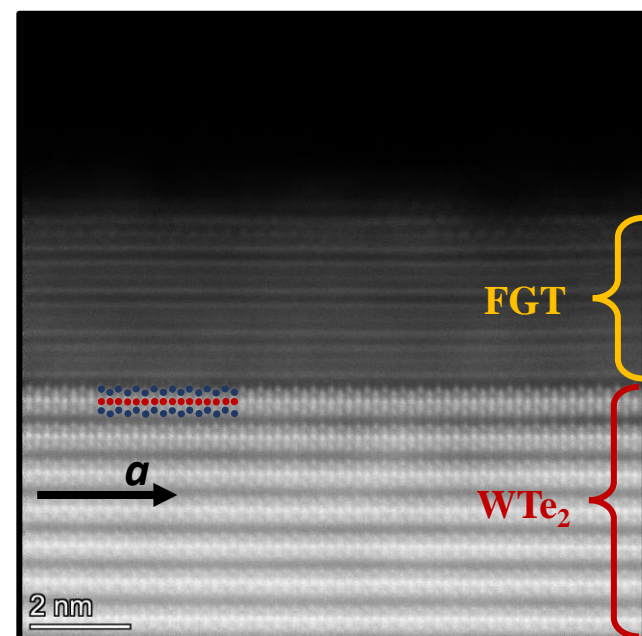
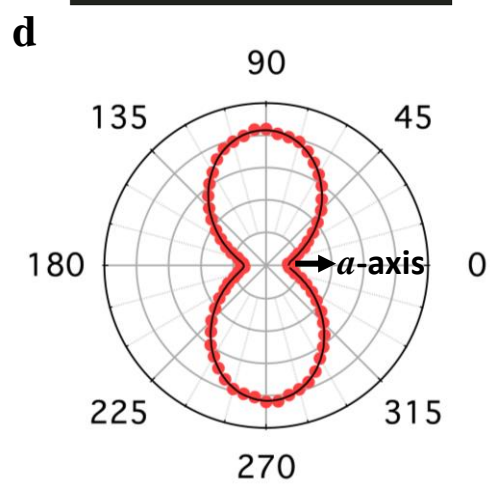
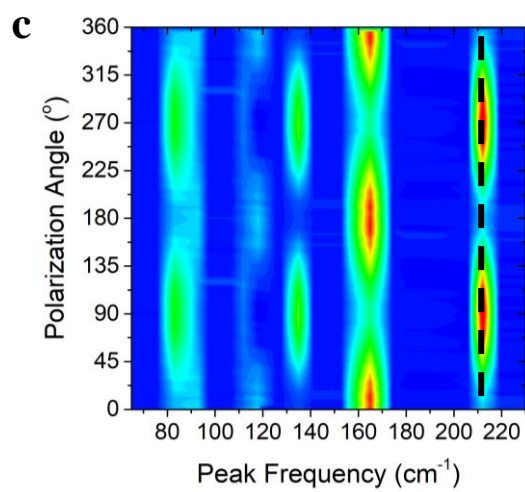
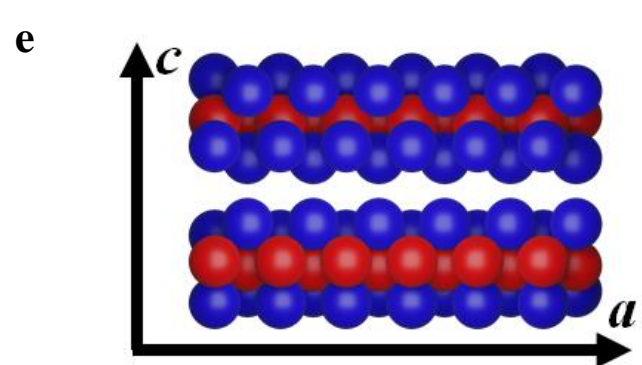
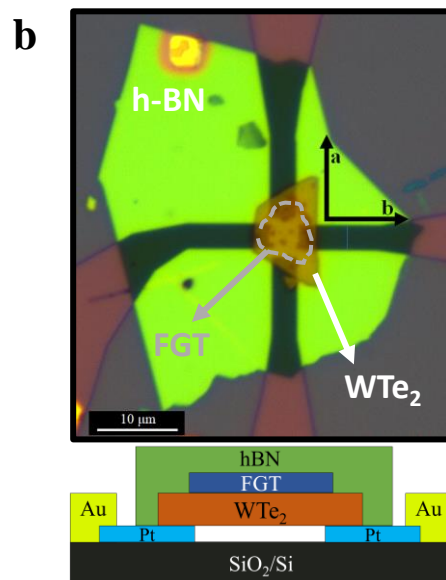
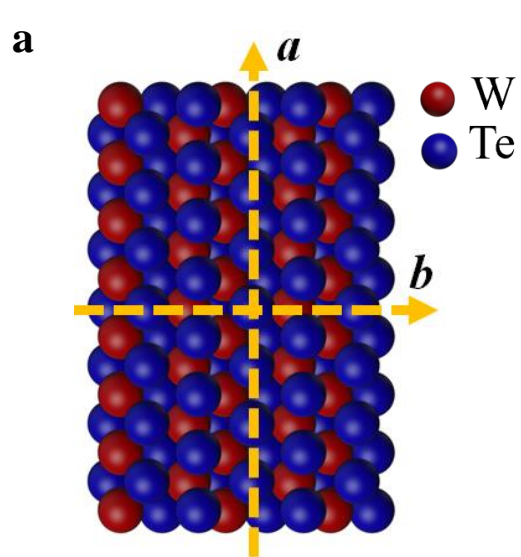
The authors declare no competing interests.

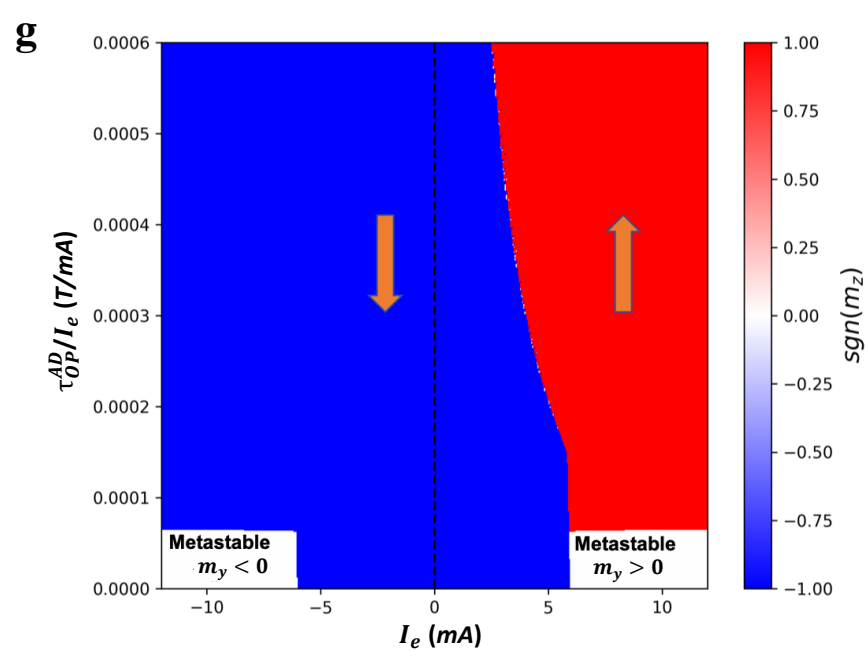
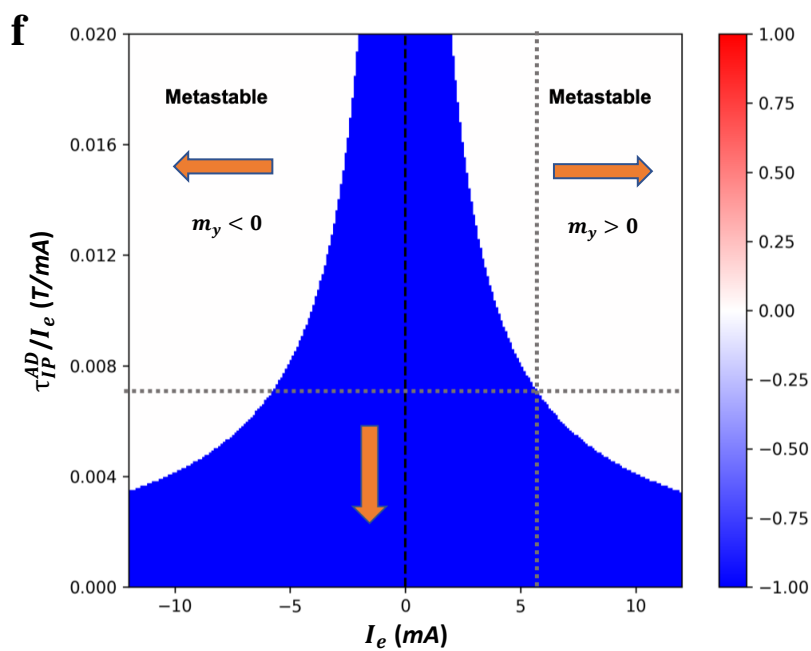
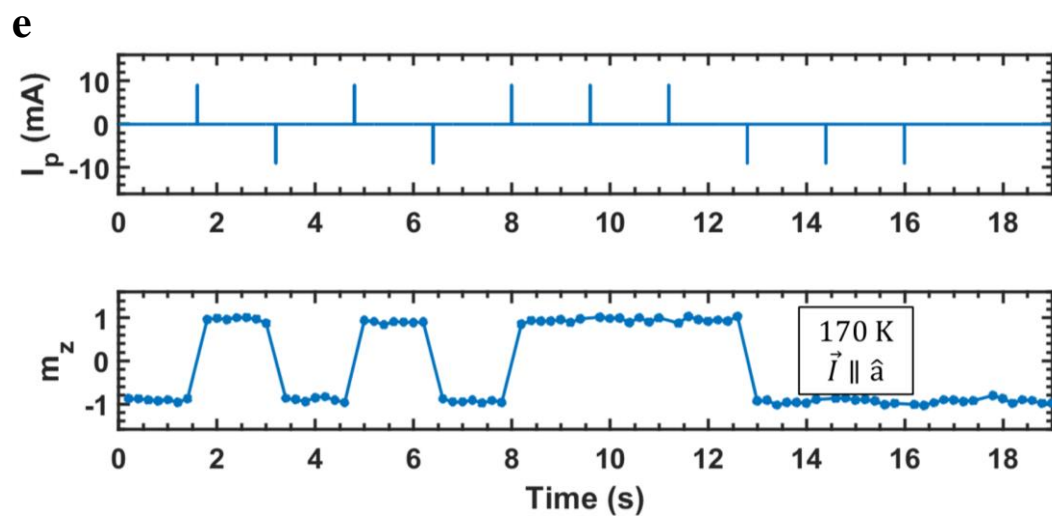
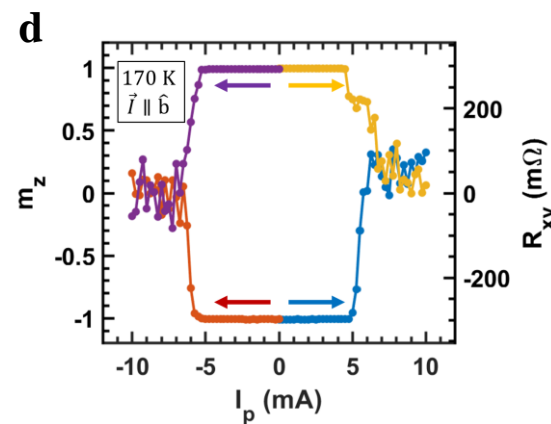
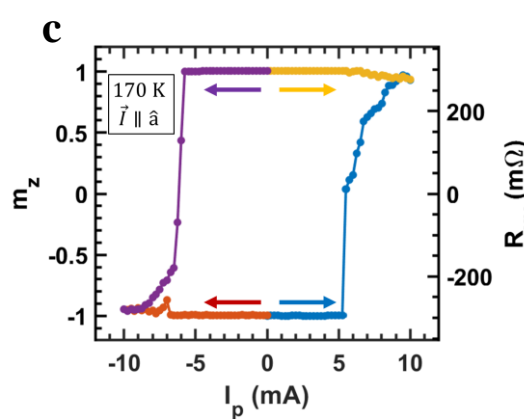
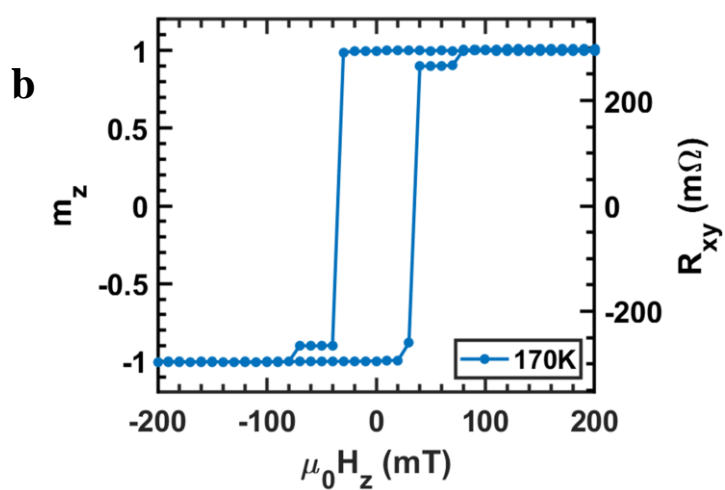
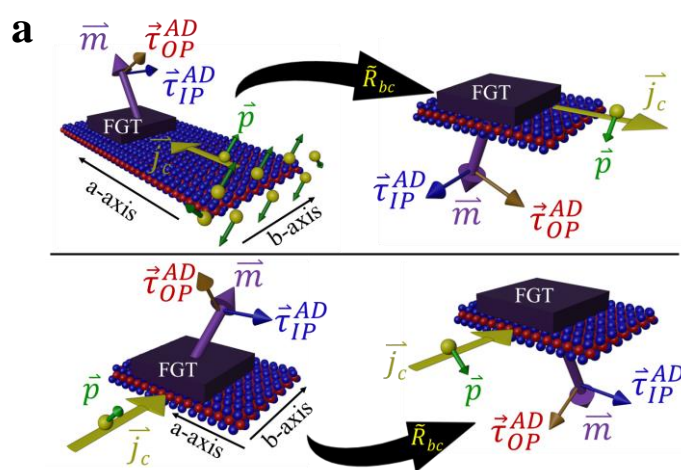
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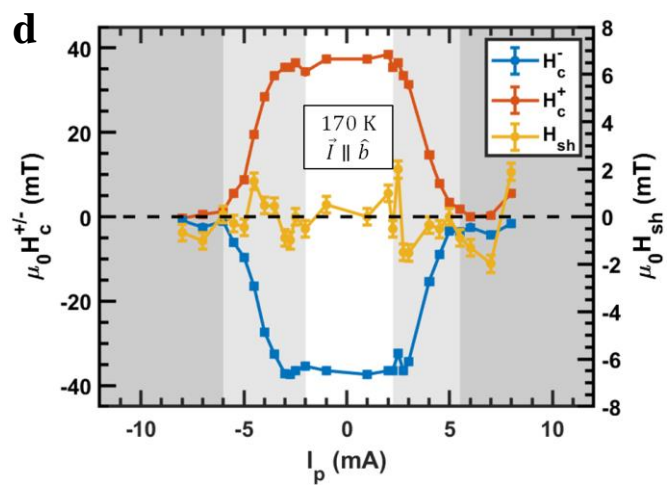
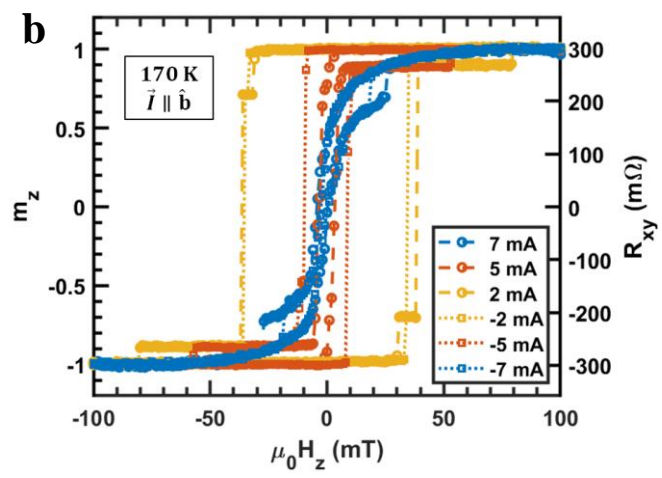
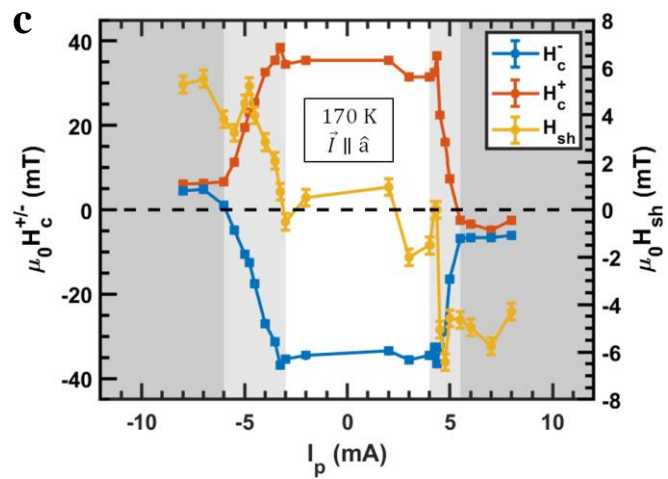
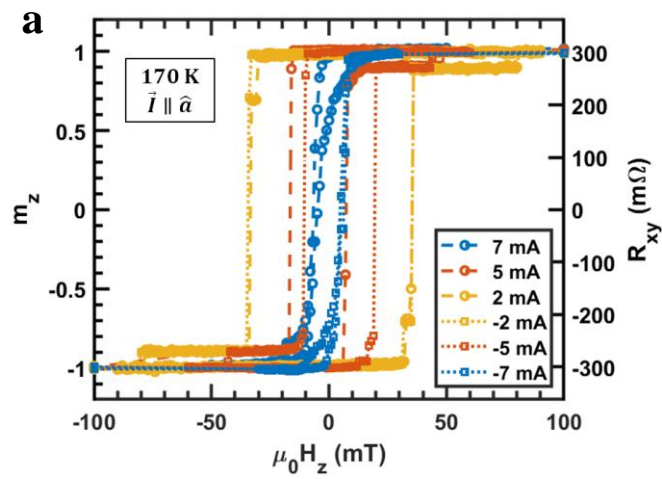
Fig. 1. Crystal structure, polarized Raman, and electron microscopy of the WTe₂/ FGT device. **a**, The crystal structure of WTe₂ with *a*-axis and *b*-axis labeled. The crystal is invariant (noninvariant) upon an *bc* (*ac*) mirror operation. **b**, An optical image of the device A. The electrodes are set up to allow current pulses along the *a*- and *b*-axis of WTe₂ separately. Lower panel: The side view of the device. **c**, The angle dependent polarized Raman spectra of WTe₂ of the device A, obtained by rotating the laser polarization with respect to the long edge(*a*-axis) of WTe₂ flake. **d**, The angle dependent Raman peak intensities of the Raman peak at 212 cm⁻¹, corresponds to dashed line in (c). **e**, The top panel shows the atomic arrangement in WTe₂ along the *a*-axis. Bottom panel: Cross-sectional STEM image of device A viewed along the *b*-axis orientation of WTe₂, which confirms that the lateral direction is the *a*-axis of WTe₂.

Fig. 2. The spin-orbit torque induced switching in WTe₂/ FGT bilayers. **a**, Schematic to show how different spin-orbit torques change upon a *bc*-plane mirror operation (denoted by \tilde{R}_{bc}) depending on whether a charge current is applied along the *a*-axis or *b*-axis. **b**, the AHE hysteresis loop as a function of H_z at 170 K. **c,d**, Current induced spin-orbit torque switching with magnetized state initialized in positive (negative) state and pulse sweeping from zero to large positive (negative) pulses while $\vec{I} \parallel \hat{a}$ (**c**) and $\vec{I} \parallel \hat{b}$ (**d**). **e**, The deterministic switching by a series of 500 μ s current pulses applied along the *a*-axis. The magnitude of the write pulse is 9 mA, corresponds to $J = 1.1 \times 10^{11} A/m^2$. **f,g**, Simulations for FGT single domain switching of magnetization with $\vec{I} \parallel \hat{b}$ (**f**) and $\vec{I} \parallel \hat{a}$ (**g**). The blue, red and white region correspond to unswitched, switched and metastable magnetic states, respectively.

Fig. 3. Pulse current induced AHE loop shift due to SOT. **a,b**, The measured AHE hysteresis loops with $\vec{H} \parallel \hat{z}$ while 500 μ s current pulses are applied along the *a*-axis (**a**) and *b*-axis (**b**) at each field. **c,d**, The field shift $\mu_0 H_{sh}$ and magnetization reversal field $\mu_0 H_c^\pm$ as a function of the applied pulse current along the *a*-axis (**c**) and *b*-axis (**d**). The white, light-grey, and dark-grey regions depict the field-induced, current-assisted, and current-induced magnetization switching regime, respectively.







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Note 1. Device Fabrication

Mechanical exfoliation of WTe_2 , hBN, and $\text{Fe}_{2.78}\text{GeTe}_2$ (FGT) was performed on separate silicon wafers with 300nm of SiO_2 inside of an Ar environment. Flakes were selected through optical investigation through a microscope. WTe_2 flakes that have well defined and straight edges were used because the a-axis tends to be along them¹. Prior to heterostructure fabrication, electrodes were defined on a separate Si/ SiO_2 chip using electron beam lithography and electron beam deposition with a PMMA/MMA bilayer resist. The electrodes were made such that Pt(8 nm) contacted the heterostructure and Cr(5nm)/Au(110nm) contacted the Pt for wire bonding pads. The heterostructure was fabricated using a custom transfer tool in an Ar environment. A transfer slide consisting of a polydimethylsiloxane (PDMS) slab and thin film of polycarbonate (PC) was used for picking up hBN, FGT, and WTe_2 in that order and then putting the stack on the Pt electrodes.

Note 2. Thickness, Interface, and Crystallographic Orientation of WTe₂/FGT Devices

Three WTe₂/FGT van der Waals (vdW) heterostructures were fabricated and named device A, B, and C. All of the results presented in the main paper come from device A. To determine the thickness, crystallographic orientation, and interface quality of the devices, we utilize atomic force microscopy (AFM), polarized Raman spectroscopy, and scanning transmission electron microscopy (STEM).

Device A was made by mechanically stacking exfoliated flakes of WTe₂ (25.8 nm)/ FGT (4.1 nm)/ hBN (39.6 nm) on to a pre-written Pt Hall cross, allowing for current to be applied in both the a- and b-axis of WTe₂. Device B has a heterostructure of WTe₂ (24.4 nm)/ FGT (7.7 nm)/ hBN (30-40 nm), stacked on a pre-written Pt Hall bar, which only allows current to be passed through the b-axis of WTe₂. The crystallographic orientation of device A is confirmed by both cross-sectional STEM and polarized Raman, while the axis of orientation of device B is confirmed solely through cross-sectional STEM. Device C consists of a heterostructure of WTe₂ (1.44 nm)/ FGT (10.3 nm) resting on a pre-written Pt Hall bar where the relationship between the current channel direction and the crystallographic orientation of WTe₂ was not verified. Both device A and B are capped with hBN to avoid oxidation. The results shown in all figures are from device A unless otherwise stated.

For device A, individual flakes and the resulting device can be found in Figure S1a. To characterize the thickness of the components of the device, we utilize AFM in semi-contact mode. The tip scanning direction was set to be near-perpendicular to all steps to acquire the correct thickness. Figure S1b,c, and d show the thickness of Pt, WTe₂, and hBN respectively. Arrows in Figure S1a show the location and direction of scanning for each height measured in b-d. The results from AFM are in good agreement with the cross-sectional STEM results (Fig. 1e in the

main text).

Polarized Raman spectra were collected in an inVia Renishaw Raman microscope. The device was loaded onto the microscope stage and positioned in such a way that the long edge of the flake (as indicated in Figure S1a) was aligned parallel to the laser polarization ($\theta = 0^\circ$). In this configuration, the incident laser is polarized in the vertical polarization at $\theta = 0^\circ$. The incident laser was rotated from 0 - 360° by 5° increments using a polarization rotator, while an analyzer was set to only allow vertically polarized light to enter the spectrometer. Raman spectra were collected at each polarization with 633 nm excitation, and two accumulations of 10 s. The laser power was set to 1 mW to avoid any damage by heating. Following spectral collection, the (baseline corrected) integrated intensities under each peak were calculated for the contour plot (Fig. 1c in the main text) and polar plots in Figure S2.

For device B, individual flakes can be found in Figure S3a as well as the completed stack on the pre-written electrodes. We utilize cross-sectional STEM to characterize both the crystallographic orientation of WTe_2 and the thickness of each component by making the STEM cut along the current channel. As displayed in Figure S3b, the STEM image shows the sample structure: $\text{SiO}_2/\text{Pt}/\text{WTe}_2/\text{FGT}/\text{hBN}$ (from bottom to top). Amorphous WTe_2 at the Pt/WTe_2 interface is due to either oxidation from the suspended region or due to plasma cleaning when preparing the sample for STEM. A zoomed in STEM image at the WTe_2/FGT interface (Fig. S3c) shows an atomically sharp interface and that the STEM cut is along the b-axis of WTe_2 (and therefore the current direction of device B).

For device C, individual flakes can be found in Figure S4a as well as the completed stack on the pre-written Pt electrodes. Figure S4b and c show the thickness of WTe_2 and FGT respectively. The arrows shown in Figure S4a show the location and direction of scanning for each height

measured in b and c. We find the thickness of WTe_2 to be 1.44 nm, corresponding to bilayer. The thickness of FGT was determined to be 10.3 nm.

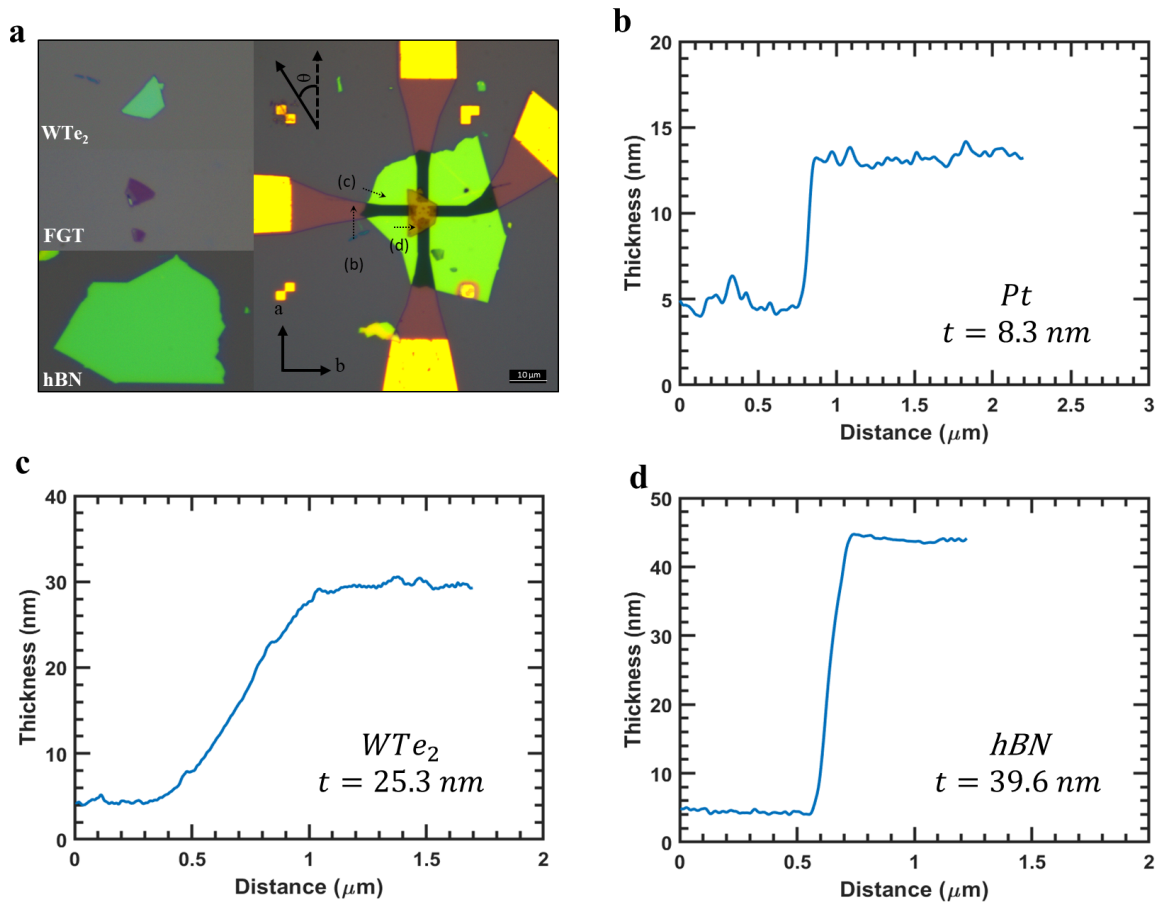


Figure S1 | The thickness characterization of device A obtained by AFM line scans. a, the optical images of individual 2D flakes (left) and the complete stack (right), where the dotted arrows show the lines scanned by AFM tip. **b,c,d**, relative thickness as a function of distance obtained by AFM line scan along the dotted arrows, reflecting the thickness of the Pt electrodes (**b**), WTe_2 (**c**), and hBN (**d**).

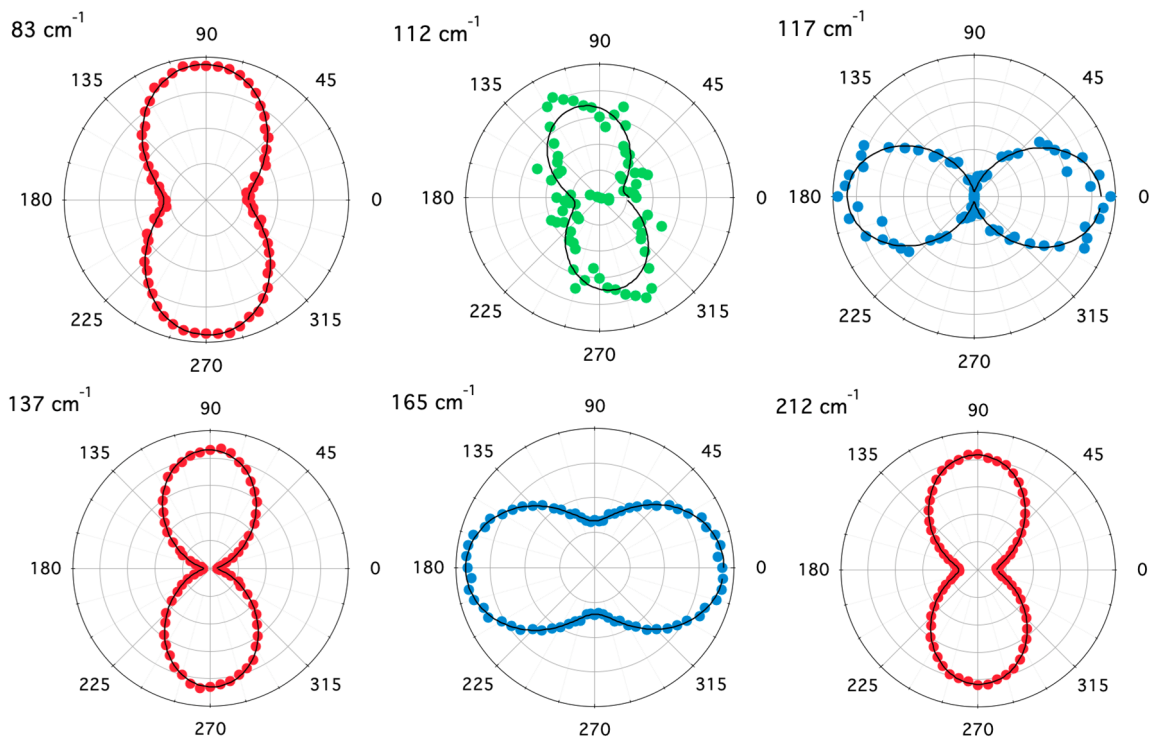


Figure S2 | Polarized Raman of device A. Raman data was collected as a function of polarization angle where the $\theta = 0^\circ$ is aligned to the long edge of WTe_2 (as shown in figure S1a). Each Raman peak value is displayed on the top left of the corresponding plot. The peaks are individually fitted and the integrated intensity for each peak is plotted for every polarization angle as a polar plot. The data confirms that the a-axis of WTe_2 is where $\theta = 0^\circ$.

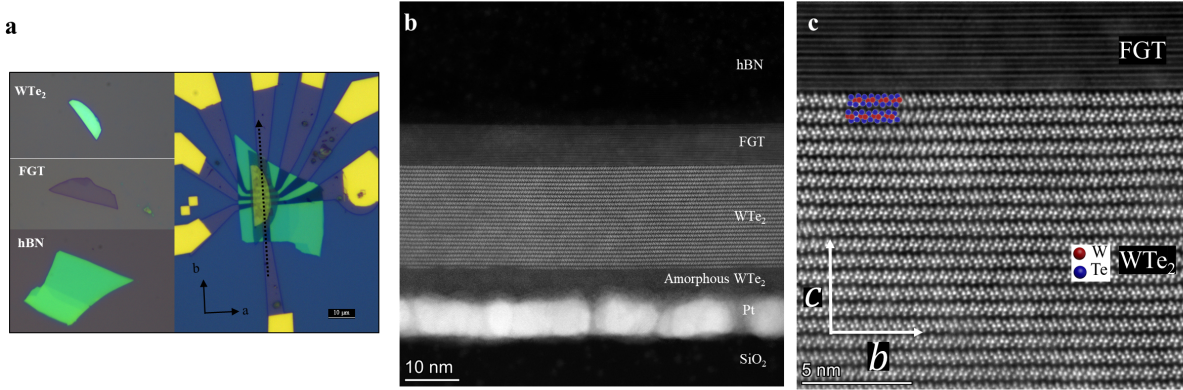


Figure S3 | The WTe₂ crystallographic orientation and thickness characterization of device B. **a**, the optical images of individual 2D flakes (left) and the completed stack (right), where the dotted arrow shows the direction of the STEM cut. **b**, The cross-sectional STEM of device B, showing the stack structure and atomically sharp interfaces. **c**, The zoomed in cross-sectional STEM image of the interface of WTe₂ and FGT showing that the cut is along the b-axis of WTe₂. Our model is overlaid to denote the type of atom.

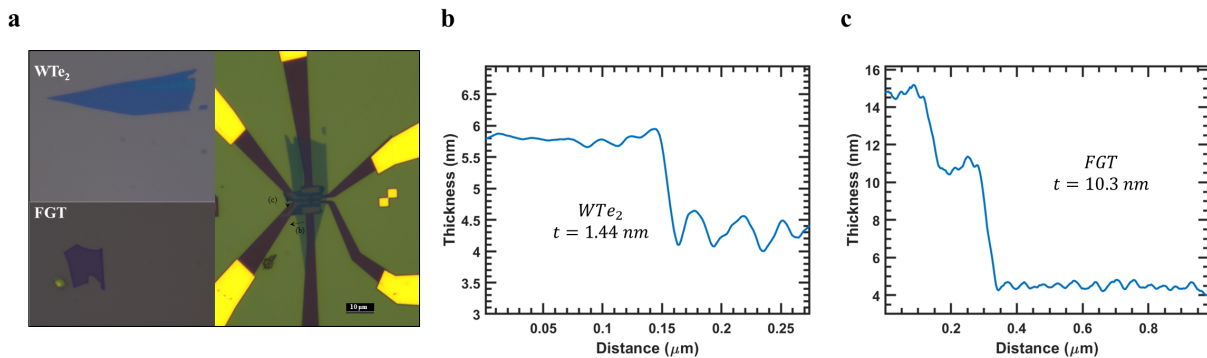


Figure S4 | The thickness characterization obtained by AFM line scans on device C. **a**, Optical images of individual 2D flakes (left) and the complete stack (right), where the dotted arrows show the lines scanned by the AFM tip. **b,c**, relative thickness as a function of distance obtained by AFM line scan along the dotted arrows, reflecting the thickness of WTe₂ (**b**) and FGT (**c**).

Note 3. Longitudinal Resistance and Shunt Factor

To quantify the amount of current shunting through the WTe_2 , the longitudinal resistance R_{xx} of all devices are measured. First, we define \hat{x} as the direction of the positive current. Considering the parallel resistor model, the longitudinal resistivity of the device can be written as $\rho_{xx} = \rho_{xx}^{\text{WTe}_2} \left[\frac{t_{\text{WTe}_2}}{t} + \frac{\rho_{xx}^{\text{WTe}_2}}{\rho_{xx}^{\text{FGT}}} \frac{t_{\text{FGT}}}{t} \right]^{-1}$, where $\rho_{xx}^{\text{WTe}_2}$ (ρ_{xx}^{FGT}) is the resistivity of WTe_2 (FGT), t_{WTe_2} (t_{FGT}) is the thickness of WTe_2 (FGT), and $t = t_{\text{WTe}_2} + t_{\text{FGT}}$. Since WTe_2 has a lower resistivity compared to FGT, the total resistivity ρ_{xx} is mostly contributed by WTe_2 . Especially for device A and B, we expect $\rho_{xx} \approx \rho_{xx}^{\text{WTe}_2}$ because $t_{\text{WTe}_2} \gg t_{\text{FGT}}$. Previous reported values of $\rho_{xx}^{\text{FGT}}(T)$ have shown rather weak temperature dependence²⁻⁴, while $\rho_{xx}^{\text{WTe}_2}(T)$ has shown to have a strong temperature dependence⁵.

Since the Hall bar geometry of device B allows for 4-point measurements, we first show the longitudinal resistivity results of device B in Figure S5a. The strong temperature dependence of ρ_{xx} confirms that $\rho_{xx} \approx \rho_{xx}^{\text{WTe}_2}$. To estimate $\rho_{xx}^{\text{WTe}_2}$, we take the values reported by Z. Fei *et al.*³ for the resistivity of FGT and use the parallel resistor model to estimate the resistivity of WTe_2 . We note that our estimated $\rho_{xx}^{\text{WTe}_2}$ is very close to the value reported by P. Li *et al.* for WTe_2 flakes with similar thickness (35 nm)⁵. We then calculate the shunt factor as a function of temperature, $X(T)$, for both WTe_2 and FGT (Fig. S5b), which indicates that most of the current shunts through WTe_2 in device B.

As for device A, R_{xx} is measured by the 2-point measurement along the a-axis instead of the 4-point measurement due to the geometry of the Hall cross. The WTe_2/FGT heterostructure is assumed as a cuboid with dimensions of $5 \mu\text{m} \times 3 \mu\text{m} \times 29.9 \text{ nm}$. The measured resistance includes the resistance of the WTe_2/FGT heterostructure, Pt electrodes, and contact resistance R_C . As shown in Figure S5c, the contribution of the Pt (8 nm) electrodes, with total length ~ 39

μm , is subtracted from the measured total resistance to obtain the resistance of the WTe_2 /FGT bilayer by considering resistors in series. We use the values reported by M. Alghamdi *et al.* for the resistivity of Pt^2 . The contact resistance is assumed to be independent of temperature and equal to 209Ω by matching $\rho_{xx}^{WTe_2}$ between device A and B in the low temperature regime ($T < 50K$). The longitudinal resistivity results of device A (Fig. S5d) show minor differences in $\rho_{xx}^{WTe_2}$ with respect to B. Such a difference could be explained by the fact that the current is applied along the a- (b-) axis in device A (B) respectively. We then calculate $X(T)$ for both WTe_2 and FGT as a function of temperature (Fig. S5e), which again indicates that most of the current shunts through WTe_2 . The shunt factor is used to calculate the current density flowing in WTe_2 (J_{WTe_2}), and hall resistivity $\rho_{xy} = E_y/J_{FGT}$, where J_{FGT} is the current density flowing in FGT.

The longitudinal resistivity results of device C (Fig. S5f) show that WTe_2 and FGT almost equally contribute to the total resistivity of the device because $t_{FGT} > t_{WTe_2}$. The estimated $\rho_{xx}^{WTe_2}$ in device C may be lower than the real value, since FGT is less resistive. The Shunt factor of WTe_2 and FGT (Fig. S5g) indicates that the current flows almost equally in WTe_2 and FGT in device C. Note that the real value of the current flowing in FGT may be larger than the estimated value because of the lower ρ_{xx}^{FGT} .

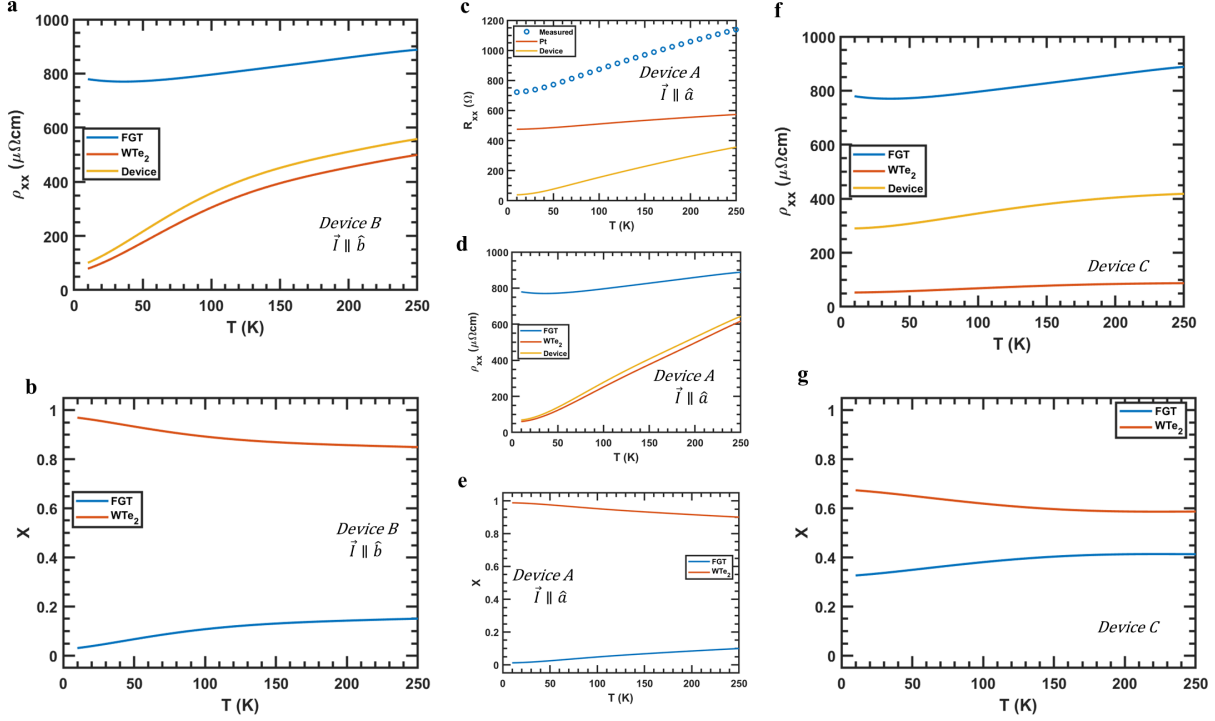


Figure S5 | The temperature-dependence of longitudinal resistance of WTe₂/FGT heterostructures. **a**, The estimated longitudinal resistivity ρ_{xx} of the WTe₂/FGT bilayer, WTe₂ layer, and FGT layer in device B. **b**, The shunt factor as a function of temperature for device B. **c**, the longitudinal resistance R_{xx} of device A as a function of temperature determined by 2-point measurements and the estimated contribution from the 39 μm -long Pt (8 nm) electrodes. **d**, the estimated longitudinal resistivity ρ_{xx} of the WTe₂/FGT bilayer, WTe₂ layer, and FGT layer in device A. **e**, The shunt factor as a function of temperature for device A. **f**, the estimated longitudinal resistivity ρ_{xx} of the WTe₂/ FGT bilayer, WTe₂ layer, and FGT layer in device C. **g**, The shunt factor as a function of temperature for device C.

Note 4. Temperature Dependence of AHE Hysteresis Loops

For device A, the Hall resistivity, $\rho_{xy}(\mu_0 H_z)$, as a function of the field applied along the easy axis of FGT was measured at various temperatures from 50 K to 220 K (Fig. S6a). These results confirm hard magnet behavior, highly square hysteresis loops, and no indication of the formation of multi-domains. We define $\rho_{AHE}(T)$ as the half-resistivity difference between the two saturated states and plot it as a function of temperature (Fig. S6b). We confirm the existence of a ferromagnetic phase. The antiferromagnetic coupling and a similar peak at $T < T_c$ have been reported in pristine FGT^{6,7}. The coercive field $H_c = (H_c^+ - H_c^-)/2$, where H_c^\pm is the positive/negative field for which the magnetization reverses, increases with decreasing temperature (Fig. S6c), and reaches 360 mT at 50 K. We also determined the effective magnetic anisotropic field $\mu_0 H_k \approx 4.12$ T at 170 K by measuring the hard axis AHE loop (Supplementary Note 6), which indicates strong perpendicular magnetic anisotropy. The coercive field H_c is much smaller than H_k , indicating that the switching is through incoherent magnetization reversal.

We also perform field-dependent Hall resistivity measurements at various temperatures on device B and C and obtain very similar results (Fig. S7,8). The trend of the measured ρ_{AHE} for device C is close to the trend reported in Pt/FGT systems². The Curie temperature of device B and C are higher than device A due to the increased FGT thickness, which agrees with the previously reported thickness dependent study of the magnetic property of FGT flakes³.

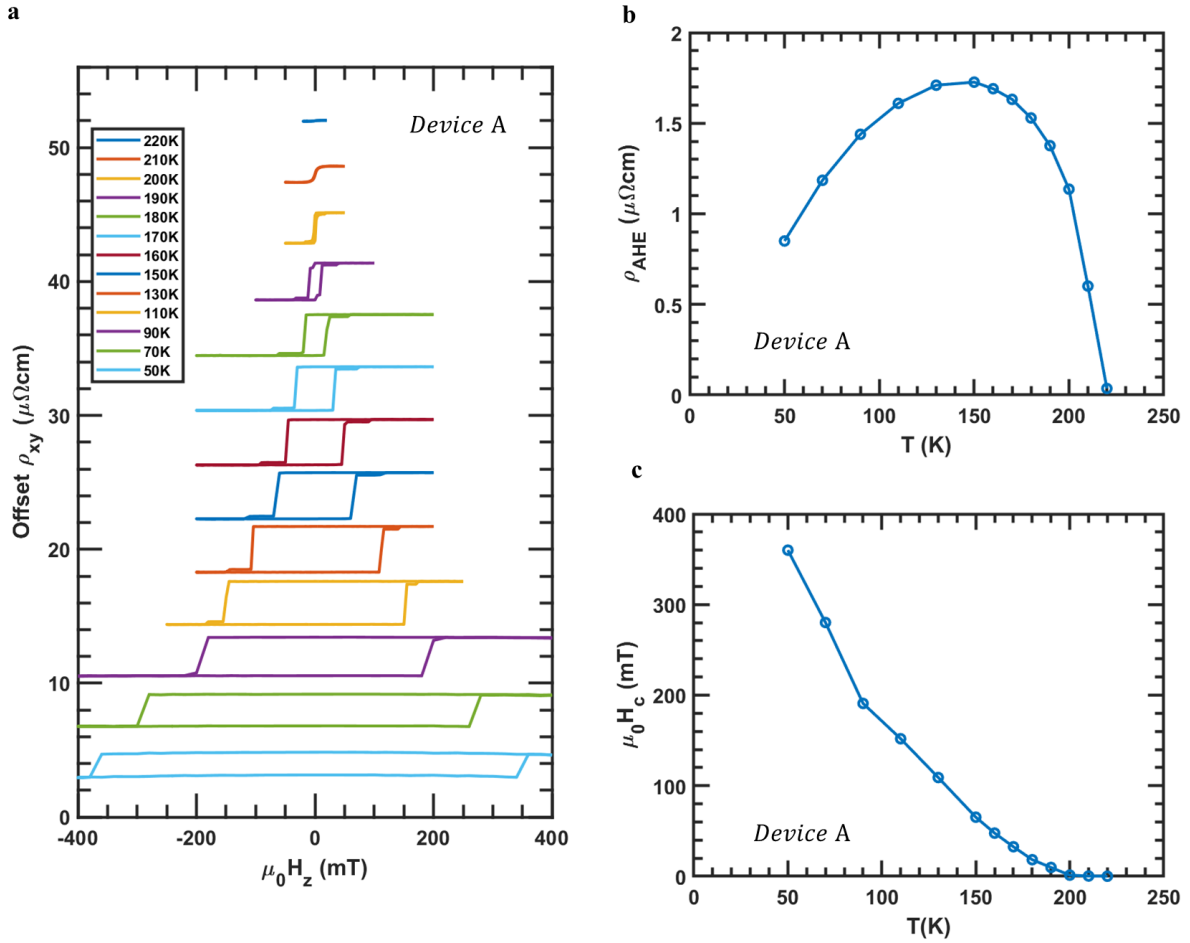


Figure S6 | The temperature-dependent magnetic property of device A. a, The transverse resistivity ρ_{xy} as a function of applied field from 50 K to 220 K. **b**, The Anomalous Hall resistivity ρ_{AHE} as a function of temperature. **c**, The coercive field $\mu_0 H_c$ as a function of temperature.

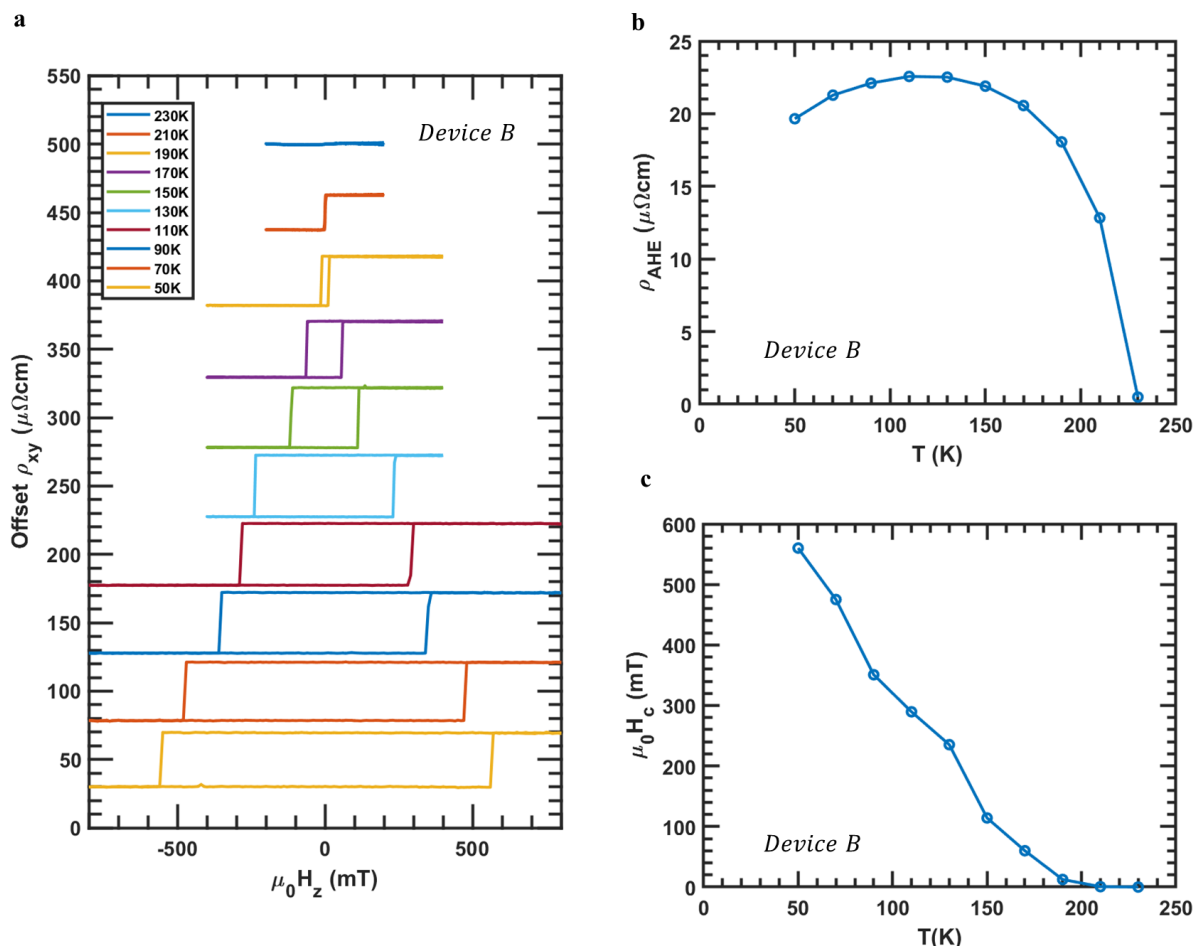


Figure S7 | The temperature-dependent magnetic property of device B. a, The transverse resistivity ρ_{xy} as a function of applied field from 50 K to 230 K. **b**, The Anomalous Hall resistivity ρ_{AHE} as a function of temperature. **c**, The coercive field $\mu_0 H_c$ as a function of temperature.

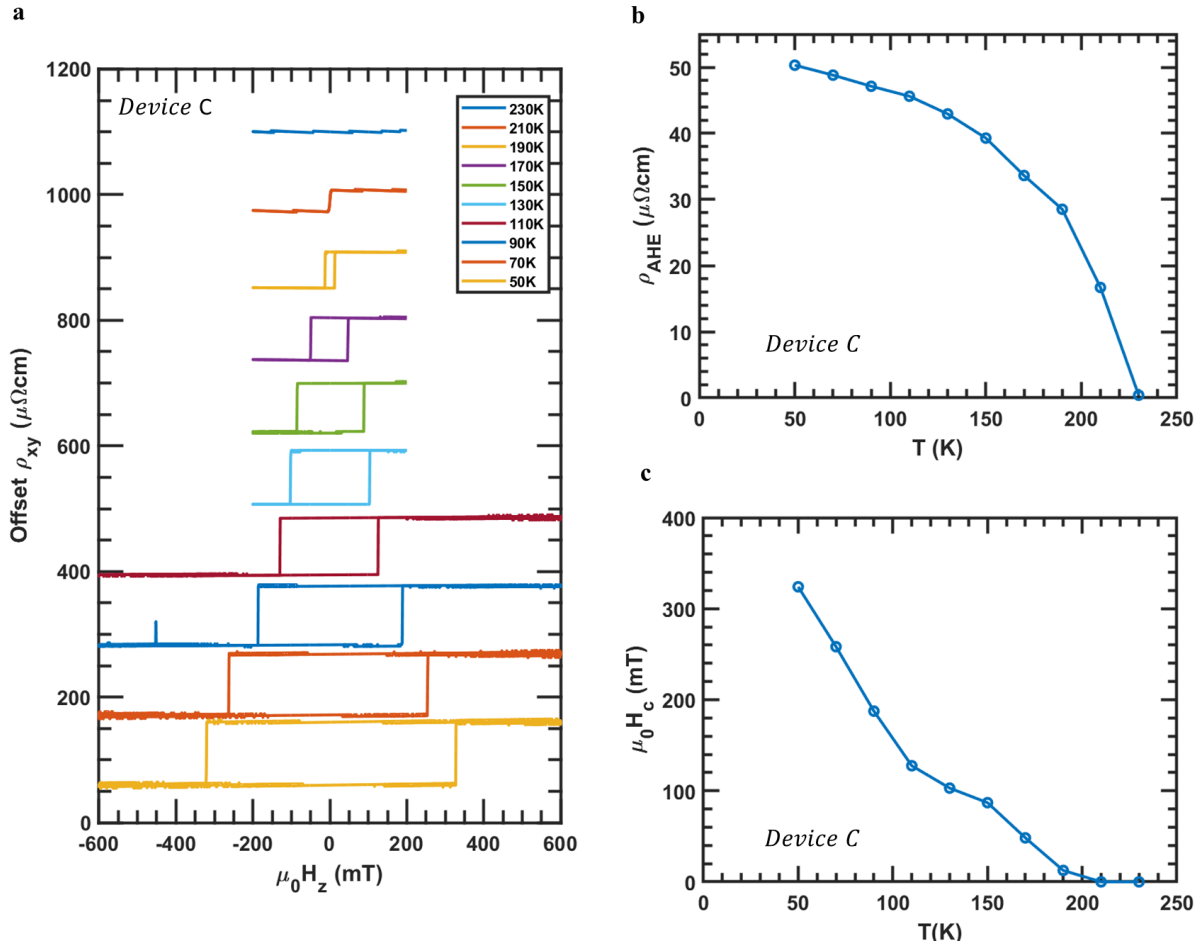


Figure S8 | The temperature-dependent magnetic property of device C. a, The transverse resistivity ρ_{xy} as a function of applied field from 50 K to 230 K. **b,** The Anomalous Hall resistivity ρ_{AHE} as a function of temperature. **c,** The coercive field $\mu_0 H_c$ as a function of temperature.

Note 5. The Pulse Current-Induced Joule Heating and Reduction of Coercive Field

Current-induced Joule heating has been reported in WTe_2/FGT vdW heterostructures⁸ and Pt/FGT ⁴ in similar measurements, which could potentially assist the SOT-induced switching. To examine the impact of Joule heating in device A, due to the limitation of having a hall cross geometry, we utilize the longitudinal component measured in transverse resistance. The measured raw transverse resistance, $R_{xy,raw}(H_z) = R_{OHE}H_z + R_{AHE}m_z(H_z) + R_L$, is a function of the perpendicular field H_z (Fig. S9a), where R_{OHE} is the ordinary Hall resistance, R_{AHE} is the anomalous Hall resistance, R_L is the longitudinal resistance, and m_z is the normalized perpendicular magnetization. By fitting the positive (negative) saturated branch with a linear function, we determine R_{OHE} and define the positive (negative) resistance $R_{pos}(R_{neg})$ as the raw transverse resistance of positive (negative) saturated states at zero field. We can then calculate $R_{AHE} = (R_{pos} - R_{neg})/2$ and $R_L = (R_{pos} + R_{neg})/2$ as a function of temperature by measuring the AHE loop at various temperatures (Fig. S9b). The separation between R_{pos} and R_{neg} is clearly due to AHE and R_L comes from the longitudinal resistance which increases mostly-linearly with increasing temperature. The change of resistance per Kelvin is $\alpha = 2.6 \pm 0.2 \text{ m}\Omega/\text{K}$, determined by a linear fit to $R_L(T)$. During the SOT switching measurements, R_{xy} is measured a few seconds after the pulse current is injected. For all the deterministic switching measurements conducted, we observe that R_{xy} always returns to the same point with deviations much smaller than $2.6 \text{ m}\Omega$ (a temperature difference of 1 K) after completing a full loop. This shows that there is no substantial heat accumulation in our device.

From the results of the AHE loop shift measurements, we can obtain $R_L(I_p)$ and $R_{AHE}(I_p)$ as a function of pulse current, I_p , in the same way. To translate R_L to the actual temperature T_{JH} elevated by Joule heating, we consider $T_{JH}(I_p) = \Delta T(I_p) + T_{sp}$, where ΔT is the temperature difference induced by the applied current pulse and T_{sp} is the set point temperature of the

controller. We first use $T(R_L)$ obtained in Fig. S9b to convert $R_L(I_p)$ to $T_{JH}(I_p)$. We find that $T_{JH}(I_p)$ has a clear I_p^2 dependence, which indicates Joule heating. Compared to the resistance obtained by delta mode, the resistance obtained by pulse delta mode has a resistance offset, so we use the quadratic fit result of $T_{JH}(I_p)$ to enforce $T_{JH}(I_p = 0) = T_{sp}$. As shown in Figure S9c and e, the I_p dependence of T_{JH} when $\vec{I} \parallel \hat{a}$ and $\vec{I} \parallel \hat{b}$ both show that T_{JH} could surpass 240 K at $I_p = 8mA$, which corresponds to $J_p \approx 9.44 \times 10^{10} A/m^2$.

The fact that $T_{JH} > T_c$ may be surprising, however, it should be noted that the temperature of FGT may not be the same as the temperature of WTe_2 . Since most of the current is shunting through WTe_2 , R_L may not be a good indicator for the elevated temperature of FGT (T_{JH}^{FGT}). To verify this, we use $T(R_{AHE})$ (obtained in Fig. S9b) to convert $R_{AHE}(I_p)$ to $T_{JH}^{FGT}(I_p)$ and find that $T_{JH}^{FGT}(I_p)$ has a similar trend but is roughly 30 K below $T_{JH}(I_p)$. Points in the low current regime for the linear interpolation of $T_{JH}^{FGT}(I_p)$ are omitted because R_{AHE} has a weak temperature dependence near 170K as shown in Figure S9g. We also note that the T_{JH} is higher at the same I_p when $\vec{I} \parallel \hat{b}$, which may be due to slight differences in resistance when current is applied along different axes.

To link the Joule heating to the observed reduction of H_c induced by current injection, we plot $H_c(I_p)$ when $\vec{I} \parallel \hat{a}$ and $\vec{I} \parallel \hat{b}$ in Figure S9d and f. The onset of the reduction in H_c starts close to where T_{JH}^{FGT} starts to rise, indicating that the reduction of H_c is related to Joule heating. Because the spin torques generated by the current may also reduce H_c , the reduction of H_c may be the consequence of Joule heating and current-induced spin torque. Note that the peak in H_c cannot be explained by Joule heating, which is the signature of magnetic excitations due to spin current induced steady precessional states. These results indicate that the current-induced SOT switching in the WTe_2 /FGT heterostructure is similar to the thermal-assisted switching, where the current raises the temperature of the ferromagnetic layer in order to lower the energy barrier

between two stable states.

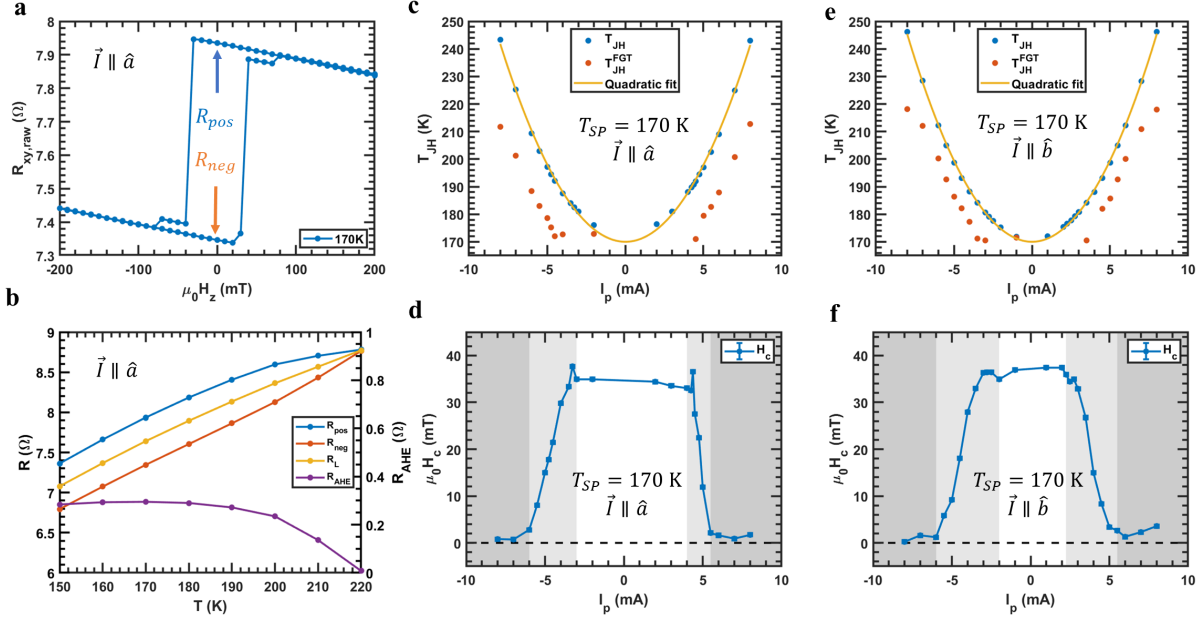


Figure S9 | The current-induced coercive field reduction and joule heating. **a**, The AHE hysteresis loop as a function of the perpendicular magnetic field H_z at 170 K without the background removed, where R_{pos} (R_{neg}) is defined as the resistance measured at the positive (negative) state at zero field. **b**, The longitudinal component R_L and R_{AHE} extracted from the measured transverse resistance R_{xy} as a function of temperature plotted with R_{pos} and R_{neg} . R_{AHE} is plotted on the right axis. **c,e**, The estimated temperature raised by joule heating, T_{JH} , and T_{JH}^{FGT} as a function of I_p applied along the a-axis (**c**) and b-axis (**e**). **d,f**, The I_p dependence of H_c measured with $\vec{H} \parallel \hat{z}$ while the current pulse is applied along the a-axis (**d**) and b-axis (**f**).

Note 6. Effective Magnetic Anisotropy H_k and in-Plane SOT in WTe_2/FGT Heterostructure

The in-plane current in WTe_2 is expected to induce a strong in-plane spin polarization, which could exert in-plane field-like and antidamping torques to the magnetic moment in FGT. To examine the strength of current-induced in-plane torque, we apply an external field H tilted away from the x- and y-axis towards the z-axis by a small angle $\beta = 5^\circ$ to measure the effective field generated by the current. This measurement is similar to the one performed by Liu *et al.* in a conventional SOT system⁹. We assume coherent magnetization rotation and measure the normalized perpendicular magnetization $m_z = \text{Cos}\theta = R_{xy}/R_{AHE}$ at each field, where θ is the spherical polar angle of the magnetization and \hat{z} is the out-of-plane direction. The resistance is measured by averaging 10 consecutive 500 μs current pulses in pulse delta mode to avoid heat accumulation. Note that the effect of OHE and R_{AHE} is determined independently by measuring the AHE loop with $\vec{H} \parallel \hat{z}$.

When current is applied along the x-axis, the in-plane spin polarization is in the y-direction, which could potentially generate effective antidamping and field-like fields denoted as H_{IP}^{AD} and H_{IP}^{FL} respectively. Since H_{IP}^{AD} is collinear to $\hat{m} \times \hat{y}$ and H_{IP}^{FL} is collinear to \hat{y} , the AHE loop will be modulated by H_{IP}^{AD} (H_{IP}^{FL}) when $\vec{H} \parallel \hat{x}$ ($\vec{H} \parallel \hat{y}$). The external field needed to tilt \hat{m} away from the z-axis by θ , when $\pm I_p$ is applied, can be written as $H_{\pm}(\theta) = [H_k \text{Sin}\theta \text{Cos}\theta \mp H_{IP}^{AD(FL)}]/\text{Cos}(\theta + \beta)$, derived by Liu *et al.*⁹. We define the even part $H_{even}(\theta) = [H_+(\theta) + H_-(\theta)]/2 = H_k \text{Sin}\theta \text{Cos}\theta / \text{Cos}(\theta + \beta)$, and the odd part $H_{odd}(\theta) = [H_-(\theta) - H_+(\theta)]/2 = H_{IP}^{AD(FL)} / \text{Cos}(\theta + \beta)$. Therefore, by calculating $H_{even}(\theta)$ and $H_{odd}(\theta)$ from the measured AHE loops, H_k and $H_{IP}^{AD(FL)}$ can be obtained by a one parameter fit. We first measure H_k at 170 K in delta mode with a small current of 50 μA , at which H_{IP}^{AD} , H_{IP}^{FL} , and Joule heating are negligible. As shown in Figure S10, we determine $H_k \approx 4.14$ T at 170 K, which is close to the reported

value by Alghamdi *et al.* at 180 K².

To quantify H_{IP}^{AD} , we perform AHE loop measurements by applying an external field $\vec{H} \parallel \hat{y}$ for both $\vec{I} \parallel \hat{a}$ and $\vec{I} \parallel \hat{b}$. As shown in Figure S11a and b, the clear difference in $m_z(H)$ between $I_p = +7$ mA and $I_p = -7$ mA indicates strong H_{IP}^{AD} . The points at lower fields are excluded because the magnetization reversal occurs in the low field regime. As shown in Figure S11c and d by fitting $H_{even}(\theta)$ and $H_{odd}(\theta)$, we determine $H_{IP}^{AD} \approx 28$ mT and $H_k \approx 2.03$ T when $\vec{I} \parallel \hat{a}$, and $H_{IP}^{AD} \approx 32$ mT and $H_k \approx 1.4$ T when $\vec{I} \parallel \hat{b}$. Strikingly, $H_{IP}^{AD}/J_p \approx 36 \frac{mT}{10^{11}A/m^2}$ in our device is about 20 times larger than $H_{IP}^{AD}/J_p \approx 1.7 \frac{mT}{10^{11}A/m^2}$, reported in the conventional SOT system of Pt/Co/AlO_x⁹. The observation of strong in-plane antidamping torques is in good agreement with the theoretically predicted high spin-hall angle $\theta_{SHE} = -0.54$ in WTe₂¹⁰, and the experimental results from spin-torque ferromagnetic resonance^{11,12}. The significant decrease of H_k is due to Joule heating and the difference in H_k between $\vec{I} \parallel \hat{a}$ and $\vec{I} \parallel \hat{b}$ is due to the difference in T_{JH} as mentioned in Note 4.

To quantify the field-like case, H_{IP}^{FL} , we measure AHE loops by applying an external field $\vec{H} \parallel \hat{y}$ for both $\vec{I} \parallel \hat{a}$ and $\vec{I} \parallel \hat{b}$. We observe no substantial difference in $m_z(H)$ between $I_p = +7$ mA and $I_p = -7$ mA (Fig. S12a and b), showing weak H_{IP}^{FL} . As shown in Figure S12c and d, we determine $H_{IP}^{FL} \approx -2.2$ mT and $H_k \approx 1.81$ T when $\vec{I} \parallel \hat{a}$ and $H_{IP}^{FL} \approx -3.7$ mT and $H_k \approx 1.29$ T when $\vec{I} \parallel \hat{b}$. However, we should also consider the Oersted effect, which could generate an Oersted field $\mu_0 H_{Oe} \approx \frac{\mu_0 t W T e_2}{2} J \approx 1.3$ mT, pointing towards $\mp \hat{y}$ at $I_p = \pm 7$ mA. Therefore, we conclude that the observed in-plane field-like field is likely due to the Oersted effect. Furthermore, no significant H_{IP}^{FL} is observed, which is again in good agreement with the experimental results from spin-torque ferromagnetic resonance measurements^{11,12}.

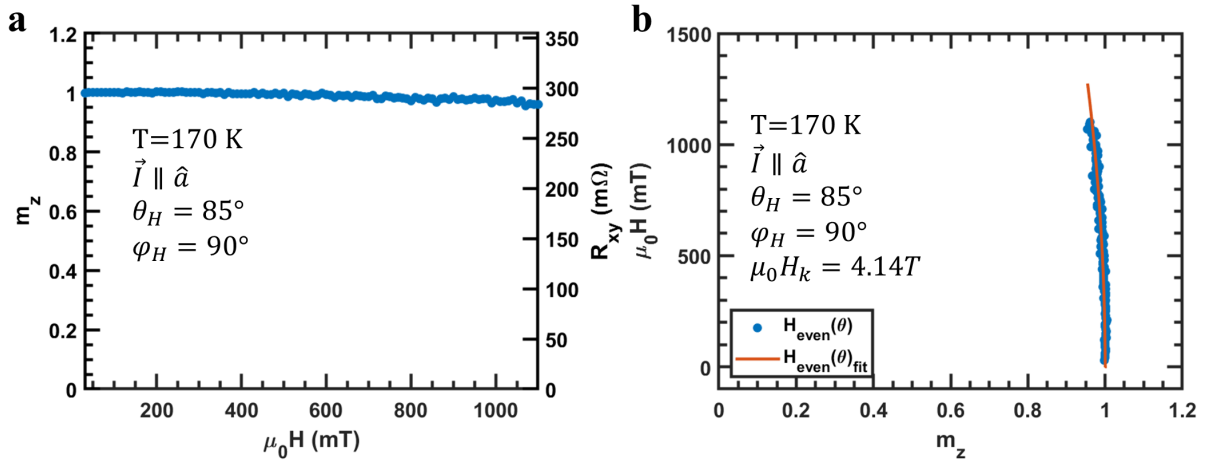


Figure S10 | The determination of effective magnetic anisotropy. **a**, The AHE hysteresis loop as a function of field applied in yz plane but tilted 5° away from the y-axis. **b**, Points: the measured value of $H(m_z)$ obtained from (a). Line: The fit curve obtained by one parameter fit, which yields $\mu_0 H_k = 4.14\text{ T}$.

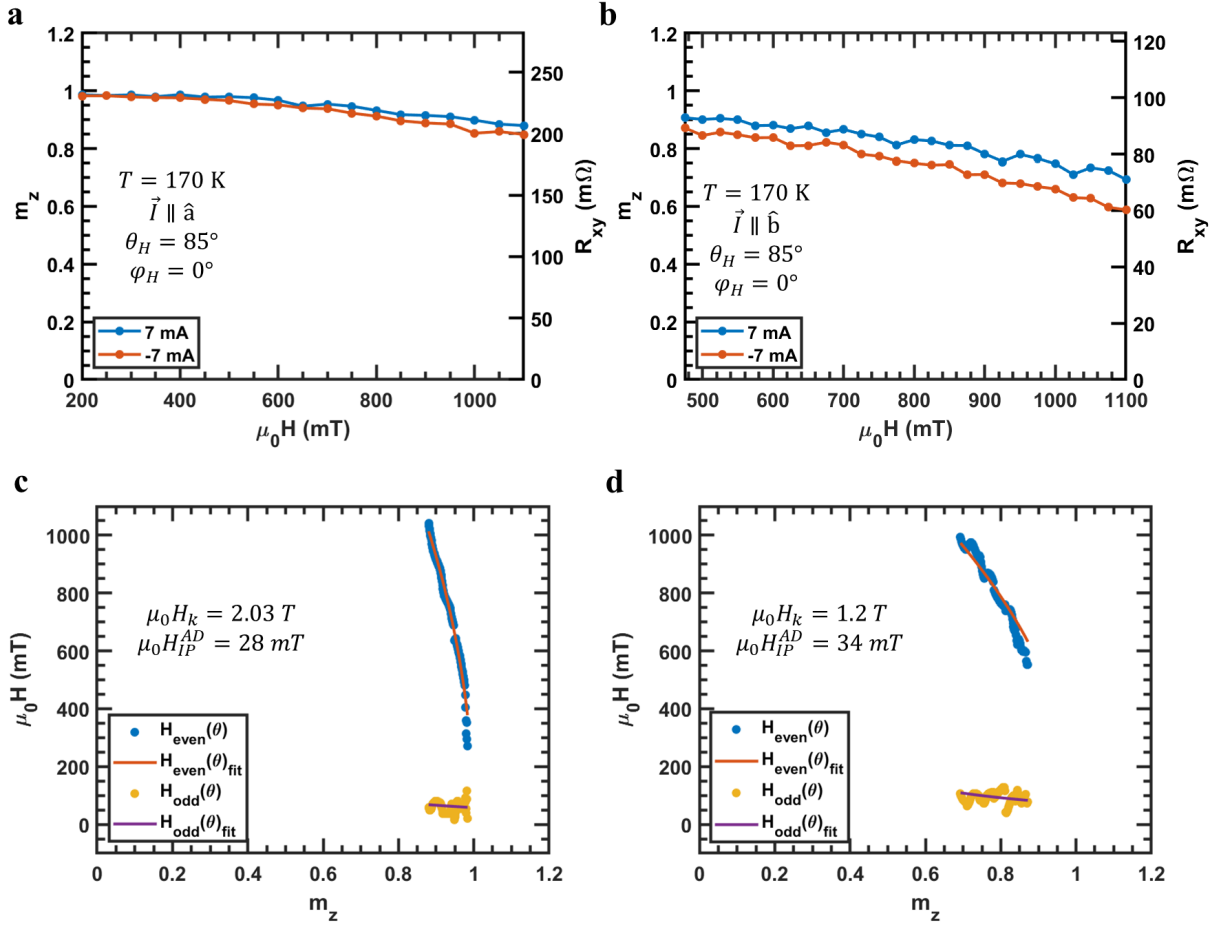


Figure S11 | The in-plane antidamping effective field in WTe₂/FGT. **a,b**, The perpendicular magnetization is measured when the field is applied in xz plane but tilted +5° away from x-axis while current applied along the a-axis (**a**) and b-axis (**b**). **c,d** Points: The measured value of $H_{\text{even}}(m_z)$ and $H_{\text{odd}}(m_z)$ obtained from (**a**) and (**b**), respectively. Lines: The fit curve obtained by one parameter fit to determine H_k and H_{IP}^{AD} .

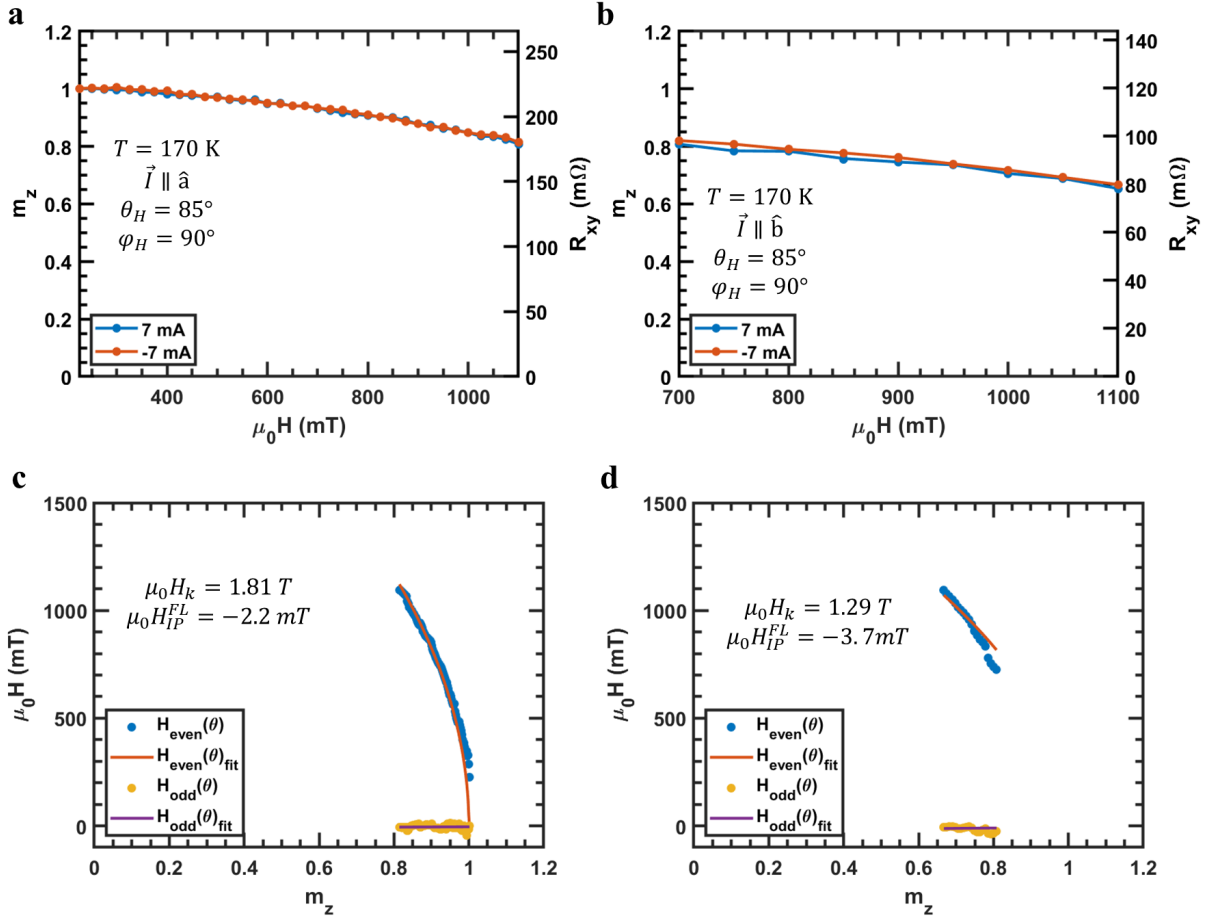


Figure S12 | The in-plane field-like effective field in WTe_2/FGT . **a,b**, the perpendicular magnetization is measured when the field is applied in yz plane but tilted $+5^\circ$ away from y -axis while current applied along the a -axis (**a**) and b -axis (**b**). **c,d**, Points: The measured value of $H_{\text{even}}(m_z)$ and $H_{\text{odd}}(m_z)$ obtained from (**a**) and (**b**), respectively. Lines: The fit curve obtained by one parameter fit to determine H_k and H_{IP}^{FL} .

Note 7. Current-Induced SOT Switching in the Presence of an in-Plane Field

In conventional heavy metal systems, an in-plane field H_x applied collinear to the current is required to achieve deterministic switching due to the absence of τ_{OP}^{AD} , which should be a similar scenario when $\vec{I} \parallel \hat{b}$. Therefore, we perform current-induced SOT switching in the presence of H_x to test both the robustness of switching when $\vec{I} \parallel \hat{a}$ and the response of H_x when $\vec{I} \parallel \hat{b}$. The results when $H_x = 0$ mT (Fig. S13a and d) show clear deterministic switching when $\vec{I} \parallel \hat{a}$, while demagnetized states occur at high current values when $\vec{I} \parallel \hat{b}$ due to Joule heating and in-plane torques that tend to form multi-domains. As shown in Figure S13a-c, the applied field of ± 100 mT has little effect on the SOT switching when $\vec{I} \parallel \hat{a}$. This proves that the observed deterministic switching is not the same as SOT switching induced by in-plane antidamping torques which could be assisted by a stray field.

When $\vec{I} \parallel \hat{b}$ with $H_x = \pm 100$ mT, we find that the negative (positive) terminal state at high positive currents moves down (up) (Fig. S13d-f). However, it is difficult to distinguish if the difference is contributed by the change of response to antidamping torques that depend on the sign of H_x or by the H_z component from the small magnetic field misalignment. The formation of multi-domains due to the increase of temperature at high current values also complicates the analysis.

The other signature of switching induced by in-plane antidamping torques is the chirality reversal in the switching hysteresis loop when H_x reverses. However, we do not see clear chirality reversal in device A when $\vec{I} \parallel \hat{b}$, as shown in Fig. S13a and b. The loops are not centered due to the slight misalignment of the magnetic field and the unsaturated magnetization is due to the formation of multi-domains, as observed in Pt/FGT systems^{2,4}. It is interesting that the formation of such domains has little influence on the terminal states when $\vec{I} \parallel \hat{a}$. In order to ex-

tract details of how the terminal states are achieved by in-plane antidamping torques at $T \approx T_c$ time-resolved domain imaging techniques are needed.

We also perform SOT switching in device B at various fields, including switching at zero field. As shown in Figure S14a, the switching chirality is counter-clockwise when $\mu_0 H_x = +100$ mT. While when $\mu_0 H_x = -100$ mT (Fig. S14b), the chirality reverses to clockwise. The chirality reversal in device B is clear and consistent with switching induced by in-plane antidamping torque. We plot SOT switching results at various fields in Figure S14c and d. For sufficient $|\mu_0 H_x| \geq 20$ mT, the chirality of the loop is determined entirely by the sign of H_x , as expected for field-assisted SOT switching. We found that the switching is inefficient at zero field and the chirality is the same as when $H_x < 0$ and the switching is optimized at $|\mu_0 H_x| = 50 - 100$ mT. The switching at zero field may be explained by stray fields, a small τ_{OP}^{AD} induced by a slight misalignment of the current channel, and (or) current spreading. At higher fields, the loop is narrowed with increasing $|H_x|$, indicating the formation of multi-domains.

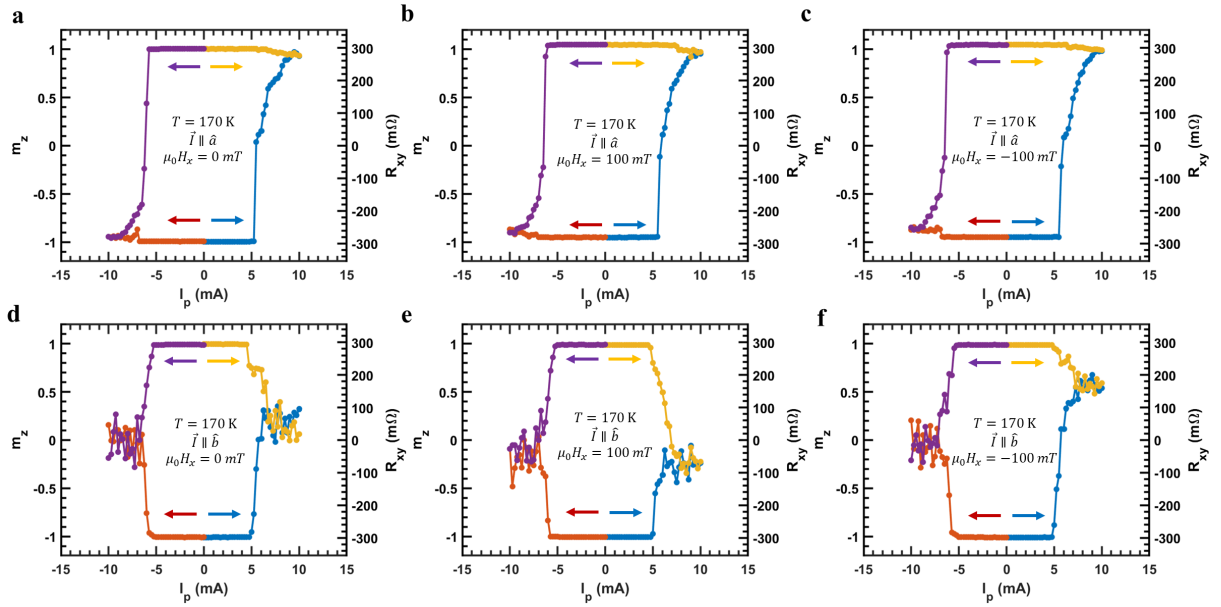


Figure S13 | The pulse-induced SOT switching of device A with and without field H_x applied along the current. For all measurements, the magnetization is initialized to $m_z = \pm 1$ prior to the application of the current. Starting from zero, current is gradually pulsed towards the negative or positive direction indicated by arrows. **a-f**, The pulse-induced SOT switching at 170 K while $\vec{I} \parallel \hat{a}$ (**a-c**) and $\vec{I} \parallel \hat{b}$ (**d-f**) with $\mu_0 H_x = 0$ mT (**a,d**), 100 mT (**b,e**), and -100 mT (**c,f**) applied collinear to the current direction.

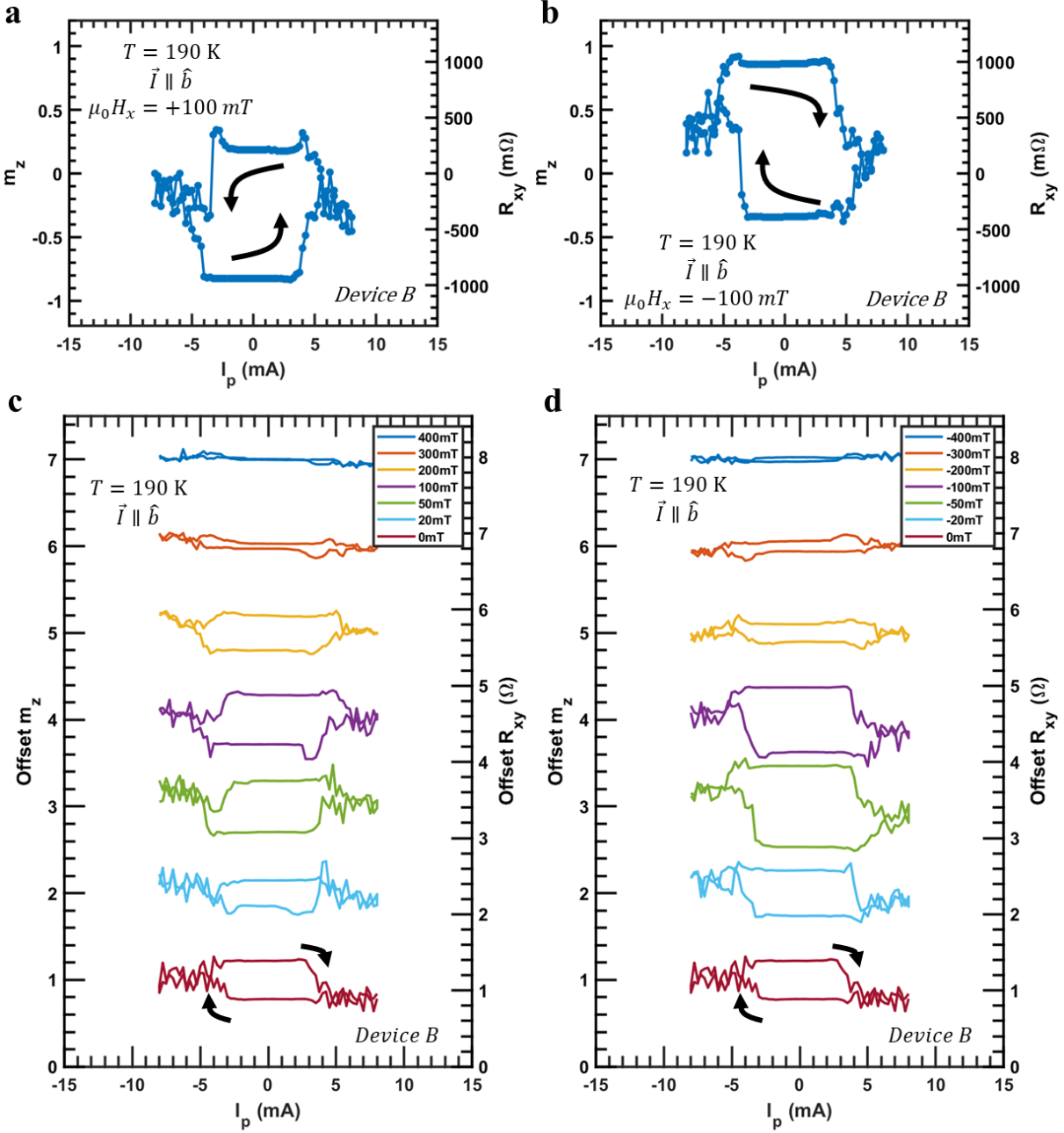


Figure S14 | The chirality reversal of pulse-induced SOT switching of device B at various fields H_x applied along the current. **a,b**, The pulse-induced SOT switching at 190 K while $\vec{I} \parallel \hat{b}$ with $\mu_0 H_x = +100$ mT (**a**), and -100 mT (**b**) applied collinear to current direction. The chirality reverses when H_x reverses. **c,d**, The pulse-induced SOT switching at 190 K while $\vec{I} \parallel \hat{b}$ at various fields with $H_x \geq 0$ (**c**), and $H_x \leq 0$ (**d**) applied collinear to current direction. When $|H_x| > 0$, the chirality is determined by the in-plane field, while the chirality is clockwise when $\mu_0 H_x = 0$ mT.

Note 8. Current-Induced Field-Free Switching in Device C

Although the crystallographic orientation in device C is not verified by cross-sectional STEM or polarized Raman spectroscopy, the current channel is likely aligned to the a-axis of WTe_2 based on the cleaving directions of the flake and magnetotransport measurements. As shown in Figure S15a (b), similar to device A, we also observe field-free deterministic switching in device C with m_z initially prepared in the negative (positive) state. The offset of the loops is likely due to an insufficient torque magnitude to bring the magnetization state to saturation.

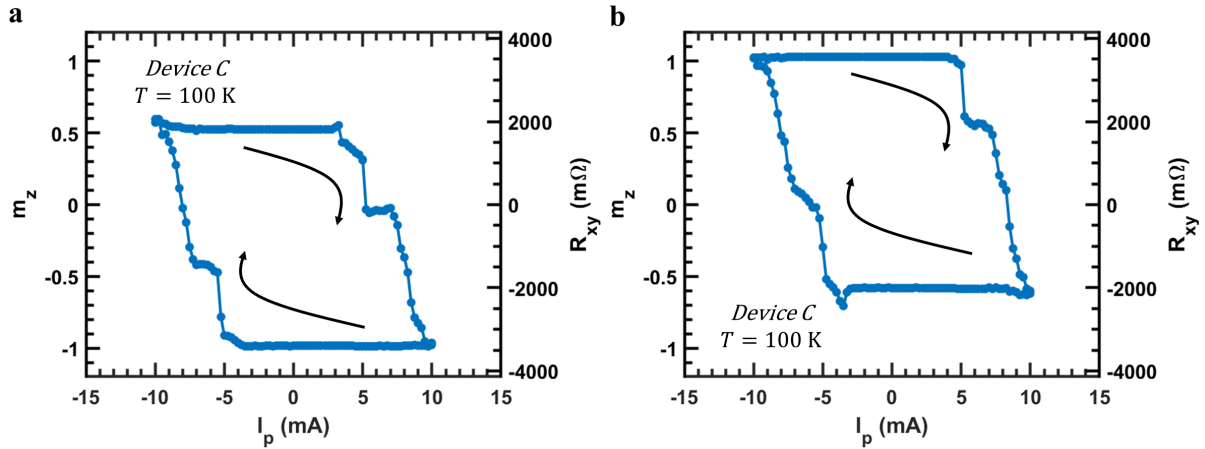


Figure S15 | The current-induced zero field SOT switching of device C. a,b, The current-induced SOT switching at 100 K with m_z initialized in negative (a) and positive (b) saturated state.

Note 9. SOT Switching at Various Temperatures in WTe₂/FGT Heterostructures

We further demonstrate the deterministic SOT switching at various temperatures from 150 K to 190 K when $\vec{I} \parallel \hat{a}$ (Fig. S16a) and determine J_{th} , defined as $(J_{th}^+ + J_{th}^-)/2$ where $J_{th}^{+(-)}$ is the current density pulse magnitude that drives the magnetization state across $m_z = 0$ at positive (negative) pulse sides. The magnetization could be almost fully reversed from one saturated state to the opposite magnetization with $|m_z| \geq 0.88$. The non-saturated component is likely due to multi-domain formation due to Joule heating and the torques contributed by the Oersted effect and SHE that tend to drive the magnetization toward the plane. To compare the efficiency with similar vdW heterostructures, we plot the temperature dependence of the current density threshold J_{th} from 150 K to 190 K (Fig. S16b). At lower temperatures, higher current is required to switch the magnetization due to the increase in H_c .

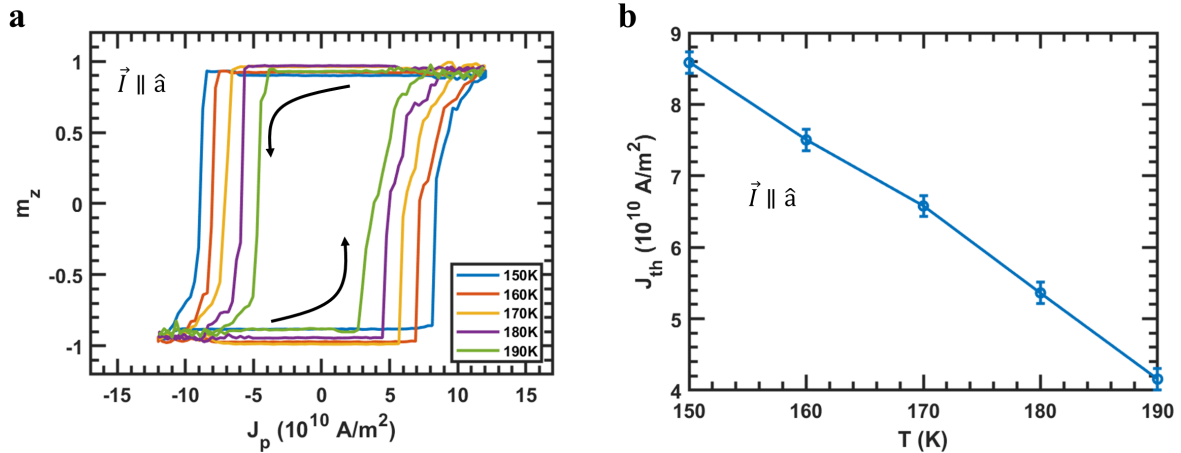


Figure S16 | Current pulse-induced SOT switching and current density threshold at various temperatures of device A. **a**, Current pulse-induced SOT switching full hysteresis loop while $\vec{I} \parallel \hat{a}$ at various temperatures from 150 K to 190 K. **b**, The current density threshold J_{th} as a function of temperature.

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