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Title

Imagers as Sensors: Correlating Plant CO2 Uptake with Digital Visible-Light Imagery

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Authors

Hyman, Josh
Graham, Eric
Hansen, Mark
et al.

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Imagers as sensors: Correlating plant CO₂ uptake with digital visible-light imagery

Josh Hyman, Eric Graham, Mark Hansen, Deborah Estrin

Center for Embedded Networked Sensing - <http://www.cens.ucla.edu>

Introduction: Use imagers to predict hard-to-measure natural phenomena

Some phenomena are difficult to measure

- Existing sensors are hard to use in the field**
Measuring some biological phenomena require *bulky* or *invasive* sensors which make deployments difficult to manage and increase experimental error.
- More creative sensing techniques are required**
These issues suggest the use of a *model* based on other sensing modalities which can provide sufficiently *accurate prediction* as a substitute for direct measurement.

Imagers are an untapped sensing modality

- Domain knowledge can suggest meaningful ways to process images of a given biological phenomena**
Biologists know which signals are important for understanding a particular phenomena. This *domain specific* knowledge can be codified into a set of *image features* which we can compute.
- Models based on image features turn imagers into first-class biological sensors**
These models can predict ground-truth that isn't readily apparent from the images, a technique we call *applied vision*. Unlike general vision, the ground-truth is not easily recognizable by humans.

Problem Description: Estimating CO₂ uptake of a drought tolerant moss from images

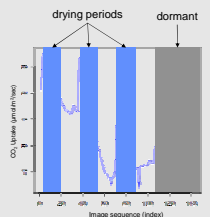
Field measurement of CO₂ uptake is bulky and invasive

- What is CO₂ uptake?**
CO₂ uptake ($\mu\text{mol}/\text{m}^2/\text{sec}$) is the amount of CO₂ *absorbed* or *released* by a plant during photosynthesis. Domain knowledge suggests that the *greenness* of the plant should be a good predictor of CO₂ uptake.
- Why is CO₂ uptake important?**
Dense measurement of plant CO₂ uptake can be extrapolated to entire forests. Such measurements can be used to refine the model of the *global carbon cycle*.



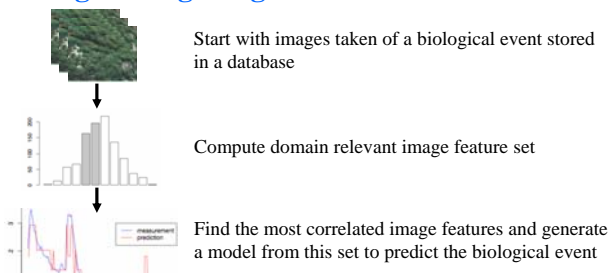
Experimental Setup

- Water the moss and cycle light source on and off**
Simulate a rain event and subsequent days and nights. The moss dries as water evaporates; during darkness, the water is redistributed. When dry throughout, the moss becomes dormant.
- Measure CO₂ uptake using spectroscopy**
Moss samples are kept in a controlled environment (left top), intake and exhaust air's CO₂ contents is measured (left bottom). Labeled graph of CO₂ uptake from one drying cycle shown to the right.



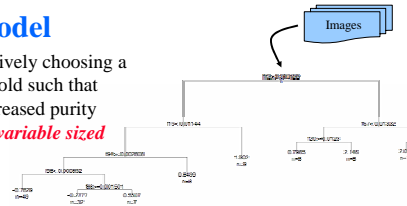
Proposed Solution: Build statistical models from ground truth data gathered in the lab

Building sensing imagers

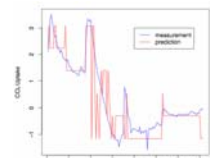


Regression based model

Build a *regression tree* by recursively choosing a feature and corresponding threshold such that examples in child nodes have increased purity (resulting tree on right). Creates *variable sized* pseudo-bands based on the data.



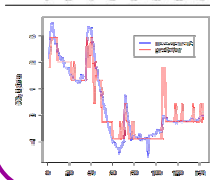
Prediction accuracy



Classification based model	
Lab sensor measurement error	0.10 μmol
Acceptable model error	0.50 μmol
Model's RMS error	0.74 μmol

Explanation of error

- too few classes to cover all drying states
- many classes had too little training data
- classes of fixed size, doesn't reflect reality



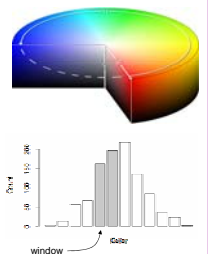
Regression based model	
Lab sensor measurement error	0.10 μmol
Acceptable model error	0.50 μmol
Model's RMS error	0.49 μmol

Better prediction

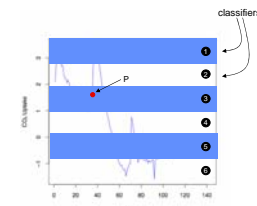
- nine (9) "bands" chosen intelligently
- "bands" are *data adaptive* rather than static

Extracted Features

- Domain knowledge suggests that color, specifically *greenness*, is a good predictor
- Compute HSV (Hue, Saturation, Value) *histogram*
 - more stable than RGB
 - inexpensive to compute
- Compute a set of variable sized *windows*, grouping similar colors (right bottom)



Classification based model



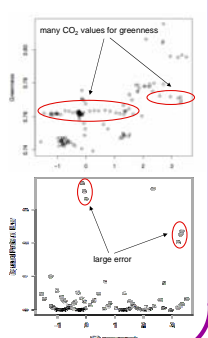
Classifier	1	2	3	4	5	6
Response	-2.19	1.54	3.08	2.33	-1.37	-3.21

Response is the distance to the hyper-surface separating class K from all other points

- Training**
Divide range of values into six *equal-sized* bands and train six binary *SVM* based classifiers using all generated features.
- Prediction**
A point P is in class K if the Kth binary classifier responds most strongly (table to the left). A classified point P is assigned the *median* value of class K.

Error analysis

- Likely locations of high error revealed by rudimentary greenness measure (right top)
- Many different CO₂ measurements for a greenness value makes prediction more difficult
- The squared error is *parabolic-shaped* because one value is assigned to each "band" (right bottom).



Biological reason:

- Same approximate color for different stages of drying
- Moss drying stage dictates CO₂ uptake